



Revisiting the training of RBMs

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Introduction : generative approach



• Variational AutoEncoder (VAE)

Introduction : generative approach





Energy based models (EBMs)



• Learning : adjust the parameters so that the dataset configurations are typical configurations of the model.

$$L = \prod_{m=1}^{m} p\left(v^{(m)}\right)$$

Gradient ascent

 $\nabla_{\theta}L$

• Problem $Z = \sum_{m{v}, m{h}} p(m{v}, m{h})$ Is in generally impossible to compute exactly We need Monte Carlo Sampling

Energy based models (EBMs)



Restricted Boltzmann Machines

• Deep Boltzmann Machines



• Generative ConvNets



Why Restricted Boltzmann Machines (RBMs)?

In this talk we focus on RBM for the following reason:

- It is an *Ising model*: a canonical model for statistical physicists
- We can write explicitly the probability distribution which give us tools to study it
- It relies on a simple shallow neural network that can be looked into: can it be used to extract dataset features (interpretability) ?
- It can model complex dataset : it can be shown in the binary case that it can overfit anything...

Reasons to not use it:

- The training can be (very) capricious for complicated reasons
- Generate new data can be long ... (How long?)
- So far, no implementation of a convolutional RBM has been made usable in practice

RBM (biased) Historical events

Machine Learning aspects

- It was introduced by Smolenski and popularized by Hinton ~80/90
 → introducing the Contrastive Divergence it was proved to be "practical"
- It was getting popular as a pre-training tools for deep-network
- Then, the interest for RBMs slowly decreases around ~2010
- The rise of GAN/VAE alternative achieve to out-faschion RBM

Statistical Physics aspects

- Many works on RBM in ~2010 anaylising the <u>phase diagram of RBM</u>
- Works on the learning dynamics
- Works on message-passing learning algorithm

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Restricted Boltzmann Machine

Smolensky (1989)



Energy of a configuration

$$E[\boldsymbol{v}, \boldsymbol{h}; \boldsymbol{w}, \boldsymbol{\eta}, \boldsymbol{\theta}] = -\sum_{ia} v_i w_{ia} h_a - \sum_i \eta_i v_i - \sum_a \theta_a h_a$$

Visible : data



Hidden : "Neurons" → **features extracted** (interpretability!)

Restricted Boltzmann Machine

Smolensky (1989)



$$E[\boldsymbol{v},\boldsymbol{h};\boldsymbol{w},\boldsymbol{\eta},\boldsymbol{\theta}] = -\sum_{ia} v_i w_{ia} h_a - \sum_i \eta_i v_i - \sum_a \theta_a h_a$$



Hidden : "Neurons" → **features extracted** (interpretability!)

Sequencing context: Tubiana, Cocco, Monasson, *Elife (2019)*; Shimagaki, Weigt, *PRE (2019)*, Yelmen *et al.*, *PLoS genetics (2021)*; *Bravi* et al. *PloS CB (2021)*; *Bravi* et al. *Cell Systems (2021)*; *→ Tubiana's talk* 10 / 45

Training vs. Sampling and RBM



Gibbs sampling of a trained RBM



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Learning an RBM

• Gibbs equilibrium distribution

$$p[\boldsymbol{v}, \boldsymbol{h} | \boldsymbol{w}, \boldsymbol{\eta}, \boldsymbol{\theta}] = \frac{\exp(-E[\boldsymbol{v}, \boldsymbol{h}; \boldsymbol{w}, \boldsymbol{\eta}, \boldsymbol{\theta}])}{Z} \quad \text{with } Z = \sum_{\{\boldsymbol{v}, \boldsymbol{h}\}} e^{-E[\boldsymbol{v}, \boldsymbol{h}]}$$

- Dataset $S = \{ \boldsymbol{v}^{(1)}, \cdots, \boldsymbol{v}^{(M)} \}$ are the **typical samples** of $p(\boldsymbol{v})$
- Maximize the log-likelihood $\mathcal{L}(\boldsymbol{w}, \boldsymbol{\eta}, \boldsymbol{\theta} | S) = \sum_{1}^{M} \ln p(\boldsymbol{v} = v^{(m)} | \boldsymbol{w}, \boldsymbol{\eta}, \boldsymbol{\theta})$

• Gradient ascent
$$\frac{\partial \mathcal{L}}{\partial w_{ia}} = \langle v_i h_a \rangle_{\mathcal{D}} - \langle v_i h_a \rangle_{\mathcal{H}}$$
$$\frac{\partial \mathcal{L}}{\partial \eta_i} = \langle v_i \rangle_{\mathcal{D}} - \langle v_i \rangle_{\mathcal{H}} \text{ and } \frac{\partial \mathcal{L}}{\partial \theta_a} = \langle h_a \rangle_{\mathcal{D}} - \langle h_a \rangle_{\mathcal{H}} \quad 13 / 45$$

On the interpretability (I)

• One can extract the point correlations of our data up to any order !

Once we integrate out the hidden variables:

$$E(v;\theta) = -\log\left(\sum_{\boldsymbol{h}} e^{-E[\boldsymbol{v},\boldsymbol{h};\boldsymbol{w},\boldsymbol{\eta},\boldsymbol{\theta}]}\right)$$

$$E(v) = -E_0 - \sum_i H_i v_i - \sum_{i,j} J_{i,j}^{(2)} v_i v_j - \sum_{i,j,k} J_{ijk}^{(3)} v_i v_j v_k \cdots - \sum_{j_1 \cdots j_n} J_{j_1 \cdots j_n}^{(n)} v_{j_1} \cdots v_{j_n} - \cdots$$

Effective model for the problem

On the interpretability (II)

• It can be shown that when the RBM starts to learn features of the data, the system suffers a **phase order transition** from a paramagnetic phase to a ferromagnetic phase



[Decelle, Fissore, Furtlehner J. of stat phys (2018)]

<u>**Para</u>**: high temperature (low variance) <u>**Ferro**</u>: strong eigenmode - low noise</u>



On the interpretability (II)

• The eigenvectors \boldsymbol{w}_i of matrix $\boldsymbol{\omega}$ align with the important directions of the dataset:

$$m_i = \langle \boldsymbol{v} \cdot \boldsymbol{w}_i \rangle_{\mathcal{D}} \neq 0$$

[Decelle, Fissore, Furtlehner J. of stat phys (2018)]



CPF protein

Work in collaboration with R. Vanderhaegen, A. Decelle, A. Carbone



Monte Carlo

On the gradient

R.h.s gradient will be correctly computed if the <u>simulations thermalize</u>

 $k \sim n \tau_{\text{mixing}}$

N_s parallel Markov chains

 $\langle \cdots \rangle_{\mathcal{H}}$

initialization



$$\frac{\partial \mathcal{L}}{\partial w_{ia}} = \langle v_i h_a \rangle_{\mathcal{D}} - \langle v_i h_a \rangle_{\mathcal{H}}$$
$$\frac{\partial \mathcal{L}}{\partial \eta_i} = \langle v_i \rangle_{\mathcal{D}} - \langle v_i \rangle_{\mathcal{H}}$$
$$\frac{\partial \mathcal{L}}{\partial \theta_a} = \langle h_a \rangle_{\mathcal{D}} - \langle h_a \rangle_{\mathcal{H}}$$

Measure \Rightarrow r.h.s gradient

On the gradient

R.h.s gradient will be correctly computed if the <u>simulations thermalize</u>

 $k \sim n \tau_{\text{mixing}}$

N_s parallel Markov chains

 $\langle \cdots \rangle_{\mathcal{H}}$

initialization



 $\frac{\partial \mathcal{L}}{\partial w_{ia}} = \langle v_i h_a \rangle_{\mathcal{D}} - \langle v_i h_a \rangle_{\mathcal{H}}$ $\frac{\partial \mathcal{L}}{\partial \eta_i} = \langle v_i \rangle_{\mathcal{D}} - \langle v_i \rangle_{\mathcal{H}} \quad \text{for even of }$

Let's choose good starting point and approximate with k~O(10) steps

- Contrastive divergence (CD) [Hinton (2002)] Init – dataset
- Persistence contrastive divergence (PCD) [*Tieleman (2008)*] Init – previous last point
- Mean field (TAP) [Gabrié, Tramel, and Krzakala (2015)]

Or

• Simulated annealing, Parallel Tempering, ...



Rdm - 10





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Training using CD: chain initialisation at the dataset

If we sample the RBM from:

→ random NOTHING

Training using CD: chain initialisation at the dataset

If we sample the RBM from:

- → random NOTHING
- the dataset we do not get anything new

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Training using Mean Field dynamics

If we sample the RBM :

- Heat bath dynamics
 NOTHING
- With MF good data at t~k and it does not change anymore

With HB MCMC dynamics

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With MF dynamics

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Decelle, Furtlehner, Seoane arXiv:2105.13889



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Non-equilibrium regime : generation



Decelle, Furtlehner, Seoane arXiv:2105.13889

Equilibrium regime





Dynamics are much faster

Equilibrium vs. Non-eq. regimes

Decelle, Furtlehner, Seoane <u>ArXiv:2105.13889</u> (NeurIPS2021) See Decelle's poster

Non-equilibrium $k < t_{\text{therm}}$

- "Learns the dynamics"
- Advantage: Optimal for data generation
 - → random noise initialization

Nijkamp, Hill, Han, Wu, Zhu. NIPS 2019, AAAI 2020.

BM: Muntoni, Pagnani, Martin Weigt, Zamponi (2021)

• Drawbacks:

· Unpredictable if not controlled

- not a good model for the data
- Extremely slow dynamics



Training

 ∇LL

Equilibrium $k > t_{\text{therm}}$

 Learns the (unnormalized) prob. Distribution of the data

• Advantage:

- Fits a good model for the data
- Sampling is stable

• Drawbacks:

- Very slow training: need large k
- Generating new configurations can become prohibitive 28 / 45/

Equilibration: how long? Easy : MNIST



Equilibration: how long? Hard : GENE



The thermalisation time jumps suddenly beyond 10⁵ MCMC steps.

The equilibrium regime is beyond our reach...



What does it happen?

$$E[\boldsymbol{v},\boldsymbol{h}] = -\sum_{ia} v_i \boldsymbol{w}_{ia} h_a - \sum_i \eta_i v_i - \sum_a \theta_a h_a$$



: *i*-th eigenvector $m_i = \langle \boldsymbol{v} \cdot \boldsymbol{w}_i \rangle_{\mathcal{D}} \neq 0$ of the W matrix



What does it happen?

 $\underline{t_{\text{age}}} = 144$ As learning advances we start to have metastable states 3 2 m_1 Ising $\mathcal{H} = -J\sum \sigma_i \sigma_j - h\sum^n \sigma_j,$ $^{-1}$ -2 model i=1 m_0 $\langle i,j \rangle$ (a) (c) m т (b` h a) 0 -50 (c)0 \sim -100 0 ----h $(\underline{w})^{-150}_{-200}$ -150 $T_{\rm c}$ Tて 3 -300 0 -350 -400 -450 -33/45 -0.6 -0.2 -0.4 0.0 m 0.2 0.6 0.8 0.4

Structured datasets

We do the PCA of the data and project the data long the first 2 eigenvectors



Clusterized datasets 34/45

Step back : high dimensional clusters along 1D

We feed the RBM with points belonging to different clusters (in high dimensions) but Separated only in one



- Standard RBM training procedure fails completely to fit such dataset
- Yet, this simple low dimensional dataset can be trained analytically [Decelle, Furtlehner, PRL 2021]
 - We can have a perfect model ω , θ , η to test the biased sampling

[Bereux, Decelle, Furtlehner, Seoane, *In preparation*]

Problems of the standard MCMC sampling



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Problems of the standard MCMC sampling



of the W matrix (normalized)

The Tethered Monte Carlo approach (I)

[Fernandez, Martin-Mayor, Yllanes - Nuclear physics (2009), Martin-Mayor, Seoane, Yllanes, Journal of Statistical Physics (2011), Fernández, Martín-Mayor, Seoane, Verrocchio, PRL (2012)]

$$Z = \sum_{\boldsymbol{v},\boldsymbol{h}} e^{-E(\boldsymbol{v},\boldsymbol{h})} = \sqrt{\frac{N}{2\pi}} \int_{-\infty}^{\infty} d\hat{m} \sum_{\boldsymbol{v},\boldsymbol{h}} e^{-E(\boldsymbol{v},\boldsymbol{h})} e^{-N(\hat{m}-m_0(\boldsymbol{v}))^2/2} = \int_{-\infty}^{\infty} d\hat{m} e^{-N\Omega(\hat{m})}$$

$$\langle O(\boldsymbol{v}, \boldsymbol{h}) \rangle = \frac{\sum_{\boldsymbol{v}, \boldsymbol{h}} O e^{-E(\boldsymbol{v}, \boldsymbol{h})}}{\sum_{\boldsymbol{v}, \boldsymbol{h}} e^{-E(\boldsymbol{v}, \boldsymbol{h})}} = \int_{-\infty}^{\infty} d\hat{m} \, \langle O \rangle_{\hat{m}} \, e^{-N\Omega(\hat{m})}$$

$$\hat{m}_{i}^{15}$$

$$\langle O(\boldsymbol{v}, \boldsymbol{h}) \rangle_{\hat{m}} = \frac{\sum_{\boldsymbol{v}, \boldsymbol{h}} O \ \omega(\hat{m}, \boldsymbol{v}, \boldsymbol{h})}{\sum_{\boldsymbol{v}, \boldsymbol{h}} \omega(\hat{m}, \boldsymbol{v}, \boldsymbol{h})}$$

$$\omega(\hat{m}, \boldsymbol{v}, \boldsymbol{h}) = e^{-E(\boldsymbol{v}, \boldsymbol{h})} e^{-N(\hat{m} - m_0(\hat{v}))^2/2}$$

- Run *K* simulations at \hat{m}_i , with *i*=1,...,*K* fixed
- We break the metastability: fast thermalisation 38 / 45

The Tethered Monte Carlo approach (II)

[Fernandez, Martin-Mayor, Yllanes - Nuclear physics (2009), Martin-Mayor, Seoane, Yllanes, Journal of Statistical Physics (2011), Fernández, Martín-Mayor, Seoane, Verrocchio, PRL (2012)]



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[Bereux, Decelle, Furtlehner, Seoane, In preparation]

Learning with TMCMC

 \hat{m}_i **►**t

$$\frac{\partial \mathcal{L}}{\partial w_{ia}} = \langle v_i h_a \rangle_{\mathcal{D}} - \langle v_i h_a \rangle_{\mathcal{H}}$$
$$\frac{\partial \mathcal{L}}{\partial \eta_i} = \langle v_i \rangle_{\mathcal{D}} - \langle v_i \rangle_{\mathcal{H}}$$
$$\frac{\partial \mathcal{L}}{\partial \theta_a} = \langle h_a \rangle_{\mathcal{D}} - \langle h_a \rangle_{\mathcal{H}}$$

 $\langle O(\boldsymbol{v}, \boldsymbol{h}) \rangle_{\mathcal{H}} = \int_{-\infty}^{\infty} d\hat{m} \, \langle O \rangle_{\hat{m}} \, e^{-N\Omega(\hat{m})}$

Learning with TMCMC

Generalization to higher number of conserved observables is straigtforward...

$$\omega(\hat{m}_{1}, \hat{m}_{2}, \boldsymbol{v}, \boldsymbol{h}) = e^{-E(\boldsymbol{v}, \boldsymbol{h})} e^{-N(\hat{m}_{2} - m_{0}(\hat{v}))^{2}/2} e^{-N(\hat{m}_{2} - m_{1}(\hat{v}))^{2}/2}$$

$$\Omega'(\hat{m}) \rightarrow \boldsymbol{\nabla}\Omega = \left(\langle \hat{m}_{0} - m_{0} \rangle_{\hat{m}_{0}, \hat{m}_{1}} \langle \hat{m}_{1} - m_{1} \rangle_{\hat{m}_{0}, \hat{m}_{1}} \right)$$

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Conclusions

Decelle, Furtlehner, Seoane <u>ArXiv:2105.13889</u>

- RBM have a major advantage in terms of interpretability of the extracted patterns, but training is very unstable following the standard recipes.
- Instability is a consequence of the nonequilibrium sampling during the sampling and can be controlled and taken in advance to generate good samples with short trainings.
- In order to fit a good model for the data, the sampling during the learning must equilibrate:
 - Datasets without structure : mixing time grows with Nb. Updates
 - Structured datasets: thermalisation is hampered by coexistence of states → biased sampling

Parameters MNIST

- Number of hidden nodes: $N_h = 500$
- Learning rate: $\alpha = 0.01$
- Minibatch size: $n_{mb} = 500$
- no ℓ_2 regularization of momentum.
- The gradient is centered according to [1]
- The visible biases are initialized to match the empirical frequency of the training dataset:

$$\eta_i = \log\left(\frac{\bar{m}_i}{1 - \bar{m}_i}\right) \text{ where } \bar{m}_i = \frac{1}{M} \sum_m s_i^{(m)} \tag{1}$$

- The number of MC chains used for the negative term was always equal to n_{mb}
- The number of MC steps for the negative chains is indicated by the variables $t_{\rm GL}$ and can vary.

RBM: learning and phase transition

We can confirm experimentally that the divergence of the mixing time correspond to the 2nd order phase transition

