

# Space-Time Finite Element Methods in Moving Domains

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# Outline

1 Introduction

2 Space-time variational formulation

3 Space-time finite element method

4 Numerical example

# Introduction

- Consider bounded reference domain  $\Omega \subset \mathbb{R}^n$ ,  $n = 2, 3$ , with Lipschitz boundary  $\partial\Omega = \Gamma$
- For  $T \in (0, \infty)$  consider moving domain

$$\Omega(t) := \left\{ \mathbf{y} = \varphi(t, \mathbf{x}) \text{ for } \mathbf{x} \in \Omega \right\}, \quad \text{for } t \in (0, T).$$

- Deformation  $\varphi$  bijective for all  $t$  and sufficiently regular, satisfying  $\varphi(0, \mathbf{x}) = \mathbf{x}$  for all  $\mathbf{x} \in \Omega$ .

# Introduction

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- Deformation  $\varphi$  bijective for all  $t$  and sufficiently regular, satisfying  $\varphi(0, \mathbf{x}) = \mathbf{x}$  for all  $\mathbf{x} \in \Omega$ .
- For fixed  $\mathbf{x} \in \Omega$  consider trajectory  $\mathbf{y}(t) = \varphi(t, \mathbf{x})$  with velocity  $\mathbf{v}(t, \mathbf{y}) = \frac{d}{dt} \mathbf{y}(t)$ .
- Space-time domain

$$Q := \left\{ (\mathbf{y}, t) \in \mathbb{R}^{n+1} : \mathbf{y} = \varphi(t, \mathbf{x}) \in \Omega(t), t \in (0, T), \mathbf{x} \in \Omega \right\}.$$

# Heat equation

- Heat equation

$$\varrho(t, \mathbf{y}) \left[ \frac{\partial}{\partial t} u(t, \mathbf{y}) + \mathbf{v}(t, \mathbf{y}) \cdot \nabla_{\mathbf{y}} u(t, \mathbf{y}) \right] - \operatorname{div}_{\mathbf{y}} [\Lambda(t, \mathbf{y}) \nabla_{\mathbf{y}} u(t, \mathbf{y})] = f(t, \mathbf{y})$$

for  $(\mathbf{y}, t) \in Q$ , where  $\varrho(t, \mathbf{y})$  heat capacity, diffusion  $\Lambda(t, \mathbf{y})$  positive definite and uniformly elliptic.

- Homogeneous initial and Dirichlet boundary conditions:

$$u(0, \mathbf{x}) = 0 \quad \text{for } \mathbf{x} \in \Omega,$$

$$u(t, \mathbf{y}) = 0 \quad \text{for } \mathbf{y} \in \partial\Omega(t), \quad t \in (0, T).$$

# Bochner spaces

- Introduce Bochner spaces:

$$Y := L^2(0, T; H_0^1(\Omega(t))),$$

$$X := \left\{ u \in Y : \frac{d}{dt}u \in Y^*, \ u(0, \mathbf{x}) = 0 \quad \text{for } \mathbf{x} \in \Omega \right\},$$

with norms

$$\|u\|_Y^2 = \int_0^T \int_{\Omega(t)} [\Lambda(t, \mathbf{y}) \nabla_y u(t, \mathbf{y})] \cdot \nabla_y u(t, \mathbf{y}) d\mathbf{y} dt,$$

$$\|u\|_X^2 = \|u\|_Y^2 + \|\varrho \frac{d}{dt}u\|_{Y^*}^2,$$

$$\|\varrho \frac{d}{dt}u\|_{Y^*} = \sup_{0 \neq z \in Y} \frac{\langle \varrho \frac{d}{dt}u, z \rangle_Q}{\|z\|_Y}.$$

# Eddy current problem

- Eddy current problem

$$\sigma_{\Omega(t)} \frac{d}{dt} u(t, \mathbf{y}) - \operatorname{div} (\nu_{\Omega(t)} (|\nabla u|) \nabla_y u(t, \mathbf{y})) = j_z + M^\perp \quad \text{for } (t, \mathbf{y}) \in Q,$$

with different conductivities  $\sigma$  and reluctivities  $\nu$ .

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- Bochner spaces  $X$  and  $Y$  as before, with norms

$$\|u\|_Y^2 = \int_0^T \int_{\Omega(t)} [\nu_{\Omega(t)} \nabla_y u(t, \mathbf{y})] \cdot \nabla_y u(t, \mathbf{y}) d\mathbf{y} dt,$$

$$\|u\|_X^2 = \|u\|_Y^2 + \|\sigma_{\Omega(t)} \frac{d}{dt} u\|_{Y^*}^2, \quad \|\sigma_{\Omega(t)} \frac{d}{dt} u\|_{Y^*} = \sup_{0 \neq z \in Y} \frac{\langle \sigma_{\Omega(t)} \frac{d}{dt} u, z \rangle_Q}{\|z\|_Y}.$$

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# Variational formulation - Heat equation

- Find  $u \in X$ , such that

$$a(u, z) = \langle f, z \rangle_Q \quad \text{for all } z \in Y,$$

where

$$\begin{aligned} a(u, z) &:= \int_0^T \int_{\Omega(t)} \left[ \varrho(t, \mathbf{y}) \frac{d}{dt} u(t, \mathbf{y}) z(t, \mathbf{y}) \right. \\ &\quad \left. + [\Lambda(t, \mathbf{y}) \nabla_y u(t, \mathbf{y})] \cdot \nabla_y z(t, \mathbf{y}) \right] d\mathbf{y} dt \\ &= \int_0^T \int_{\Omega(t)} \left( \varrho(t, \mathbf{y}) \left[ \frac{\partial}{\partial t} u(t, \mathbf{y}) + \mathbf{v}(t, \mathbf{y}) \cdot \nabla_y u(t, \mathbf{y}) \right] z(t, \mathbf{y}) \right. \\ &\quad \left. + [\Lambda(t, \mathbf{y}) \nabla_y u(t, \mathbf{y})] \cdot \nabla_y z(t, \mathbf{y}) \right) d\mathbf{y} dt \end{aligned}$$

# Variational formulation - Eddy current problem

- Find  $u \in X$ , such that

$$a(u, v) = \langle F_{\Omega(t)}, v \rangle \quad \text{for all } v \in Y,$$

where

$$a(u, v) = \int_Q \left( \sigma_{\Omega(t)} \frac{d}{dt} uv + \nu_{\Omega(t)}(|\nabla u|) \nabla_y u \cdot \nabla_y v \right) d(\mathbf{y}, t),$$

$$\langle F_{\Omega(t)}, v \rangle = \int_0^T \int_{\Omega_C} j_z v \, d(\mathbf{y}, t) + \int_0^T \int_{\Omega_m(t)} M^\perp \cdot \nabla_y v \, d(\mathbf{y}, t).$$

# Variational formulation

- $a$  is bounded, i.e.

$$|a(u, z)| \leq \sqrt{2} \|u\|_X \|z\|_Y.$$

## Lemma 1 (Steinbach, 2015)

For  $u \in X$  there holds the inf-sup stability condition

$$\frac{1}{\sqrt{2}} \|u\|_X \leq \sup_{0 \neq z \in Y} \frac{a(u, z)}{\|z\|_Y}.$$

## Lemma 2

For all  $z \in Y \setminus \{0\}$  there exists a  $\tilde{u} \in X$  such that

$$a(\tilde{u}, z) \neq 0.$$

- Unique solvability follows from Babuška-Nečas Theorem!

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## Galerkin variational formulation

- Consider admissible decomposition of  $Q$  into shape regular simplicial finite elements
- Introduce FE space  $X_h = Y_h \subset X \subset Y$  of piecewise linear and continuous basis functions
- Space-time FE Galerkin variational form: Find  $u_h \in X_h$ , s.t.

$$a(u_h, z_h) = \langle f, z_h \rangle \quad \text{for all } z_h \in Y_h.$$

### Lemma 3

For  $u \in X_h$  there holds the discrete inf-sup stability condition

$$\frac{1}{\sqrt{2}} \|u_h\|_{X_h} \leq \sup_{0 \neq z_h \in Y_h} \frac{a(u_h, z_h)}{\|z_h\|_Y}.$$

- Standard stability and error estimates follow.

# Perturbed Galerkin variational formulation - Heat equation

- Find  $u_h \in X_h$  such that

$$\begin{aligned} & \int_0^T \int_{\Omega(t)} \left( \varrho(t, \mathbf{y}) \left[ \frac{\partial}{\partial t} u_h(t, \mathbf{y}) + \mathbf{v}(t, \mathbf{y}) \cdot \nabla_y u_h(t, \mathbf{y}) \right] z_h(t, \mathbf{y}) \right. \\ & \quad \left. + [\Lambda(t, \mathbf{y}) \nabla_y u_h(t, \mathbf{y})] \cdot \nabla_y z_h(t, \mathbf{y}) \right) d\mathbf{y} dt \\ &= \int_0^T \int_{\Omega(t)} f(t, \mathbf{y}) z_h(t, \mathbf{y}) d\mathbf{y} dt. \end{aligned}$$

- Usually  $\mathbf{v}(t, \mathbf{y})$  is not known, but approximation  $\mathbf{v}_h(t, \mathbf{y})$ .
  - Perturbed variational form: Find  $\tilde{u}_h \in X_h$  such that
- $$\tilde{a}(\tilde{u}_h, z_h) = \langle f, z_h \rangle_Q \quad \text{for all } z_h \in Y_h.$$
- Numerical Analysis via Strang-Lemma.

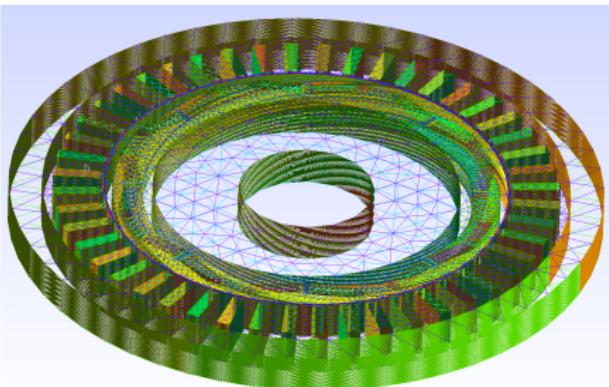
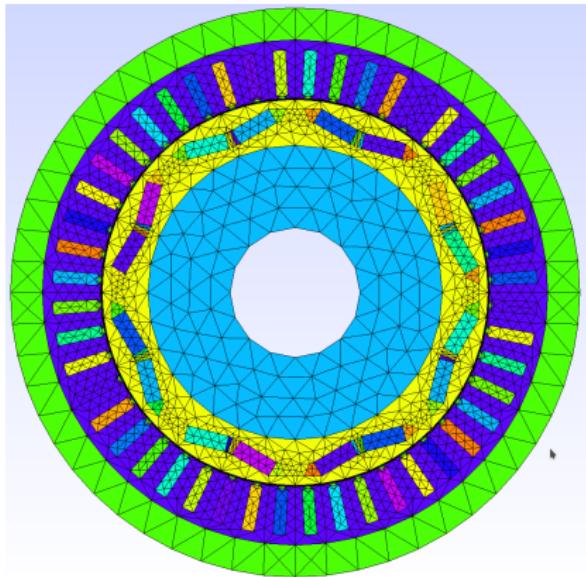
## 1 Introduction

## 2 Space-time variational formulation

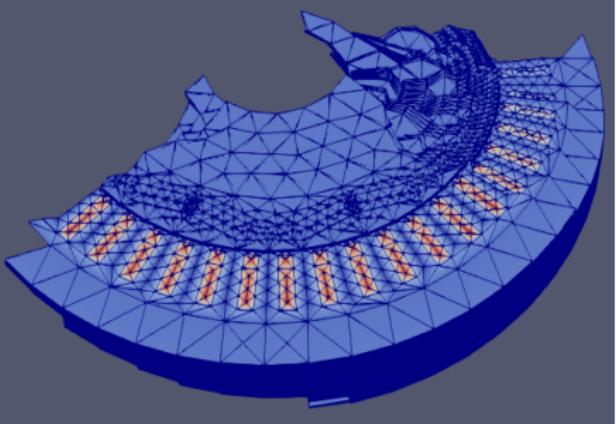
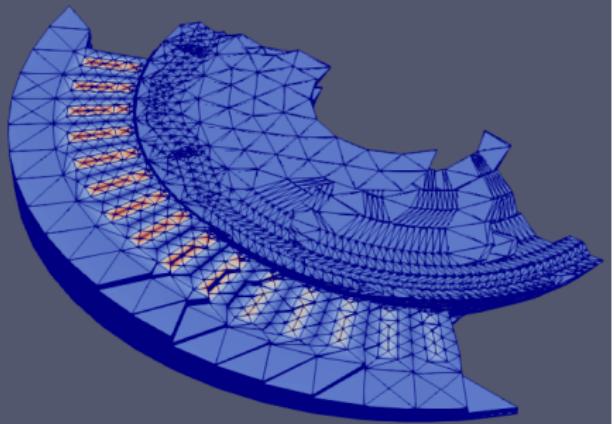
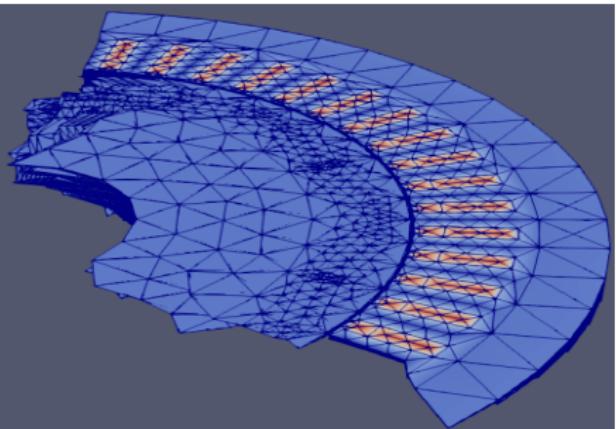
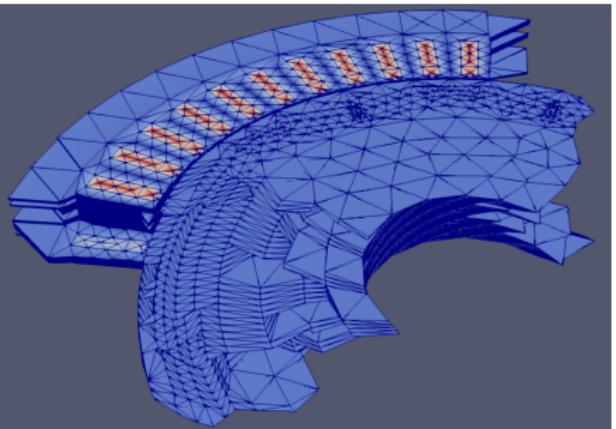
## 3 Space-time finite element method

## 4 Numerical example

# Mesh of the electric motor



number of elements: 642716  
number of points: 104144

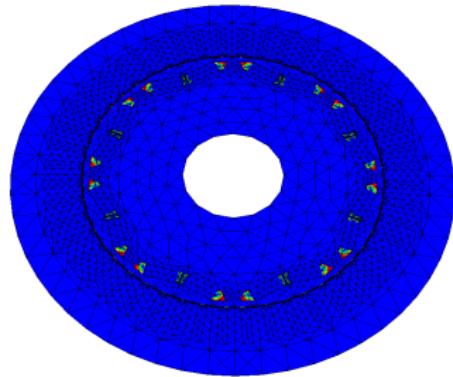
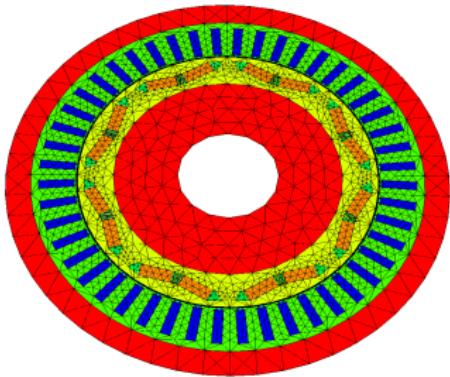


# Computation of the velocity field

$$(u, p) \in X : \int_{Q_{air}} \left[ \frac{\partial u}{\partial t} \cdot v + \nu \nabla_y u : \nabla_y v - \operatorname{div}_y(u)q - \operatorname{div}_y(v)p \right] d(y, t) = 0,$$

for  $(v, q) \in X$ .

Viscosity  $\nu = 0.001$ .

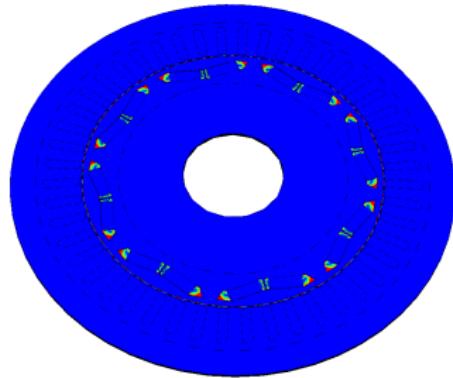
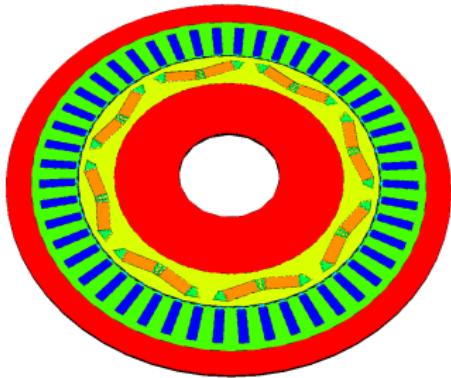


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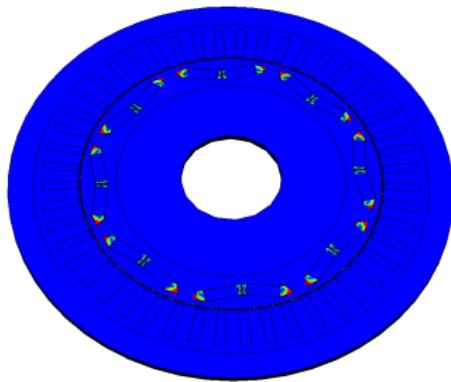
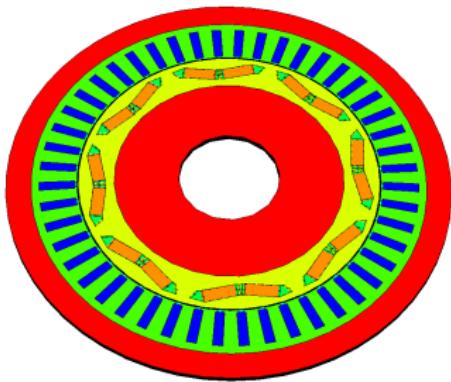


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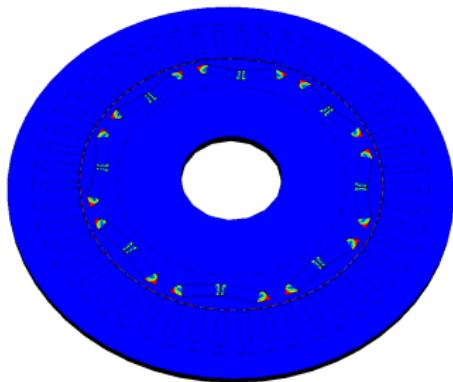
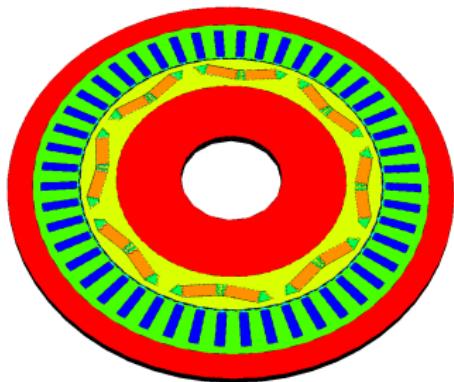


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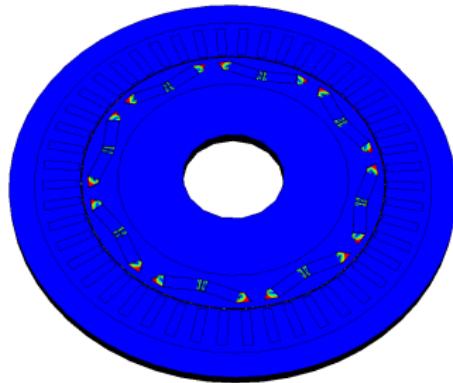
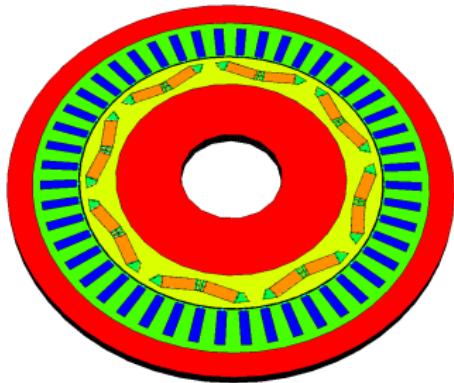


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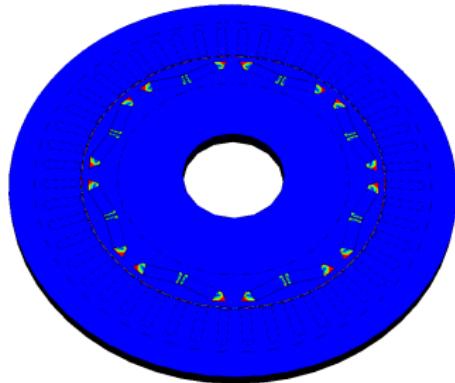
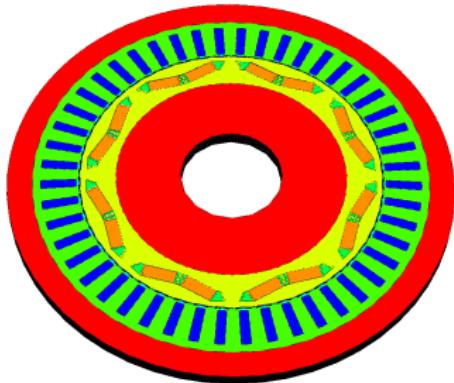


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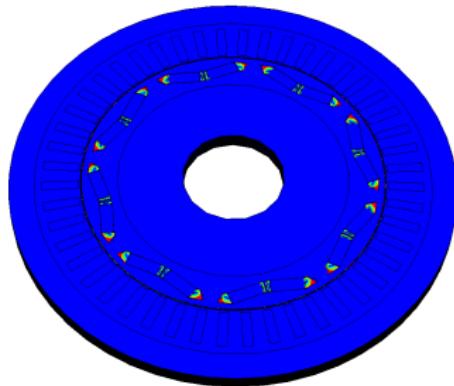
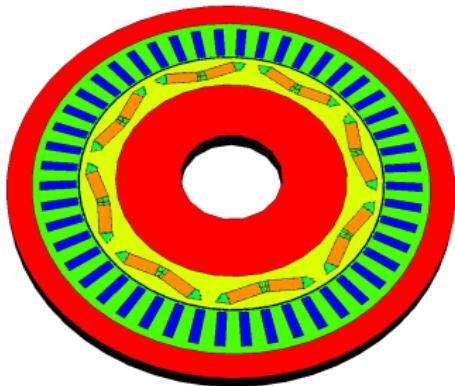


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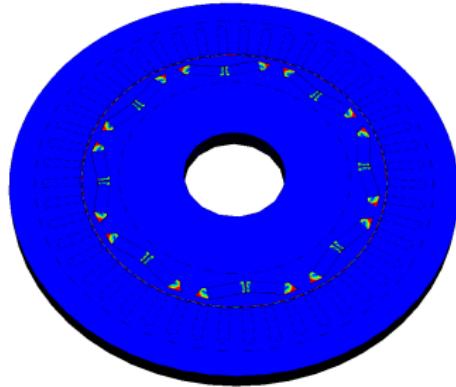
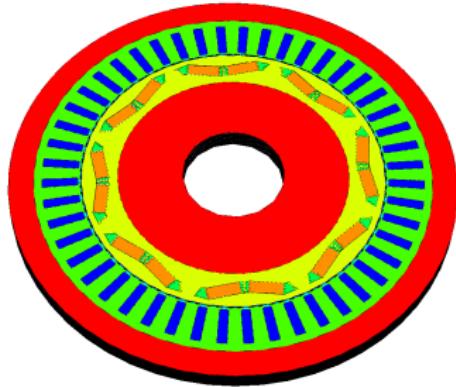


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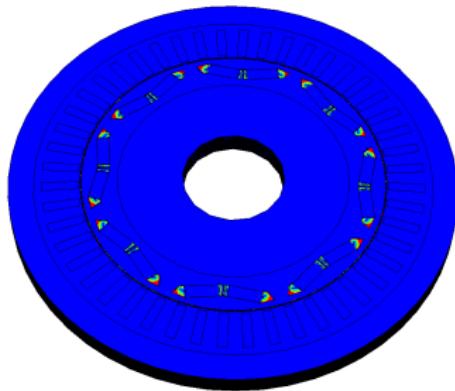
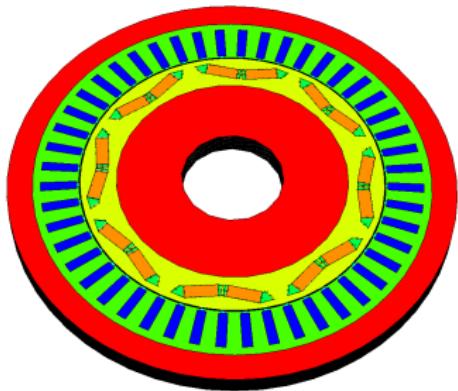


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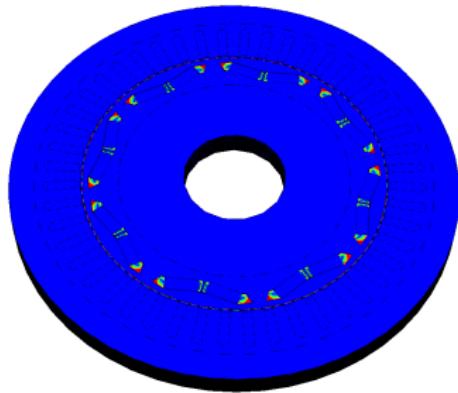
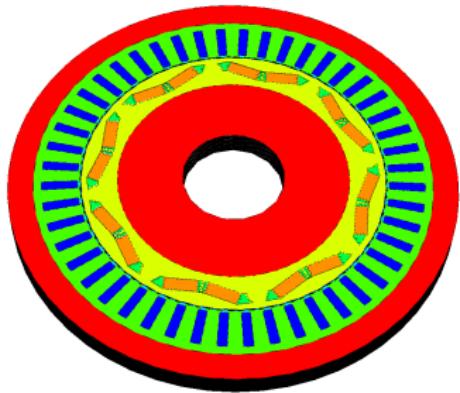


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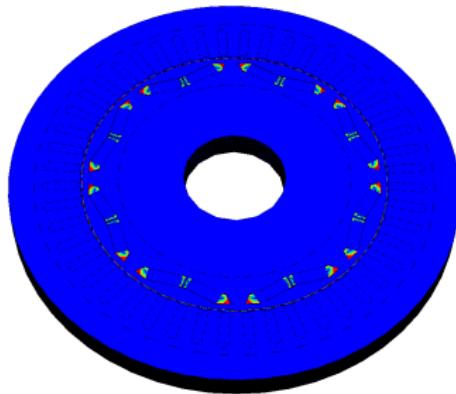
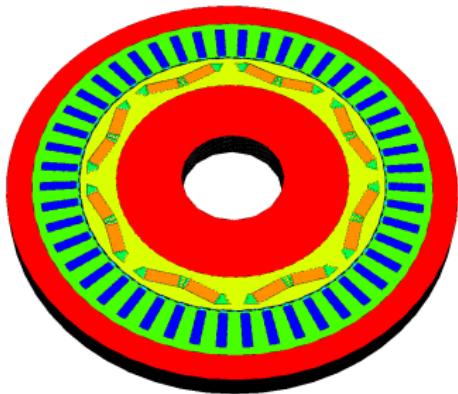


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for  $(v, q) \in X$ .

Viscosity  $\nu = 0.001$ .



# Heat equation

$$c_{air}\rho_{air} \frac{\partial u}{\partial t} - \operatorname{div}_y(\Lambda_{air} \nabla_y u) + b_{air} \operatorname{div}_y(uV) = f_{air} \quad \text{in } Q_{air}$$

$$c_{iron}\rho_{iron} \frac{\partial u}{\partial t} - \operatorname{div}_y(\Lambda_{iron} \nabla_y u) + b_{iron} \operatorname{div}_y(uV) = f_{iron} \quad \text{in } Q \setminus \overline{Q}_{air}$$

$$c_{air}\rho_{air} = 1005 * 1.293,$$

$$c_{iron}\rho_{iron} = 465 * 7860,$$

$$\Lambda_{air} = 0.026, \quad \Lambda_{iron} = 40,$$

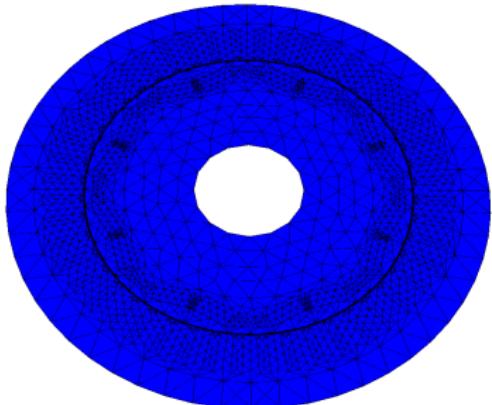
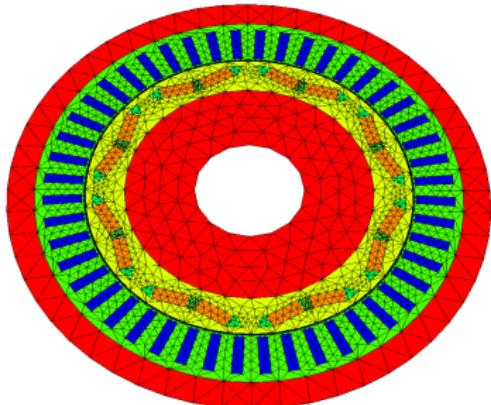
$$b_{air} = c_{air}\rho_{air}, \quad b_{iron} = c_{iron}\rho_{iron}$$

$$f_{air} = 0, \quad f_{iron} = \begin{cases} 1, & Q_{coils} \\ 0, & \text{otherwise} \end{cases}$$

# Heat equation

$$c_{air}\rho_{air}\frac{\partial u}{\partial t} - \operatorname{div}_y(\Lambda_{air}\nabla_y u) + b_{air}\operatorname{div}_y(uV) = f_{air} \quad \text{in } Q_{air}$$

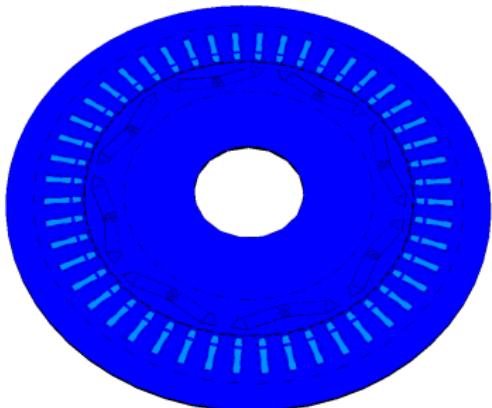
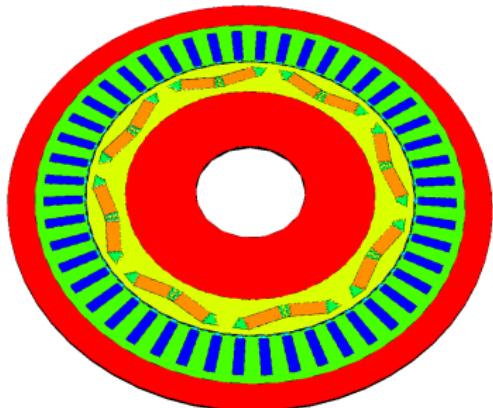
$$c_{iron}\rho_{iron}\frac{\partial u}{\partial t} - \operatorname{div}_y(\Lambda_{iron}\nabla_y u) + b_{iron}\operatorname{div}_y(uV) = f_{iron} \quad \text{in } Q \setminus \overline{Q}_{air}$$



# Heat equation

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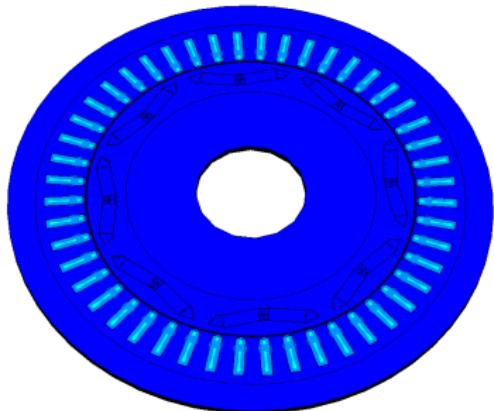
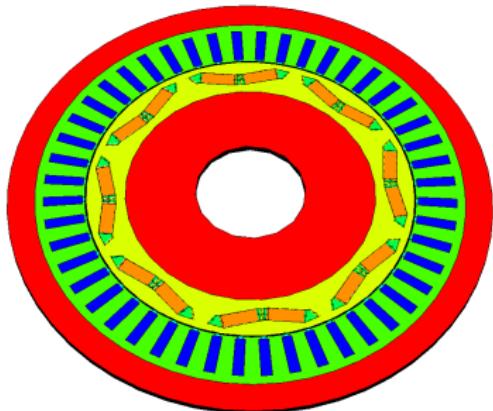
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# Heat equation

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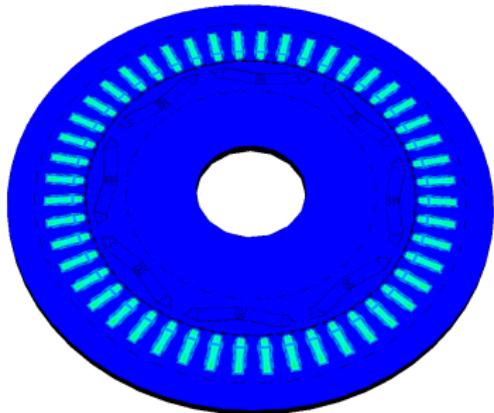
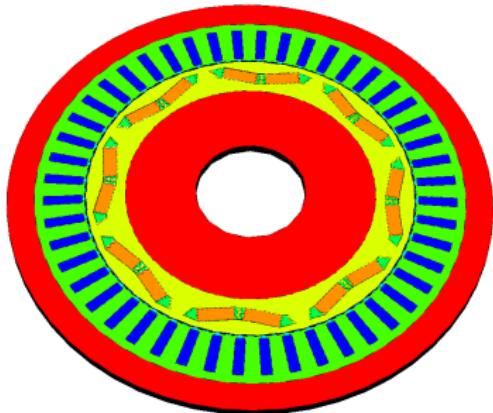
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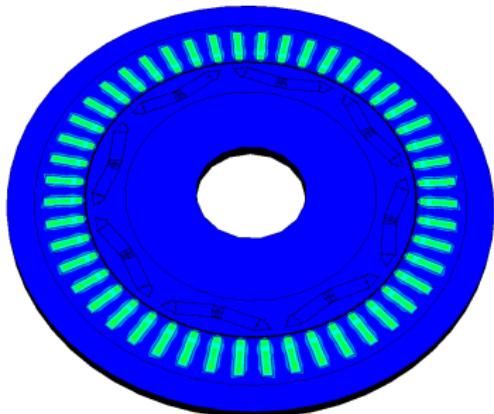
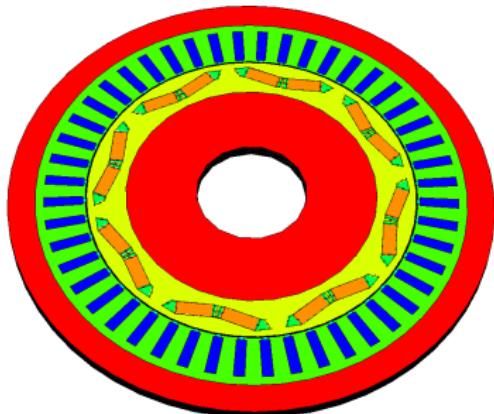
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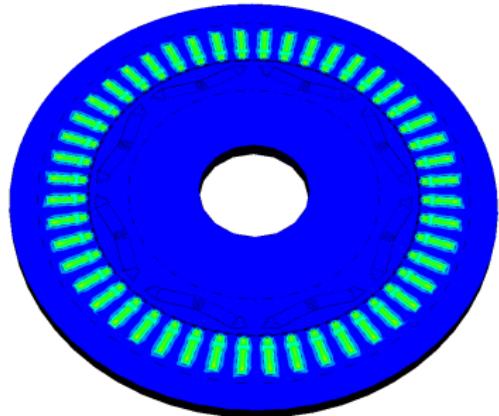
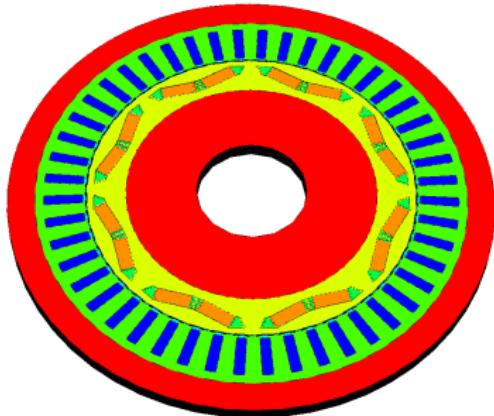
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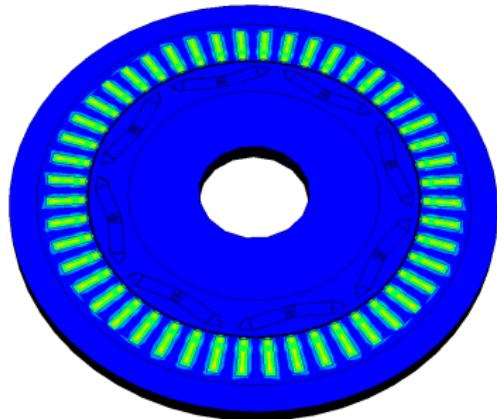
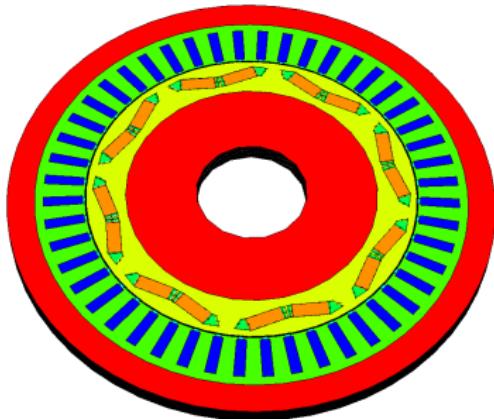
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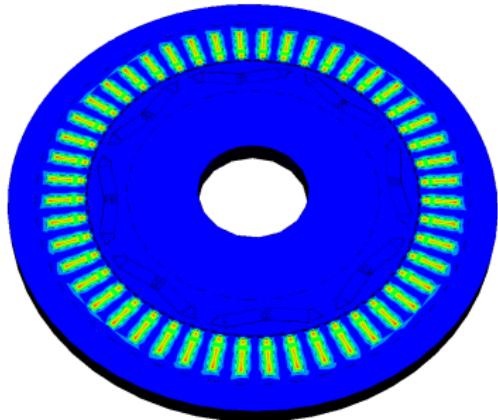
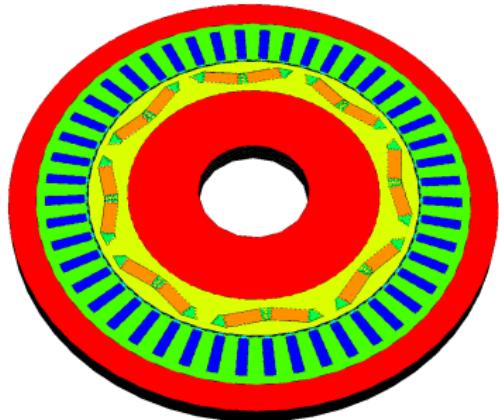
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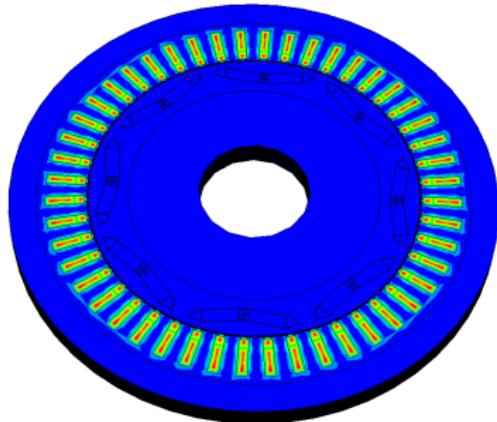
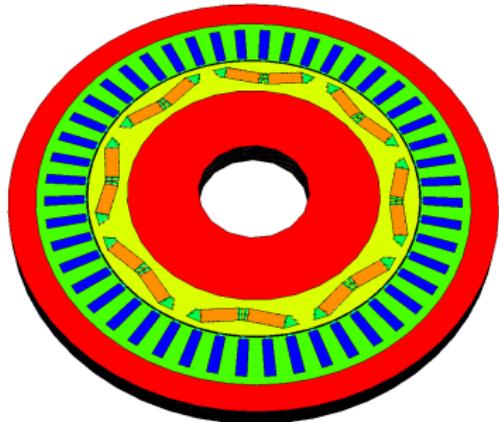
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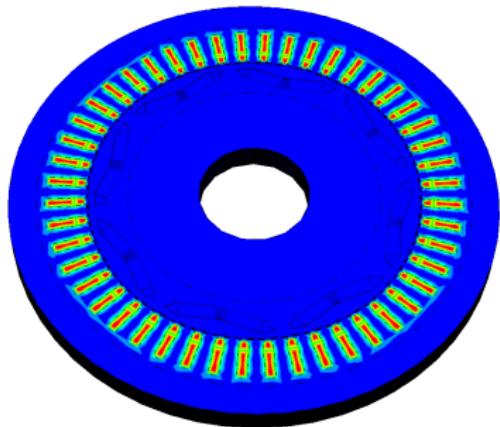
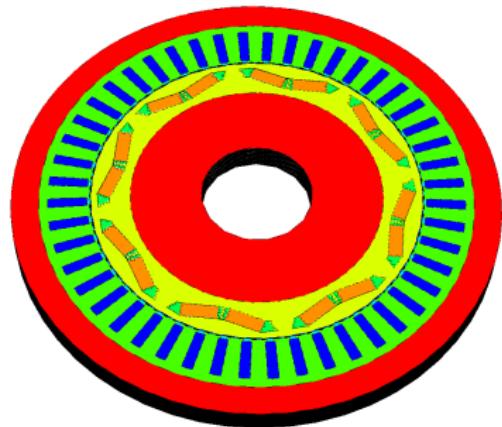
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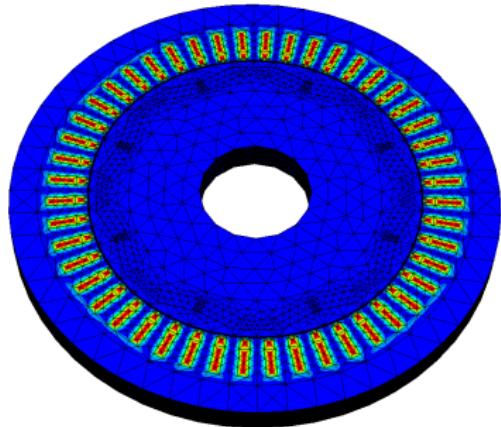
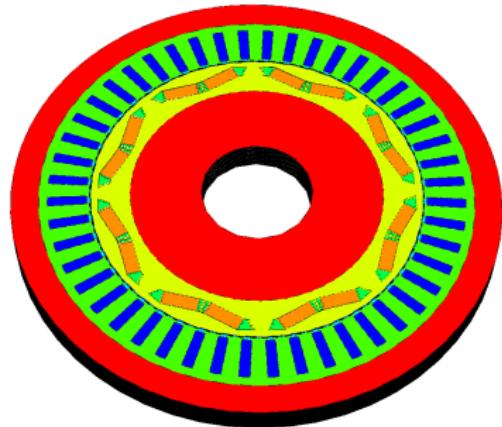
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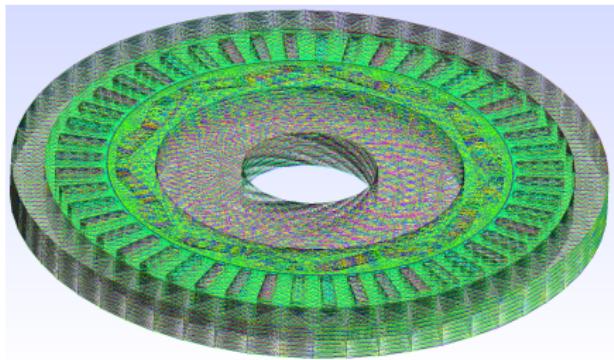
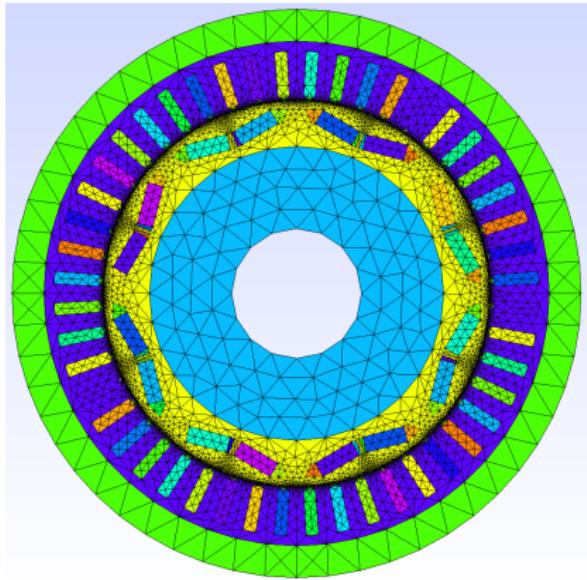
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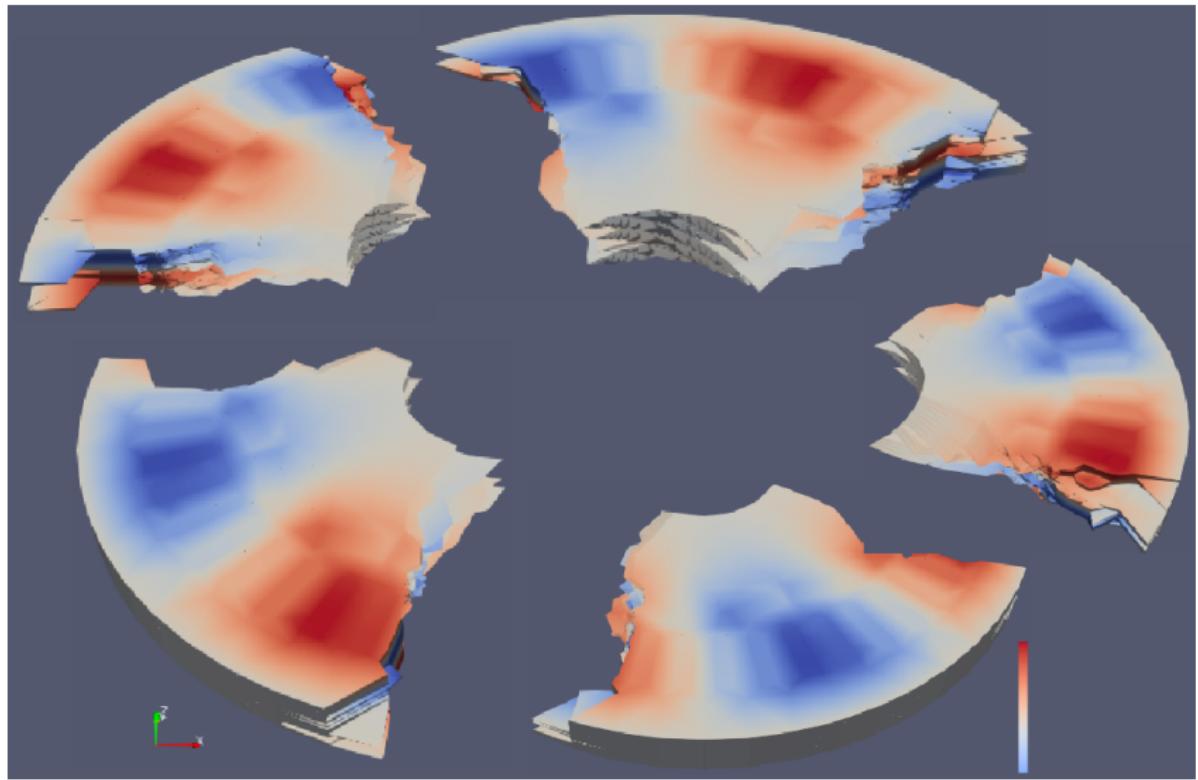
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## Mesh of the electric motor



number of elements: 1978689  
number of points: 333288



# Eddy current problem

$$\int_Q \sigma_{\Omega(t)} \frac{d}{dt} uv + \nu_{\Omega(t)}(|\nabla u|) \nabla_y u \cdot \nabla_y v \, d(\mathbf{y}, t) = \langle F_{\Omega(t)}, v \rangle \quad v \in Y,$$

where

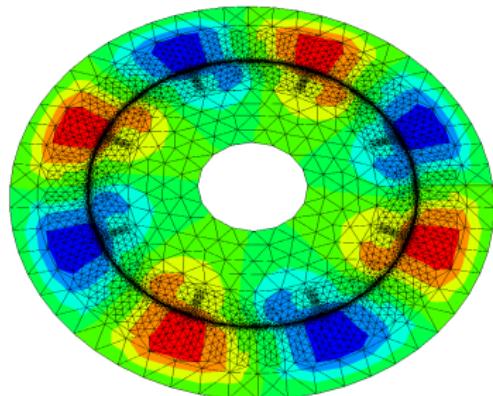
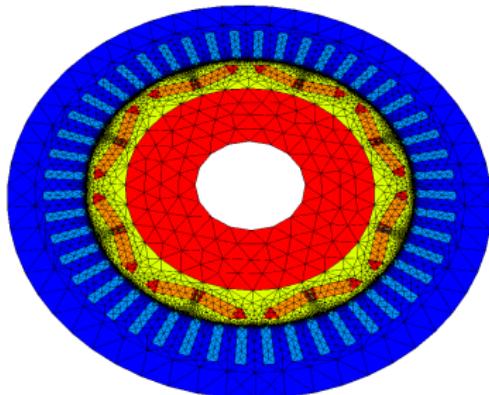
$$\langle F_{\Omega(t)}, v \rangle = \int_0^T \int_{\Omega_C} j_z v \, d(\mathbf{y}, t) + \int_0^T \int_{\Omega_m(t)} M^\perp \cdot \nabla_y v \, d(\mathbf{y}, t).$$

$$M^\perp := \nu_{\text{mag}} B_R \begin{pmatrix} -M_2 \\ M_1 \end{pmatrix}, \quad \nu_{\text{mag}} = \nu_0 / 1.05, \quad B_R = 1.05 * 1.158$$

$$\nu_{\Omega(t)}(|\nabla u|) = \begin{cases} \nu_0 & \text{air, coils,} \\ \nu_{\text{mag}} & \text{magnets,} \\ \nu(|\nabla u|) & \text{iron.} \end{cases} \quad \sigma_{\Omega(t)} = \begin{cases} 0 & \text{air,} \\ 0 & \text{coils,} \\ 0 & \text{magnets,} \\ 0 & \text{iron.} \end{cases}$$

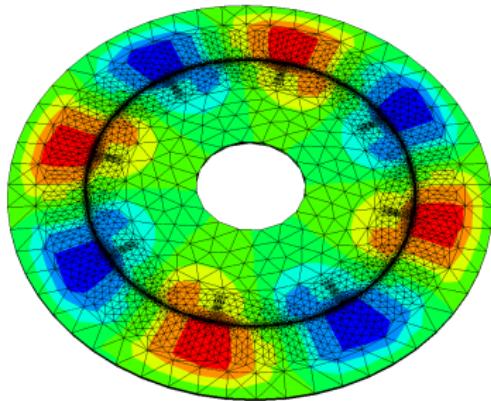
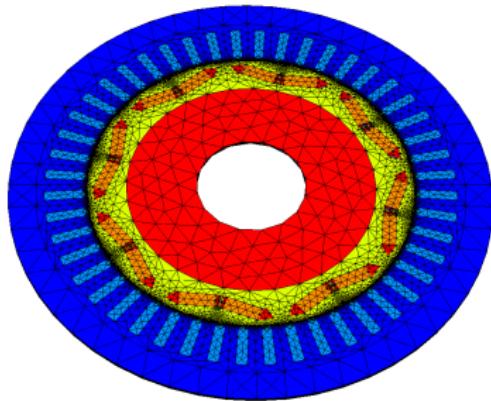
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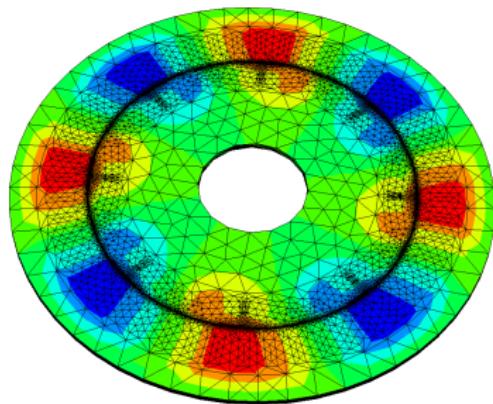
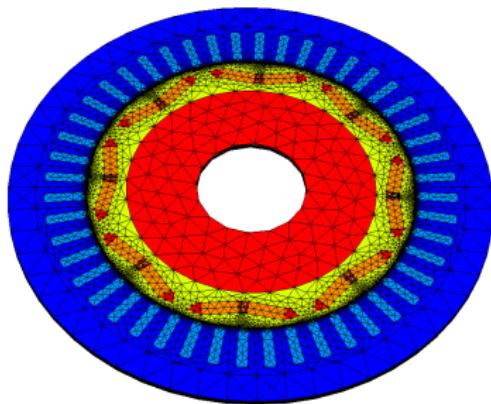
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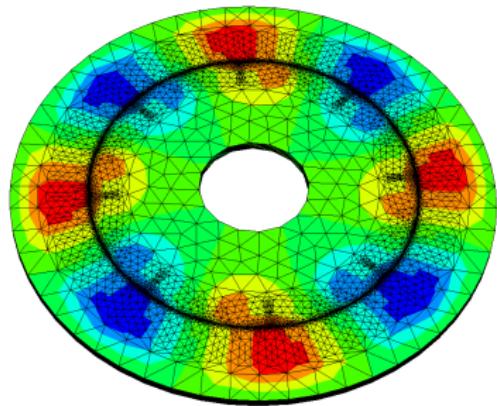
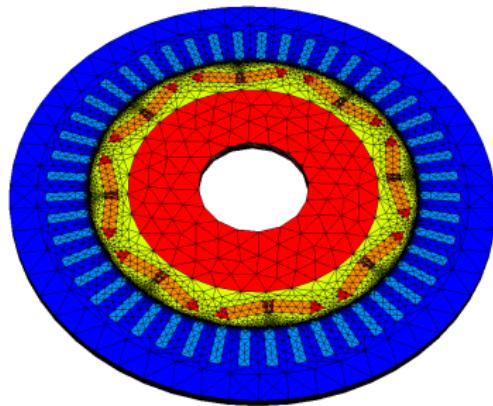
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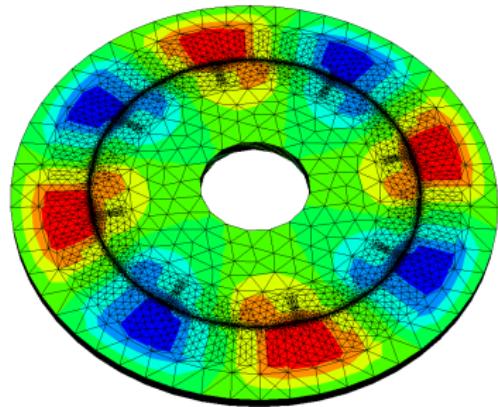
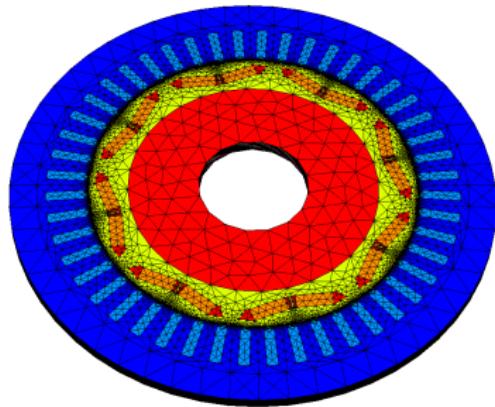
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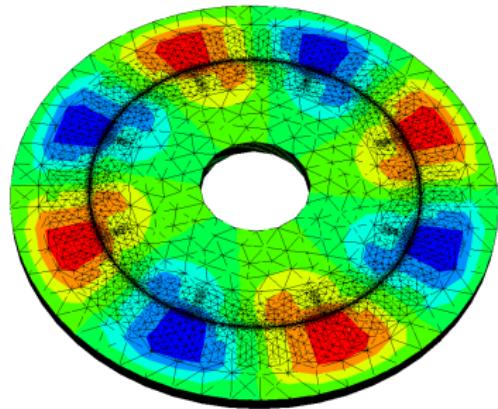
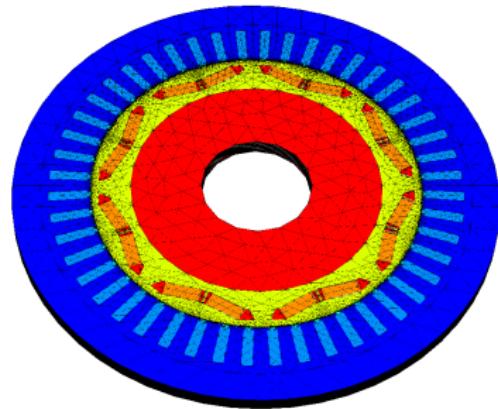
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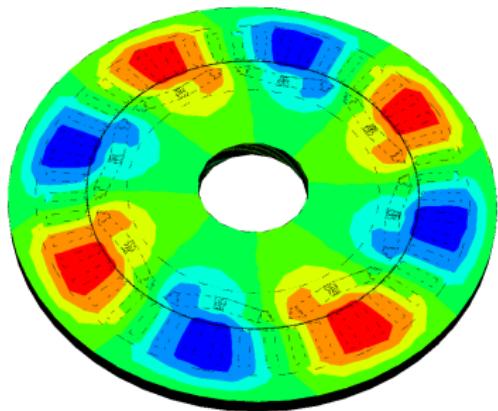
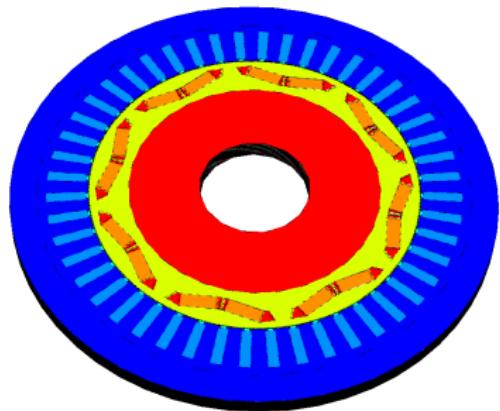
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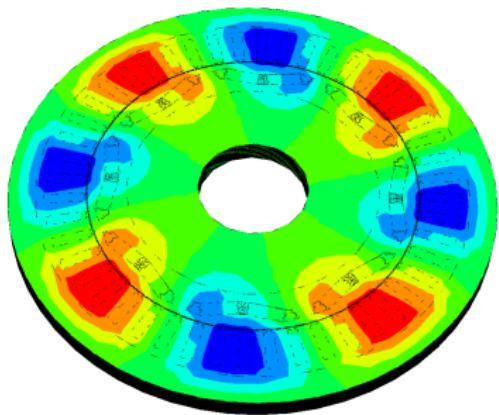
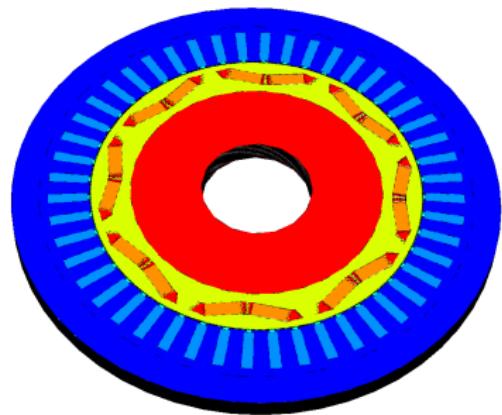
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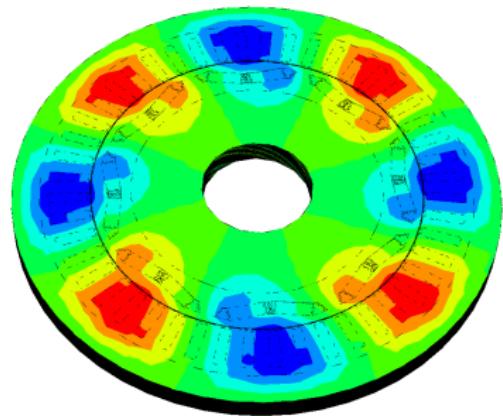
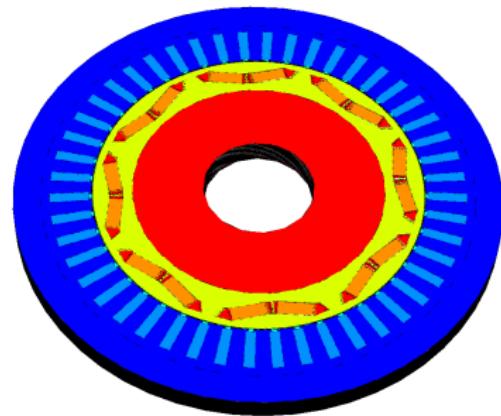
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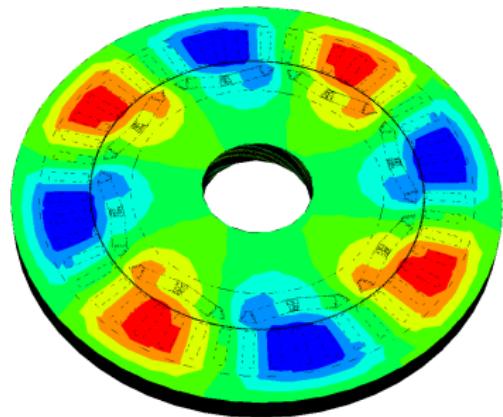
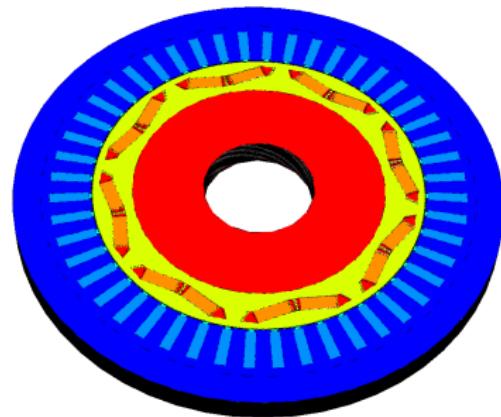
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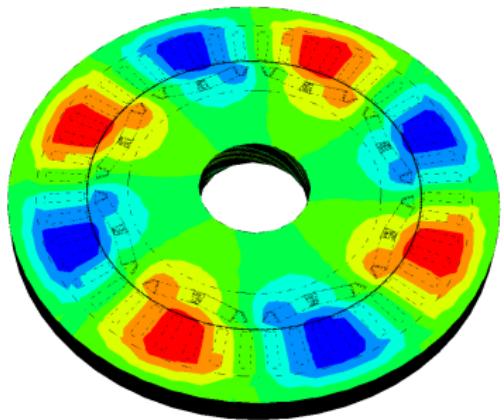
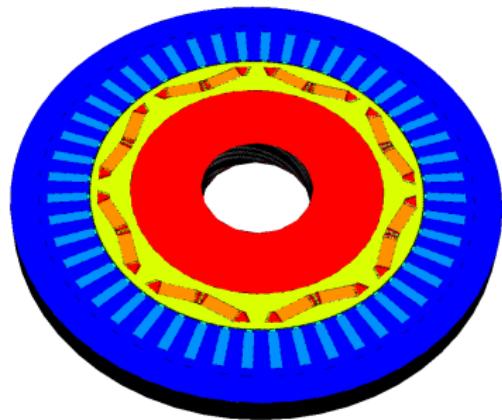
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# Iron losses

- For every element  $\tau$  in iron, calculate  $B_r^\tau(0), B_r^\tau(\Delta t), B_r^\tau(2\Delta t), \dots, B_r^\tau(T)$  and  $B_\phi^\tau(0), B_\phi^\tau(\Delta t), B_\phi^\tau(2\Delta t), \dots, B_\phi^\tau(T)$ .
- Calculate Fourier-Coefficients

$$a_k^{r/\phi} = \frac{2}{T} \int_0^T B_{r/\phi}^\tau(t) \cos(k(\frac{2\pi}{T}t - \pi)) dt,$$

$$b_k^{r/\phi} = \frac{2}{T} \int_0^T B_{r/\phi}^\tau(t) \sin(k(\frac{2\pi}{T}t - \pi)) dt,$$

for  $k = 1, \dots, 20$ . Then:

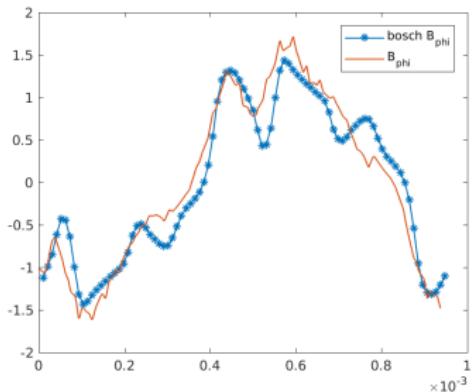
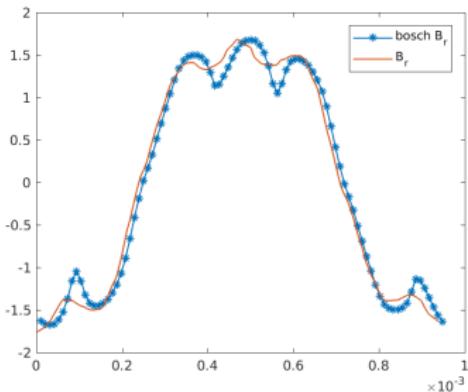
$$A_k^{r/\phi} = \sqrt{(a_k^{r/\phi})^2 + (b_k^{r/\phi})^2}.$$

# Iron losses

- $P = P_{eddy} + P_{phys}$  with  $f_k = k \frac{1}{T}$

$$P_{eddy} = \sum_{k=1}^{20} 0.468 * (A_k^r)^2 * f_k^2 + 0.468 * (A_k^\phi)^2 * f_k^2$$

$$P_{phys} = \sum_{k=1}^{20} 195 * (A_k^r)^2 * f_k + 195 * (A_k^\phi)^2 * f_k^2$$



## Summary and Outlook

- Heat equation for the motor
- Eddy current problem for 90 degree rotation
- Parallel computations for space time VF

## Summary and Outlook

- Heat equation for the motor
- Eddy current problem for 90 degree rotation
- Parallel computations for space time VF
- Motor for one rotation or even more
- Shape/Topological optimization of electrical machines.
- Numerical scheme:
  - Parallelization
  - Domain decomposition methods
  - Preconditioners