

Analyzing black-box optimization algorithms - why and how?



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Journées ALEA, CIRM



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Optimization (in its simplest form)

optimization: for a given function $f: S \rightarrow \mathbb{R}$,
find $x \in S$ with $f(x)$ maximal/minimal

Examples:

- **TSP:** traveling salesperson problem
- **shortest path** between two vertices in a graph
- grid percolation model: smallest radius such that the graph is connected
- ...

(more or less)
well-studied (academic) problems,
often with hand-crafted solutions

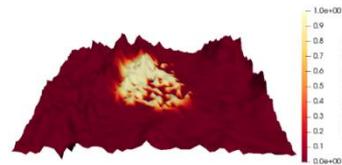
Optimization in (my) real life



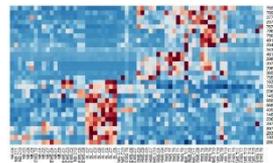
*complex
problems*



logistics



network optimization



biomedicine



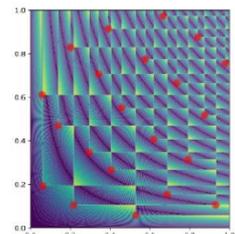
engineering



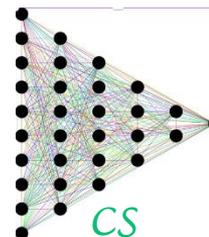
*high time
pressure*



economics



math (!)



CS

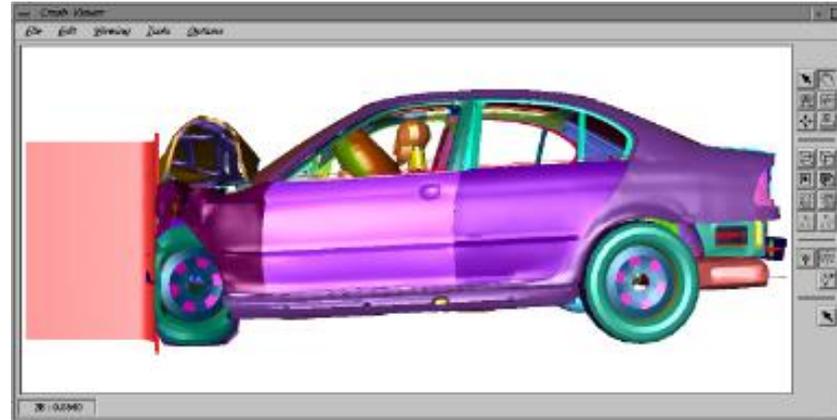
etc...

Black-box optimization



Evaluations:

- simulations



[Picture: Dissertation Norbert Frisch]

Black-box optimization

x →



Evaluations:

- simulations
- physical experiments



pictures taken from <https://pixabay.com/>

Black-box optimization

x →



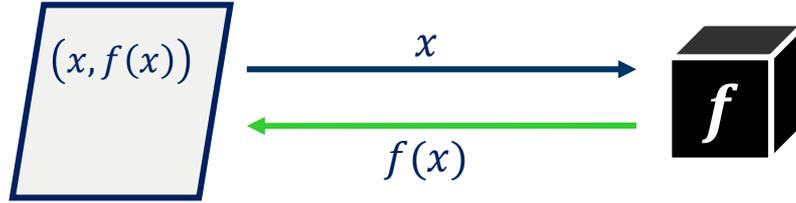
Evaluations:

- simulations
- physical experiments
- user study



Bouillabaisse, picture taken from <https://www.tasteatlas.com/best-dishes-in-marseille>

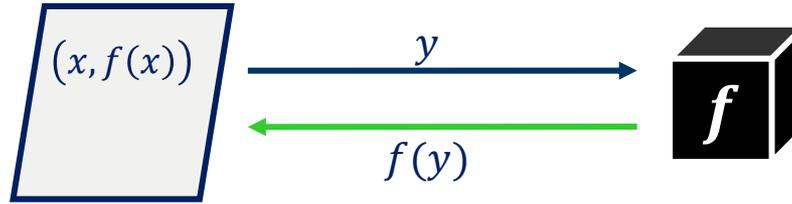
Black-box optimization



Evaluations:

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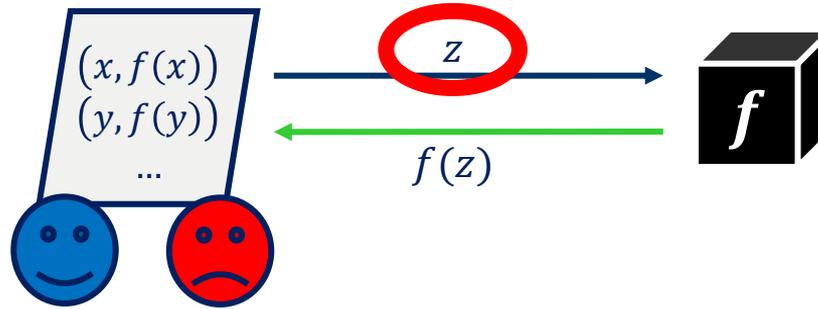
Black-box optimization



Evaluations:

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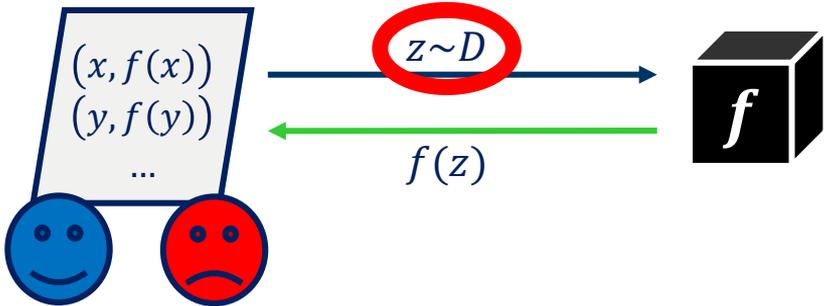
Black-box optimization



Evaluations:

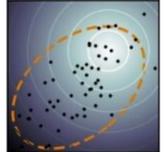
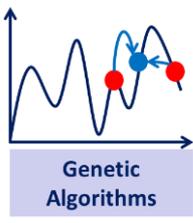
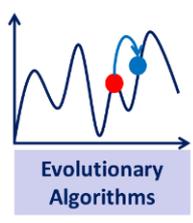
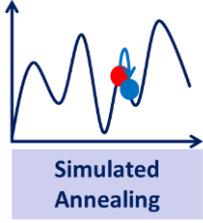
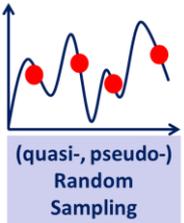
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Black-box optimization



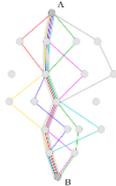
Evaluations:

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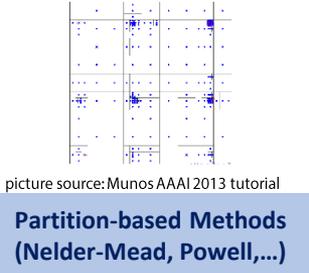
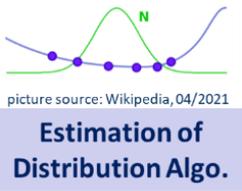


picture source: Wikipedia, 04/2021

Population-based Algo.



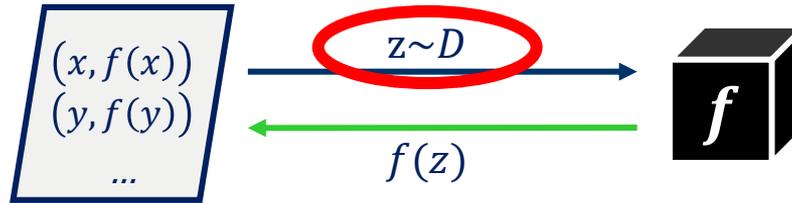
Swarm Intelligence



many (MANY!) more...

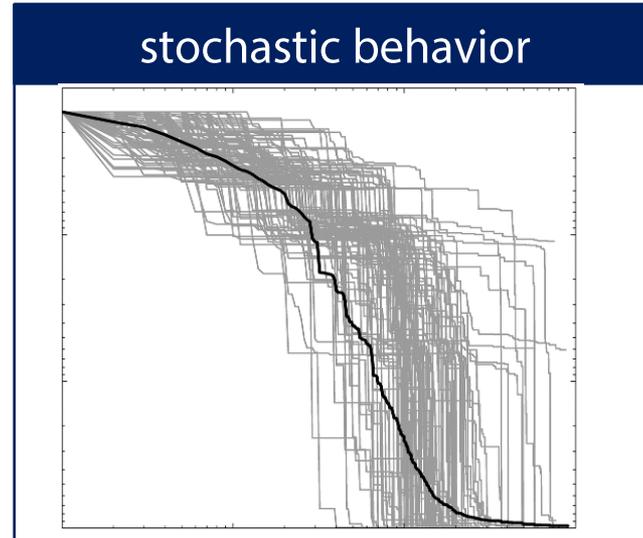
Which algorithm to use for which problem?

Complexity of analyzing black-box optimization algorithms

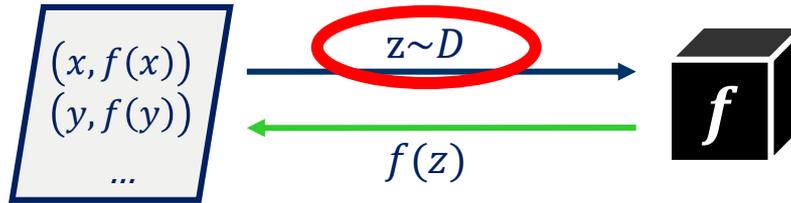


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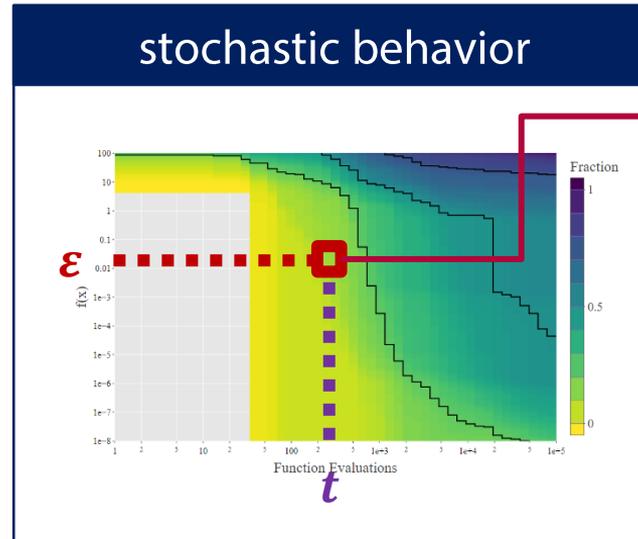


Complexity of analyzing black-box optimization algorithms



Evaluations:

- simulations
- physical experiments
- user study



attainment function:
probability that algo A finds
a **solution of loss $\leq \epsilon$**
within the first t evaluations

**in discrete
optimization: expected
optimization time**

(Some of) our research objectives

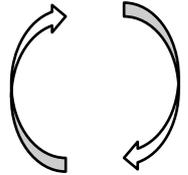
1 mathematical curiosity: understand the performance and the behavior of black-box optimization algorithms and not: given a problem, design an efficient algorithm

2 configuration: how does the performance depend on chosen (hyper-/control)parameters?

3 selection: which algorithm to use for what kind of problems?



Theory



Practice



Example

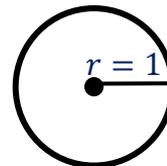
Randomized Local Search (RLS) for maximizing $f: \{0, 1\}^n \rightarrow \mathbb{R}$

Initialization:

Choose $x \in \{0, 1\}^n$ uniformly at random (u.a.r.).

Optimization: in iteration $t = 1, 2, \dots$ do

1. *variation:* create y from x by flipping a randomly chosen bit
2. *greedy selection:* if $f(y) \geq f(x)$, replace x by y



- ✓ simple
- ✓ no memory needed
- ? slow (?)
- × can get stuck in local optima

Example

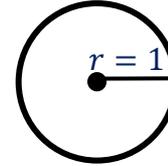
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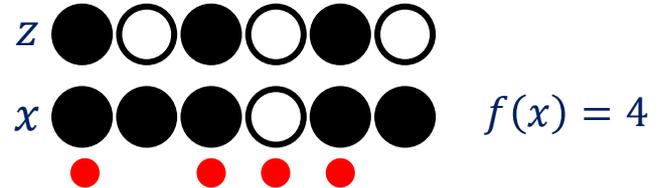


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The OneMax problem (*Mastermind with 2 colors*)

Unknown target vector $z \in \{0,1\}^n$

Score of a search point x is $\# \{i \mid x_i = z_i\} = n - H(x, z)$



expected optimization time for RLS to solve OneMax?

when $f(x) = i$, then $\mathbb{P}[f(y) = i + 1] = \frac{n-i}{n}$

coupon collector (with random initial assets) $\rightarrow (1 \pm o(1)) n \ln(n)$

Theorem (Erdős, Renyi 1963): Query complexity of OneMax is $\Theta(n/\log n)$

Proof: (upper bound) sample $2n/\log n$ strings u.a.r. (+some basic math).



Example

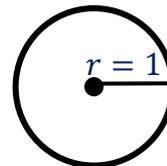
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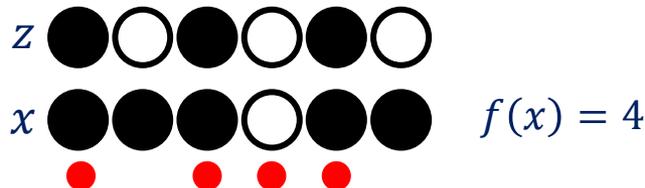


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Example

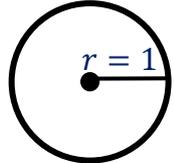
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- ? slow (?)
- ✗ can get stuck in local optima

change neighborhood from which candidates are sampled

change selection to less greedy (e.g., Simulated Annealing)

...

active control of radius ("step size")

random choice of radius ("step size")

...

Example for parameter control

Randomized Local Search (RLS)

with active ε -greedy multi-armed bandit parameter control

given: possible parameter values (=radii) r_1, \dots, r_k

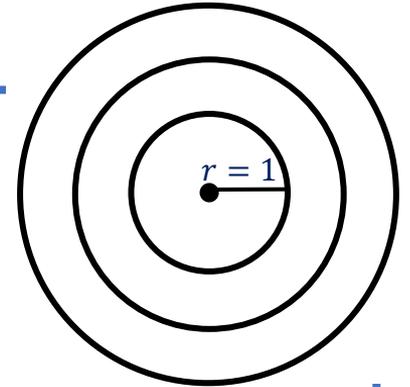
Initialization:

Choose $x \in \{0,1\}^n$ uniformly at random (u.a.r.).

Initialize all confidences c_1, \dots, c_k as $1/k$

Optimization: in iteration $t = 1, 2, \dots$ do

1. *choose radius:*
 - with probability $1-\varepsilon$, choose radius r with highest confidence (ties broken u.a.r.)
 - choose r u.a.r. otherwise
2. *variation:* create y from x by flipping r randomly chosen bit
3. *greedy selection:* if $f(y) \geq f(x)$, replace x by y
4. *update the confidences* c_1, \dots, c_k



Example for random parameter choice

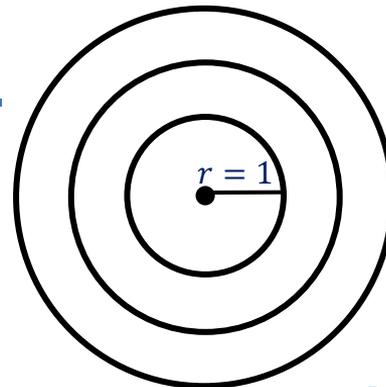
The (1+1) Evolutionary Algorithm with mutation rate $0 < p < 1$
= Randomized Local Search (RLS) with randomly chosen radius

Initialization:

Choose $x \in \{0,1\}^n$ uniformly at random (u.a.r.).

Optimization: in iteration $t = 1, 2, \dots$ do

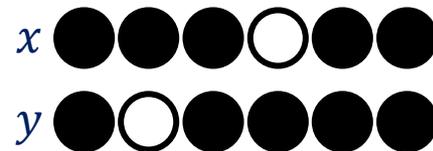
1. *choose radius r from binomial distribution $\text{Bin}(n, p)$*
2. *variation:* create y from x by flipping r randomly chosen bit
3. *greedy selection:* if $f(y) \geq f(x)$, replace x by y



Why “evolutionary” algorithm?

alternative way to do steps 1 and 2:

create y from x by flipping each bit with probability $1/n$



The (1+1) EA behaves like RLS “on average” but can escape local optima.

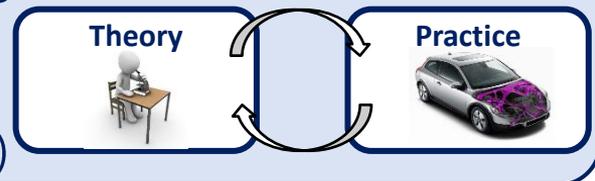
Expected optimization time on OneMax: $\leq en \ln n$

goals of the ERC project (in a nutshell)

“from controlling parameters to dynamic choice of algorithms”

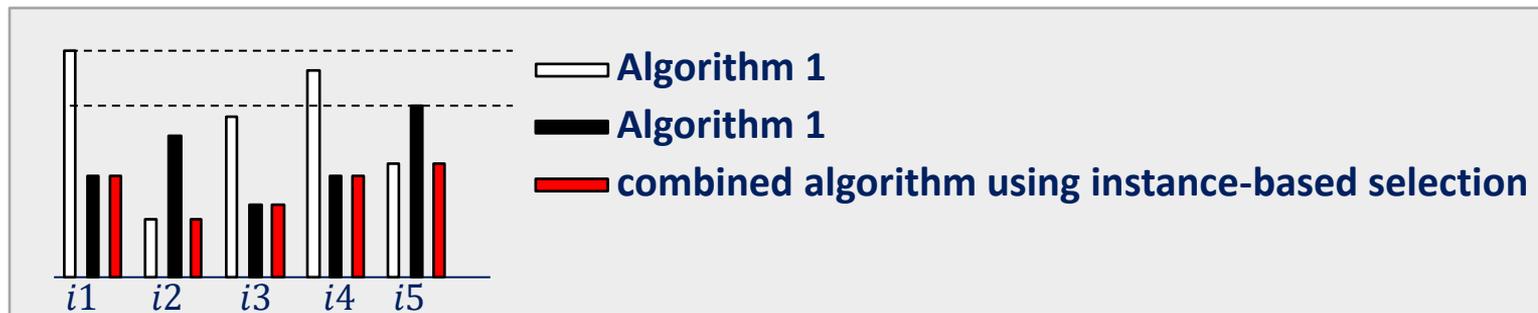
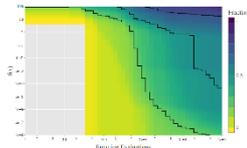
leverage strengths of different algorithms

- ✓ for different phases of the optimization process
- ✓ for different types of problems (type not known in advance!)



Key challenges (theory):

- forces us to understand **attainment functions**
 - > much more fine-grained than “just” expected optimization times
- **warm-starting**: how to hand over information from one algo to another one?
- from worst-case analysis to **instance-based analysis**

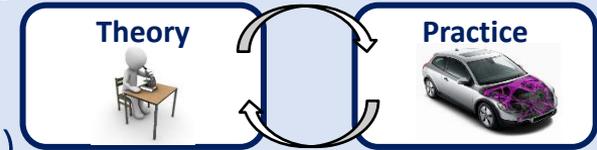


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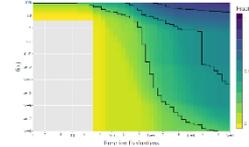
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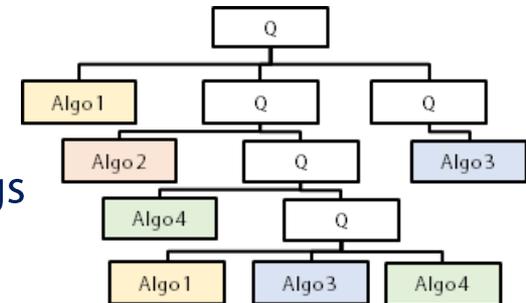
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Key challenges (practice):

- develop guidelines for **default solver(s)** for popular settings

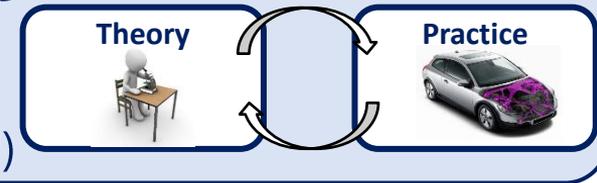


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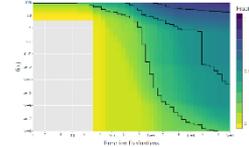
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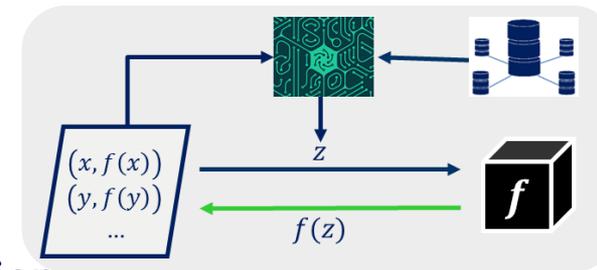
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Key challenges (practice):

- develop guidelines for **default solver(s)** for popular settings
- use of **machine learning techniques** to guide dynamic selection



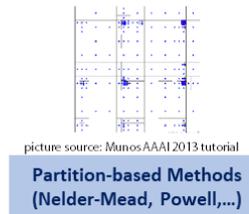
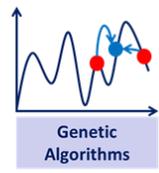
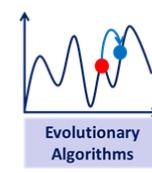
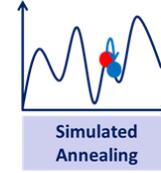
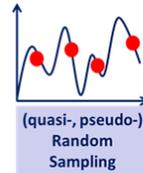
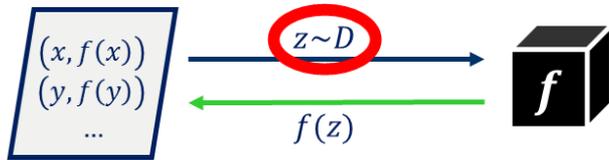
Take-home message(s)

Black-box optimization algorithms are

- ✓ quite crucial for solving many real-world problems
- ✗ not well understood (neither theoretically nor practically/empirically)



Many randomized decisions – we probably use many similar tools
(concentration bounds, potential function arguments, drift theorems,...)



many (MANY!) more...