

Nonparametric Bayesian inference for Hawkes processes

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Joint work with

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Oxford University



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Oxford University



Intensity of a point process

Definition (Point process)

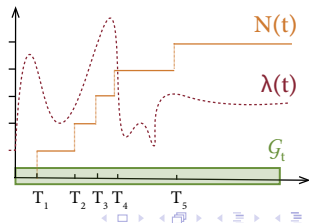
A **point process** $N = (N_t)_t$ is a random countable set of points of \mathbb{R} or equivalently a non-decreasing integer-valued process.

Definition (Intensity of a point process)

The **intensity** λ_t of N represents the probability to observe a point at the time t conditionally on the past before t :

$$\lambda_t dt = \mathbb{P}(N \text{ has a jump} \in [t, t + dt] \text{ conditionally on the past before } t)$$

Example: **Poisson processes** correspond to the case where $(\lambda_t)_t$ is not random. And the Poisson process is **homogeneous** if, in addition, λ_t does not depend on t .



Univariate Hawkes processes

$\lambda_t dt = \mathbb{P}(N \text{ has a jump } \in [t, t + dt] \text{ conditionally on the past before } t)$

Definition (univariate Hawkes process)

Let $\Phi : \mathbb{R} \mapsto \mathbb{R}_+$ and $h : \mathbb{R}_+ \mapsto \mathbb{R}$ such that $\|h\|_1 < 1$. Then any point process N whose intensity is

$$\lambda_t = \Phi \left(\int_{-\infty}^{t-} h(t-u) dN_u \right) = \Phi \left(\sum_{T \in N, T < t} h(t-T) \right)$$

is called a **univariate Hawkes process**.

See [Hawkes \(1971\)](#), [Hawkes and Oakes \(1974\)](#), [Brémaud and Massoulié \(1996, 2001\)](#).

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Definition (linear univariate Hawkes process)

If $\Phi(x) = x + \nu$ with $\nu > 0$ and $h \geq 0$, the Hawkes process is **linear**:

$$\lambda_t = \nu + \int_{-\infty}^{t-} h(t-u) dN_u = \nu + \sum_{T \in N, T < t} h(t-T)$$

with ν called the **spontaneous rate** and h the **self-exciting function**.

The study of linear Hawkes processes is much easier thanks to the **cluster representation**

Cluster representation for linear Hawkes processes

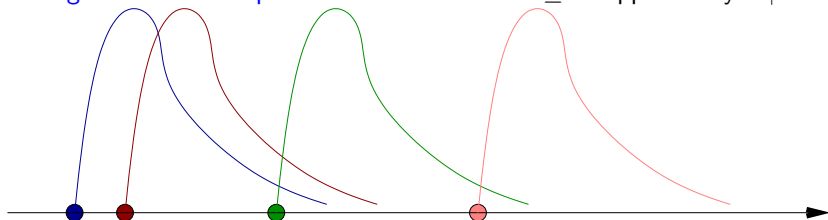
A univariate linear Hawkes process can be viewed as a branching process over an homogeneous Poisson process. Let $\nu > 0$ and $h \geq 0$ supported by \mathbb{R}_+ .



- Ancestors: Realizations of a Poisson Process with $\lambda_t = \nu$

Cluster representation for linear Hawkes processes

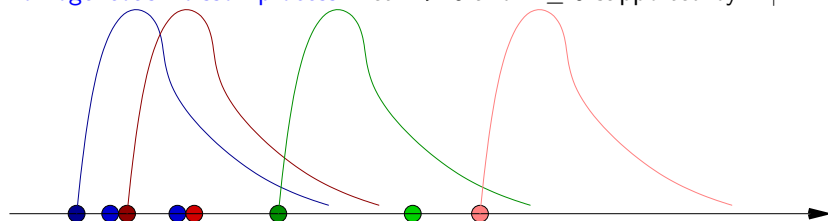
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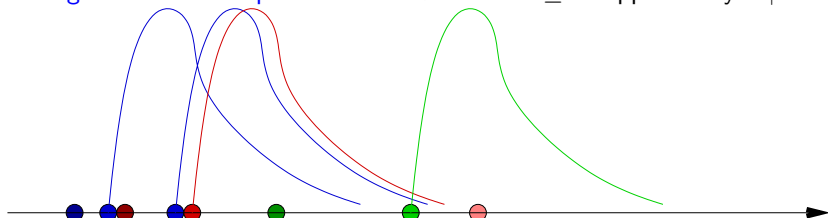
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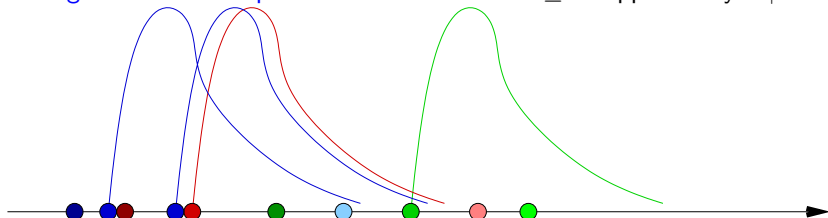
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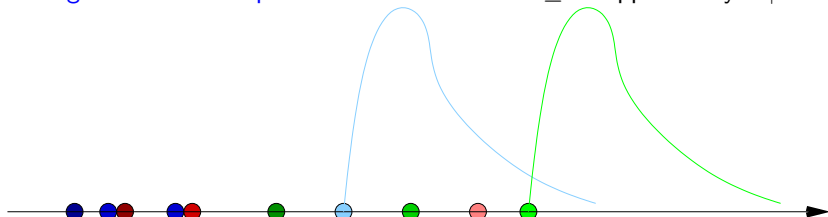
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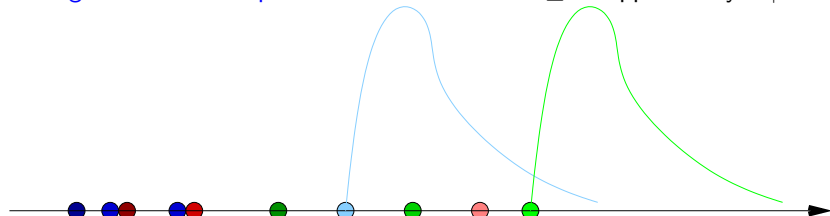
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Cluster representation for linear Hawkes processes

A **univariate linear Hawkes process** can be viewed as a **branching process over an homogeneous Poisson process**. Let $\nu > 0$ and $h \geq 0$ supported by \mathbb{R}_+ .



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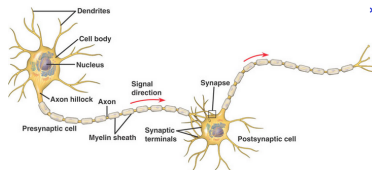
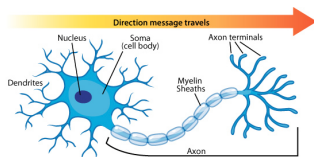
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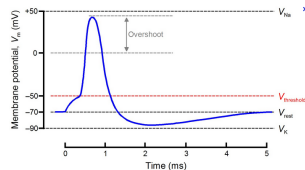
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- Extinction if $\int_0^{+\infty} h(t)dt < 1$
- Hawkes process = all the points where colors are not distinguished
- See [Hawkes and Oakes \(1974\)](#)

Multivariate Hawkes process: Neurobiological motivations

A **neuron** is an electrically **excitable** cell that processes and transmits information through electrical signals



If upstream signal is strong enough, this cell produces an **action potential** (also called spike), which is a **spiky** (electric) signal. Then, this signal is propagated to downstream neurons.



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Action potentials can be recorded and **the excitations times can be seen as a point process**, each point corresponding to the peak of one action potential of this neuron.

Goal: Using the recorded activity of K neurons, we wish to **infer the graph** between them. For this purpose, we use models based on **multivariate Hawkes processes**.

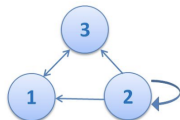
Multivariate Hawkes processes

- We naturally modify the intensity of a univariate Hawkes process given by

$$\lambda_t = \Phi\left(\nu + \int_{-\infty}^{t-} h(t-u) dN_u\right) = \Phi\left(\nu + \sum_{T \in N, T < t} h(t-T)\right),$$

to model interactions between K neurons: For a given neuron $k \in \llbracket 1; K \rrbracket$, we model its activity by a **point process** $N^{(k)}$ whose intensity is

$$\begin{aligned}\lambda_t^{(k)} &= \Phi_k\left(\nu_k + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{\ell k}(t-u) dN^{(\ell)}(u)\right) \\ &= \Phi_k\left(\nu_k + \sum_{\ell=1}^K \sum_{T_\ell \in N^{(\ell)}, T_\ell < t} h_{\ell k}(t-T_\ell)\right)\end{aligned}$$



- We obtain **mutually exciting and inhibiting processes**:

$\nu_k > 0$: **background rates**

$h_{\ell k}$: **interaction functions**

- If $h_{\ell k} \geq 0$: excitation
- If $h_{\ell k} \leq 0$: inhibition
- If $h_{\ell k}$ is signed: excitation and inhibition

Φ_k : **link function**. Typical examples:

- Ex (linear): $\Phi_k(x) = x$ [requires $h_{\ell k} \geq 0$]
- Ex (nonlinear): $\Phi_k(x) = \max(x, 0)$
- Ex (nonlinear): $\Phi_k(x) = \exp(x)$

Multivariate Hawkes processes

Definition

A K -dimensional continuous time process $N = (N_t)_t = (N_t^{(1)}, \dots, N_t^{(K)})_t$ is a multivariate nonlinear Hawkes process if

- (i) almost surely, for $k \neq \ell$, $(N_t^{(k)})_t$ and $(N_t^{(\ell)})_t$ never jump simultaneously
- (ii) for all k , the intensity of $(N_t^{(k)})_t$ is given by

$$\lambda_t^{(k)} = \Phi_k \left(\nu_k + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{\ell k}(t-u) dN^{(\ell)}(u) \right).$$

Theorem (Brémaud and Massoulié (1996))

Existence and uniqueness of a stationary distribution for N :

- if $\forall k \in \llbracket 1; K \rrbracket \|\Phi_k\|_{\infty} < \infty$ or
- if $\forall k \in \llbracket 1; K \rrbracket \Phi_k$ is 1-Lipschitz and the matrix Γ with entries $\Gamma_{\ell k} = \|h_{\ell k}\|_1$ has a spectral radius $\rho(\Gamma) < 1$.

Applications of Hawkes processes

Hawkes processes are useful to model many situations where **excitation or inhibition phenomena** play a crucial role.

- to model earthquakes: Ozaki (1979), Ogata and Akaike (1982), Vere-Jones and Ozaki (1982) and Zhuang, Ogata and Vere-Jones (2002)
- to **neuroscience**: Chornoboy, Schramm and Karr (1988) combined **Hawkes processes with maximum likelihood** in the parametric setting.
- to genome analysis: Gusto and Schbath (2005), Carstensen, Sandelin, Winther and Hansen (2010) and Reynaud-Bouret and Schbath (2010)
- to financial data: Embrechts, Liniger and Lin (2011), Bacry and Muzy (2013, 2014) and Bacry, Delattre, Hoffmann and Muzy (2012)
- to study diffusion across social networks: Crane and Sornette (2008) and Yang and Zha (2013)
- to analyze and predict the diffusion of COVID-19: Mengersen, Paraha, R, Rousseau and Sulem (2020)
- etc.

State of the art in the nonparametric setting

- **Nonparametric inference** for multivariate Hawkes processes:

$$\lambda_t^{(k)} = \Phi_k \left(\nu_k^* + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{\ell k}^*(t-u) dN^{(\ell)}(u) \right).$$

Statistical Goal: **Estimation of $f^* = (\nu_k^*, (h_{\ell k}^*)_{\ell \in \llbracket 1; K \rrbracket})_{k \in \llbracket 1; K \rrbracket}$** based on observations of $N = (N^{(k)})_{k \in \llbracket 1; K \rrbracket}$ on $[0, T]$ with intensity process $(\lambda^{(k)})_{k \in \llbracket 1; K \rrbracket}$.

- **Linear case:** $\Phi_k(x) = x$
 - Lasso-type estimation: **Hansen, Reynaud-Bouret and R (2015)** extended by **Chen, Witten and Shojaie (2017)**. See also **Bacry, Bompairé, Gaïffas and Muzy (2020)**
 - Bayesian estimation: **Donnet, R and Rousseau (2020)**
- **Nonlinear case:**
 - **Chen, Shojaie, Shea-Brown and Witten (2019)** derived bounds on the weak dependence coefficient for the Hawkes process using the coupling technique of **Dedecker and Prieur (2014)**, providing an asymptotic analysis of **second order statistics** (cross-covariance)
 - **Estimation of f^* in full generality** remains an open question (to the best of our knowledge)

Our contributions

Inference for nonlinear Hawkes models

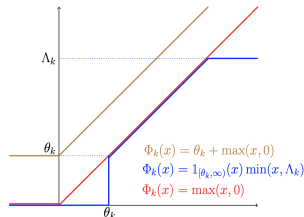
- We now consider

$$\lambda_t^{(k)} = \Phi_k \left(\nu_k^* + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{\ell k}^*(t-u) dN^{(\ell)}(u) \right)$$

with in mind 3 examples:

- Model 1: $\Phi_k(x) = \theta_k + \max(x, 0)$
- Model 2: $\Phi_k(x) = 1_{[\theta_k, \infty)}(x) \min(x, \Lambda_k)$
- Model 3: $\Phi_k(x) = \max(x, 0)$

with $0 < \theta_k < \Lambda_k$



Inference for nonlinear Hawkes models

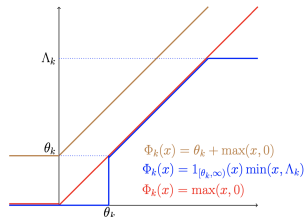
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- Statistical Goals:

1. Estimation of $f^* = (\nu_k^*, (h_{\ell k}^*)_{\ell \in \llbracket 1; K \rrbracket})_{k \in \llbracket 1; K \rrbracket}$ based on observations of $N = (N^{(k)})_{k \in \llbracket 1; K \rrbracket}$ on $[0, T]$ (with in mind $T \rightarrow +\infty$). The Φ_k 's are known
2. The θ_k 's are unknown. With $\theta = (\theta_k)_{k \in \llbracket 1; K \rrbracket}$, Estimation of (f^*, θ) . The Λ_k 's are known
3. We consider the Bayesian approach

- Assumptions:

1. The $h_{\ell k}^*$'s are bounded and have support $[0, A]$, with $A < \infty$ known
2. The matrix Γ^* with entries $\Gamma_{\ell k}^* = \|h_{\ell k}^*\|_1$ has a spectral norm < 1 . This implies existence and uniqueness of a stationary distribution

Identifiability

- Remember

$$\lambda_t^{(k)} = \Phi_k \left(\nu_k^* + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{\ell k}^*(t-u) dN^{(\ell)}(u) \right)$$

with 3 possible models:

- Model 1: $\Phi_k(x) = \theta_k + \max(x, 0)$
- Model 2: $\Phi_k(x) = 1_{[\theta_k, \infty)}(x) \min(x, \Lambda_k)$
- Model 3: $\Phi_k(x) = \max(x, 0)$

We set $f^* = (\nu_k^*, (h_{\ell k}^*)_{\ell \in \llbracket 1; K \rrbracket})_{k \in \llbracket 1; K \rrbracket}$ and $\theta = (\theta_k)_{k \in \llbracket 1; K \rrbracket}$

- Identifiability:

- Models 1, 2 and 3: Estimation of f^* : we need $\forall (k, \ell) \in \llbracket 1; K \rrbracket$

$$\|(h_{\ell k}^*)^-\|_{\infty} < \begin{cases} \nu_k^* & \text{(Models 1 and 3)} \\ \nu_k^* - \theta_k & \text{(Model 2)} \end{cases}$$

- Models 1 and 2: Estimation of (f^*, θ) : We also need: $\forall k \exists \ell, (h_{\ell k}^*)^-(0) = 0$ and $(h_{\ell k}^*)^-$ is continuous and increasing on $[0, v_0)$ for some $v_0 > 0$

The Bayesian statistical approach

- The **log-likelihood function of the process** observed on the interval $[0, T]$ is

$$\mathcal{L}_T(f) := \sum_{k=1}^K \left[\int_0^T \log(\lambda_t^{(k)}(f)) dN_t^{(m)} - \int_0^T \lambda_t^{(k)}(f) dt \right],$$

where $\lambda_t^{(k)}(f)$ is the intensity associated with $f = (\nu_k, (h_{\ell k})_{\ell \in \llbracket 1; K \rrbracket})_{k \in \llbracket 1; K \rrbracket}$

- We fix a prior Π on the **set** \mathcal{F}^1 of parameters f such that (for Models 1 and 3)
 - the $h_{\ell k}$'s are bounded and are supported by $[0, A]$
 - the matrix with entries $\|h_{\ell k}\|_1$ has a spectral radius < 1
 - $\forall (k, \ell) \in \llbracket 1; K \rrbracket, \|(h_{\ell k})^-\|_\infty < \nu_k$
- We study the **posterior distribution** $\Pi(\cdot|N)$, with for any $B \subset \mathcal{F}$,

$$\Pi(B|N) = \frac{\int_B \exp(\mathcal{L}_T(f)) d\Pi(f)}{\int_{\mathcal{F}} \exp(\mathcal{L}_T(f)) d\Pi(f)}.$$

For a distance d , we derive **concentration rates**: for $\epsilon_T \rightarrow 0$, when $T \rightarrow +\infty$,

$$\mathbb{E}_{f^*} [\Pi(d(f^*, f) > \epsilon_T | N)] = o(1).$$

From the posterior distribution, we can build **estimates**, **credible sets**, etc.

¹modified in a natural way for Model 2 and for estimating (f^*, θ)

Posterior concentration rates for estimating f^*

- For a distance d , **posterior concentration** means that for $\epsilon_T \rightarrow 0$, when $T \rightarrow +\infty$,

$$\mathbb{E}_{f^*} [\Pi(d(f, f^*) > \epsilon_T | N)] = o(1).$$

We study posterior concentration rates for d the **classical \mathbb{L}_1 -distance**:

$$d(f, f^*) := \|f - f^*\|_1 := \sum_{k=1}^K |\nu_k - \nu_k^*| + \sum_{k=1}^K \sum_{\ell=1}^K \|h_{\ell k} - h_{\ell k}^*\|_1$$

- We apply the standard **Ghosal Ghosh and van der Vaart approach** and write

$$\Pi(B|N) = \frac{\int_B \exp(\mathcal{L}_T(f)) d\Pi(f)}{\int_{\mathcal{F}} \exp(\mathcal{L}_T(f)) d\Pi(f)} = \frac{\int_B \exp(\mathcal{L}_T(f) - \mathcal{L}_T(f^*)) d\Pi(f)}{\int_{\mathcal{F}} \exp(\mathcal{L}_T(f) - \mathcal{L}_T(f^*)) d\Pi(f)} =: \frac{N_T}{D_T}.$$

- We deal with the numerator by using **\mathbb{L}_1 -tests**, so we need convenient concentration inequalities
- We deal with the denominator by controlling the **Kullback-loss** on

$$B(\epsilon_T, R) := \{f = (\nu_k, (h_{\ell k})_{\ell})_k \in \mathcal{F} : |\nu_k - \nu_k^*| \leq \epsilon_T, \|h_{\ell k} - h_{\ell k}^*\|_{\infty} \leq \epsilon_T, \|h_{\ell k}\|_{\infty} \leq R \forall \ell, k\}$$

Posterior concentration rates for estimating f^*

Theorem

Assume

$$\limsup_{T \rightarrow +\infty} \frac{1}{T} \mathbb{E}_{f^*} \left[\int_0^T \frac{1_{\{\lambda_t^{(k)}(f^*) > 0\}}}{\lambda_t^{(k)}(f^*)} dt \right] < +\infty, \quad \forall k \in \llbracket 1; K \rrbracket.$$

Let Π be a prior distribution and $\epsilon_T \rightarrow 0$ such that

$$\log^3(T) = O(T\epsilon_T^2).$$

(i) There exists $R > 0$ such that

$$\Pi(B(\epsilon_T, R)) \geq e^{-\square T \epsilon_T^2}$$

(ii) There exists a subset $\mathcal{F}_T \subset \mathcal{F}$, such that

$$\frac{\Pi(\mathcal{F}_T^c)}{\Pi(B(\epsilon_T, R))} \leq e^{-\square T \epsilon_T^2}$$

(iii) The metric entropy of the space \mathcal{F}_T for the \mathbb{L}_1 -norm satisfies

$$\log \mathcal{N}(\epsilon_T, \mathcal{F}_T, \|\cdot\|_1) \leq \square T \epsilon_T^2$$

Then, for C a constant large enough,

$$\mathbb{E}_{f^*} [\Pi(\|f - f^*\|_1 > C\epsilon_T | N)] = o(1).$$

Discussion - Rates for Bayesian estimators

Remember:

$$\lambda_t^{(k)} = \Phi_k \left(\nu_k^* + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{\ell k}^*(t-u) dN^{(\ell)}(u) \right)$$

- Model 1: $\Phi_k(x) = \theta_k + \max(x, 0)$
- Model 2: $\Phi_k(x) = 1_{[\theta_k, \infty)}(x) \min(x, \Lambda_k)$
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So, the previous condition

$$\limsup_{T \rightarrow +\infty} \frac{1}{T} \mathbb{E}_{f^*} \left[\int_0^T \frac{1_{\{\lambda_t^{(k)}(f^*) > 0\}}}{\lambda_t^{(k)}(f^*)} dt \right] < +\infty, \quad \forall k \in \llbracket 1; K \rrbracket$$

is satisfied for Models 1 and 2. For Model 3, it is satisfied if for instance for any ℓ $h_{\ell k}^*$ is an histogram and for all t , $h_{\ell k}^*(t) \in \mathbb{Q}$.

Corollary

We assume conditions of the previous theorem are satisfied. If

$$\int \|f\|_1 d\Pi(f) < +\infty,$$

then the **posterior mean** $\hat{f} = \mathbb{E}^\pi[f|N]$ is converging to f^* at the rate ϵ_T : for C a constant large enough

$$\mathbb{P}_{f^*} \left(\|\hat{f} - f^*\|_1 > C\epsilon_T \right) = o(1).$$

Posterior rates for estimating (f^*, θ^*) - Prior models

- We consider (change notations $\theta_k \rightarrow \theta_k^*$):
 - Model 1: $\Phi_k(x) = \theta_k^* + \max(x, 0)$
 - Model 2: $\Phi_k(x) = 1_{[\theta_k^*, \infty)}(x) \min(x, \Lambda_k)$
 We estimate $\theta^* = (\theta_k^*)_{k \in \llbracket K \rrbracket}$
- Adapting naturally the setting to the problem of estimating (f^*, θ^*) , we obtain:

$$\mathbb{E}_{f^*} [\Pi(\|\theta - \theta^*\|_1 + \|f - f^*\|_1 > C\epsilon_T | N)] = o(1) \quad (\text{Model 1})$$

$$\mathbb{E}_{f^*} [\Pi(\|\theta - \theta^*\|_1 > C\sqrt{\epsilon_T} | N) + \Pi(\|f - f^*\|_1 > C\epsilon_T | N)] = o(1) \quad (\text{Model 2})$$
- We also derive a Bayesian estimate $\hat{\theta}$ such that under mild assumptions

$$\mathbb{P}_{f^*} (\|\hat{\theta} - \theta^*\|_1 > C\epsilon_T) = o(1) \quad (\text{Model 1})$$

$$\mathbb{P}_{f^*} (\|\hat{\theta} - \theta^*\|_1 > C\sqrt{\epsilon_T}) = o(1) \quad (\text{Model 2})$$

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- Posterior concentration rates are obtained for random histogram priors based on random partitions. And on Hölder classes $\mathcal{H}(\beta, L)$, with $\beta \leq 1$, we obtain the posterior concentration rate

$$\epsilon_T = (\log T)^{\frac{3\beta}{2\beta+1}} T^{-\frac{\beta}{2\beta+1}}$$

Difficulties and technical tools

- Since $\mathbb{P}(dN^{(k)}t = 1 | \text{past before } t) = \lambda_t^{(k)}(f^*)$, the **first step** consists in obtaining rates for the stochastic loss defined through intensities:

$$d_{1,T}(f, f^*) := \frac{1}{T} \sum_{k=1}^K \int_0^T |\lambda_t^{(k)}(f) - \lambda_t^{(k)}(f^*)| dt$$

by using

1. new **Bernstein-type concentration inequalities** for martingales
 2. an **ergodic theorem** (**Reynaud-Bouret and Roy (2003)**)
 3. a sharp control of the **number of points falling in intervals**
- For points 2 and 3, the cluster representation is the main tool. In particular:
Lemma: Assume $\|\Gamma\| < 1$ and consider ζ such that $0 \leq \zeta \leq \frac{1 - \|\Gamma\|}{2\sqrt{M}} \log\left(\frac{1 + \|\Gamma\|}{2\|\Gamma\|}\right)$. Then, for any ancestor of type ℓ , if W^ℓ the number of points in its cluster,

$$\mathbb{E}[\exp(\zeta W^\ell)] \leq \frac{1 + \|\Gamma\|}{2\|\Gamma\|}.$$

- **Crucial assumption:** $\Phi_k(x) = x$ and the $h_{\ell k}$'s non negative
- See **Hansen, Reynaud-Bouret and R (2015)**

Difficulties and technical tools

- **Second step:** To move from rates on intensities to rates on parameters: based on controls (with large probability) of **the stochastic distance** by **the deterministic one**:

$$\lambda_t^{(k)}(f_1) := \nu_{1k} + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{1\ell k}(t-u) dN^{(\ell)}(u) \quad \lambda_t^{(k)}(f_2) := \nu_{2k} + \sum_{\ell=1}^K \int_{-\infty}^{t-} h_{2\ell k}(t-u) dN^{(\ell)}(u)$$

$$d_{1,T}(f_1, f_2) := \frac{1}{T} \sum_{k=1}^K \int_0^T |\lambda_t^{(k)}(f_1) - \lambda_t^{(k)}(f_2)| dt \lesssim \|f_1 - f_2\|_1 := \sum_{k=1}^K |\nu_{1k} - \nu_{2k}| + \sum_{k=1}^K \sum_{\ell=1}^K \|g_{1\ell k} - g_{2\ell k}\|_1$$

With $J_T \rightarrow +\infty$ well chosen (in particular $J_T = o(T)$) and

$$Z_{k,m} := \int_{\frac{2mT}{2J_T}}^{\frac{(2m+1)T}{2J_T}} |\lambda_t^{(k)}(f_1) - \lambda_t^{(k)}(f_2)| dt = \int_{\frac{2mT}{2J_T}}^{\frac{(2m+1)T}{2J_T}} \left| \nu_{1k} - \nu_{2k} + \sum_{\ell=1}^M \int_{t-A}^{t-} (g_{1\ell k} - g_{2\ell k})(t-s) dN_s^{(k)} \right| dt$$

The $Z_{k,m}$'s only depend on points of the process of the interval $\mathcal{I}_{m,T} := \left[\frac{2mT}{2J_T} - A; \frac{(2m+1)T}{2J_T} \right]$, so they are "almost independent" (**cluster representation**), since $\max(\mathcal{I}_{m,T}) \ll \min(\mathcal{I}_{m+1,T})$

$$\begin{aligned} T d_{1,T}(f, f^*) &\geq \max_{1 \leq k \leq K} \left\{ \sum_{m=1}^{J_T-1} \mathbb{E}[Z_{k,m}] + \sum_{m=1}^{J_T-1} [Z_{k,m} - \mathbb{E}[Z_{k,m}]] \right\} \\ &\gtrsim T \|f_1 - f_2\|_1 + \max_{1 \leq k \leq K} \left\{ \sum_{m=1}^{J_T-1} [\tilde{Z}_{k,m} - \mathbb{E}[\tilde{Z}_{k,m}]] \right\} \gtrsim T \|f_1 - f_2\|_1 \end{aligned}$$

- Crucial assumption: $\Phi_k(x) = x$ and the $h_{\ell k}$'s non negative
- See **Donnet, R and Rousseau (2020)**

New probabilistic tools

- We cannot rely on the cluster representation anymore, which allows the Hawkes process N to be represented as a sum of independent processes,
- But [Costa, Graham, Marsalle and Tran \(2018\)](#) have studied Hawkes processes with signed reproduction functions by using renewal techniques: By setting

$$X_t := N|_{(t-A, t]}$$

and the [regeneration times](#)

$$\tau_j = \begin{cases} 0 & \text{if } j = 0 \\ \inf\{t \in (\tau_{j-1}, T] : X_{t-} \neq \emptyset, X_t = \emptyset\} & \text{if } j \geq 1 \end{cases},$$

we have:

- 1 the point measure $(X_t)_t$ is a strong Markov process with positive recurrent state the null measure
- 2 almost surely, the variables $(\tau_j)_j$ are finite stopping times for N
- 3 if we set, $\tau_{J_T+1} = T$, the intervals $((\tau_j, \tau_{j+1}])_{j=0, \dots, J_T}$ form a partition of $(0, T]$.
- 4 the random measures $(N|_{[\tau_j, \tau_{j+1}]})_{j \geq 1}$ are i.i.d. (called [excursion](#))
- 5 Moments properties: for some $\alpha > 0$,

$$\mathbb{E} \left[e^{\alpha(\tau_2 - \tau_1)} \right] < \infty$$

- 6 An ergodic theorem and exponential concentration inequalities were established

**Thank you for your attention.
Questions and remarks are welcomed!**

Reference:

SULEM D., RIVOIRARD V. AND ROUSSEAU J. (2020) *Bayesian estimation of nonlinear Hawkes processes*. In preparation