



Parareal algorithms for molecular dynamics simulations

Frédéric Legoll

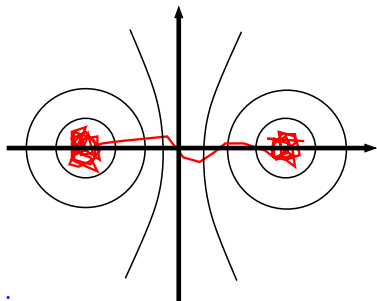
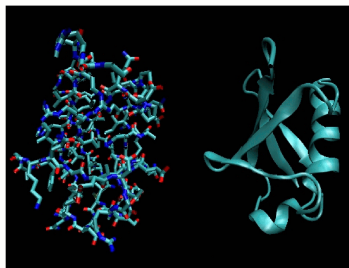
Ecole des Ponts & Inria Paris

*Joint with T. Lelièvre (ENPC), O. Gorynina (ENPC, now in Davos),
D. Perez (LANL) and U. Sharma (Berlin)*

11th conference on Parallel-in-Time integration, CIRM, 11-15 July 2022

Motivation

This work is motivated by molecular simulation, where we often have to simulate **long trajectories** of complex, metastable systems.



Typical dynamics: the Langevin equation

$$dq(t) = p(t) dt, \quad dp(t) = -\nabla V(q(t)) dt - \gamma p(t) dt + \sqrt{2\gamma\beta^{-1}} dW(t),$$

where V is the potential energy, $\gamma > 0$ a damping parameter, β^{-1} the temperature and $W(t)$ a Brownian motion.

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- It turns out that this algorithm is **not stable** for MD problems **when the time horizon is too large**

Outline

- Since we have to simulate **long-time trajectories**, it seems attractive to use a parallel-in-time algorithm, here the **parareal algorithm**
- It turns out that this algorithm is **not stable** for MD problems **when the time horizon is too large**
- We therefore introduce an **adaptive parareal algorithm**, which performs simulations on shorter time slabs and paste them together, thereby allowing for a significant CPU gain

F.L., T. Lelièvre and U. Sharma, *An adaptive parareal algorithm: application to the simulation of molecular dynamics trajectories*, SIAM Journal on Scientific Computing 2022

O. Gorynina, F.L., T. Lelièvre and D. Perez, *Long-time simulation of diffusing self-interstitial atoms using the parareal algorithm*, in preparation

Parallel in time algorithm for ODEs

The **parareal algorithm** is based upon two integrators to propagate the system over a time ΔT :

- a **fine, accurate integrator** $\mathcal{F}_{\Delta T}$
- a **cheap coarse integrator** $\mathcal{C}_{\Delta T}$

Algorithm:

- Initialization: **coarse** propagation that yields $\{x_n^{k=0}\}_n$:

$$\forall n, \quad x_{n+1}^{k=0} = \mathcal{C}_{\Delta T}(x_n^{k=0})$$

- Iterate over $k \geq 0$:
 - compute **jumps** (in parallel):

$$J_n^k = \mathcal{F}_{\Delta T}(x_n^k) - \mathcal{C}_{\Delta T}(x_n^k)$$

- sequential update to obtain $\{x_n^{k+1}\}_n$:

$$\forall n, \quad x_{n+1}^{k+1} = \mathcal{C}_{\Delta T}(x_n^{k+1}) + J_n^k$$

Parareal algorithm for MD simulations

- In MD, we often run simulations with time steps just below the stability limit (this often provides sufficient accuracy on the quantities of interest): **no room for choosing a much larger time step in $\mathcal{C}_{\Delta T}$ than in $\mathcal{F}_{\Delta T}$**

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- We thus turn to a paradigm where **$\mathcal{C}_{\Delta T}$ integrates a simpler dynamics than $\mathcal{F}_{\Delta T}$** (say with the same time step):

- $\mathcal{F}_{\Delta T}$ integrates the original Langevin dynamics (with $V_f \equiv V$)

$$dq = p dt, \quad dp = -\nabla V_f(q) dt - \gamma p dt + \sqrt{2\gamma\beta^{-1}} dW$$

- $\mathcal{C}_{\Delta T}$ integrates a Langevin dynamics run on a **simplified (cheaper to compute) potential V_c** :

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- Identical **Gaussian increments** for $\mathcal{F}_{\Delta T}$ and $\mathcal{C}_{\Delta T}$ and over all parareal iterations (to ensure as best as possible **trajectorial convergence**)

Similar paradigm (in terms of V_f vs V_c) in [Baffico et al, PRE 2002]

Simulations on toy model problems

Two model problems

- A **quadratic model** in 1D:

$$V_f(q) = \frac{q^2}{2}, \quad V_c(q) = \omega \frac{q^2}{2} \quad \text{for some } \omega > 0$$

Simple enough to be amenable to theoretical analysis, and exhibits the same issues as those appearing with more complex models.

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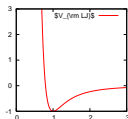
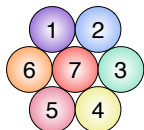
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- A slightly less simple model: a **7-atom Lennard-Jones cluster** in 2D:

$$V_f(q) = \frac{1}{2} \sum_{i,j \in \{1, \dots, 7\}, i \neq j} \phi_f(|q^i - q^j|), \quad \phi_f(r) = r^{-12} - 2r^{-6}$$

$V_c \equiv$ harm. approx. of V_f at the global minimum (the initial condition is chosen in the corresponding well).



Convergence criteria

- Relative error between consecutive parareal trajectories:

$$E(k, N) = \frac{\sum_{n=1}^N |q_n^k - q_n^{k-1}|}{\sum_{n=1}^N |q_n^{k-1}|}.$$

- We stop the algorithm at the first parareal iteration \bar{k} for which

$$E(\bar{k}, N) < \delta_{\text{conv}} = 10^{-5}$$

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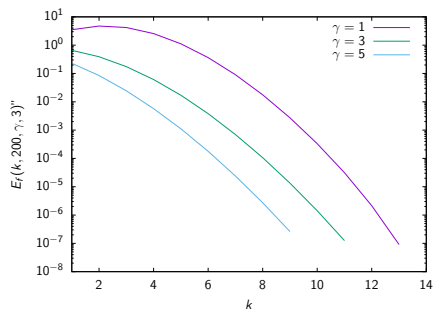
- The gain is then

$$\text{gain} = \frac{N}{\bar{k}} = \frac{\# \text{ fine propagations for a sequential algorithm}}{\# \text{ fine propagations for the parareal algorithm}}$$

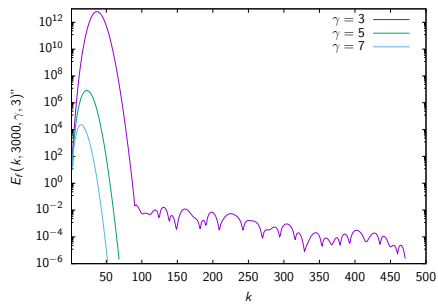
$E_f(k, N)$ = relative error with respect to the reference trajectory

Instability at large times

Plot of $E_f(k, N)$ as a function of k :



$N = 200$

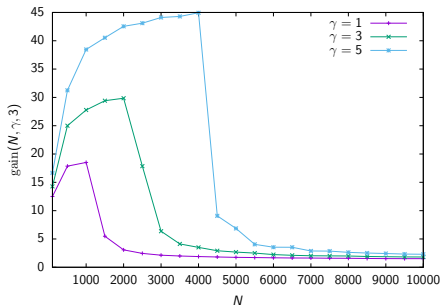


$N = 3000$

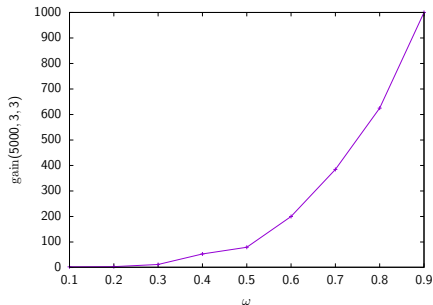
- For **small N** , **fast convergence** of the parareal iterations (**gain ≈ 10**)
- For **large N** , **the error increases to large values** when k increases (because the trajectory goes far away), before eventually converging

Harmonic model, $\omega = 0.1$, $\Delta T = 0.05$, $\beta = 3$

Gain as a function of N and ω



Gain as a function
of N ($\omega = 0.1$)



Gain as a function
of ω ($\gamma = 3$, $N = 5000$)

- Fixed coarse model: the gain decreases to 1 when N increases
- Fixed N : the gain decreases when the coarse model differs too much from the fine one

Harmonic model, $\Delta T = 0.05$, $\beta = 3$

Theoretical analysis on a toy problem

- Reference problem: $V_f(x) = x^2/2$ and

$$\frac{dx}{dt} = -V'_f(x) = -x$$

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- **Coarse model:** $V_c(x) = \omega x^2/2$ and

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- We have a complete understanding (see [SISC 2022]) of the error as a function of **the trajectory length N** and of $y = \frac{\mathcal{F}_{\Delta T}}{\mathcal{C}_{\Delta T}} - 1$, which **quantifies how much the coarse and fine models differ.**

A typical result

$R_{n,k}$ = relative error at time n and iteration $\# k$

In the case $y = \frac{\mathcal{F}_{\Delta T}}{\mathcal{C}_{\Delta T}} - 1 > 0$, then

$0 < R_{n,k} \leq 1$ and $k \mapsto R_{n,k}$ is decreasing

- If y is such that $y \leq c/n$ (the coarse model is very close to the fine; the longer the trajectory, the closer the models should be), then

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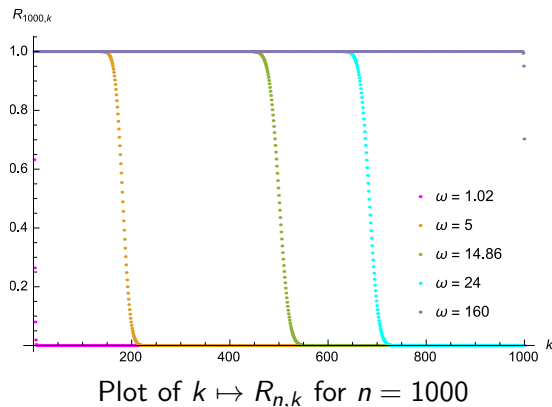
- If y is such that $y \geq c n$ (the coarse model is very different from the fine), then

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- If y is in-between, then there exists $\bar{p} \approx \frac{n|y|}{1+|y|} \in [1, n]$ such that

$k \mapsto R_{n,k}$ is concave for $1 \leq k \leq \bar{p}$ and convex for $\bar{p} \leq k \leq n$

Numerical illustration



The error (as a function of k) is

- convex for $\omega = 1.02$ (excellent convergence)
- concave for $\omega = 160$ (error close to 100% for almost all $k \dots$)
- concave then convex for in-between ω (infl. point depends on y & n)

This analysis on an oversimplified model is illustrative of the general situation.

Adaptive algorithm

Adaptive algorithm

Relative error $E \equiv$ relative error between consecutive trajectories

- On the time-slab $[0, N\Delta T]$, we run the parareal algorithm until E is
 - either **smaller than the convergence threshold** δ_{conv}
 - or **larger than an explosion threshold** δ_{expl} (attained at parareal iteration $\# k_{\text{cur}}$)

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- In the **blow-up case**, for the parareal iteration k_{cur} , we find the first time iteration $1 + \tilde{m}_1 \leq N$ for which E exceeds δ_{expl} , and we **shorten the slab to** $[0, \tilde{m}_1\Delta T]$.
- We then **proceed** with the parareal iterations on the slab $[0, \tilde{m}_1\Delta T]$, that we possibly further shorten, **until the relative error (on $[0, \tilde{m}_1\Delta T]$) is smaller than δ_{conv} . No need to redo the first k_{cur} iterations!**

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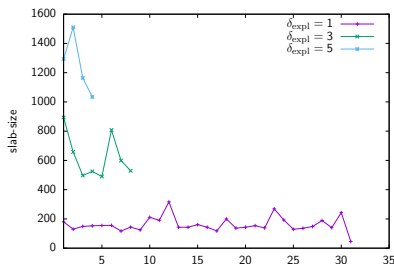
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- Once we have converged on $[0, \tilde{m}_1\Delta T]$, we proceed with the next part of the time range and **define the new (tentative) time-slab as** $[\tilde{m}_1\Delta T, N\Delta T]$.

Explosion threshold

The slab sizes are such that $E \leq \delta_{\text{expl}}$:

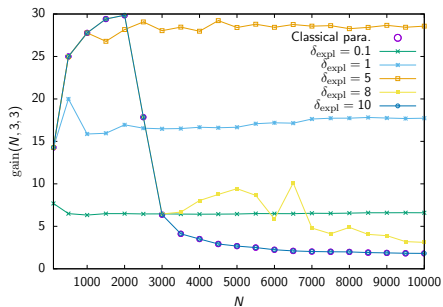
- if δ_{expl} is chosen large, the adaptive criterion is never triggered: vanilla parareal
- if δ_{expl} is chosen small, the slabs are short: no parallelism anymore
- the optimal choice of δ_{expl} is somewhere in-between

List of the sizes of the time-slabs found by the algorithm:

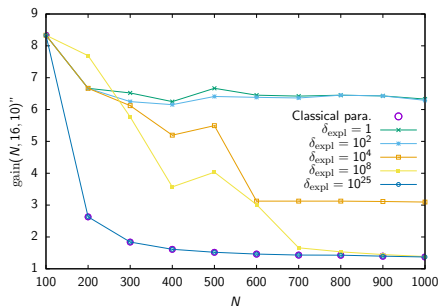


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Gain



Har-1d ($\omega = 0.1$)



LJ7-2d

- For moderate values of δ_{expl} , the gain seems independent of N
- For large N , the adaptive algorithm always outperforms the classical version (gain ≈ 30 for Har-1d, gain ≈ 7 for LJ7-2d)

Conclusions on this part

- In the long time limit, the trajectories provided by the **classical parareal algorithm** are far away from the reference trajectories
- The **adaptive algorithm** always outperforms the classical version

F.L., T. Lelièvre and U. Sharma, SIAM J. Scientific Computing 2022

Support of ANR (through project CINE-PARA) and of EuroHPC (through project TIME-X) are gratefully acknowledged



Applications to the simulation of self-interstitial atoms in tungsten

Joint work with O. Gorynina, T. Lelièvre and D. Perez

Our aim

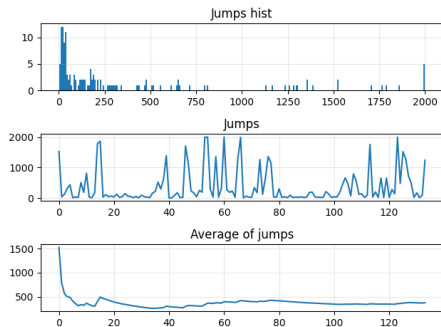
- We consider a periodic lattice of 128 tungsten atoms and add a **defect** in the lattice in the form of a **self-interstitial atom** (SIA)
- For the chosen physical parameters,
 - the system is **metastable**
 - within affordable trajectories, **several jumps of the SIA** are observed
- Quantity of interest: **distribution of the residence times** \equiv time spent by the SIA in a given well before jumping into another well (monitor “statistical accuracy”)
- Potentials:
 - **fine (reference) potential** V_f : SNAP \equiv an expensive empirical potential adjusted on quantum mechanics (DFT) results
 - **coarse potential** V_c : EAM \equiv a cheap empirical potential
- Simulations performed with **LAMMPS, a widespread MD code**

Reference results

History of residence times on a single trajectory:

$$[122, 23, 27, 476, 14, 32, 560, 245] \times \delta t$$

Distribution of residence times (25 trajectories of 2000 time steps):



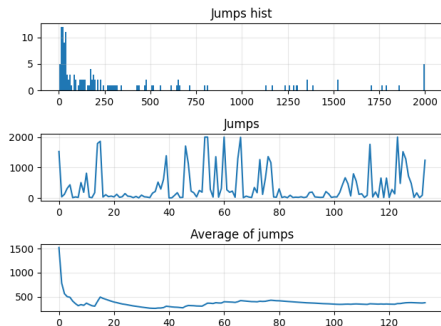
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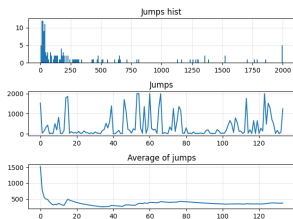


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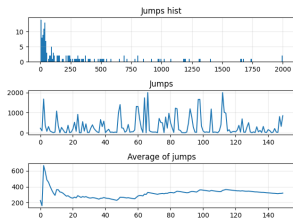
Coarse trajectory is wrong: $T_{\text{mean}} = 91 \times \delta t$, confid. interval $[81; 100] \times \delta t$

Parareal results, statistical accuracy ($\delta_{\text{conv}} = 10^{-3}$)

Reference results: $T_{\text{mean}} = 373 \times \delta t$, confidence interval $[278; 469] \times \delta t$



Parareal results: $T_{\text{mean}} = 320 \times \delta t$, confidence interval $[246; 394] \times \delta t$



Very good statistical accuracy (overlapping confidence intervals), while no pathwise accuracy for this value of δ_{conv} . Gain ≈ 5

Conclusions

- **Non-intrusive implementation within LAMMPS**, which allows to consider realistic systems
- We found a regime of intermediate δ_{conv} where
 - significant computational gains
 - no pathwise accuracy but excellent statistical accuracy

Support of ANR (through project CINE-PARA) and of EuroHPC (through project TIME-X) are gratefully acknowledged

Available postdoc position: please contact me for details!

