

# Complexity of Gröbner bases computations and applications to cryptography

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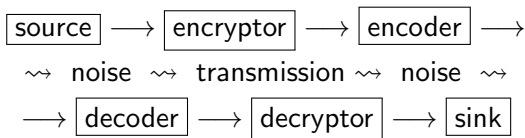
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# NONLINEAR ALGEBRA IN THE APPLICATIONS

Polynomial system solving is ubiquitous, as many models in the sciences and engineering can be described by non-linear polynomials. This includes:

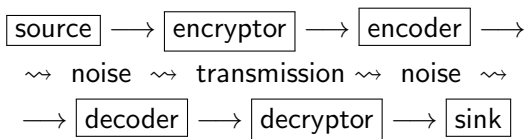
- algebraic statistics,
- algebraic biology,
- chemical reaction networks,
- coding theory,
- computer vision,
- cryptography,
- networks modelling,
- neuroscience,
- robotics,
- string theory,
- topological data analysis via (multivariate) persistent homology.

# COMMUNICATION OVER A CHANNEL



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**Rank-metric codes** are used over networks.

**Definition**

A **rank-metric code** is a vector subspace  $C \subseteq \text{Mat}_{k \times m}(\mathbb{F}_q)$ .

The **rank distance** between  $A, B \in \text{Mat}_{k \times m}(\mathbb{F}_q)$  is

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## Example

$$C = \left\langle \left( \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right), \left( \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{array} \right) \right\rangle \subseteq \text{Mat}_{3 \times 3}(\mathbb{F}_2) \text{ has } d_{\min}(C) = 2.$$

## DECODING A RANK-METRIC CODE

Let  $C$  be a rank-metric code. If  $M \in C$  is sent and  $N = M + E$  is received, then the error  $E$  can be corrected if

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In fact, if that is the case, then

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and if  $L \in C$ ,  $L \neq M$ , then

$$d(L, N) \geq d(L, M) - d(M, N) \geq \frac{d_{\min}(C)+1}{2}.$$

Hence  $M$  is the only element of  $C$  s.t.  $d(M, N) \leq \frac{d_{\min}(C)-1}{2}$ .



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Equivalently,  $M$  is the unique solution to the

### Decoding Problem

Given  $N \in \text{Mat}_{k \times m}(\mathbb{F}_q)$ , find  $M \in C$  which minimizes  $d(M, N)$ .

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Assume that  $C = \langle M_1, \dots, M_n \rangle$ , then the Decoding Problem becomes

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which, under our assumptions, is equivalent to the

## MinRank Problem

Given  $M_1, \dots, M_n, N \in \text{Mat}_{k \times m}(\mathbb{F}_q)$ , find  $x_1, \dots, x_n \in \mathbb{F}_q$  s.t.

$$\text{rank} \left( N - \sum_{i=1}^n x_i M_i \right) \leq \frac{d_{\min}(C) - 1}{2}.$$

The latter corresponds to a system of polynomial eqn's in  $\mathbb{F}_q[x_1, \dots, x_n]$ .

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# MATRIX COMPLETION AND THE NETFLIX PROBLEM

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## The Netflix Problem

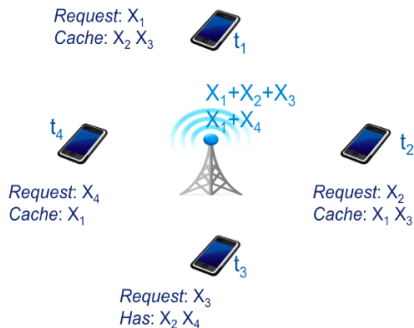
Given a ratings matrix whose entry  $(i, j)$  represents the rating of movie  $j$  by customer  $i$  if customer has watched movie  $j$ , and is otherwise missing, fill the remaining entries so that the matrix has low rank.

low rank  $\leftrightarrow$  user preferences depend on few factors

# MATRIX COMPLETION AND INDEX CODING

## Index coding

Find an optimal coding scheme for broadcasting multiple messages to receivers with different side information.



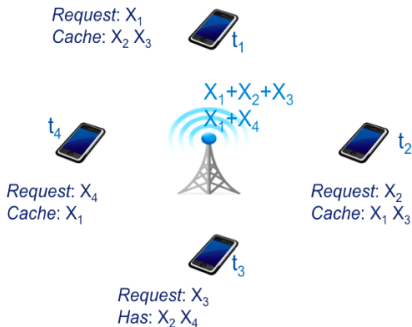


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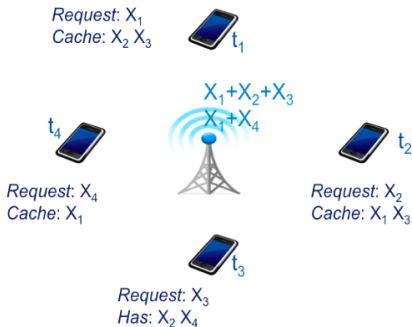
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the rank of the completion is the number of messages to be broadcasted



## MULTIVARIATE CRYPTOGRAPHY

$\mathbb{F}_q$  finite field,  $q_1, \dots, q_m \in \mathbb{F}_q[x_1, \dots, x_n]$  usually quadratic

$$Q: \begin{array}{ccc} \mathbb{F}_q^n & \longrightarrow & \mathbb{F}_q^m \\ \alpha = (\alpha_1, \dots, \alpha_n) & \longmapsto & (q_1(\alpha_1, \dots, \alpha_n), \dots, q_m(\alpha_1, \dots, \alpha_n)) \end{array}$$

$T: \mathbb{F}_q^m \longrightarrow \mathbb{F}_q^m$ ,  $S: \mathbb{F}_q^n \longrightarrow \mathbb{F}_q^n$  random affine linear maps,  $\mathcal{P} := T \circ Q \circ S$

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Bob knows  $Q, S, T$ , so he can recover  $\alpha = \mathcal{P}^{-1}(\beta) = S^{-1} \circ Q^{-1} \circ T^{-1}(\beta)$ .

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**Security:** Eve's task is finding  $\alpha$  s.t.  $\beta = \mathcal{P}(\alpha)$ , knowing  $\mathcal{P}$  and  $\beta$ .  
She may solve the system  $f_1(x_1, \dots, x_n) = \beta_1, \dots, f_m(x_1, \dots, x_n) = \beta_m$ .

# THE MULTIVARIATE QUADRATIC PROBLEM AND GRÖBNER BASES

The security of multivariate cryptographic primitives relies on the computational hardness of solving a system of polynomial equations over a finite field.

## Multivariate Quadratic (MQ) Problem

Compute the solutions of  $f_1 = \dots = f_m = 0$  over a field, where  $\deg(f_i) = 2$ .

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## Assumption

The system has a finite number of solutions over the algebraic closure, possibly zero.

Over  $\mathbb{F}_q$ , one can find the solutions by exhaustive search. Gröbner bases allow us to find the solutions of a system, under the assumption that they are finitely many. Computing a Gröbner basis has exponential complexity.



# CRYPTOGRAPHIC SECURITY

Systems coming from multivariate cryptographic schemes and digital signatures usually...

- ... consist of equations of small degree, often 2 or 3,
- ... are defined over small finite fields and contain the field equations,
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Systems coming from index calculus on elliptic curves (or on abelian varieties)...

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The complexity of computing a Gröbner basis of a system gives an upper bound on the security of the corresponding cryptographic scheme.

# MONOMIALS AND TERM ORDERS

$K$  a field,  $R = K[x_1, \dots, x_n]$

## Definition

A **monomial** is a product of powers of variables  $x^a := x_1^{a_1} \cdots x_n^{a_n} \in R$ , where  $a \in \mathbb{N}^n$ .

E.g.,  $x^{(3,0,1,2)} = x_1^3 x_3 x_4^2 \in K[x_1, x_2, x_3, x_4]$  is a monomial.

## Definition

A **term order** on  $R$  is a total order  $<$  on the set of monomials such that:

- if  $x^a < x^b$ , then  $x^{a+c} < x^{b+c}$  for any  $c \in \mathbb{N}^n$  (multiplicative)
- $1 \leq x^a$  for any  $a \in \mathbb{N}^n$  (well-ordering).

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## Example

If  $R = K[x]$ , then we only have one term order  $1 < x < x^2 < \dots$

## TWO EXAMPLES OF TERM ORDERS

## Example (Lexicographic order – lex)

$x_1^{a_1} \cdots x_n^{a_n} >_{\text{lex}} x_1^{b_1} \cdots x_n^{b_n}$  if the first nonzero coordinate of  $(a_1 - b_1, \dots, a_n - b_n)$  is positive.

E.g.,  $x_1x_3 >_{\text{lex}} x_2^d$  for any  $d$ ,  $x_1^2x_2^2 >_{\text{lex}} x_1x_2^2x_3$ , and  $x_1x_2^2 >_{\text{lex}} x_1x_2x_3$ .

## Example (Degree Reverse Lexicographic order – drl)

$x_1^{a_1} \cdots x_n^{a_n} >_{\text{drl}} x_1^{b_1} \cdots x_n^{b_n}$  if either  $\sum_{i=1}^n a_i > \sum_{i=1}^n b_i$  or  $\sum_{i=1}^n a_i = \sum_{i=1}^n b_i$  and the last nonzero coordinate of  $(a_1 - b_1, \dots, a_n - b_n)$  is negative.

E.g.,  $x_1x_3 >_{\text{drl}} x_2$ ,  $x_1x_2^2 >_{\text{drl}} x_1x_2x_3$ , and  $x_1x_2^2x_3^2 <_{\text{drl}} x_1^2x_2x_3^2$ .

For the sequel, we fix a term order.

## LEADING TERMS AND GRÖBNER BASES

$I = (f_1, \dots, f_m) = \{\sum_{i=1}^m h_i f_i \mid h_i \in R\}$  ideal generated by  $f_1, \dots, f_m \in R$

## Definition

The leading term of  $f = \sum_{a \in \mathbb{N}^n} \alpha_a x^a \in R$  is  $\text{in}(f) = \max\{x^a \mid \alpha_a \neq 0\}$ .

E.g., in  $R = \mathbb{F}_3[x_1, x_2]$  with the lex term order,  $\text{in}(x_2^3 - x_1 x_2^2) = x_1 x_2^2$ .

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The **initial ideal** of  $I$  is  $\text{in}(I) = (\text{in}(f) \mid f \in I)$ .

The polynomials  $g_1, \dots, g_s \in I$  are a **Gröbner basis** of  $I$  if

$$\text{in}(I) = (\text{in}(g_1), \dots, \text{in}(g_s)).$$

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$$I = (x_2^3 - x_1 x_2^2, x_1^2 + x_2^2) \ni -x_2^4 = (x_1 + x_2)(x_2^3 - x_1 x_2^2) + x_2^2(x_1^2 + x_2^2),$$

$$\text{in}_<(I) = (x_1^2, x_1 x_2^2, x_2^4)$$

and  $x_2^3 - x_1 x_2^2, x_1^2 + x_2^2, x_2^4$  is a (lex) Gröbner basis of  $I$ .

# GRÖBNER BASES

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There is a flat family whose special fiber is  $\text{in}(I)$  and whose general fiber is  $I$ . This implies that many algebraic invariants and properties are preserved when passing from  $I$  to  $\text{in}(I)$ . This makes Gröbner bases an important tool in commutative algebra and algebraic geometry.

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## Definition

A Gröbner basis  $g_1, \dots, g_s$  of  $I$  is **reduced** if  $\text{in}(g_1), \dots, \text{in}(g_s)$  are a minimal system of generators of  $\text{in}(I)$  and  $\text{in}(g_i)$  does not divide any monomial in the support of  $g_j$  for  $j \neq i$ .

# THE IMPORTANCE OF BEING LEX

## Proposition (Shape Lemma)

Fix the lex term order on  $R = K[x_1, \dots, x_n]$ ,  $I = (\mathcal{F}) = (f_1, \dots, f_m) \subseteq R$ .

Assume that  $\mathcal{F}$  has finitely many solutions over  $\overline{K}$  and for any solutions  $\alpha, \beta \in \overline{K}^n$   $\alpha_n \neq \beta_n$ . If  $(\mathcal{F})$  is radical, then the reduced Gröbner basis of  $(\mathcal{F})$  has the form

$$x_1 - h_1(x_n), x_2 - h_2(x_n), \dots, x_{n-1} - h_{n-1}(x_n), h_n(x_n)$$

where  $\deg(h_n) = \text{number of solutions of } f_1 = \dots = f_m = 0$ .

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$$x_1 - h_1(x_n), x_2 - h_2(x_n), \dots, x_{n-1} - h_{n-1}(x_n), h_n(x_n)$$

where  $\deg(h_n) = \text{number of solutions of } f_1 = \dots = f_m = 0$ .

Hence to solve the polynomial system  $f_1 = \dots = f_m = 0$  we:

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## Proposition (Shape Lemma)

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# BUCHBERGER'S ALGORITHM

It generalizes Gaussian elimination and the Euclidean Algorithm.

## Example

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Hence  $x_1x_2 + x_2, x_2^2 - 1, x_1 + 1$  are a lexicographic Gröbner basis of  $(f_1, f_2)$ .

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Buchberger's Algorithm computes and reduces S-pairs for each pair of elements in the Gröbner basis and adds the results to the Gröbner basis. When all the S-pairs reduce to zero, a Gröbner basis has been found.

# LINEAR ALGEBRA BASED ALGORITHMS

They are the most efficient. They include  $F_4/F_5$  and XL and its variants.



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## Definition

For each degree  $d$  one has a **Macaulay matrix**:

- columns  $\leftrightarrow$  monomials of degree  $\leq d$
- rows  $\leftrightarrow$  polynomials  $x^a f_i$  of degree  $\leq d$
- the entry  $(i, j)$  is the coefficient of the monomial corresponding to column  $j$  in the polynomial corresponding to row  $i$

The matrix is brought in RREF. If the rows are not a Gröbner basis of  $I = (f_1, \dots, f_m)$ , then one looks at the Macaulay matrix in the next degree.

Some variants add new rows to the matrix, whenever a degree drop occurs.

## EXAMPLE

 $f_1 = x_1x_2 + x_2, f_2 = x_2^2 - 1$ , lex order

	$x_1^2$	$x_1x_2$	$x_1$	$x_2^2$	$x_2$	1
$f_1$	0	1	0	0	1	0
$f_2$	0	0	0	1	0	-1

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$x_1f_1$	0	1	0	0	1	0	0	0	0	0
$x_1f_2$	0	0	0	1	0	-1	0	0	0	0
$x_2f_1$	0	0	0	1	0	0	0	1	0	0
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	0	0	0	1	0	0	0	0	0	1
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## Algorithm (Faugère, Gianni, Lazard, Mora)

*A Gröbner basis for  $I = (f_1, \dots, f_m)$  wrt a given term order can be converted into a Gröbner basis for  $I$  wrt a different term order with  $\mathcal{O}(n^2 d^3)$  operations, where  $d$  is the number of solutions of  $f_1 = \dots = f_m = 0$ .*

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## COMPUTING A LEX GRÖBNER BASIS IN PRACTICE

- compute a drr Gröbner basis using a linear algebra based algorithm
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- compute a drl Gröbner basis using a linear algebra based algorithm
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For cryptographic systems, the complexity is dominated by the first step.

## Theorem

*The complexity of Gaussian elimination in an  $a \times b$  matrix is  $\mathcal{O}(a^2b)$  operations in  $K$ .*

If we compute matrices up to degree  $s$ , then the largest has

$$a = \sum_{i=1}^m \binom{n + s - d_i - 1}{s - d_i} \quad \text{and} \quad b = \binom{n + s - 1}{s}$$

where  $d_i = \deg(f_i)$ .

# SOLVING DEGREE

Let  $\mathcal{F} = \{f_1, \dots, f_m\}$ , fix the degree reverse lexicographic order.

## Definition

The **solving degree** of  $\mathcal{F}$ , denoted  $\text{sol. deg}(\mathcal{F})$ , is the least degree for which Gaussian elimination in the drl Macaulay matrix of degree  $d$  yields a Gröbner basis of  $(\mathcal{F}) = (f_1, \dots, f_m)$ .

$\text{max. GB. deg}(\mathcal{F})$  denotes the largest degree of a polynomial in a reduced drl Gröbner basis of  $(\mathcal{F})$ .

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## Remark

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## Example

The Gröbner basis of  $f_1 = x_1x_2 + x_2$ ,  $f_2 = x_2^2 - 1$  wrt the lexicographic order is  $x_1 + 1, x_2^2 - 1$ , so  $\text{max. GB. deg}(\mathcal{F}) = 2 < 3 = \text{sol. deg}(\mathcal{F})$ .

# HOMOGENEOUS POLYNOMIALS AND HOMOGENIZATION

## Definition

A polynomial  $f$  is **homogeneous** if all the monomials in the support of  $f$  have the same degree.

E.g.,  $x_1^2 x_3 - 2x_2^3$  is homogeneous, but  $x_1^2 x_3 - 2x_2$  is not.

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## Definition

The **homogenization** of  $f = \sum_{a \in \mathbb{N}^n} \alpha_a x^a \in K[x_1, \dots, x_n]$  wrt  $x_0$  is

$$f^h = \sum_{a \in \mathbb{N}^n} \alpha_a x^a x_0^{\deg(f) - |a|} \in K[x_0, \dots, x_n],$$

where  $|a| = a_1 + \dots + a_n = \deg(x^a)$ .

E.g., the homogenization of  $f = x_1^2x_3 - 2x_2$  wrt  $x_0$  is  $f^h = x_1^2x_3 - 2x_0^2x_2$ .



# A PROVABLE BOUND FOR THE SOLVING DEGREE

Let  $I = (f_1, \dots, f_m) \subseteq R = K[x_1, \dots, x_n]$ ,  $\deg(f_i) = d_i$ ,  $d_1 \geq \dots \geq d_m$   
 $\mathcal{F}^h = \{f_1^h, \dots, f_m^h\}$ ,  $\subseteq S = K[x_0, \dots, x_n]$ .

## Theorem (Lazard)

*Suppose that  $(\mathcal{F}^h)$  is in generic coordinates, then*  
 $\text{solv. deg}(I) \leq d_1 + \dots + d_{n+1} - n$ .

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## Theorem (Caminata, G.)

Suppose that  $(\mathcal{F}^h)$  is in generic coordinates, then  
 $\text{reg}(\mathcal{F}^h) \geq \max. \text{GB. deg}(\mathcal{F}^h) = \text{solv. deg}(\mathcal{F}^h) \geq \text{solv. deg}(\mathcal{F})$

where  $\text{reg}(\mathcal{F}^h)$  is the *Castelnuovo-Mumford regularity* of  $(\mathcal{F}^h)$ .

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# THE CASTELNUOVO-MUMFORD REGULARITY

$J = (F_1, \dots, F_m)$ ,  $F_i \in S = K[x_0, \dots, x_n]$  homogeneous of  $\deg(F_i) = d_i$

$J$

# THE CASTELNUOVO-MUMFORD REGULARITY

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Have we made any progress?

Yes, because we know a lot on the Castelnuovo-Mumford regularity.

## EXAMPLE – THE COMPLEXITY OF MINRANK

## MinRank Problem

Given  $M_1, \dots, M_n, N \in \text{Mat}_{k \times m}(\mathbb{F}_q)$  and  $r < \min\{k, m\}$ , find  $x_1, \dots, x_n \in \mathbb{F}_q$  s.t.

$$\text{rank} \left( N - \sum_{i=1}^n x_i M_i \right) \leq r.$$

## EXAMPLE – THE COMPLEXITY OF MINRANK

## Generalized MinRank Problem

Given  $M \in \text{Mat}_{k \times m}(K[x_1, \dots, x_n])$  and  $r < \min\{k, m\}$ , find  $x_1, \dots, x_n \in K$  s.t.

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$$\text{rank}(M) \leq r.$$

The next result was shown by Faugère, Safey El Din, and Spaenlehauer for  $d_{ij} = d \geq 1$ .

## Theorem (Caminata, G.)

Let  $M \in \text{Mat}_{k \times m}(R)$ , let  $r < k \leq m$  and  $n \geq (m - r)(k - r)$ .

Assume that the entries of  $M$  are generic of degree  $d_{ij}$  with  $d_{ij} > 0$  and  $d_{ij} + d_{h\ell} = d_{i\ell} + d_{hj}$  for all  $i, j, h, \ell$ .

Let  $\mathcal{F}$  be the homogeneous polynomial system of the minors of size  $r + 1$  of  $M$ .  
Then

$$\text{solv. deg}(\mathcal{F}) \leq (m - r) \sum_{i=1}^r d_{i,i} + \sum_{i=r+1}^k \sum_{j=r+1}^m d_{ij} - (m - r)(k - r) + 1.$$



# ALGEBRA AND GEOMETRY

$K$  field,  $\mathcal{F} = \{f_1, \dots, f_m\} \subseteq R = K[x_1, \dots, x_n]$ ,  $I = (\mathcal{F})$

## Definition

The **affine variety** associated to  $I$  is

$$V(I) = \{P = (x_1, \dots, x_n) \in K^n \mid f_1(P) = \dots = f_m(P) = 0\} \subseteq K^n.$$

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Affine varieties in  $K^n$  are the closed sets of the **Zarisky topology** on  $K^n$ .

If  $K = \mathbb{F}_q$ , then the Zarisky topology is the discrete topology.

If  $K$  is infinite, then any  $\emptyset \neq U \subseteq K^n$  open is dense, i.e.  $\overline{U} = K^n$ .

# GENERICITY

## Definition

A property is **generic** if it holds on a nonempty Zarisky-open set.

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Over a finite field this is meaningless, but over an infinite field this means that the property holds “almost everywhere”. However, when one can describe the open set via the equations of its complement, then one can check whether any given point belongs to the open set.

## Example

Genericity conditions for the statement on the complexity of MinRank:

- the homogenization of the minors of  $M$  are the minors of the matrix obtained from  $M$  by homogenizing its entries,
- the zero locus of the minors has codimension  $(m - r)(k - r)$ .

# IDEALS IN GENERIC COORDINATES

$K = \overline{K}$ ,  $S = K[x_0, \dots, x_n]$ ,  $J \subseteq S$  homogeneous

$G = \text{GL}_{n+1}(K)$  acts on  $S$  as changes of coordinates

## Theorem (Galligo)

*There is a nonempty open  $U \subseteq G \subseteq K^{(n+1)^2}$  s.t.  $\text{in}(gJ) = \text{in}(hJ)$  for  $g, h \in U$ .*

## Definition

$\text{gin}(J) := \text{in}(gJ)$  for  $g \in U$  is the **generic initial ideal** of  $J$  wrt the chosen term order.

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## Theorem (Bayer, Stillman)

Fix the degree reverse lexicographic order, then

$$\text{reg}(J) = \text{reg}(\text{gin}(J)).$$

Hence, if  $J$  is in generic coordinates, then

$$\text{reg}(J) = \text{reg}(\text{in}(J)).$$

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I do not know of any deterministic algorithm that does that.



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### Theorem (Caminata, G.)

$\mathcal{F} \subseteq \mathbb{F}_q[x_1, \dots, x_n]$ . Assume that

$$x_1^q - x_1, \dots, x_n^q - x_n \in \mathcal{F} \quad \text{or} \quad x_1^q - x_2, \dots, x_{n-1}^q - x_n, x_n^q - x_1 \in \mathcal{F}.$$

Then  $(\mathcal{F}^h)$  is in generic coordinates.

### Corollary (Macaulay Bound)

$\mathcal{F} = \{f_1, \dots, f_m\} \subseteq R = \mathbb{F}_q[x_1, \dots, x_n]$ ,  $\deg(f_i) = d_i$ ,  $d_1 \geq \dots \geq d_m$ ,  $m \geq n + 1$ . Assume that  $(\mathcal{F}^h)$  is in generic coordinates, or that  $\mathcal{F}$  contains the field equations. Then

$$\text{solv. deg}(\mathcal{F}) \leq d_1 + \dots + d_{n+1} - n.$$

## SUMMARY

- polynomial systems arise in many models from engineering and the sciences
- they can be solved over finite fields by computing a Gröbner basis
- the complexity of linear algebra algorithms for computing Gröbner bases is upper bounded by a function of the solving degree, which is the least degree for which Gaussian elimination in the Macaulay matrix yields a Gröbner basis
- the Castelnuovo-Mumford regularity of the homogenization of a system is an upper bound for its solving degree
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Thank you for your attention!