

Recent advances on algorithms for geodetic sets

D. C.

Joint work with

Sandip Das, Florent Foucaud, Harmendar Gahlawat, Dimitri Lajou, Bodhayan Roy

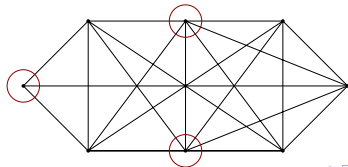
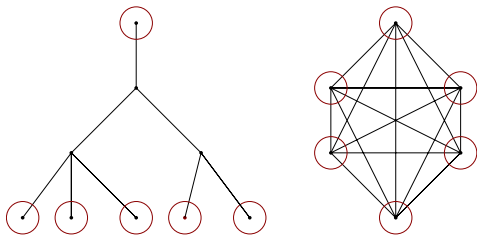
Metric Graph Theory

December 9, 2021

Definition

A set S of vertices is a *geodetic set* if any vertex $v \in V(G)$ lies in some $I(x, y)$ where $\{x, y\} \subseteq S$.

MINIMUM GEODETIC SET (MGS) is to find decide whether a graph G has a geodetic set of size at most k ?



Timeline of algorithmic results

Introduced by
(Harary *et al.*)



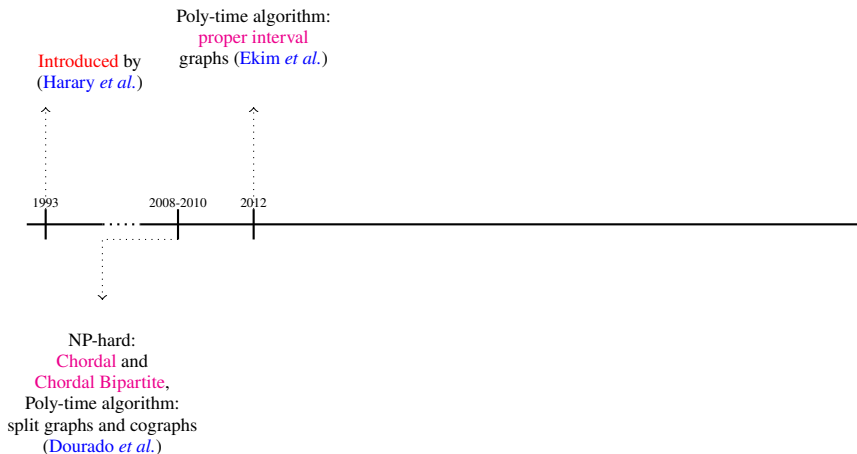
Timeline of algorithmic results

Introduced by
(Harary *et al.*)

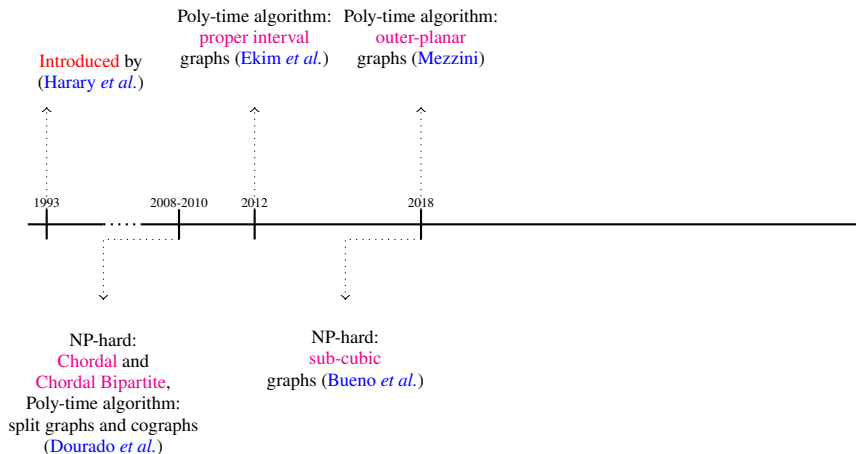


NP-hard:
Chordal and
Chordal Bipartite,
Poly-time algorithm:
split graphs and cographs
(Dourado *et al.*)

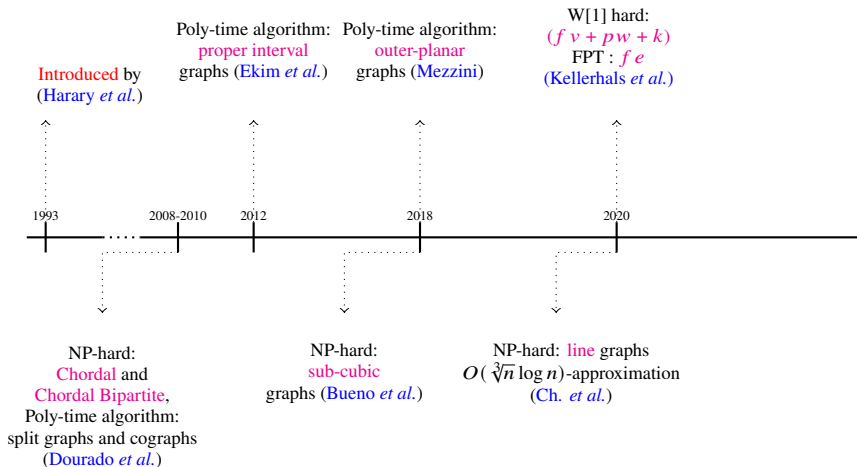
Timeline of algorithmic results



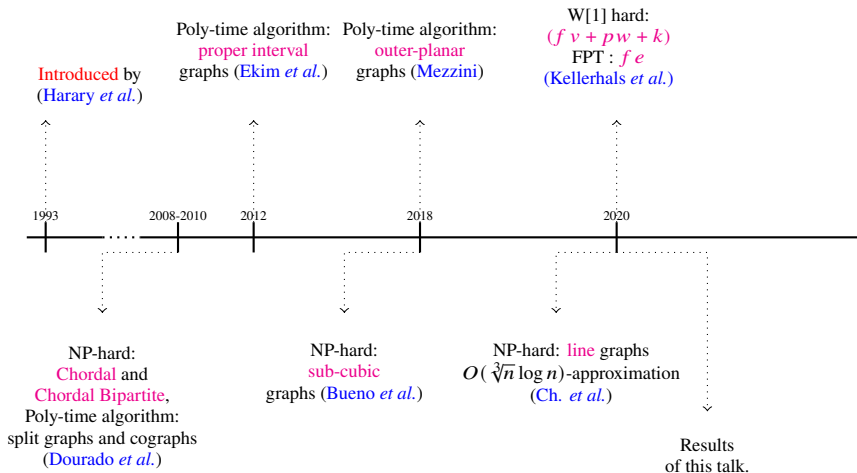
Timeline of algorithmic results



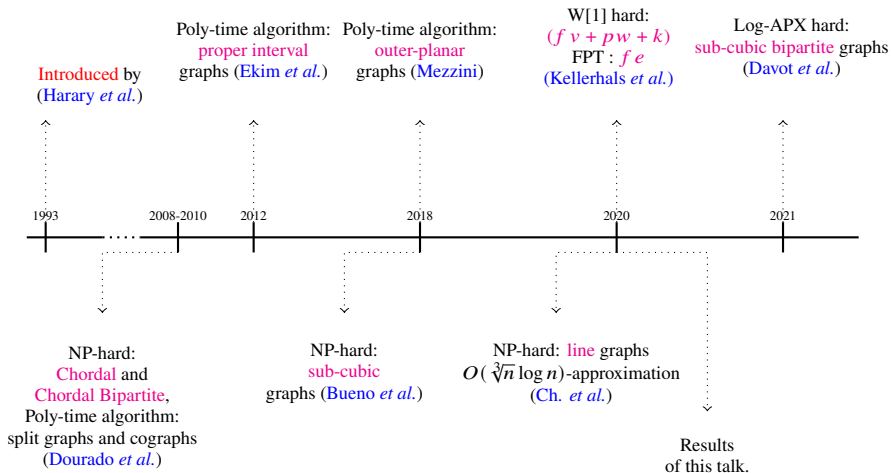
Timeline of algorithmic results



Timeline of algorithmic results



Timeline of algorithmic results



Results

Theorem

There is a *linear time* algorithm for MGS on *solid grids*.

Theorem

MGS is NP-hard on *sub-cubic patial grids*.

Theorem

MGS is NP-hard on *interval graphs* with no induced $K_{1,5}$.

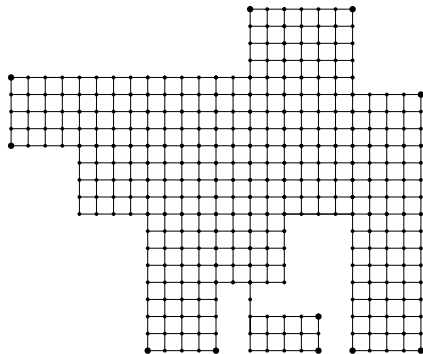
Theorem

MGS can be solved in time $O(2^{2^\omega} n^{O(1)})$ for *chordal graphs* and in time $O(2^\omega n^{O(1)})$ for *interval graphs*, where n and ω are the order and clique number of the input graph, respectively.

Solid grids

Theorem

There is a *linear time* algorithm for MGS on *solid grids*.

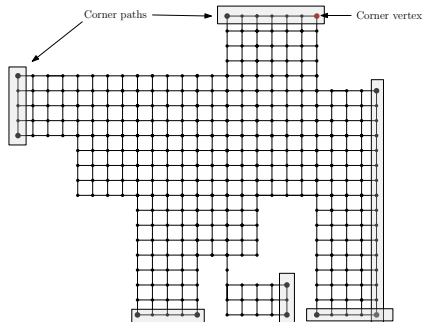


A graph is a *solid grid* if it has a grid embedding such that all interior faces have unit area.

Solid grids (Proof sketch)

A path P of G is a *corner path* if

- (i) no vertex of P is a cut-vertex,
- (ii) both end-vertices of P have degree 2, and
- (iii) all other vertices of P have degree 3.



Lemma

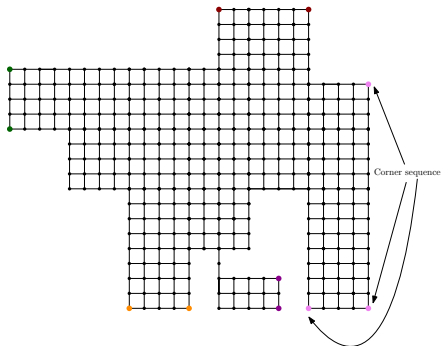
Any geodetic set contains at least one vertex from each corner path.

Solid grids (Proof sketch)

Definition

We say that u_1, u_2, \dots, u_k forms a *corner sequence* if for each $1 \leq i \leq k - 1$,

1. there is a corner path with u_i and u_{i+1} as endpoints, and
2. there is no corner vertex in the clockwise traversal of the boundary of the grid embedding from u_i to u_{i+1} .



Solid grids (Proof sketch)

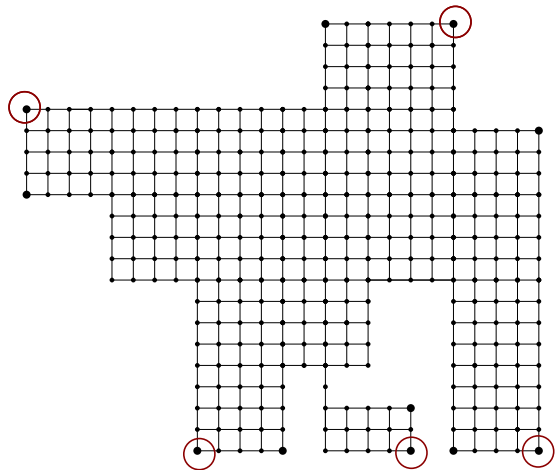
Lemma

Let \mathcal{S} be the set of all maximal corner sequences of a solid grid G , and let t be the number of vertices of G with degree 1. Then, $gn(G) \geq t + \sum_{S \in \mathcal{S}} \lfloor |S|/2 \rfloor$.

Algorithm:

- Choose all vertices with degree 1,
- Traverse the embedding in the clockwise direction, and for each maximal corner sequence, choose vertices alternatively.

Solid grids (Proof sketch)



Lemma

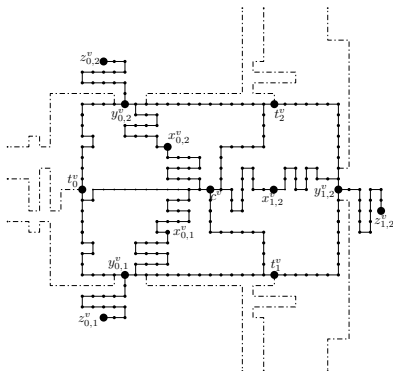
The set of vertices chosen by the above algorithm is a geodetic set.

Partial grids

Theorem

MGS is NP-hard on sub-cubic partial grids.

Reduce from **MINIMUM VERTEX COVER** on cubic planar graphs.



Interval graphs

Theorem

MGS is NP-hard on *interval graphs* with no induced $K_{1,5}$.

Reduce from 3-SAT.

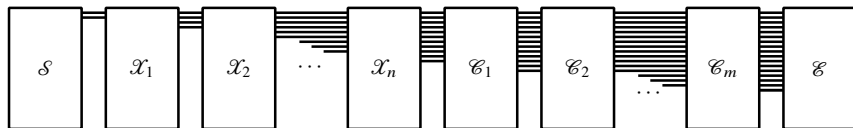


Figure: Overview of the construction. Each box represents one of the main gadget. Lines between such gadgets represent the tracks.

Corollary

Assuming ETH, there is no $(2^{o(\sqrt{n})})$ -time algorithm for MGS on *interval graphs* of order n .

Chordal graphs

Theorem

MGS can be solved in time $O(2^{2^\omega} n^{O(1)})$ for chordal graphs and in time $O(2^\omega n^{O(1)})$ for interval graphs, where n and ω are the order and clique number of the input graph, respectively.

- Dynamic programming on the nice tree decomposition T of a chordal graph G .
- Width of T is ω .
- Each *bag* or *node* of T is a clique cut-set.

Chordal graphs (Proof sketch)

- With each bag X_v of T , associate $O(2^{2^\omega})$ many “types of partial solutions”.

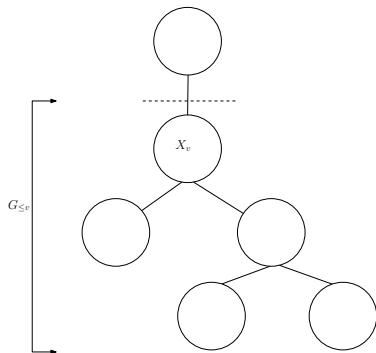
Chordal graphs (Proof sketch)

- With each bag X_v of T , associate $O(2^{2^\omega})$ many “types of partial solutions”.
- A “type of partial solution” τ for a node X_v is a 4-tuple $(\tau^{ext}, \tau^{int}, \tau^{cov}, \tau^{bag})$ where
 - τ^{ext} and τ^{int} are collections of subsets of X_v ,
 - τ^{cov}, τ^{bag} are subsets of X_v

Chordal graphs (Proof sketch)

- With each bag X_v of T , associate $O(2^{2^\omega})$ many “types of partial solutions”.
- A “type of partial solution” τ for a node X_v is a 4-tuple $(\tau^{ext}, \tau^{int}, \tau^{cov}, \tau^{bag})$ where
 - τ^{ext} and τ^{int} are collections of subsets of X_v ,
 - τ^{cov}, τ^{bag} are subsets of X_v

D is a solution of type $\tau = (\tau^{ext}, \tau^{int}, \tau^{cov}, \tau^{bag}, \dots)$ if



Summary

Theorem

There is a *linear time* algorithm for MGS on *solid grids*.

Theorem

MGS is NP-hard on *sub-cubic patial grids*.

Theorem

MGS is NP-hard on *interval graphs* with no induced $K_{1,5}$.

Theorem

MGS can be solved in time $O(2^{2^\omega} n^{O(1)})$ for *chordal graphs* and in time $O(2^\omega n^{O(1)})$ for *interval graphs*, where n and ω are the order and clique number of the input graph, respectively.

Open problems

- Polynomial time algorithm for Series-parallel graphs.
- Improve the running time for Chordal graphs.
- Constant factor approximation for planar graphs, interval graphs.