

Title: Support stability of maximizing measures

Abstract: In this talk we present the results of [1] that establishes a fundamental difference between \mathbb{Z} subshifts of finite type and \mathbb{Z}^2 subshifts of finite type in the context of ergodic optimization. Specifically we consider a subshift of finite type X as a subset of a full shift F . We then introduce a natural penalty function f , defined on F , which is 0 if the local configuration near the origin is legal and -1 otherwise.

We show that in the case of \mathbb{Z} subshifts, for all sufficiently small perturbations, g , of f , the g -maximizing invariant probability measures are supported on X (that is the set X is *stably maximized* by f). However, in the two-dimensional case, we show that the well-known Robinson tiling fails to have this property: there exists arbitrarily small perturbations, g , of f , for which the g -maximizing invariant probability measures are supported on $F \setminus X$. This is a joint work with Anthony Quas and Jason Siefken.

[1] Juliano S. Gonschorowski, Anthony Quas and Jason Siefken, **Support stability of maximizing measures for shifts of finite type** *Ergodic Theory and Dynamical Systems*, Volume 41, Issue 3, March 2021, pp. 869 - 880