

Time parallelisation for optimal control and data assimilation

Julien Salomon

Joint work with F. Kwok, S. Reyes-Riffo, L. Perrin

JLL & INRIA, ANGE project-team (Inria, Paris-Sorbonne Université, CNRS)

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Problem: assimilation on an unbounded interval

$[t_0, +\infty)$

Given a (linear) dynamic

$$\dot{x}(t) = Ax(t) + Bu(t)$$

whose initial condition is **NOT known**, and an output

$$y(t) = Cx(t),$$

which is **known**.

<p>Objective: Combine observer approaches with a time-parallelization.</p>

- 1 Unbounded time domains and assimilation
- 2 A time parallelization strategy
- 3 The case of the Parareal algorithm
 - The algorithm
 - Analysis of the coupling
 - Numerical example
- 4 The case of the Paraexp algorithm
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Unbounded time domains and assimilation

The problem

Given a (linear) dynamic

$$\dot{x}(t) = Ax(t) + Bu(t)$$

whose initial condition is **NOT known**, and an output

$$y(t) = Cx(t),$$

which is **known**: data to be assimilated.

→ **Solver**: Luenberger observer

$$\dot{\hat{x}}(t) = A\hat{x}(t) + Bu(t) + L(C\hat{x}(t) - y(t)).$$

In general:

$$\hat{x}(t_0) \neq x(t_0).$$

Theoretical result: Assume the observability condition

$$\text{rank} \begin{pmatrix} C \\ CA \\ CA^2 \\ \vdots \\ CA^{n-1} \end{pmatrix} = n,$$

then **there exists** L such that

$$\rho(\exp(A - LC)) \leq 1 \Rightarrow \|x(t) - \hat{x}(t)\| \leq \kappa e^{-\lambda t} \|x(0) - \hat{x}(0)\|,$$

with $\lambda = \min_{\alpha \in \text{spec}(A-LC)} |\alpha|$, $\kappa = \text{Cond}(A - LC)$.

→ *Standard algorithms to design L : Routh's or Hurwitz criterion, Ackermann's formula, LQ theory... Pole assignment procedures.*

Important remark: in

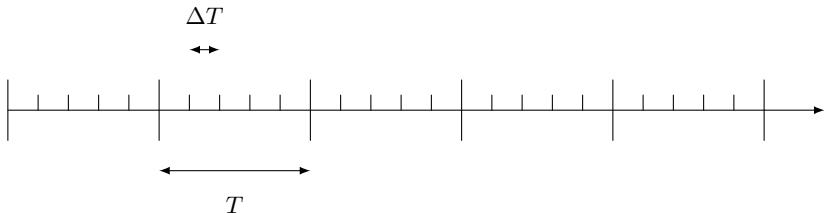
$$\|x(t) - \hat{x}(t)\| \leq \kappa e^{-\lambda t} \|x(0) - \hat{x}(0)\|,$$

the factor $\|x(0) - \hat{x}(0)\|$ is unknown...Only the rate of convergence is known.

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A time parallelization strategy

Idea: In order to accelerate the assimilation, simulate the observer using time-parallelization on **Windows**.



Consider a time-domain decomposition associated with a time-parallelization procedure and introduce

- **Windows:** interval of length T on which a time-parallelization algorithm is applied.
- **Subintervals:** set of N intervals of length ΔT that make up the decomposition on which the algorithm are based.

A time parallelization strategy

We proceed as follows: Suppose we are on the window ℓ

$$W_\ell := [t_\ell, t_{\ell+1} = t_\ell + T],$$

- 1 Consider an approximation $\hat{x}_\parallel(t_\ell)$ of $\hat{x}(t_\ell)$.
- 2 Compute a time-parallelized approximation \hat{x}_\parallel of \hat{x} on W_ℓ , with a tolerance Tol_ℓ such that **the rate of convergence is preserved**.
- 3 Let the final state $\hat{x}_\parallel(t_{\ell+1})$ be the initial state for the next window.

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The case of the Parareal algorithm

The time parallelization algorithm

Suppose we are on the window ℓ

$$W_\ell := [t_\ell, t_{\ell+1} = t_\ell + T],$$

- 1 Consider an approximation $\hat{x}_\parallel(t_\ell)$ of $\hat{x}(t_\ell)$.
- 2 Apply k_ℓ **iterations of the Parareal algorithm** to get an approximation of \hat{x} on W_ℓ .
- 3 Let the final state $\hat{x}_\parallel(t_{\ell+1})$ be the initial state for the next window.

Mandatory:

$$k_\ell \ll N.$$

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The case of the Parareal algorithm

Analysis of the coupling

Lemma: We have

$$\left\| \varepsilon_{\parallel}(t_n^{\ell-}) \right\| \leq \gamma \left(\|x(0) - \hat{x}(0)\| + \sum_{j=1}^{\ell} e^{\mu j T} \|\mathcal{J}_j^h\| \right) e^{-\mu \ell T}$$

where $\varepsilon_{\parallel}(t) = x(t) - \hat{x}_{\parallel}(t)$ is the error of approximation and $\mathcal{J}_j^h = -\sum_{n=1}^{N-1} e^{(A-LC)(N-n)\Delta T} J_{j,n}^h$.

The case of the Parareal algorithm

Analysis of the coupling

Proof: Let $\ell \geq 1$. We have

$$\begin{aligned}\varepsilon_{\parallel}(t_n^{\ell-}) &= x(t_n^{\ell}) - \hat{x}_{\parallel}(t_n^{\ell-}) = e^{(A-LC)\Delta T} e^{-(A-LC)\Delta T} (x(t_n^{\ell}) - \hat{x}_{\parallel}(t_n^{\ell-})) \\ &= e^{(A-LC)\Delta T} (x(t_{n-1}^{\ell}) - \hat{x}_{\parallel}(t_{n-1}^{\ell+})) \\ &= e^{(A-LC)\Delta T} (x(t_{n-1}^{\ell}) - \hat{X}_{\ell,n-1}^h) \\ &= e^{(A-LC)\Delta T} (x(t_{n-1}^{\ell}) - \hat{x}_{\parallel}(t_{n-1}^{\ell-}) - J_{\ell,n-1}^h) \\ &= e^{(A-LC)\Delta T} (\varepsilon_{\parallel}(t_{n-1}^{\ell-}) - J_{\ell,n-1}^h)\end{aligned}$$

so that

$$\varepsilon_{\parallel}(t_N^{\ell}) = \varepsilon_{\parallel}(t_0^{\ell+1}) = e^{(A-LC)T} \varepsilon_{\parallel}(t_0^{\ell}) + \mathcal{J}_{\ell}^h, \quad (1)$$

where we have used the continuity of \hat{x}_{\parallel} in t_N^{ℓ} . In the same way, we obtain

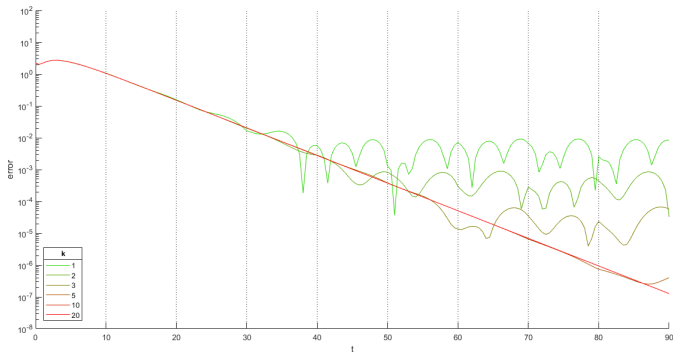
$$\varepsilon_{\parallel}(T_{\ell}) = e^{(A-LC)\ell T} \varepsilon_{\parallel}(0) + \sum_{j=1}^{\ell} e^{(A-LC)(\ell-j)T} \mathcal{J}_j^h.$$

The result follows from the contraction property of \hat{x} .

The case of the Parareal algorithm

Analysis of the coupling

What happens when $k_\ell = k_{\max}$ is fixed for all windows ?



This is not surprising: k_{\max} parareal iterations introduce a constant error.

The case of the Parareal algorithm

Analysis of the coupling

Definition of k_ℓ :

Let us assume h is obtained from the stopping criterion in W_ℓ

$$\gamma \sum_{n=1}^{N-1} e^{-\mu(N-n)\Delta T} \|J_{\ell,n}^h\| \leq \tilde{\gamma} \frac{e^{-\mu\ell T}}{2^\ell}$$

where $\tilde{\gamma}$ is an arbitrary parameter. Then, the rate of convergence of $\hat{x}_\parallel(t)$ to $x(t)$ is bounded by μ , i.e.

$$\left\| \varepsilon_\parallel(T_\ell) \right\| \leq \gamma (\|x(0) - \hat{x}(0)\| + \tilde{\gamma}) e^{-\mu\ell T}.$$

The case of the Parareal algorithm

Analysis of the coupling

Proof: By definition of \mathcal{J}_ℓ^h , we have

$$\|\mathcal{J}_\ell^h\| \leq \sum_{n=1}^{N-1} \gamma e^{-\mu(N-n)\Delta T} \|J_{\ell,n}^h\| \leq \tilde{\gamma} \frac{e^{-\mu\ell T}}{2^\ell}.$$

From (1), we deduce that

$$\begin{aligned} \|\varepsilon_\parallel(T_\ell)\| &\leq \gamma e^{-\mu\ell T} \left(\|x(0) - \hat{x}(0)\| + \sum_{j=1}^{\ell} e^{\mu j T} \cdot \tilde{\gamma} \frac{e^{-\mu j T}}{2^j} \right) \\ &= \gamma \left(\|\varepsilon_\parallel(0)\| + \tilde{\gamma} \sum_{j=1}^{\ell} \frac{1}{2^j} \right) e^{-\mu\ell T} \\ &\leq \gamma \left(\|\varepsilon_\parallel(0)\| + \tilde{\gamma} \right) e^{-\mu\ell T}. \end{aligned}$$

The result then follows from $\varepsilon_\parallel(0) = x(0) - \hat{x}_\parallel(0) = x(0) - \hat{x}(0)$.

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The case of the Parareal algorithm

Numerical example

Example: $N = 20$.

$$A = \begin{pmatrix} 0 & 1 \\ -1 & -2 \end{pmatrix}$$

$$B = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, C = \begin{pmatrix} 0 & 1 \end{pmatrix}, L = \begin{pmatrix} 0.8 \\ -1.1 \end{pmatrix}$$

$$u(t) = 3 + 0.5 \sin(0.75t)$$

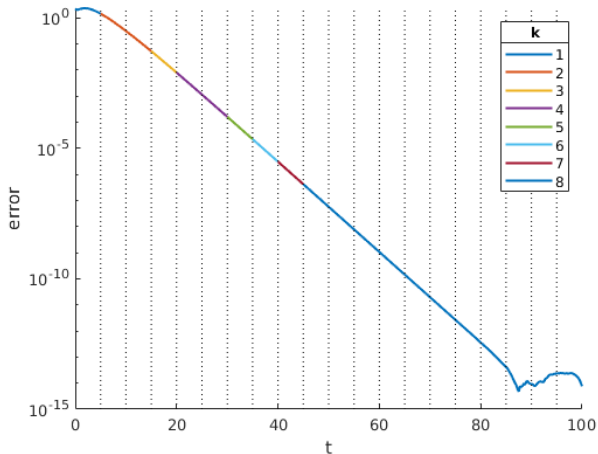
$$T = 5, \Delta T = \frac{T}{N} = 0.25.$$

$$\Delta t = \Delta T, \delta t = \frac{\Delta t}{25}.$$

The case of the Parareal algorithm

Numerical example

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The case of the Parareal algorithm

Numerical example

Efficiency: CPU time to reach $\|\varepsilon_{\parallel}\| = \|x(t) - \hat{x}_{\parallel}(t)\| \leq 10^{-12}$.

- CPU_{\parallel} : 0.0144 s
- $CPU_{sequential}$: 0.0579 s
- ratio = 0.579
- efficiency = 47%

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The case of the Paraexp algorithm

The time parallelization algorithm

Setting :

- Parallel integration of the following linear initial problem :

$$\begin{cases} \dot{\mathbf{x}}(t) = M\mathbf{x}(t) + \mathbf{g}(t), & t \in [0, T] \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases} \quad (2)$$

$$M \in \mathcal{M}_{m \times m}(\mathbb{R}), \mathbf{x}(t), \mathbf{g}(t) \in \mathbb{C}^m.$$

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$M \in \mathcal{M}_{m \times m}(\mathbb{R})$, $\mathbf{x}(t), \mathbf{g}(t) \in \mathbb{C}^m$.

- We separate the homogeneous IVP and the inhomogeneous with null initial condition:

$$\begin{cases} \dot{\mathbf{w}}(t) = M\mathbf{w}(t), \\ \mathbf{w}(0) = \mathbf{x}_0, \end{cases} \quad \begin{cases} \dot{\mathbf{v}}(t) = M\mathbf{v}(t) + \mathbf{g}(t), \\ \mathbf{v}(0) = \mathbf{0}, \end{cases}, \quad t \in [0, T]$$

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- The solution of (2) is given by :

$$\mathbf{x}(t) = \mathbf{v}(t) + \mathbf{w}(t).$$

The case of the Paraexp algorithm

The time parallelization algorithm

→ divide our interval $[0, T]$ in N subintervals (N #processors), solve **Type 1** problems in parallel, then **Type 2** problems in parallel (matrix exponential).

PARAEXP: A parallel integrator for linear initial-value problems, M.J. Gander and S. Güttel, SIAM J. Sci. Comp., Vol. 35 (2), 2013.

The case of the Paraexp algorithm

The time parallelization algorithm

Considering the Luenberger observer, we can write it :

$$\dot{\hat{\mathbf{x}}}(t) = M\hat{\mathbf{x}}(t) + \mathbf{g}(t), \quad \hat{\mathbf{x}}(0) = \hat{\mathbf{x}}_0, \quad t \geq 0,$$

with :

$$\begin{cases} M = (A - LC), \\ \mathbf{g}(t) = B\mathbf{u}(t) + L\mathbf{y}(t). \end{cases}$$

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- Compute $\hat{\mathbf{x}}$ on a window W_ℓ falls under the setting of the ParaExp scheme on each window $W_\ell = (T_{\ell-1}, T_\ell)$.
- $\hat{\mathbf{x}}_{\parallel}(t)$: approximation of $\hat{\mathbf{x}}(t)$ by the parallel observer

The error only comes from the source term and we use RK4 :

$$\Rightarrow h_{\ell+1} \leq \left((h_\ell)^4 e^{-\mu T} \right)^{1/4}, \quad \forall \ell \in \mathbb{N}^*.$$

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The case of the Paraexp algorithm

Numerical results

Submarine toy model (*Grimble, van der Molen, Liceaga-Castro, Submarine depth and pitch control, 1993*).

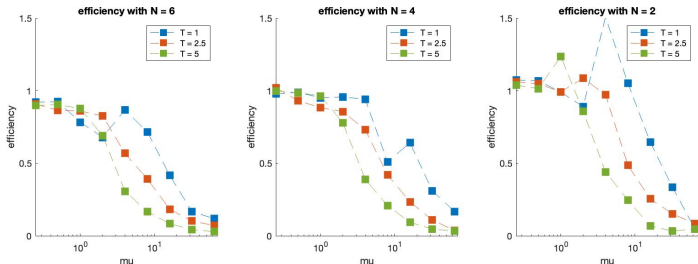


Figure: Results, reminder : N is the number of processors, T the size of the windows, μ the smallest magnitude of the eigenvalues.

The case of the Paraexp algorithm

Numerical results

Heat equation on $\Omega = [0, 1]^2$:

$$\begin{cases} \partial_t x(s, t) = \Delta x(s, t) + g(s, t), & s \in \Omega, \\ x(s, t) = 0, & s \in \partial\Omega, \\ x(s, 0) = u_0, & s \in \Omega. \end{cases}$$

and the observer, ω being the circle of center $(1/2, 1/2)$ with radius r :

$$\begin{cases} \partial_t \hat{x}(s, t) = \Delta \hat{x}(s, t) + g(s, t) + \mathcal{L}(\hat{x}|_{\omega}(s, t) - x|_{\omega}(s, t)), & s \in \Omega, \\ \hat{x}(s, t) = 0, & s \in \partial\Omega, \\ \hat{x}(s, 0) = \hat{x}_0, & s \in \Omega. \end{cases}$$

Pole assignment does not work !

$$\mathcal{L} = -\gamma 1|_{\omega}^{\top}.$$

The case of the Paraexp algorithm

Numerical results

2D Heat equation on $[0, 1]^2$, #cpu = 8.

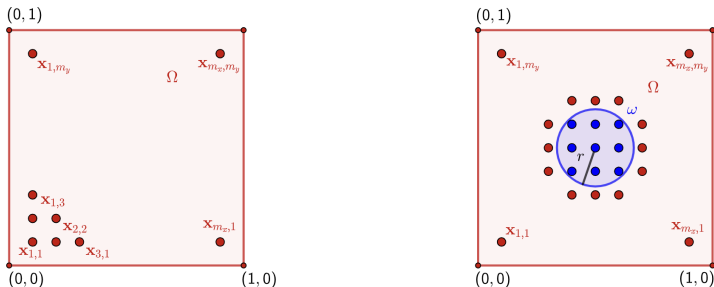
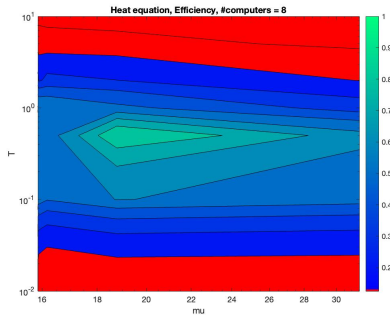


Figure: Setting Heat 2D, A size (91×91) .

The case of the Paraexp algorithm

Numerical results

2D Heat equation on $[0, 1]^2$, $r = 0.15$, #cpu = 8.



The case of the Paraexp algorithm

Numerical results

2D Wave equation on $\Omega = [0, 1]^2$:

$$\begin{cases} \partial_{tt}x(s, t) = \Delta x(s, t) + g(s, t), & s \in \Omega, \\ x(s, t) = 0, & s \in \partial\Omega, \\ x(s, 0) = u_0, & s \in \Omega. \end{cases}$$

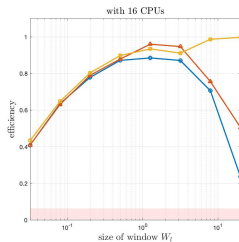
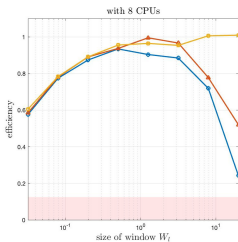
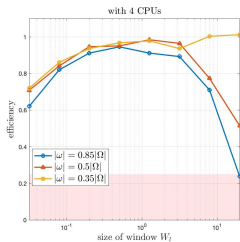
and the observer, ω being the circle of center $(1/2, 1/2)$ with radius r :

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Coupling time parallelization with data assimilation

- The **Luenberger observer** is for **unbounded time intervals**,
- **Time parallelization** scheme work on **bounded intervals**.

Coupling time parallelization with data assimilation

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Strategy to apply time parallelization on unbounded tom intervals :

- ① Divide our unbounded time interval $[0, \infty)$ into windows of length $T > 0$: $W_\ell = (T_{\ell-1}, T_\ell)$, $\ell \geq 1$.

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- ② Apply a time parallelization procedure (*Parareal*, *ParaExp*, etc) on each windows succesively.

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- ③ Estimate the error (at the end of the window on T_ℓ) gives a criterion to switch to the next window.
- ④ Strategy : Time parallelization error decays with the same rate as the observer error.

Merci !