
The Vlasov-Navier-Stokes system with absorption : viscous penalization ?

A. Moussa

LJLL, SU & DMA, ENS

Outline

- 1 The Vlasov-Navier-Stokes system
- 2 Mathematical analysis of VNS
- 3 Trace theory for Vlasov/transport equation
- 4 Viscous penalization

Fluid/kinetic systems

Dispersed phased moving within a continuous one

- $f(t, \mathbf{x}, \mathbf{v})$: kinetic equation for the particles
- $\mathbf{u}(t, \mathbf{x})$ and $p(t, \mathbf{x})$: fluid mechanics

The Vlasov-Navier-Stokes system

- Thin spray : no fraction volume, no internal interaction
- Fluid : viscous, homogeneous, incompressible
- Interaction : **drag** force and **Brinkman** force

$$\left\{ \begin{array}{l} \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} - \Delta \mathbf{u} + \nabla p = - \int_{\mathbf{v}} (\mathbf{u} - \mathbf{v}) f \, d\mathbf{v}, \\ \operatorname{div} \mathbf{u} = 0, \\ \partial_t f + \mathbf{v} \cdot \nabla_{\mathbf{x}} f + \nabla_{\mathbf{v}} \cdot (f(\mathbf{u} - \mathbf{v})) = 0. \end{array} \right.$$

Boundary conditions

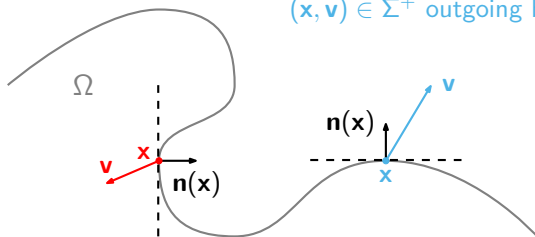
- Physical setting : aerosoltherapy
 - f : aerosol
 - \mathbf{u} : air
 - Ω : (part of) pulmonary duct
 - $\partial\Omega$: mucus
- homogeneous Dirichlet + absorption

Boundary conditions

→ $\mathbf{u}(t, \mathbf{x}) = 0$ for $\mathbf{x} \in \partial\Omega$

→ $f(t, \mathbf{x}, \mathbf{v}) = 0$ for $\mathbf{x} \in \partial\Omega$ and $\mathbf{v} \cdot \mathbf{n}(\mathbf{x}) < 0$

$(\mathbf{x}, \mathbf{v}) \in \Sigma^+$ outgoing boundary



$(\mathbf{x}, \mathbf{v}) \in \Sigma^-$ ingoing boundary

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The energy-dissipation identity

Defining

$$E(t) = \frac{1}{2} \int_{\mathbf{x}} |\mathbf{u}(t)|^2 + \frac{1}{2} \int_{\mathbf{x}, \mathbf{v}} f(t) |\mathbf{v}|^2,$$

$$D_{\text{diss}}(t) = \int_{\mathbf{x}} |\nabla \mathbf{u}(t)|^2 + \int_{\mathbf{x}, \mathbf{v}} f(t) |\mathbf{u}(t) - \mathbf{v}|^2,$$

we have formally

$$\frac{d}{dt} E(t) + D_{\text{diss}}(t) = 0.$$

Mathematical analysis, without boundary

- Existence : [BDGm '09]
 - Energy estimate + scheme
 - Leray \mathbf{u} and renormalized f
- Uniqueness : [HKM³ '20]
 - For the moment only $d = 2$ (Leray)
 - Expected for $d = 3$ (Kato)

Mathematical analysis, without boundary

Boudin, Desvillettes,
Grandmont & M., DIE 2009

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Han-Kwan, Miot,
M. & Moyano, RMI 2020

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- Large-time : [CK '15], [HKM² '20], [HK '22]
 - Monokinetic behavior $f(t) \simeq \rho_f(t) \otimes \delta_{\mathbf{u}(t)}$
- Hydrodynamic limits : [HKM '22]
 - Non-homogeneous Navier-Stokes
- Derivation : [DGR '08], [H '18], [HmS '19], [HC '20]
 - Brinkman force only
 - non-inertial

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Choi & Kwon, Nonlinearity 2015

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Han-Kwan, M. & Moyano,
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Han-Kwan,
PMP 2022

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Han-Kwan & Michel
Mem. AMS 2022

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Desvillettes, Golse & Ricci JSP 2008

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Hillairet, ARMA 2018

And with boundary ?

- Existence : [BGm '17], [BMm '20]
 - Non-cylindrical domain or polydispersed aerosol
- Uniqueness : \emptyset
- Large-time : [GHKm '18], [EHKm '21], [E '21]
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Boudin, Grandmont & M., JDE 2017

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Vlasov = transport

Vlasov equation

$$\partial_t f + \mathbf{v} \cdot \nabla_x f + \nabla_v \cdot [(\mathbf{u} - \mathbf{v})f] = 0,$$

for $\mathbf{b} = (\mathbf{v}, \mathbf{u} - \mathbf{v})$ is a transport equation on $\mathbb{R}^d \times \mathbb{R}^d$

$$\partial_t f + \mathbf{b} \cdot \nabla f = df,$$

with \mathbf{b} having Sobolev regularity

Approximation procedure

- On $\mathbb{R}_+ \times \mathbb{R}^d \times \mathbb{R}^d$, DiPerna-Lions : well-posedness, stability ✓
- Characteristics method, $f(t, \mathbf{x}, \mathbf{v}) = f_0(\mathbf{Z}_{t,0}(\mathbf{x}, \mathbf{v}))e^{dt}$
- Solution f_{abs} on Ω vanishing on Σ^- then given

$$f_{\text{abs}}(t) = f(t)\mathbf{1}_{A_t},$$

where $A_t := \{(\mathbf{x}, \mathbf{v}) : \forall s \in [0, t], \mathbf{Z}_{t,s}(\mathbf{x}, \mathbf{v}) \in \Omega \times \mathbb{R}^d\}$.

→ well-posedness, stability ?

Trace theory

$\Omega \subset \mathbb{R}^d$ bounded, Lipschitz, $\Omega_T := (0, T) \times \Omega$, $\Gamma_T := (0, T) \times \partial\Omega$.

Theorem (Boyer '05 - Mischler '00)

$\mathbf{b} \in L^1_t(W_x^{1,1})$, $\operatorname{div} \mathbf{b} \in L^\infty(\Omega_T)$ and $f, g \in L^\infty(\Omega_T)$.

$$\partial_t f + \mathbf{b} \cdot \nabla f = g \text{ in } \mathcal{D}'(\Omega_T).$$

Then $f \in \mathcal{C}_t^0(L_x^p)$ and has a trace $\gamma_f \in L^\infty(\Gamma_T, |\mathbf{b} \cdot \mathbf{n}| dx dt)$.

- analogy with Sobolev trace theory
- in line with [DiPerna-Lions '89]
- well-posedness, stability of f and γ_f

Trace theory

Precise meaning of γ_f ?

Only element of $L^\infty(\partial\Omega, |\mathbf{b} \cdot \mathbf{n}|d\mathbf{x})$ such that

$$\int_{\mathbb{R}_+} \int_{\Omega} \beta(f)(\partial_t \varphi + \operatorname{div}(\mathbf{b}\varphi)) + \int_{\mathbb{R}_+} \int_{\Omega} \varphi \beta'(f) \mathbf{g} = \int_{\partial\Omega} \beta(\gamma_f) \mathbf{b} \cdot \mathbf{n},$$

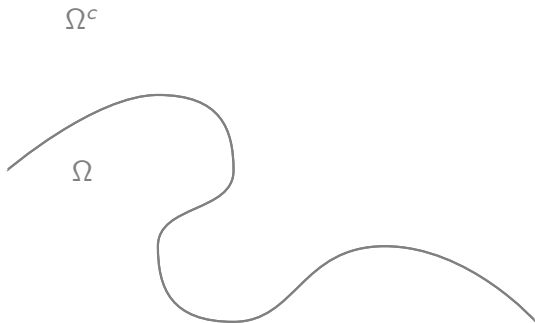
for arbitrary $\varphi \in \mathcal{D}(\mathbb{R}_+^* \times \mathbb{R}^d \times \mathbb{R}^d)$ and $\beta \in \mathcal{C}^1(\mathbb{R})$.

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The program

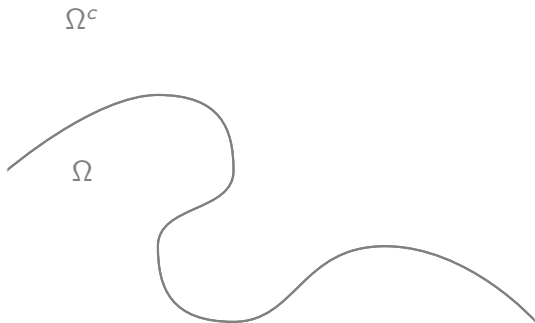
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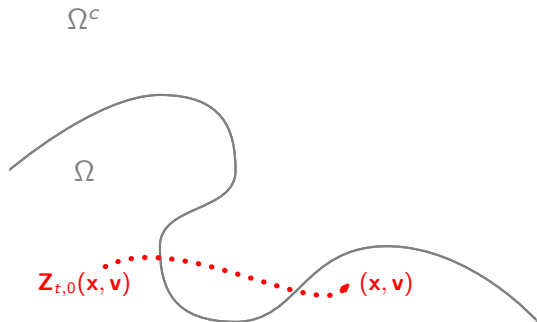
→ $\text{Supp}(f_0) \subset \Omega$ not sufficient
to avoid entering trajectories



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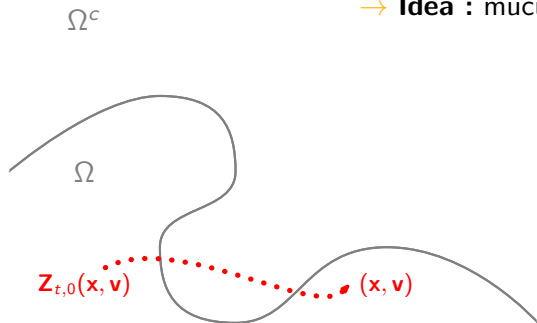
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- **Idea** : mucus slows down

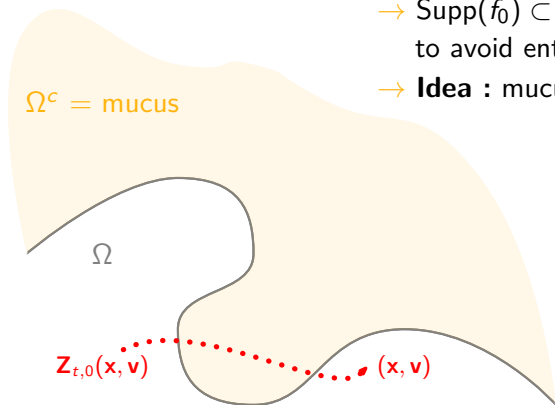


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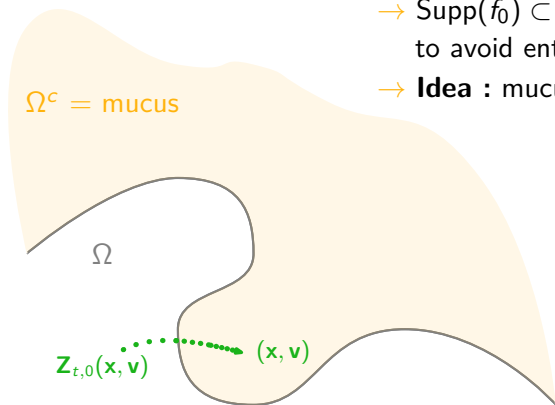
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Penalization strategies

- For Navier-Stokes (homogeneous Dirichlet)
 - L^2 -penalization : $-\varepsilon^{-1}\mathbf{u}$
 - H^1 -penalization
 - [Angot-Bruneau-Fabrie '99]
 - $\operatorname{div}(D(\mathbf{u})) \leftrightarrow \operatorname{div}(\varepsilon^{-1}D(\mathbf{u}))$
- For Vlasov (specular reflection)
 - [Mischler '00]
 - $-\varepsilon^{-1}\mathbf{n}$

Penalized VNS

Inhomogeneous viscosity $\mu_\varepsilon := \mathbf{1}_\Omega + \varepsilon^{-1}\mathbf{1}_{\Omega^c}$

$$\left\{ \begin{array}{l} \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} - \operatorname{div}(\mu_\varepsilon \mathbf{D}(\mathbf{u})) + \nabla p = -\mu_\varepsilon \int_{\mathbf{v}} (\mathbf{u} - \mathbf{v}) f \, d\mathbf{v}, \\ \operatorname{div} \mathbf{u} = 0, \\ \partial_t f + \mathbf{v} \cdot \nabla_{\mathbf{x}} f + \nabla_{\mathbf{v}} \cdot (\mu_\varepsilon f(\mathbf{u} - \mathbf{v})) = 0. \end{array} \right.$$

- Drag and Brinkman forces depend on viscosity
- Rough : mucus not newtonian and $\partial_t \partial \Omega \neq 0$

Energy estimate

$$D_{\text{diss}}^\varepsilon(t) = \int_{\mathbf{x}} \mu_\varepsilon |D(\mathbf{u}_\varepsilon)(t)|^2 + \int_{\mathbf{x}, \mathbf{v}} \mu_\varepsilon f_\varepsilon(t) |\mathbf{u}_\varepsilon(t) - \mathbf{v}|^2,$$

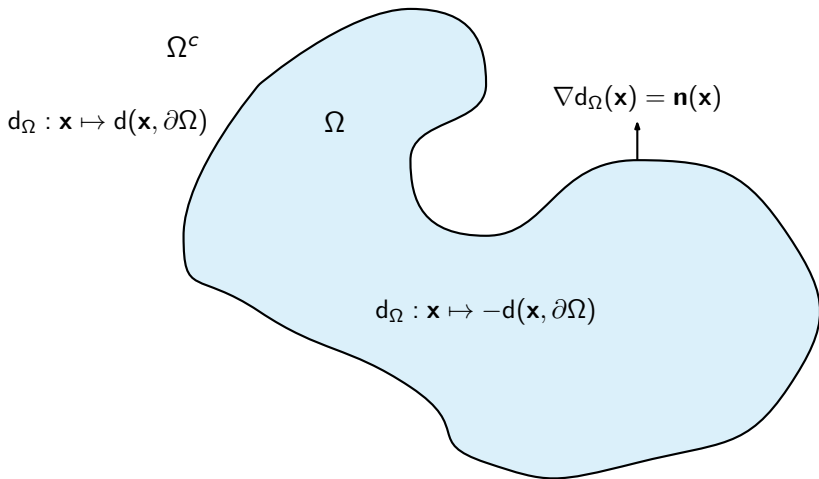
- Existence theory ✓
- As $\varepsilon \rightarrow 0$, expected :
 - $D(\mathbf{u}_\varepsilon)$ and $f_\varepsilon^{1/2} |\mathbf{u}_\varepsilon - \mathbf{v}|$ are $O_{L^2}(\varepsilon^{1/2})$ in Ω^c
 - $\mathbf{u}_\varepsilon \simeq$ rigid outside Ω , even $\mathbf{u}_\varepsilon \simeq 0$ for adequate BC
 - $f_\varepsilon \simeq \rho_f \otimes \delta_0$

⚠ High friction limit (\rightsquigarrow Daniel's talk)

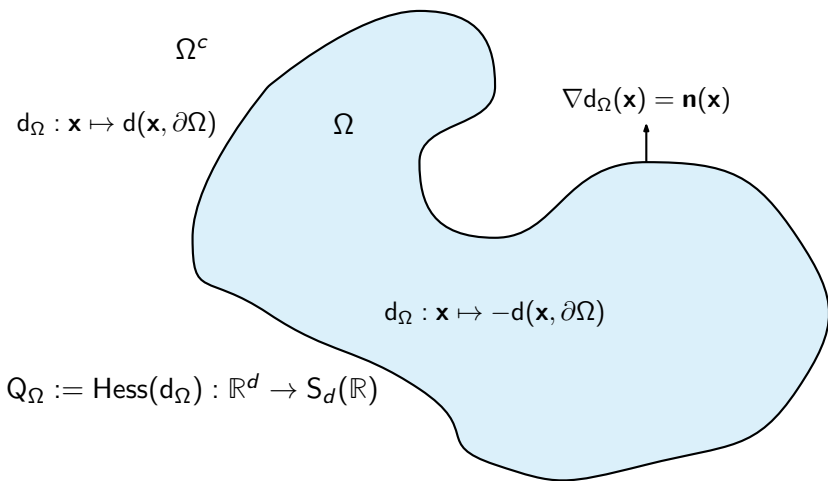
Simplified case

- Ω bounded smooth domain
- Penalization when \mathbf{u} given with vanishing trace on $\partial\Omega$?

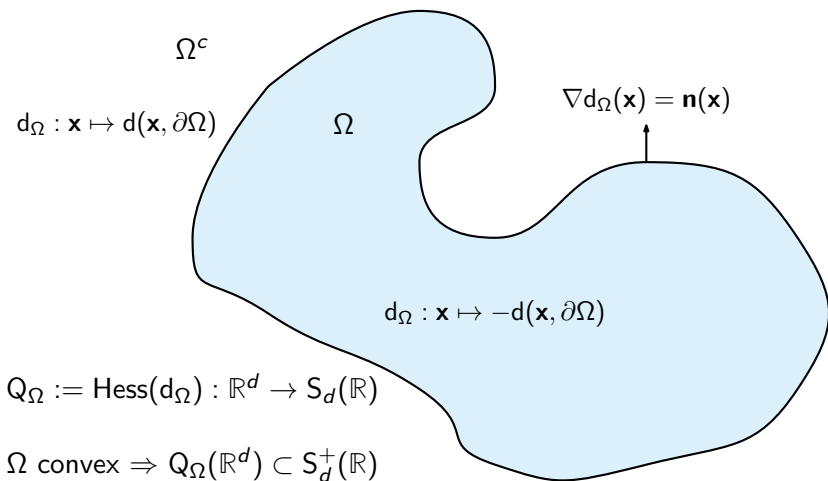
Signed distance function



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$$Q_\Omega := \text{Hess}(d_\Omega) : \mathbb{R}^d \rightarrow S_d(\mathbb{R})$$

$$\Omega \text{ convex} \Rightarrow Q_\Omega(\mathbb{R}^d) \subset S_d^+(\mathbb{R})$$