

Nonlinear coupling of Poisson-Nernst-Planck equations with Discrete Duality Finite Volumes : Application to Dendritic spines.

CIRM 2022

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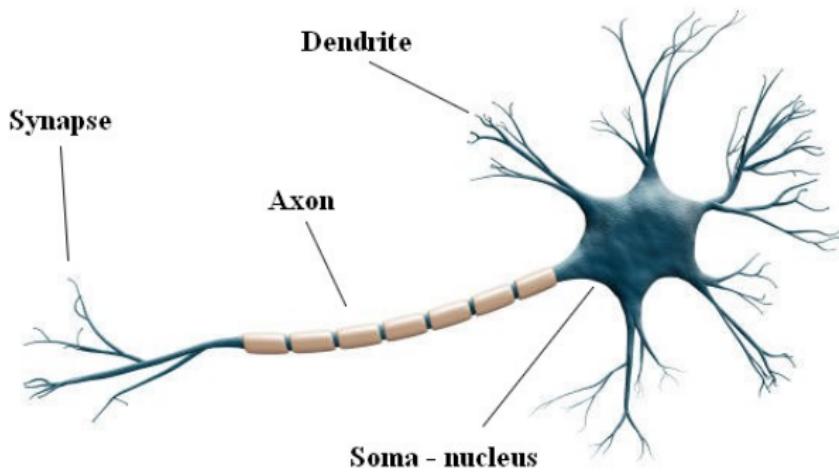
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Laboratoire J.A.Dieudonné

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Context of the study

- Nerve cell specializing in information processing

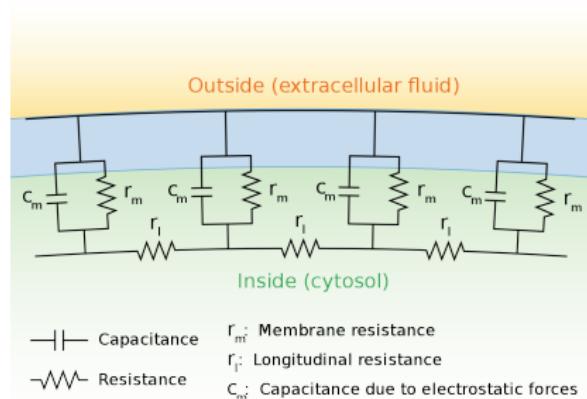


Source : Neuron-bank-istockphoto.com

Cable Theory

→ 1D equation with the Cable Theory (1850s)

◆ V the electric potential



Source : Wikipedia

Nodal rule (Kirchhoff)

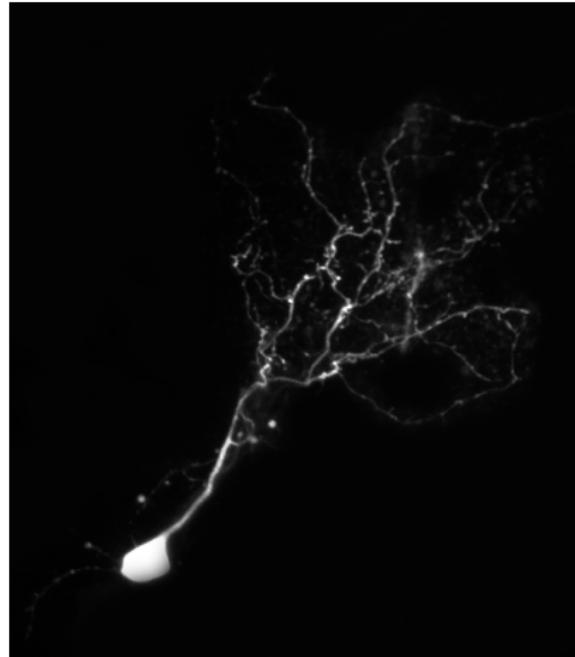
$$i_m = i_c + i_r$$

Following Model

$$\frac{1}{r_l} \frac{\partial^2 V}{\partial x^2} = c_m \frac{\partial V}{\partial t} + \frac{V}{r_m}$$

Limits of the model and interest on a new model

- Dendritic spine diameter $\sim 0.1\mu\text{m}$



Calcium imaging from the Haas Lab (Brain Research Center, UBC, Vancouver)

General system of equations

Poisson-Nernst-Planck (PNP) system for i ionic species on domain Ω and with T_f a finite time (+B.Cs on $\partial\Omega$ and I.Cs)

- ▶ Ionic concentration of i species c_i with $z_i = \pm 1$
- ▶ Electric potential V

$$\operatorname{div}(\nabla V) = - \sum_i A z_i c_i, \quad \text{in } \Omega \times (0, T_f),$$

$$\frac{\partial c_i}{\partial t} - \operatorname{div}(D_i \nabla c_i + \Lambda D_i z_i c_i \nabla V) = 0, \quad \text{in } \Omega \times (0, T_f).$$

◆ $c_i(x, t)$ and $V(x, t)$ unknowns of the system

◆ $A = \frac{F}{\epsilon \epsilon_0}$, $\Lambda = \frac{F}{RT_\theta}$ and D_i physical parameters

PNP system in 1D for $i = 1$

PNP system for a cation on Ω (+B.Cs on $\partial\Omega$ and I.Cs)

- ▶ Ionic concentration of a cation c_P with $z_P = +1$
- ▶ Electric potential V

$$\begin{aligned}\frac{\partial^2 V}{\partial x^2} &= -A c_P, && \text{in } \Omega \times (0, T_f), \\ \frac{\partial c_P}{\partial t} - \frac{\partial}{\partial x} \left(D_P \frac{\partial c_P}{\partial x} + \Lambda D_P c_P \frac{\partial V}{\partial x} \right) &= 0, && \text{in } \Omega \times (0, T_f).\end{aligned}$$

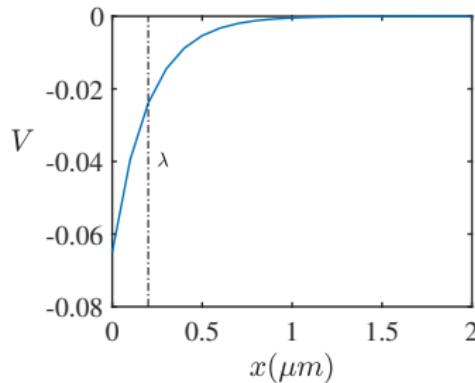
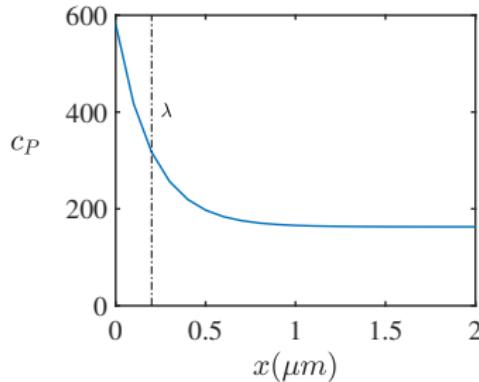
- ◆ Behaviours of $c_P(x, t)$ and $V(x, t)$?

Stationary solutions of c_P and V

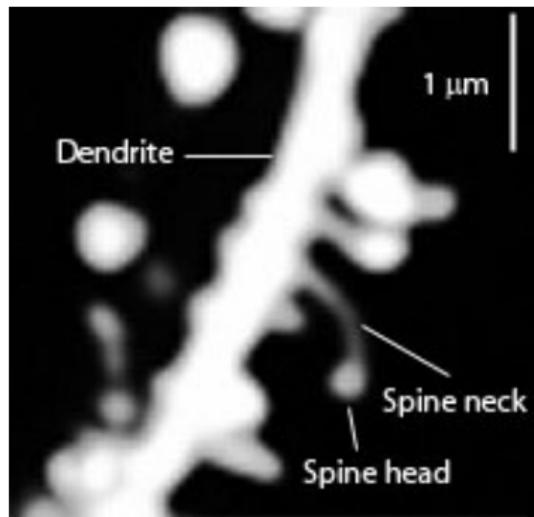
► Asymptotic development → Electric boundary layer (λ the Debye layer)

~~~ Approximated solutions of  $c_P$  and  $V$

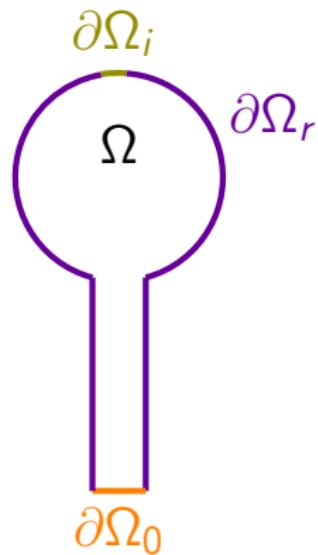
$$c_P = c_0 e^{-\frac{F}{RT_\theta} V} \quad \text{and} \quad V \approx V_0 e^{-\frac{x}{\lambda}} \quad \text{with } \lambda^2 = \frac{\epsilon \epsilon_0 R T_\theta}{F^2 C_P}.$$



# Dendritic spine



Imaging of dendritic spine  
(Wikipedia).



Spine representation with  $\Omega$   
domain and boundaries  
 $\partial\Omega = \partial\Omega_i \cup \partial\Omega_r \cup \partial\Omega_o$ .

## Configuration of PNP system on dendritic spine domain

- ▶ Ionic concentration of a cation  $c_P$  with  $z_P = +1$
- ▶ Ionic concentration of an anion  $c_N$  with  $z_N = -1$
- ▶ Electric potential  $V$

$$\operatorname{div}(\nabla V) = -A(c_P - c_N), \quad \text{in } \Omega \times (0, T_f),$$

$$\frac{\partial c_P}{\partial t} - D_P \operatorname{div}(\nabla c_P + \Lambda c_P \nabla V) = 0, \quad \text{in } \Omega \times (0, T_f),$$

$$\frac{\partial c_N}{\partial t} - D_N \operatorname{div}(\nabla c_N - \Lambda c_N \nabla V) = 0, \quad \text{in } \Omega \times (0, T_f).$$

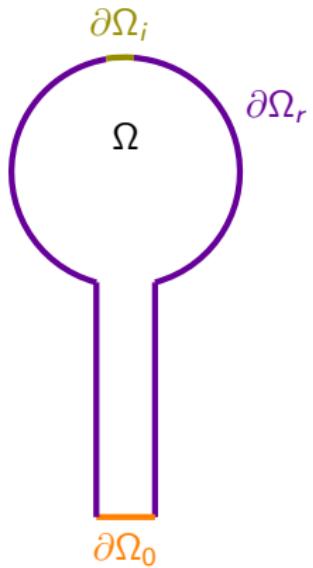
◆  $c_P(x, t)$ ,  $c_N(x, t)$  and  $V(x, t)$  unknowns of the system

## Boundary conditions of dendritic spine domain

On  $\partial\Omega_o \times (0, T_f)$

- ◆  $V = 0$ ,
- ◆  $c_P = c_P^0$ ,
- ◆  $c_N = c_N^0$ .

►  $c_P^0, c_N^0$  initial ionic concentrations.



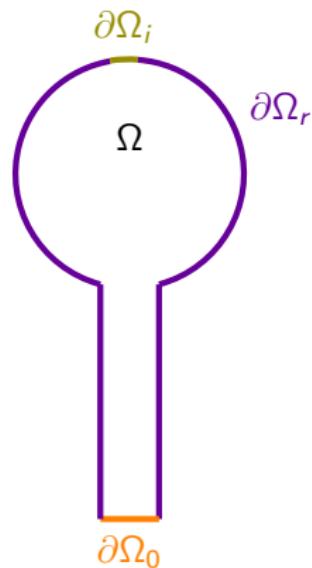
## Boundary conditions of dendritic spine domain

On  $\partial\Omega_i \cup \partial\Omega_r \times (0, T_f)$

$$\diamond \frac{\partial c_N}{\partial n} - \Lambda c_N \frac{\partial V}{\partial n} = 0.$$

On  $\partial\Omega_r \times (0, T_f)$

$$\diamond \frac{\partial c_P}{\partial n} + \Lambda c_P \frac{\partial V}{\partial n} = 0.$$



## Boundary conditions of dendritic spine domain

On  $\partial\Omega_i \cup \partial\Omega_r \times (0, T_f)$

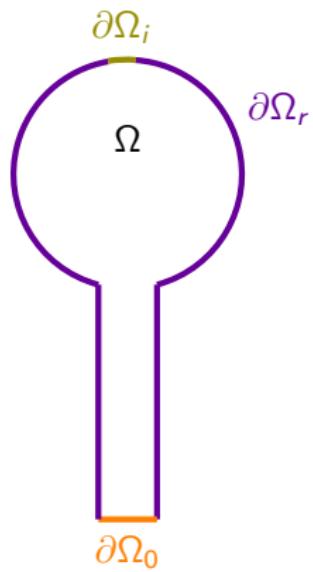
◆  $\frac{\partial V}{\partial n} = -\frac{\rho}{\epsilon\epsilon_0}$ .

►  $\rho$  the charge density.

On  $\partial\Omega_i \times (0, T_f)$

◆  $\frac{\partial c_P}{\partial n} + \Lambda_{CP} \frac{\partial V}{\partial n} = I$ .

►  $I$  the injected synaptic current.



## Dendritic spine coefficients

- ▶ Injected synaptic current from [Cartailler and al.2018]

- ◆  $I = \frac{I_{stim}(t)}{\pi r_i^2 F D_P}$  with  $I_{stim}(t) = I_{max} \frac{t}{\tau} \exp(-\frac{t}{\tau} + 1)$

- ◆  $I_{max}$  the maximal current

- ◆  $\tau$  the decay time constant

- ◆  $r_i$  the radius of  $\partial\Omega_i$

- ▶ Initial conditions

$$V(\cdot, 0) = 0, \quad \text{in } \Omega,$$

$$c_P(\cdot, 0) = c_P^0, \quad \text{in } \Omega,$$

$$c_N(\cdot, 0) = c_N^0, \quad \text{in } \Omega.$$

## Key property

- Reformulation in non-linear form [Cancès and al.2018]

$$\frac{\partial c_P}{\partial t} = D_P \operatorname{div}(c_P \nabla(\log c_P + \Lambda V))$$

$$\frac{\partial c_N}{\partial t} = D_N \operatorname{div}(c_N \nabla(\log c_N - \Lambda V)).$$

⇒ Positivity of  $c_P, c_N$

- ◆ Solving PNP system with the non-linear term using Discrete Duality Finite Volume (DDFV) method.

## DDFV notations

- $\mathcal{T}$  the set of primal and dual meshes  $\mathcal{T} = (\mathcal{M}, \mathcal{M}^*)$
- $\mathfrak{D}$  the diamond mesh

Discrete solutions :  $\rightsquigarrow \mathbf{u}_{\mathcal{T}} = (u_{\mathcal{M}}, u_{\mathcal{M}^*}) \in \mathbb{R}^{\mathcal{T}}$

- $\text{div}^{\mathcal{T}}(\xi^{\mathfrak{D}})$  the discrete divergence operator
- $\nabla^{\mathfrak{D}}(\mathbf{u}_{\mathcal{T}})$  the discrete gradient operator
- ◆  $\mathcal{K}$  and its neighbour  $\mathcal{L}$ , centers in  $\mathcal{M}$
- ◆  $\mathcal{K}^*$  and its neighbour  $\mathcal{L}^*$ , vertices in  $\mathcal{M}^*$

## PNP scheme

- DDFV scheme for  $(c_P^{n+1}, c_N^{n+1}, V_T^{n+1})$  (+B.Cs and I.Cs)

$$-\operatorname{div}^{\mathcal{T}}(\nabla^{\mathfrak{D}} V_T^{n+1}) + A(c_N^{n+1} - c_P^{n+1}) = 0,$$

$$\frac{c_P^{n+1} - c_P^n}{\Delta t} + D_P \operatorname{div}^{\mathcal{T}}(J_{\mathfrak{D}}^{n+1}) = 0,$$

$$\frac{c_N^{n+1} - c_N^n}{\Delta t} + D_N \operatorname{div}^{\mathcal{T}}(G_{\mathfrak{D}}^{n+1}) = 0,$$

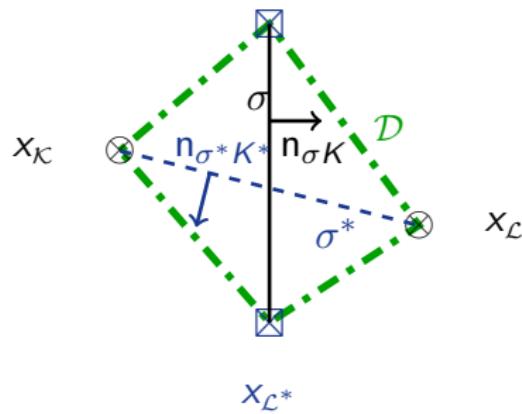
$$J_{\mathfrak{D}}^{n+1} = -r^{\mathfrak{D}}(c_P^{n+1}) \nabla^{\mathfrak{D}} (\log c_P^{n+1} + \Lambda V_T^{n+1}),$$
$$G_{\mathfrak{D}}^{n+1} = -r^{\mathfrak{D}}(c_N^{n+1}) \nabla^{\mathfrak{D}} (\log c_N^{n+1} - \Lambda V_T^{n+1}).$$

## DDFV operator

## RECONSTRUCTION OPERATOR

$$x_{k^*}$$

constant on each diamond cell



$\forall \mathcal{D} \in \mathfrak{D},$

$$r^{\mathcal{D}}_{\textcolor{violet}{UT}} = \frac{1}{4}(u_{\mathcal{K}} + u_{\mathcal{L}} + u_{\mathcal{K}^*} + u_{\mathcal{L}^*}).$$

## Numerical results

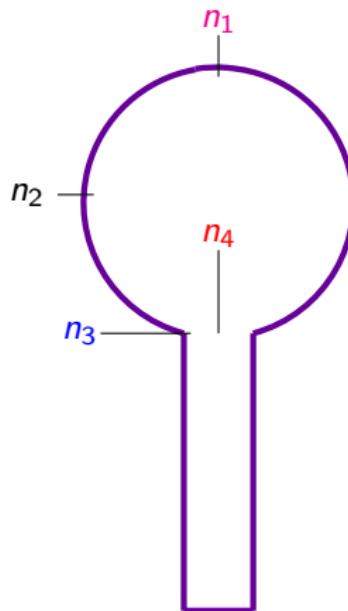
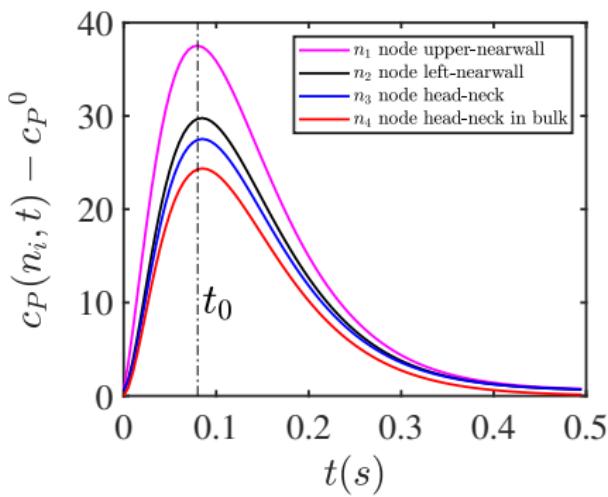
- ▶ Application to ionic and voltage dynamics in a dendritic spine  
*cP* simulation (left) and zoom simulation of the junction head-neck (right)  
on  $\Omega$  with  $T_f = 0.5\text{s}$ .

## Numerical results

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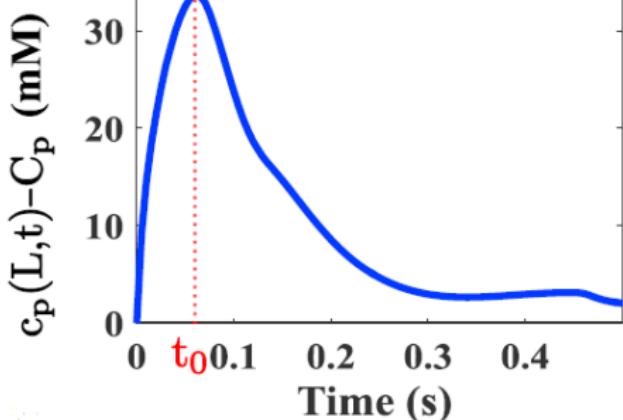
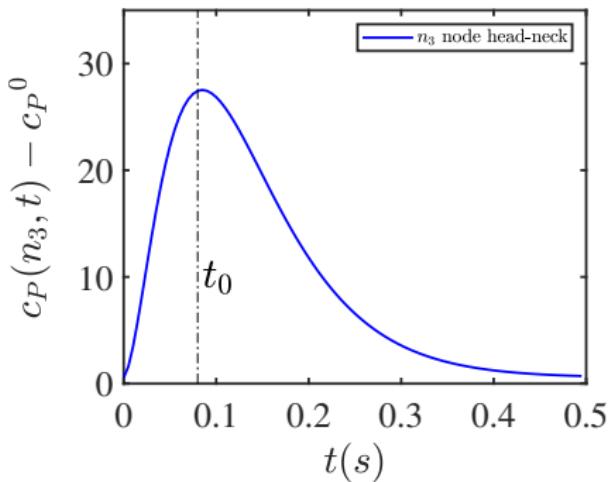
## Numerical results

$c_P$  simulations at different locations on  $\Omega$



## Comparaison with existing results with biological data

$c_P$  simulations : left from our code and right from [Cartailler and al.2018]



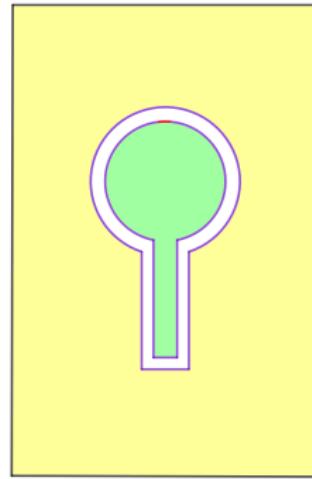
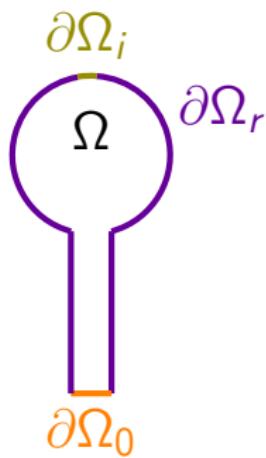
## Conclusion and Perspectives

- ▶ Numerical scheme with positivity conservation on ionic concentrations

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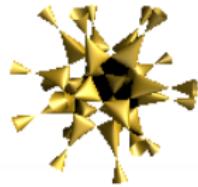
- ▶ Numerical scheme with positivity conservation on ionic concentrations
- ▶ Is the BC for  $V$  on  $\partial\Omega_i \cup \partial\Omega_r$  right ?

◆ Reminder :  $\frac{\partial V}{\partial n} = -\frac{\rho}{\epsilon\epsilon_0}$ , on  $\partial\Omega_i \cup \partial\Omega_r \times (0, T_f)$ .



# Conclusion and Perspectives

Thank you for your attention



## References

- ▶ Hodgkin AL, Huxley AF (August 1952). "A quantitative description of membrane current and its application to conduction and excitation in nerve". *The Journal of Physiology*. 117 (4) : 500–44.
- ▶ Kirby, B. J. (2010). "Micro-and nanoscale fluid mechanics : transport in microfluidic devices." Cambridge university press.
- ▶ Cartailler, J., Kwon, T., Yuste, R., Holcman, D. (2018). Deconvolution of voltage sensor time series and electro-diffusion modeling reveal the role of spine geometry in controlling synaptic strength. *Neuron*, 97(5), 1126-1136.
- ▶ Cancès, C., Chainais-Hillairet, C., Krell, S. (2018). Numerical analysis of a nonlinear free-energy diminishing discrete duality finite volume scheme for convection diffusion equations. *Computational Methods in Applied Mathematics*, 18(3), 407-432.

## Annexe

### ► Scheme for Neumann boundary conditions

$$m_\sigma \nabla^{\mathcal{D}} V_{\mathcal{T}}^{n+1} \cdot n = 0, \quad \forall \mathcal{D} \in \mathfrak{D}_{\partial\Omega_i \cup \partial\Omega_r},$$

$$m_\sigma G_{\mathcal{D}}^{n+1} \cdot n = 0, \quad \forall \mathcal{D} \in \mathfrak{D}_{\partial\Omega_i \cup \partial\Omega_r},$$

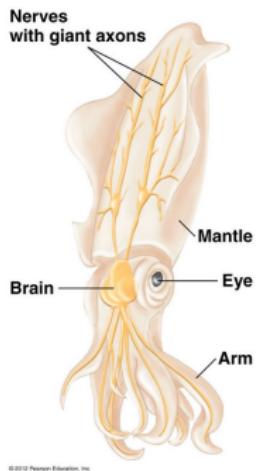
$$m_\sigma J_{\mathcal{D}}^{n+1} \cdot n = 0, \quad \forall \mathcal{D} \in \mathfrak{D}_{\partial\Omega_r},$$

$$m_\sigma J_{\mathcal{D}}^{n+1} \cdot n = I, \quad \forall \mathcal{D} \in \mathfrak{D}_{\partial\Omega_i},$$

# Hodgkin and Huxley model

First mathematical model published by Hodgkin and Huxley in 1952

- ▶ Squid Giant Axon with diameter  $\sim 1\text{mm}$



Source : Researchgate.com

Source : Wikipedia