

A survey of the basics of 3D DDFV schemes, and the 2D CVFE (co-volume) scheme

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based on works of

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- 1 **Main features of 2D DDFV**
- 2 **The 3D CeVeFE-DDFV scheme**
- 3 **The 2D co-volume scheme is a Discrete Duality scheme**
- 4 **The 3D CeVe-DDFV scheme**

Main features of 2D DDFV

(having in mind the calculus of gradient schemes)

2D DDFV meshes and functional framework.

- Domain Ω partitioned twice by double mesh $\mathcal{T} = (\mathfrak{M}, \mathfrak{M}^*)$ consisting of a **primal mesh** \mathfrak{M} + its **dual mesh** $\overline{\mathfrak{M}^*} = \mathfrak{M}^* \cup \partial\mathfrak{M}^*$;
 \rightsquigarrow discrete function $u^{\mathcal{T}} = (u^{\mathfrak{M}}, u^{\mathfrak{M}^*})$, $u^{\mathfrak{M}} = (u_K)_{K \in \mathfrak{M}}$, idem $u^{\mathfrak{M}^*}$
 \rightsquigarrow **space $\mathbb{R}^{\mathcal{T}}$ of discrete functions, scalar product**

$$[u^{\mathcal{T}}, v^{\mathcal{T}}] := \frac{1}{2} \sum_{K \in \mathfrak{M}} |K| u_K v_K + \frac{1}{2} \sum_{K^* \in \mathfrak{M}^*} |K^*| u_{K^*} v_{K^*}$$

\rightsquigarrow zero boundary values: up-to-the-boundary space $\mathbb{R}_0^{\overline{\mathcal{T}}}$

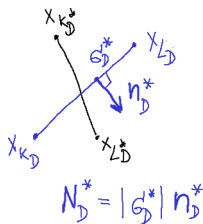
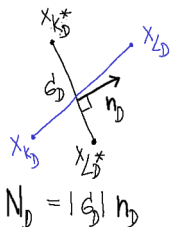
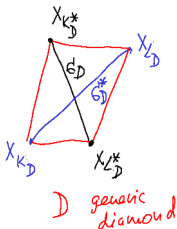
- **Diamond mesh** \mathfrak{D} \rightsquigarrow discrete fields $\mathcal{F}^{\mathfrak{D}} = (\mathcal{F}_D)_{D \in \mathfrak{D}}$
 \rightsquigarrow **Space $(\mathbb{R}^2)^{\mathfrak{D}}$ of discrete fields, scalar product**

$$\{\mathcal{F}^{\mathfrak{D}}, \mathcal{G}^{\mathfrak{D}}\} := \sum_{D \in \mathfrak{D}} |D| \mathcal{F}_D \cdot \mathcal{G}_D$$

- **discrete gradient** $\nabla^{\mathfrak{D}} : \mathbb{R}_0^{\overline{\mathcal{T}}} \rightarrow (\mathbb{R}^2)^{\mathfrak{D}}$
discrete divergence $\operatorname{div}^{\mathcal{T}} : (\mathbb{R}^2)^{\mathfrak{D}} \rightarrow \mathbb{R}^{\mathcal{T}}$
- projections of $C_c(\Omega)$ functions / of $C_c(\Omega; \mathbb{R}^2)$ fields:

$$\mathbb{P}^{\overline{\mathcal{T}}} \text{ (projection on } \mathbb{R}_0^{\overline{\mathcal{T}}}\text{),} \quad \mathbb{P}^{\mathfrak{D}} \text{ (projection on } (\mathbb{R}^2)^{\mathfrak{D}}\text{)}$$

Notation in a diamond. Discrete gradient. Exactness on affine functions.



- diamonds $\mathcal{D} \in \mathcal{D}$ used as generic label.
Formalism of per-diamond weighted normals: $\mathbf{N}_D, \mathbf{N}_D^*$
- Discrete gradient defined per diamond by

$$\nabla_{\mathcal{D}} u^{\overline{T}} := \frac{1}{2|\mathcal{D}|} \left((u_{L_D} - u_{K_D}) \mathbf{N}_D + (u_{L_D^*} - u_{K_D^*}) \mathbf{N}_D^* \right)$$

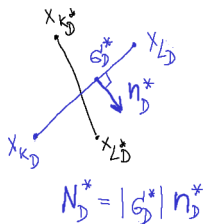
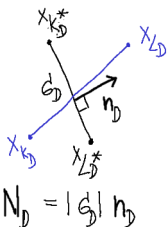
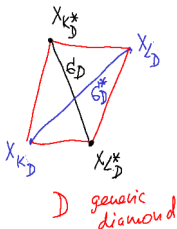
- Per-projection representation, explaining the definition:

$$\nabla_{\mathcal{D}} u^{\overline{T}} \cdot \overrightarrow{x_{K_D} x_{L_D}} = u_{L_D} - u_{K_D}$$

$$\nabla_{\mathcal{D}} u^{\overline{T}} \cdot \overrightarrow{x_{K_D^*} x_{L_D^*}} = u_{L_D^*} - u_{K_D^*}$$

- Exactness: if $\forall x \in \mathcal{D}, \nabla u(x) \equiv \mathcal{G} = \text{const}$, then $\nabla_{\mathcal{D}} \mathbb{P}^{\overline{T}} u = \mathcal{G}$

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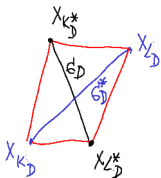
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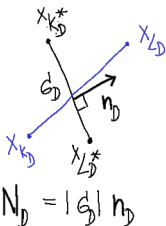
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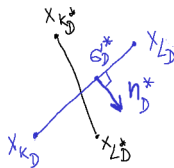
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\mathcal{D} generic diamond



$$\mathbf{N}_D = |g_D| n_D$$



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Discrete divergence. Discrete Duality.

- Notation: $\mathcal{D} \sim K$ if $\sigma_{\mathcal{D}} \subset \partial K$; idem $\mathcal{D} \sim K^*$ if $\sigma_{\mathcal{D}}^* \subset \partial K^*$
- Per-diamond weighted normals associated with cells:

$$\text{for } \mathcal{D} \sim K, \quad \mathbf{N}_{\mathcal{D}}^K = \begin{cases} +\mathbf{N}_{\mathcal{D}} & \text{if } K = K_{\mathcal{D}} \\ -\mathbf{N}_{\mathcal{D}} & \text{if } K = L_{\mathcal{D}}. \end{cases}$$

Idem for $\mathcal{D} \sim K^*$: $\mathbf{N}_{\mathcal{D}}^{K^*} = +\mathbf{N}_{\mathcal{D}}^*$ or $-\mathbf{N}_{\mathcal{D}}^*$ (the outward choice).

- **Discrete divergence** defined per primal/dual cell in the FV way:

$$\iint_K \operatorname{div} \mathcal{F} = \int_{\partial K} \mathcal{F} \cdot \mathbf{n}^K = \sum_{\sigma \subset \partial K} \mathcal{F}|_{\sigma} \cdot \underbrace{|\sigma| \mathbf{n}^K}_{\mathbf{N}^K}, \quad \text{and idem for } K^*$$

$$\implies$$

$$\operatorname{div}_K \mathcal{F}^{\mathcal{D}} = \frac{1}{|K|} \sum_{\mathcal{D} \sim K} \mathcal{F}_{\mathcal{D}} \cdot \mathbf{N}_{\mathcal{D}}^K$$

$$\operatorname{div}_{K^*} \mathcal{F}^{\mathcal{D}} = \frac{1}{|K^*|} \sum_{\mathcal{D} \sim K^*} \mathcal{F}_{\mathcal{D}} \cdot \mathbf{N}_{\mathcal{D}}^{K^*}$$

- **Discrete Duality** (the key feature):

$$\forall u^T \in \mathbb{R}_0^T \quad \forall \mathcal{F}^{\mathcal{D}} \in (\mathbb{R}^2)^{\mathcal{D}} \quad [\operatorname{div}^T \mathcal{F}^{\mathcal{D}}, u^T] = -\{\mathcal{F}^{\mathcal{D}}, \nabla^{\mathcal{D}} u^T\}$$

Proof: rearrange per diamond $[\cdot, \cdot] = \sum_K \sum_{\mathcal{D} \sim K} + \sum_{K^*} \sum_{\mathcal{D} \sim K^*}$

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The core properties of DDFV (cf. "gradient schemes" calculus)

- **Discrete Duality** : $-\operatorname{div}^{\mathcal{T}}$ in duality with $\nabla^{\mathcal{D}}$

- (Strong) consistency of $\nabla^{\mathcal{D}} \circ \mathbb{P}^{\mathcal{T}}$

$$\forall \phi \in C_c^1(\Omega), \quad \left\| \nabla^{\mathcal{D}} \mathbb{P}^{\mathcal{T}} \phi - \nabla \phi \right\|_{\infty} \longrightarrow 0 \quad \text{as } h_{\mathcal{T}} \rightarrow 0$$

Proof: exactness of $\nabla^{\mathcal{D}}$ on affine functions + Taylor

- **Weak consistency of $\operatorname{div}^{\mathcal{T}} \circ \mathbb{P}^{\mathcal{D}}$** (cf. [Droniou M3AS'14] survey):

$$\forall \psi \in C_c^1(\Omega; \mathbb{R}^2), \quad \text{provided } \|\nabla^{\mathcal{D}} w^{\mathcal{T}}\|_{L^1(\Omega)} \leq \text{const},$$

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Proof: calculations similar to the proof of Discrete Duality
+ approx. of ψ by averages over σ / σ^* + **uniform mesh regularity**

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Compactness, reconstruction, penalization. DDFV vs gradient schemes.

A toy scheme Discretization of the toy pb. $u \in H_0^1(\Omega)$, $-\Delta u = f(u)$:

$$\text{find } u^{\mathcal{T}} \in \mathbb{R}_0^{\mathcal{T}} \text{ s.t. } \forall v^{\mathcal{T}} \in \mathbb{R}_0^{\mathcal{T}} \left\{ \nabla^{\mathcal{D}} u^{\mathcal{T}}, \nabla^{\mathcal{D}} v^{\mathcal{T}} \right\} + \underbrace{h_{\mathcal{T}} \sum_{K \cap K^*} \dots}_{\text{penalization}} = [f(u^{\mathcal{T}}), v^{\mathcal{T}}]$$

A compactness feature

Given $(\mathcal{T}_n)_n$ a family of DDFV meshes with $h_{\mathcal{T}_n} \rightarrow 0$ as $n \rightarrow \infty$,
assume the meshes obey a uniform regularity property.

Assume that discrete functions $u^{\mathcal{T}_n}$ have bounded $\|\nabla^{\mathcal{D}_n} u^{\mathcal{T}_n}\|_{L^2(\Omega)}$.

Then, up to a subsequence,

$$u^{\mathcal{T}_n} : x \mapsto \underbrace{\frac{1}{2} (u^{\mathfrak{M}_n}(x) + u^{\mathfrak{M}_n^*}(x))}_{\text{the DDFV reconstruction}} \text{ converges to } u, \text{ with } u \in H_0^1(\Omega)$$

in the sense: $u^{\mathcal{T}_n} \rightarrow u$ strongly in L^2 and $\nabla^{\mathcal{D}_n} u^{\mathcal{T}_n} \rightarrow \nabla u$ weakly in L^2 .

Moreover, if $u^{\mathfrak{M}_n} - u^{\mathfrak{M}_n^*} \rightarrow 0$ in L^2 , then $u^{\mathfrak{M}_n}, u^{\mathfrak{M}_n^*} \rightarrow u$

(needed to get $[f(u^{\mathcal{T}_n}), v^{\mathcal{T}_n}] \rightarrow \int_{\Omega} f(u)v$, in passage to the limit)

\rightsquigarrow **a question: DDFV is it a gradient scheme?**

NO... but YES, if $[f(u^{\mathcal{T}}), v^{\mathcal{T}}]$ replaced by $\sum_{K, K^*} |K \cap K^*| f\left(\frac{u_K + u_{K^*}}{2}\right) \frac{v_K + v_{K^*}}{2}$

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Compactness, reconstruction, penalization. DDFV vs gradient schemes.

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$$\text{find } u^{\overline{\mathcal{T}}} \in \mathbb{R}_0^{\overline{\mathcal{T}}} \text{ s.t. } \forall v^{\overline{\mathcal{T}}} \in \mathbb{R}_0^{\overline{\mathcal{T}}} \left\{ \nabla^{\mathcal{D}} u^{\overline{\mathcal{T}}}, \nabla^{\mathcal{D}} v^{\overline{\mathcal{T}}} \right\} + \underbrace{h_{\mathcal{T}} \sum_{K \cap K^*} \dots}_{\text{penalization}} = [f(u^{\mathcal{T}}), v^{\mathcal{T}}]$$

A compactness feature

Given $(\mathcal{T}_n)_n$ a family of DDFV meshes with $h_{\mathcal{T}_n} \rightarrow 0$ as $n \rightarrow \infty$,
assume the meshes obey a uniform regularity property.

Assume that discrete functions $u^{\overline{\mathcal{T}}_n}$ have bounded $\|\nabla^{\mathcal{D}_n} u^{\overline{\mathcal{T}}_n}\|_{L^2(\Omega)}$.

Then, up to a subsequence,

$$u^{\overline{\mathcal{T}}_n} : x \mapsto \underbrace{\frac{1}{2} (u^{\mathfrak{M}_n}(x) + u^{\mathfrak{M}_n^*}(x))}_{\text{the DDFV reconstruction}} \text{ converges to } u, \text{ with } u \in H_0^1(\Omega)$$

in the sense: $u^{\overline{\mathcal{T}}_n} \rightarrow u$ strongly in L^2 and $\nabla^{\mathcal{D}_n} u^{\overline{\mathcal{T}}_n} \rightarrow \nabla u$ weakly in L^2 .

Moreover, if $u^{\mathfrak{M}_n} - u^{\mathfrak{M}_n^*} \rightarrow 0$ in L^2 , then $u^{\mathfrak{M}_n}, u^{\mathfrak{M}_n^*} \rightarrow u$

(needed to get $[f(u^{\overline{\mathcal{T}}_n}), v^{\overline{\mathcal{T}}_n}] \rightarrow \int_{\Omega} f(u)v$, in passage to the limit)

\rightsquigarrow **a question: DDFV is it a gradient scheme?**

NO... but YES, if $[f(u^{\mathcal{T}}), v^{\mathcal{T}}]$ replaced by $\sum_{K, K^*} |K \cap K^*| f\left(\frac{u_K + u_{K^*}}{2}\right) \frac{v_K + v_{K^*}}{2}$

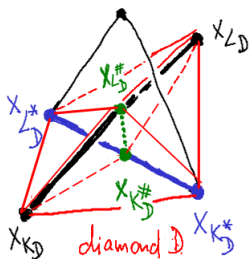
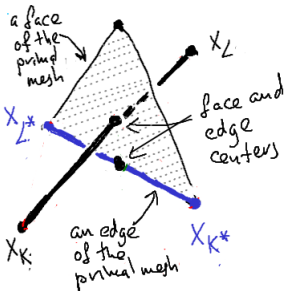
The 3D CeVeFE-DDFV scheme

precursor: [Hermeline CMAME'07]

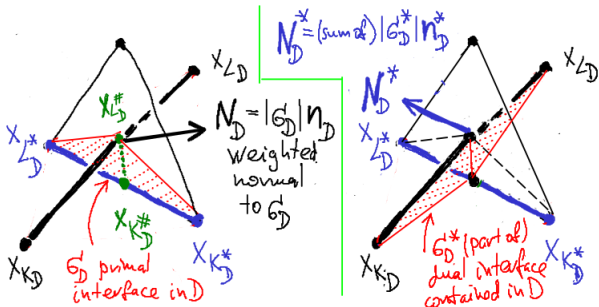
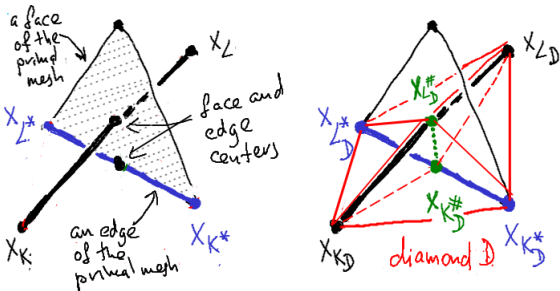
main: [Coudière, Hubert '09, puis SIAM JSC'11]

variant: [Eymard, Herbin, Guichard M2AN'12]
[Droniou, Eymard, Herbin M2AN'16]

Construction of 3D CeVeFE-DDFV [Coudière, Hubert '09,'11]



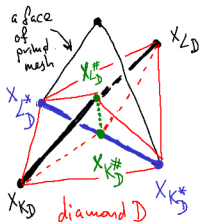
Construction of 3D CeVeFE-DDFV [Coudière, Hubert '09,'11]



it's worse for the 3rd mesh:

$$N_D^* = \sum_{i=1}^4 |G_D^{\#,i}| |N_D^{\#,i}|$$
 (four-parts' interface)

Summary of 3D CeVeFE-DDFV [Coudière, Hubert '09,'11]



X_{K_D}, X_{L_D} cell centers
 $X_{K_D^*}, X_{L_D^*}$ neighbour vertices of a cell face \equiv dual cell centers
 $X_{L_D^#}$ face center
 $X_{K_D^#}$ edge center $\} \equiv$ cell centers of the 3rd mesh
 three directions $\overrightarrow{X_{K_D} X_{L_D}}, \overrightarrow{X_{K_D^*} X_{L_D^*}}, \overrightarrow{X_{K_D^*} X_{L_D^#}}$

$N_D = |G_D| n_D$ ← unit normal to the face
 ↙ position of face included into D
 $N_D^* \approx |G_D^*| n_D^*$ ← objects for dual/3rd mesh
 $N_D^{\#} \approx |G_D^{\#}| n_D^{\#}$ ← three weighted normals

NB: Precise shape of volumes $K^{\#}$ does not count (invariance of $N^{\#}$)

- Discrete gradient defined per diamond by

$$\nabla_D u^T := \frac{1}{3|D|} \left((u_{L_D} - u_{K_D}) \mathbf{N}_D + (u_{L_D^*} - u_{K_D^*}) \mathbf{N}_D^* + (u_{L_D^{\#}} - u_{K_D^{\#}}) \mathbf{N}_D^{\#} \right)$$

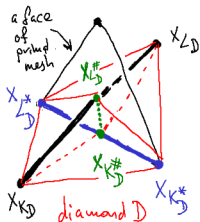
Per-projection representation analogous to 2D implies exactness:

$$\nabla_D u^T \cdot \overrightarrow{X_{K_D} X_{L_D}} = u_{L_D} - u_{K_D}, \text{ idem for projections on } \overrightarrow{X_{K_D^*} X_{L_D^*}}, \overrightarrow{X_{K_D^{\#}} X_{L_D^{\#}}}$$

- Finite Volume discrete divergence, per primal/dual/3rd mesh cell:

$$\operatorname{div}_K \mathcal{F}^D = \frac{1}{|K|} \sum_{D \sim K} \mathcal{F}_D \cdot \mathbf{N}_D^K \quad (\mathbf{N}_D^K = \pm \mathbf{N}_D), \text{ idem } \operatorname{div}_{K^*} \mathcal{F}^D, \operatorname{div}_{K^{\#}} \mathcal{F}^D$$

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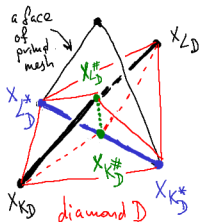
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3D CeVeFE-DDFV shares the core properties of 2D DDFV

- **Discrete Duality** is proved by elementary rearrangements: operators $-\operatorname{div}^T : (\mathbb{R}^3)^{\mathfrak{D}} \rightarrow \mathbb{R}^T$ and $\nabla^{\mathfrak{D}} : \mathbb{R}^T \rightarrow (\mathbb{R}^3)^{\mathfrak{D}}$ fulfill

$$\forall u^T \in \mathbb{R}_0^T \quad \forall \mathcal{F}^{\mathfrak{D}} \in (\mathbb{R}^3)^{\mathfrak{D}} \quad [\operatorname{div}^T \mathcal{F}^{\mathfrak{D}}, u^T] = -\{\mathcal{F}^{\mathfrak{D}}, \nabla^{\mathfrak{D}} u^T\}$$

if one takes $\{\mathcal{F}, \mathcal{G}\} = \sum_{\mathcal{D} \in \mathfrak{D}} |\mathcal{D}| \mathcal{F}_{\mathcal{D}} \cdot \mathcal{G}_{\mathcal{D}}$ and defines $[\cdot, \cdot]$ by:

$$[u^T, v^T] := \frac{1}{3} \sum_{K \in \mathfrak{M}} |K| u_K v_K + \frac{1}{3} \sum_{K^* \in \mathfrak{M}^*} |K^*| u_{K^*} v_{K^*} + \frac{1}{3} \sum_{K^\# \in \mathfrak{M}^\#} |K^\#| u_{K^\#} v_{K^\#}$$

- (Strong) consistency of $\nabla^{\mathfrak{D}} \circ \mathbb{P}^T$ comes from exactness
- Weak consistency of $\operatorname{div}^T \circ \mathbb{P}^{\mathfrak{D}}$ is also ok, as well as compactness claim, under uniform mesh regularity and employing penalization
- coercivity is true for any mesh geometry

Variant: [Eymard, Herbin, Guichard M2AN'12 / Droniou, E., H. M2AN'16]

Like for 2D DDFV, one can construct the 3D CeVeFE-DDFV meshes starting from a diamond mesh consisting of octahedra.

NB: The method is a gradient scheme, up to nonlinearities $f(u)$ etc.

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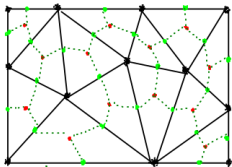
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The 2D co-volume (CVFE) scheme

2D co-volume (CVFE) scheme [Cai, Num. Math.'91], [Mikula's team]



Donald / "median dual" mesh \mathcal{T}



CVFE diamond D



CVFE cell K

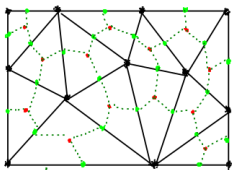
Space $(\mathbb{R}^2)^{\mathcal{D}}$, $\{\mathcal{F}^{\mathcal{D}}, \mathcal{G}^{\mathcal{D}}\} = \sum_{D \in \mathcal{D}} |D| \mathcal{F}_D \mathcal{G}_D$

Spaces $\mathbb{R}^{\mathcal{T}}, \mathbb{R}_0^{\mathcal{T}}$ $\llbracket u^{\mathcal{T}}, v^{\mathcal{T}} \rrbracket = \sum_{K \in \mathcal{M}} |K| u_K v_K$

- Discrete gradient $\nabla^{\mathcal{D}} u^{\mathcal{T}}$: Finite Element reconstruction per D
- Discrete divergence $\text{div}^{\mathcal{T}} \mathcal{F}^{\mathcal{D}}$: Finite Volume expression per K

Claim: $\llbracket -\text{div}^{\mathcal{T}} \mathcal{F}^{\mathcal{D}}, u^{\mathcal{T}} \rrbracket = \llbracket \mathcal{F}^{\mathcal{D}}, \nabla^{\mathcal{D}} u^{\mathcal{T}} \rrbracket$
[A, Bendahmane, Karlsen '08]

The 2D co-volume (CVFE) scheme is a Discrete Duality scheme



Donald / "mediandual" mesh \mathcal{T}



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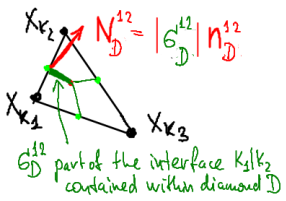
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Spaces $\mathbb{R}^{\mathcal{T}}, \mathbb{R}_0^{\mathcal{T}}, \{\mathcal{U}^{\mathcal{T}}, \mathcal{V}^{\mathcal{T}}\} = \sum_{K \in \mathcal{M}} |K| u_K v_K$

- Discrete gradient $\nabla^{\mathcal{D}} \mathcal{U}^{\mathcal{T}}$: Finite Element reconstruction per \mathcal{D}
- Discrete divergence $\text{div}^{\mathcal{T}} \mathcal{F}^{\mathcal{D}}$: Finite Volume expression per K

Claim: $\llbracket -\text{div}^{\mathcal{T}} \mathcal{F}^{\mathcal{D}}, \mathcal{U}^{\mathcal{T}} \rrbracket = \llbracket \mathcal{F}^{\mathcal{D}}, \nabla^{\mathcal{D}} \mathcal{U}^{\mathcal{T}} \rrbracket$
[A., Bendahmane, Karlsen '08]

Key ingredient: $\nabla_{\mathcal{D}} \mathcal{U}^{\mathcal{T}} = \frac{2}{|\mathcal{D}|} \left((u_{k_2} - u_{k_1}) N_{\mathcal{D}}^{12} + (u_{k_3} - u_{k_2}) N_{\mathcal{D}}^{23} + (u_{k_1} - u_{k_3}) N_{\mathcal{D}}^{31} \right)$



Claims (the 2nd "magical formula") [A., Bendahmane, Hubert, Krell IMADA'12]

- this formula represents the gradient of the affine per \mathcal{D} (Finite Element) reconstruction from DOFs $(u_k)_{k \in \mathcal{T}}$
 \rightsquigarrow exactness of $\nabla^{\mathcal{D}}$
- exactness remains true if \mathcal{D} has > 3 vertices (example: scheme of [A., Boyer, Hubert M²AN'04] on rectangles)
- this formula leads to Discrete Duality

Properties of the co-volume (CVFE) scheme

The co-volume scheme of [Cai '91], aka Afif-Amaziane scheme, aka Control Volume Finite Element scheme (CVFE, sometimes FVE), aka lumped FE scheme, is a gradient scheme [Droniou et al.]...

Moreover, regarding the core properties of DDFV, co-volume/CVFE can also be seen as a Discrete Duality Finite Volume scheme !

Indeed,

- discrete spaces, operators analogous to DDFV (though simpler)
- Discrete Duality is OK
- Strong consistency of Discret Gradient is OK
- Weak (dual) consistency of Discrete Divergence is OK
- coercivity is ok on triangular/quadrangular diamond meshes
 ↷ however, on general diamond meshes coercivity fails
 ↷ cf. the 2nd part of the talk [A., Quenjel in preparation]

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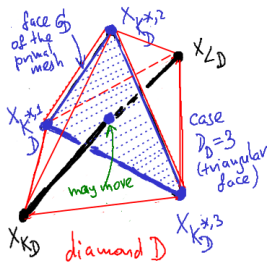
[Pierre PhD'05], [Coudière, Pierre et al. FVCA'08, IJFV'09]

[Hermeline JCP'09]

[A., Bendahmane, Karlsen FVCA'08, JHDE'10]

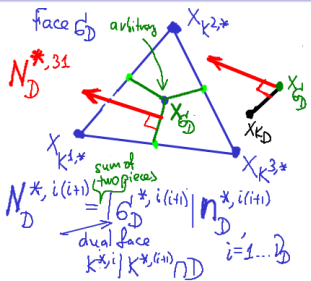
[A., Bendahmane, Hubert, Krell IMAJNA'12, CMAM'13]

Summary of 3D CeVe-DDFV [A., Bendahmane, Hubert, Krell IMAJNA'12]



X_{K_D}, X_{L_D} cell centers
 $X_{K_D^{*,i}}$ neighbour vertices of the cell face $G_D \equiv$ dual cell centers
 $i=1, \dots, D$

$$\mathbf{N}_D = |G_D| \mathbf{n}_D \leftarrow \begin{array}{l} \text{unit normal to the face} \\ \text{position of face included into } D \end{array}$$



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$$\nabla_D u^T := \frac{1}{3|D|} (u_{L_D} - u_{K_D}) \mathbf{N}_D + \frac{2}{3|D|} \sum_{i=1}^{D} (u_{K_D^{*,i+1}} - u_{K_D^{*,i}}) \mathbf{N}_D^{*,i(i+1)}$$

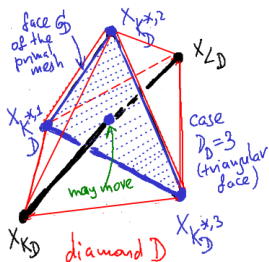
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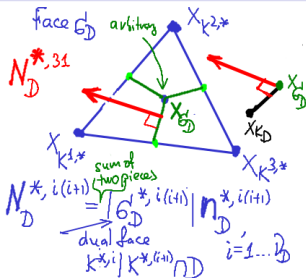
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$$\forall u^T \in \mathbb{R}_0^T \quad \forall \mathcal{F}^{\mathcal{D}} \in (\mathbb{R}^3)^{\mathcal{D}} \quad [\operatorname{div}^T \mathcal{F}^{\mathcal{D}}, u^T] = -\{\mathcal{F}^{\mathcal{D}}, \nabla^{\mathcal{D}} u^T\}$$

if one takes $\{\mathcal{F}^{\mathcal{D}}, \mathcal{G}^{\mathcal{D}}\} = \sum_{\mathcal{D} \in \mathcal{D}} |\mathcal{D}| \mathcal{F}_{\mathcal{D}} \cdot \mathcal{G}_{\mathcal{D}}$ and defines $[\cdot, \cdot]$ by:

$$[u^T, v^T] := \frac{1}{3} \sum_{K \in \mathcal{M}} |K| u_K v_K + \frac{2}{3} \sum_{K^* \in \mathcal{M}^*} |K^*| u_{K^*} v_{K^*}$$

- (Strong) consistency of $\nabla^{\mathcal{D}} \circ \mathbb{P}^T$ comes from exactness
- Weak consistency of $\operatorname{div}^T \circ \mathbb{P}^{\mathcal{D}}$ is also ok, as well as compactness claim, under uniform mesh regularity and employing penalization
- coercivity is true at least for
 - meshes with faces that are triangles (including simplicial meshes)
 - cartesian meshes and meshes topologically equivalent to cartesian

A variant [Ch. Pierre PhD'05, Coudière et al. '08,'09]

The construction where K^* overlap, to cover the domain twice, is equivalent to the above CeVe construction

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Conclusions:

- the analytical framework of DDFV schemes mainly consists of
 - meshes, discrete spaces, gradient and divergence operators
 - duality calculus for these operators
 - strong consistency for $\nabla^{\mathcal{D}}$, dual consistency for $\text{div}^{\mathcal{T}}$
 \leadsto compactness, reconstruction
- there are two different kinds of 3D DDFV schemes
 - \leadsto CeVeFE-DDFV (Cell+Vertex+Face+Edge unknowns): $3D=1D+1D+1D$
 - \leadsto CeVe-DDFV (Cell+Vertex unknowns): $3D=1D+2D$
- the 2D co-volume scheme (aka Control Volume Finite Element,...) can/should also be seen as a Discrete Duality scheme

Perspectives:

- other Discrete Duality schemes \leadsto [Quenjel's nodal NDD scheme](#)
- Benefit from the DDFV reconstruction $u^{\mathcal{T}} = \frac{1}{2}(u^{\mathfrak{M}} + u^{\mathfrak{M}^*})$?
- 4D adaptation of CeVeFE idea looks natural...
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Thank you / Merci !

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