

Highly-oscillatory evolution equations : averaging and numerics

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A class of Highly-oscillatory problems

Highly-oscillatory ODEs

$$\frac{dy^\varepsilon}{dt} = \frac{\gamma(t)}{\varepsilon} Ay^\varepsilon + R_\varepsilon(y^\varepsilon), \quad t \in [0, T], \quad y^\varepsilon(0) = y_0,$$

where A is supposed a skew-adjoint operator with all its eigenvalues in $i\mathbb{Z}$. Assume $\gamma(t) \geq 0$ for simplicity. $\varepsilon \in (0, 1]$.

Two important cases:

Case I :

$$\gamma(t) \geq \gamma_0 > 0$$

Case II :

$$\gamma(t_0) = 0 \quad \text{for some } t_0 \in [0, T].$$

Numerical difficulties

- Standard schemes of order p lead to

$$\|u^\varepsilon - u^{\varepsilon, \Delta t}\| \leq C \frac{(\Delta t)^p}{\varepsilon^q}, \quad q > 0,$$

forcing $\Delta t \sim \varepsilon$ and thus formidable costs for small values of ε .

- More sophisticated schemes of order p can be constructed in some situations but suffer from the "order reduction" phenomena :

$$\|u^\varepsilon - u^{\varepsilon, \Delta t}\| \leq C(\Delta t)^q, \quad q \ll p.$$

- **Partial remedy:** Averaging methods lead to

$$\|u^\varepsilon - \tilde{u}^{\varepsilon, \Delta t}\| \leq C((\Delta t)^p + \varepsilon^q).$$

- **Aim:** Provide with **systematic** methods allowing the **conventional numerical schemes of order p** to be **uniformly accurate**, i.e. such that

$$\sup_{\varepsilon \in (0, 1]} \|u^\varepsilon - u^{\varepsilon, \Delta t}\| \leq C(\Delta t)^p.$$

A first example : Vlasov equation with a given strong magnetic field

$$\partial_t f^\varepsilon + v \cdot \nabla_x f^\varepsilon + E \cdot \nabla_v f^\varepsilon + \frac{v \times B}{\varepsilon} \cdot \nabla_v f^\varepsilon = 0$$

Characteristics :

$$\begin{aligned}\dot{x}(t) &= v(t) \\ \dot{v}(t) &= \frac{1}{\varepsilon} v(t) \times B(x(t)) + E(x(t))\end{aligned}$$

Numerics : widely developed in collaboration with Chartier, Crouseilles, Méhats, X. Zhao.

Asymptotics : widely developed by Bostan *et al.*.

- Monofrequency case : constant modulus $|B(x)| = 1$. The oscillatory part generates a 2π - periodic trajectory.
- General case : B with varying intensity and direction. In this case, we introduce a new time s and consider t as a function of s .

$$\begin{aligned}\frac{d}{ds} t(s) &= \frac{1}{|B(\tilde{x}(s))|}, & \frac{d}{ds} \tilde{x}(s) &= \frac{\tilde{v}(s)}{|B(\tilde{x}(s))|}, \\ \frac{d}{ds} \tilde{v}(s) &= \frac{1}{\varepsilon} \tilde{v}(s) \times \frac{B}{|B(\tilde{x}(s))|} + \frac{E}{|B(\tilde{x}(s))|}.\end{aligned}$$

Main Assumption : $|B(x)| \geq \text{Constant} > 0$.

A second example : transition between quantum states

- Landau-Zener 2×2 system

$$\frac{du^\varepsilon}{dt} = -\frac{i}{\varepsilon} \begin{pmatrix} -t & \delta \\ \delta & t \end{pmatrix} u^\varepsilon + \text{corrective terms.}$$

- Transport in graphene in semiclassical regime (*Morandi-Schürer, 2012*). Joint work with *Crouseilles, Jin and Méhats*.

Unknowns are the Wigner distributions $f_+(t, x, p)$, $f_-(t, x, p)$, $f(t, x, p)$:

$$\partial_t f^+ + \frac{p}{|p|} \cdot \nabla_x f^+ - \nabla_x V \cdot \nabla_p f^+ = -\frac{p^\perp \cdot \nabla_x V}{|p|^3} \Im((p_1 + ip_2)f),$$

$$\partial_t f^- - \frac{p}{|p|} \cdot \nabla_x f^- - \nabla_x V \cdot \nabla_p f^- = \frac{p^\perp \cdot \nabla_x V}{|p|^3} \Im((p_1 + ip_2)f),$$

$$\partial_t f - \nabla_x V \cdot \nabla_p f = -\frac{2i|p|}{\varepsilon} f + i \frac{p^\perp \cdot \nabla_x V}{|p|^2} f + \frac{i}{2} \frac{p^\perp \cdot \nabla_x V}{|p|^3} (p_1 - ip_2)(f^+ - f^-).$$

where $p = (p_1, p_2)$ and $p^\perp = (-p_2, p_1)$.

This semi-classical model is derived from the Von-Neumann equation for two mixed states, by taking the Wigner transform and keeping only terms of the order of $1/\varepsilon$ and 1. The quantities f_+ and f_- are the diagonal terms in the Wigner matrix and f is the off-diagonal coefficient.

Main Assumption : 1D problem in x and p , with $p_2 > 0$ as a fixed parameter.

Generic problem

$$\frac{dy^\varepsilon}{dt} = \frac{\gamma(t)}{\varepsilon} Ay^\varepsilon + R(y^\varepsilon), \quad t \in [0, T], \quad y^\varepsilon(0) = y_0,$$

► Setting

$$u^\varepsilon(t) = \exp\left(\frac{S(t)}{\varepsilon} A\right) y^\varepsilon(t), \quad \text{with} \quad S(t) = \int_0^t \gamma(s) ds$$

$$\frac{d}{dt} u^\varepsilon(t) = F\left(\frac{S(t)}{\varepsilon}, u^\varepsilon\right), \quad F(\theta, u) = e^{-\theta A} R\left(e^{\theta A} u\right).$$

$$u^\varepsilon(0) = y_0,$$

► F is periodic in θ .

► In all cases (vanishing or not), the limit model is

$$\frac{d}{dt} \underline{u} = \langle F(\cdot, \underline{u}) \rangle, \quad \underline{u}(0) = y_0, \quad \text{where}$$

$$\langle F(\cdot, u) \rangle = \frac{1}{2\pi} \int_0^{2\pi} F(\theta, u) d\theta.$$

Asymptotic models: constant frequency $\gamma = 1$

$$\frac{d}{dt} u^\varepsilon(t) = F\left(\frac{t}{\varepsilon}, u^\varepsilon\right), \quad u^\varepsilon(0) = y_0, \quad F(\theta, u) = e^{-\theta A} R\left(e^{\theta A} u\right).$$

- Averaging techniques or two-scale expansions : Bogoliubov-Mitropolsky 1930', Perko 1968, ...

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^\varepsilon(\underline{u}^\varepsilon(t)) = \underline{u}^\varepsilon(t) + \varepsilon U_1(t/\varepsilon, \underline{u}^\varepsilon(t)) + \varepsilon^2 U_2(t/\varepsilon, \underline{u}^\varepsilon(t)) + \dots$$

$$\begin{aligned} \frac{d}{dt} \underline{u}^\varepsilon(t) &= K_0(\underline{u}^\varepsilon(t)) + \varepsilon K_1(\underline{u}^\varepsilon(t)) + \dots = K^\varepsilon(\underline{u}^\varepsilon(t)) \\ \underline{u}^\varepsilon(0) &= (\Phi_0^\varepsilon)^{-1}(y_0), \end{aligned}$$

Φ_θ is periodic in θ . No constructive method for Φ^ε and K^ε .

- Equivalently,

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^\varepsilon \circ \Psi_t \circ (\Phi_0^\varepsilon)^{-1}(y_0),$$

with

$$\frac{d\Psi_t}{dt} = K^\varepsilon(\Psi_t), \quad \Psi_0 = Id.$$

Constructive methods and structure (Lie structure, Hamiltonian and divergence free properties) : Chartier, Murua and Sanz-Serna, Castella, Méhats (2011-2012-2015) ...

➤ Equation on Φ_θ^ε

$$\begin{aligned}\partial_\theta \Phi_\theta(u) &= -\varepsilon \partial_u \Phi_\theta(u) K^\varepsilon(u) + \varepsilon f_\theta \circ \Phi_\theta(u), \\ K^\varepsilon &= \langle \partial_u \Phi_\theta(u) \rangle^{-1} \langle f_\theta \circ \Phi_\theta(u) \rangle.\end{aligned}$$

➤ Integrating this equation with $\langle \Phi_\theta \rangle = \text{id}$,

$$\begin{aligned}\Phi_\theta^{[0]} &= \text{id}, \quad \Phi_\theta^{[n+1]} = \text{id} + \varepsilon \int_0^\theta \left(f_\tau \circ \Phi_\tau^{[n]} - \partial_u \Phi_\tau^{[n]} K^{[n]} \right) d\tau \\ &\quad - \varepsilon \left\langle \int_0^\theta \left(f_\tau \circ \Phi_\tau^{[n]} - \partial_u \Phi_\tau^{[n]} K^{[n]} \right) d\tau \right\rangle \\ K^{[0]} &= \langle f \rangle, \quad K^{[n+1]} = \langle f \circ \Phi^{[n+1]} \rangle.\end{aligned}$$

➤ Averaged model

$$\frac{d\underline{u}}{dt} = K_0(\underline{u}) = \langle F(\cdot, \underline{u}) \rangle = \frac{1}{2\pi} \int_0^{2\pi} F(\theta, \underline{u}) d\theta.$$

➤ Error estimate. Let u_N^ε be the truncated averaging expansion up to ε^N , then

$$u^\varepsilon - u_N^\varepsilon = O\left(\varepsilon^{N+1}\right),$$

provided we have enough regularity on F .

➤ The first asymptotic models may be obtained by hand (Chapman-Enskog like expansion), starting from an equation on $U(t, \theta = t/\varepsilon) = u^\varepsilon(t)$

$$\partial_t U - F(\theta, U) = -\frac{1}{\varepsilon} \partial_\theta U.$$

Asymptotic models: varying frequency $\gamma(t) \geq \gamma_0 > 0$

$$\frac{d}{dt}u^\varepsilon(t) = F\left(\frac{S(t)}{\varepsilon}, u^\varepsilon\right), \quad F(\theta, u) = e^{-\theta A}K\left(e^{\theta A}u\right), \quad S(t) = \int_0^t \gamma(t')dt'$$

- Perform a change of time

$$s = S(t), \quad v^\varepsilon(s) = u^\varepsilon(t).$$

- We can see this as an equation on $(v^\varepsilon(s), t(s))$:

$$\frac{dv^\varepsilon}{ds} = \frac{1}{\gamma(t)}F\left(\frac{s}{\varepsilon}, v^\varepsilon\right), \quad \frac{dt}{ds} = \frac{1}{\gamma(t)}$$

- Averaging techniques can be applied since the quantity $\frac{1}{\gamma(t)}$ is smooth. u^ε strongly converges to \underline{u} solution to

$$\frac{d}{dt}\underline{u}(t) = \langle F(\cdot, \underline{u}(t)) \rangle, \quad \underline{u}(0) = u_0.$$

- We still have the error estimate

$$u^\varepsilon - \underline{u} = O(\varepsilon).$$

First numerical method when $\gamma(t) \geq \gamma_0 > 0$: a two-scale approach

$$\frac{d}{dt} u^\varepsilon(t) = F\left(\frac{t}{\varepsilon}, u^\varepsilon\right), \quad u^\varepsilon(0) = u_0.$$

(Crouseilles, Méhats, L. JCP, 2013, and then with Chartier, Zhao, 2015-2019) with applications to **Schrödinger equations**, and **Vlasov equations with strong magnetic field**.

- Imbed the problem into an augmented one allowing to separate the fast variable from the slow one: Set $U(t, \theta = t/\varepsilon) = u^\varepsilon(t)$

$$\partial_t U - F(\theta, U) = -\frac{1}{\varepsilon} \partial_\theta U.$$

- The only condition we have at time $t = 0$ is $U(0, 0) = u_0$. An additional degree a freedom is available on the initial condition $U(0, \theta)$.
- For any $N \in \mathbb{N}$, there exists a suitable initial condition $U(0, \theta)$ such that
 - $U(0, 0) = u_0$, and
 - the resulting solution $U(t, \theta)$ has **uniformly bounded derivatives** in time and θ up to the order $N + 1$.

Two-scale approach

- for $N = 1$, a good choice of initial condition is

$$U(0, \theta) = u_0 + \varepsilon \int_0^\theta (F(\sigma, u_0) - \langle F(\cdot, u_0) \rangle) d\sigma.$$

More generally for arbitrary N :

$$U(0, \theta) = \Phi_\theta^{[N]} \circ (\Phi_0^{[N]})^{-1} (u_0),$$

where $\Phi_\theta^{[N]}$ is the truncation up to the order ε^N of the expansion of Φ_θ^ε .

- This ensures the **uniform boundeness of the time derivatives of U up to order $N + 1$** .
- **Uniformly accurate numerical schemes of order N (or even $N + 1$)** can be constructed on this two-scale formulation, with applications to Schrodinger and kinetic equations.

Second approach for $\gamma(t) \geq \gamma_0 > 0$: a micro-macro approach

The two-scale equation uses an additional variable θ . To avoid this, we have introduced **Micro-macro decomposition** (with Chartier, Méhats, and Vilmart, *Found. Comput. Math.* 2020).

$$\frac{d}{dt} u^\varepsilon(t) = F\left(\frac{t}{\varepsilon}, u^\varepsilon\right), \quad u(0) = u_0.$$

- The idea is to write the solution u^ε as

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon(t)) + v^\varepsilon(t),$$

where $\Phi_\theta^{[N]} \circ \underline{u}(t)$ is the asymptotic expansion up to some order N . The change of variable Φ_θ^ε is periodic in θ , and $\underline{u}^\varepsilon(t)$ is the solution to a smooth averaged equation:

$$\frac{d}{dt} \underline{u}^\varepsilon(t) = K_\varepsilon^{[N]} \underline{u}^\varepsilon(t), \quad \underline{u}^\varepsilon(0) = \left(\Phi_0^{[N]}\right)^{-1}(u_0).$$

$$\begin{aligned} \frac{d}{dt} v^\varepsilon(t) &= F\left(t/\varepsilon, \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon(t)) + v^\varepsilon\right) - \left(\frac{1}{\varepsilon} \partial_\theta \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon) + \partial_u \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon) K_\varepsilon^\varepsilon \underline{u}^\varepsilon\right). \\ &= F\left(t/\varepsilon, \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon(t)) + v^\varepsilon\right) - F\left(t/\varepsilon, \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon(t))\right) + O(\varepsilon^N). \end{aligned}$$

- Solve the equations on v^ε and $\underline{u}^\varepsilon$, instead of the original equation on u^ε

Micro-macro approach

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^{[N]}(\underline{u}^\varepsilon(t)) + v^\varepsilon(t)$$

- Case $N = 0$: $u^\varepsilon(t) = \underline{u}(t) + v^\varepsilon(t)$, with

$$\frac{d}{dt}\underline{u} = \langle F(\cdot, \underline{u}) \rangle, \quad \underline{u}(0) = u_0;$$

$$\frac{d}{dt}v^\varepsilon = F(t/\varepsilon, \underline{u} + v^\varepsilon) - \langle F(\cdot, \underline{u}) \rangle, \quad v^\varepsilon(0) = 0.$$

- Case $N = 1$: $u^\varepsilon(t) = \Phi_{t/\varepsilon}^{[1]}(\underline{u}^\varepsilon(t)) + v^\varepsilon(t)$ where

$$\Phi_\theta^{[1]}(u) = u + \varepsilon(Id - \langle \cdot \rangle) \int_0^\theta (F(\sigma, u) - \langle F(\cdot, u) \rangle) d\sigma.$$

$$\frac{d}{dt}\underline{u}^\varepsilon = \langle F(\cdot, \Phi_\theta^{[1]}(\underline{u}^\varepsilon(t))) \rangle, \quad \underline{u}^\varepsilon(0) = \left(\Phi_0^{[1]}\right)^{-1}(u_0)$$

- The construction is done in a such way that, if we truncate to N the expansions of Φ^ε and of the averaged vector field K^ε , then
- $v^\varepsilon(t) = O(\varepsilon^{N+1})$ and has uniformly bounded time derivatives up to $N + 1$,
 - the equation satisfied by $v^\varepsilon(t)$ does not contain singularities in ε .

Asymptotic models: vanishing frequency $\gamma(t_0) = 0$, $t_0 \geq 0$.

(with Chartier, Méhats, and Vilmart, SIAM, 2020)

$$\gamma(t) = (p+1)|t - t_0|^p, \quad S(t) = \text{sign}(t - t_0)|t - t_0|^{p+1} + t_0^{p+1}.$$

$$\frac{d}{dt} u^\varepsilon(t) = F\left(\frac{S(t)}{\varepsilon}, u^\varepsilon\right), \quad F(\theta, u) = e^{-\theta A} f(e^{\theta A} u).$$

► Perform the change of time $s = S(t)$, $v^\varepsilon(s) = u^\varepsilon(t) = u^\varepsilon(S^{-1}(s))$.

$$\gamma(t) = |s - s_0|^{\frac{p}{p+1}}, \quad s_0 = S(t_0).$$

$$\frac{d}{ds} v^\varepsilon = \frac{1}{\gamma(t)} F\left(\frac{s}{\varepsilon}, v^\varepsilon\right), \quad \frac{dt}{ds} = \frac{1}{\gamma(t)}.$$

- Averaging techniques **can no longer be applied** since the quantity $\frac{1}{\gamma(t)}$ is not smooth at $t = t_0$.
- We no longer have the estimate $u^\varepsilon - \underline{u} = O(\varepsilon)$ but rather

$$u^\varepsilon - \underline{u} = O\left(\varepsilon^{\frac{1}{p+1}}\right)$$

Vanishing frequency: stationary phase effect.

$$\frac{d}{ds} v^\varepsilon = |s - s_0|^{-\frac{p}{p+1}} F\left(\frac{s}{\varepsilon}, v^\varepsilon\right).$$

- We rather write (taking $t_0 = s_0 = 0$ for simplicity)

$$v^\varepsilon(s) = v^\varepsilon(0) + \int_0^s \sigma^{-\frac{p}{p+1}} F\left(\frac{\sigma}{\varepsilon}, v^\varepsilon(\sigma)\right) d\sigma.$$

$$v^\varepsilon(s) = v^\varepsilon(0) + \int_0^s \sigma^{-\frac{p}{p+1}} \langle F(\cdot, v^\varepsilon(\sigma)) \rangle d\sigma + R_\varepsilon,$$

where

$$R_\varepsilon = \int_0^s \sigma^{-\frac{p}{p+1}} \left(F\left(\frac{\sigma}{\varepsilon}, v^\varepsilon(\sigma)\right) - \langle F(\cdot, v^\varepsilon(\sigma)) \rangle \right) d\sigma$$

- Typically, if $F(\sigma, u) = (1 + e^{i\sigma})u$, we have

$$R_\varepsilon = \int_0^s \sigma^{-\frac{p}{p+1}} \exp(i\sigma/\varepsilon) v^\varepsilon(\sigma) d\sigma.$$

- A change of variable $\sigma/\varepsilon \rightarrow \sigma$ gives

$$R_\varepsilon = \varepsilon^{\frac{1}{p+1}} \int_0^{s/\varepsilon} \sigma^{-\frac{p}{p+1}} e^{i\sigma} v^\varepsilon(\varepsilon\sigma) d\sigma$$

Vanishing frequency: stationary phase effect.

► Let

$$\Omega(s) = \int_s^{+\infty} \sigma^{-\frac{p}{p+1}} e^{i\sigma} d\sigma$$

and perform integration by parts

$$R_\varepsilon = \varepsilon^{\frac{1}{p+1}} (\Omega(0)v^\varepsilon(0) - \Omega(s/\varepsilon)v^\varepsilon(s)) + \varepsilon^{\frac{2}{p+1}} \int_0^{s/\varepsilon} \sigma^{-\frac{p}{p+1}} \Omega(\sigma)v^\varepsilon(\varepsilon\sigma)(1+e^{i\sigma})d\sigma.$$

► **Next term:** Observing that $|\Omega(s)| \leq C(1+s)^{-\frac{p}{p+1}}$, we get

$$\varepsilon^{\frac{2}{p+1}} \left| \int_0^{s/\varepsilon} \sigma^{-\frac{p}{p+1}} \Omega(\sigma)v^\varepsilon(\varepsilon\sigma)(1+e^{i\sigma})d\sigma \right| \leq C\varepsilon^{\frac{2}{p+1}} \int_0^{s/\varepsilon} \sigma^{-\frac{p}{p+1}} (1+\sigma)^{-\frac{p}{p+1}} d\sigma.$$

We then get a $O(\varepsilon^{\frac{2}{p+1}})$ for $p > 1$ and $O(\varepsilon \log(\varepsilon))$ for $p = 1$.

Rigorous estimate up to $\varepsilon^{2/(p+1)}$

Let

$$G(\theta, \underline{u}) = \int_0^\theta (F(\sigma, \underline{u}) - \langle F(\cdot, \underline{u}) \rangle) d\sigma - \left\langle \int_0^s (F(\sigma, \underline{u}) - \langle F(\cdot, \underline{u}) \rangle) d\sigma \right\rangle,$$

$$\Omega(s, \underline{u}) = \int_s^{+\infty} \sigma^{-p/(p+1)} (F(\sigma, \underline{u}) - \langle F(\cdot, \underline{u}) \rangle) d\sigma.$$

Let \underline{u} the solution to

$$\frac{d\underline{u}}{dt} = \langle F(\cdot, \underline{u}(t)) \rangle, \quad \underline{u}(0) = \underline{u}_0 + \frac{\varepsilon^{1/(p+1)}}{p+1} \Omega(0, \underline{u}_0).$$

Truncation error estimate

We have

$$\underline{u}^\varepsilon = \tilde{\underline{u}} + w^\varepsilon, \quad \text{with} \quad |w^\varepsilon(t)| \leq C\varepsilon^{\frac{2}{p+1}}, \quad \forall t \in [0, T],$$

and $\tilde{\underline{u}}(t) = \Phi_{\frac{s(t)}{\varepsilon}}(\underline{u}(t))$ and

$$\Phi_\theta(\underline{u}) = \underline{u} - \frac{\varepsilon^{1/(p+1)}}{p+1} \Omega(\theta, \underline{u}(t)) + \frac{\delta_p}{4} \varepsilon \log(1 + \theta) \langle (\partial_2 G) F \rangle(\underline{u}_0),$$

$\delta_p = 1$ if $p = 1$ and 0 otherwise.

Micro-Macro decomposition

Set

$$u^\varepsilon(t) = \tilde{u}(t) + w^\varepsilon(t).$$

Uniform estimate on the time derivatives of w^ε , for $p = 1$.

We have

$$\begin{aligned} \forall t \in [0, T], \quad |w^\varepsilon(t)| &\leq C\varepsilon \\ \left| \frac{dw^\varepsilon}{dt} \right| &\leq C\sqrt{\varepsilon}, \quad \left| \frac{d^2w^\varepsilon}{dt^2} \right| \leq C. \end{aligned}$$

- Instead of solving numerically the stiff equation on u , **our strategy consists in solving the system of the two smooth equations on \underline{u} and w^ε** . Then compute \tilde{u} and finally $u^\varepsilon(t) = \tilde{u}(t) + w^\varepsilon(t)$.
- The computation of \tilde{u} requires the computation of the function $\Omega(\theta, u)$. Using Fourier expansions for F , we are left with functions of "Erf" type.

The vanishing-frequency case

We test our method on the Hénon-Heiles system $y^\varepsilon = (q_1, q_2, p_1, p_2)$ with a time-varying parameter $\gamma(t) = 2(t - t_0)$

$$\begin{aligned} \dot{y}^\varepsilon(t) &= \left(\frac{\gamma(t)}{\varepsilon} p_1, p_2, -\frac{\gamma(t)}{\varepsilon} q_1 - 2q_1 q_2, -q_2 - q_1^2 + q_2^2 \right), \quad t \in [0, 1], \\ y^\varepsilon(0) &= (0.9, 0.6, 0.8, 0.5). \end{aligned}$$

The filtered unknown $u^\varepsilon(t) \in \mathbb{R}^4$ is defined by

$$u^\varepsilon(t) = (\cos(\theta)q_1(t) - \sin(\theta)p_1(t), q_2(t), \sin(\theta)q_1(t) + \cos(\theta)p_1(t), p_2(t)),$$

with $\theta = \frac{(t-t_0)|t-t_0|+t_0^2}{\varepsilon}$, and satisfies

$$\dot{u}^\varepsilon(t) = (F_1, F_2, F_3, F_4)(\theta, u^\varepsilon(t)),$$

with

$$F_1(\theta, u) = 2 \sin \theta (u_1 \cos \theta + u_3 \sin \theta) u_2, \quad F_2(\theta, u) = u_4,$$

$$F_3(\theta, u) = -2 \cos \theta (u_1 \cos \theta + u_3 \sin \theta) u_2, \quad F_4(\theta, u) = -(u_1 \cos \theta + u_3 \sin \theta)^2 + u_2^2 - u_2).$$

In our tests, several values for t_0 has been taken in $[0, 1]$, $h = 1/N$ for some $N \in \mathbb{N}^*$ and $t^{[k]} = kh$, $k = 0, \dots, N$.

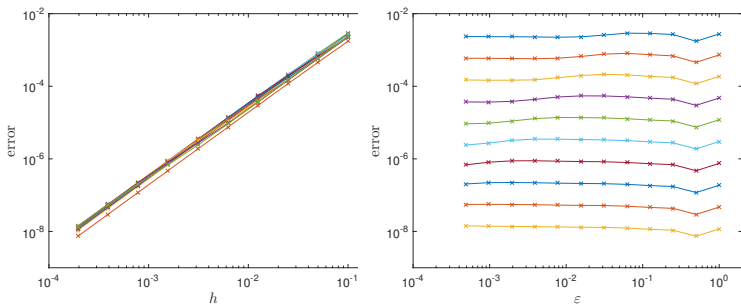


Figure: Error as a function of h for $\epsilon \in \{2^{-k}, k = 0, \dots, 11\}$ (left) and error as a function of ϵ for $h \in \{0.1/2^{-k}, k = 0, \dots, 9\}$ (right). $p = 1$.

Time-space oscillations and transport model for graphene

$$\partial_t f - \nabla_x V \cdot \nabla_p f = -\frac{2i|p|}{\varepsilon} f + \dots$$

(with N. Crouseilles, S. Jin and F. Méhats, 2020).

Combine ideas from nonlinear geometric optics (with Crouseilles and Jin, M3AS, 2017), with the above micro-macro decomposition.

Transport of electrons in graphene : Wigner distributions

$f_+(t, x, p)$, $f_-(t, x, p)$, $f(t, x, p)$, and ε is the semiclassical parameter:

$$\partial_t f^+ + \frac{p}{|p|} \cdot \nabla_x f^+ - \nabla_x V \cdot \nabla_p f^+ = -\frac{p^\perp \cdot \nabla_x V}{|p|^3} \Im((p_x + ip_y)f),$$

$$\partial_t f^- - \frac{p}{|p|} \cdot \nabla_x f^- - \nabla_x V \cdot \nabla_p f^- = \frac{p^\perp \cdot \nabla_x V}{|p|^3} \Im((p_x + ip_y)f),$$

$$\partial_t f - \nabla_x V \cdot \nabla_p f = -\frac{2i|p|}{\varepsilon} f + i\frac{p^\perp \cdot \nabla_x V}{|p|^2} f + \frac{i}{2} \frac{p^\perp \cdot \nabla_x V}{|p|^3} (p_x - ip_y)(f^+ - f^-).$$

where $|p| = (p_x^2 + p_y^2)^{1/2}$ and $p^\perp = (-p_y, p_x)$.

We construct a uniformly accurate second order method.

Important assumption: We consider a 1D problem in x so that p_y becomes a parameter. We suppose that $p_y \geq \nu_0 > 0$, so that $|p|$ **does not vanish**.

It is not a time oscillatory model!

$$\partial_t f - \nabla_x V \cdot \nabla_p f = -\frac{2i|p|}{\varepsilon} f + \dots$$

- Because of its dependence in p , the stiff term does not generate a periodic solution and cannot be filtered out as before.
- The main oscillation should involve all the variables (t, x, p) . We introduce the phase of oscillations:

$$s = S(t, x, p), \quad \partial_t S - \nabla_x V \cdot \nabla_p S = 2|p|, \quad S(0, x, p) = 0.$$

in order to bring down the problem to a time-oscillatory problem and apply the micro/macro strategy.

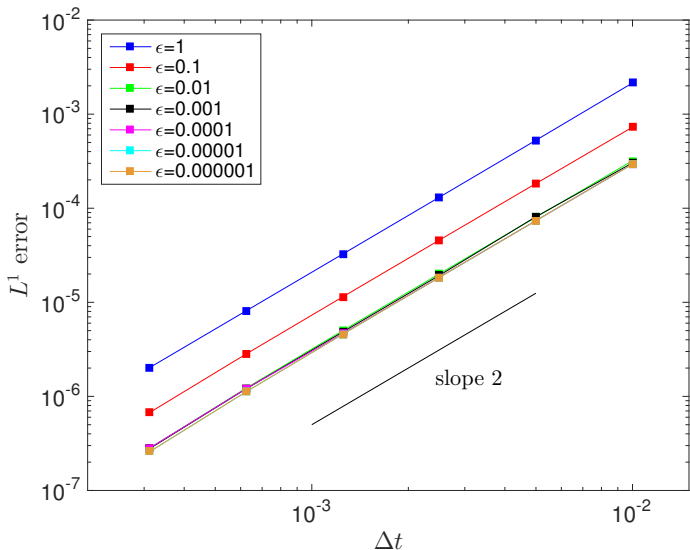
- The function $g(s = S(t, x, p), x, p) = f(t, x, p)$

$$\partial_s g - \frac{\nabla_x V}{2|p|} \cdot \nabla_p g = -\frac{i}{\varepsilon} g + \frac{1}{2|p|} \times \text{the other terms.}$$

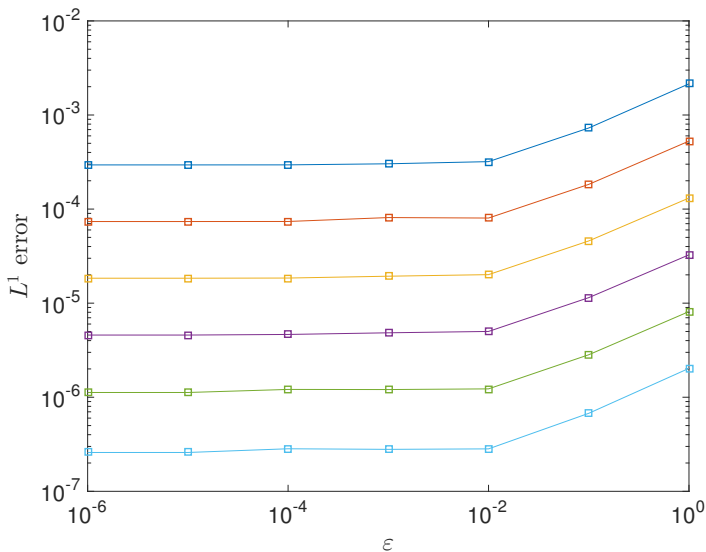
- This phase equation can be solved explicitly here:

$$S(t, x, p_x, p_y) = \frac{p_y^2}{E} \left[\xi \left(\frac{p_x + Et}{p_y} \right) - \xi \left(\frac{p_x}{p_y} \right) \right].$$

$$\xi(u) = u\sqrt{1+u^2} + \log(u + \sqrt{1+u^2})$$

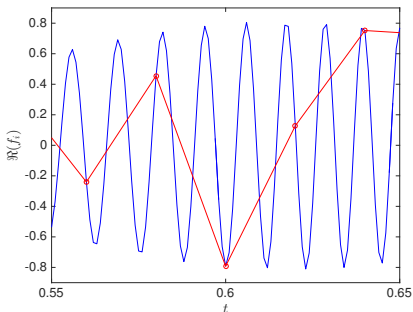
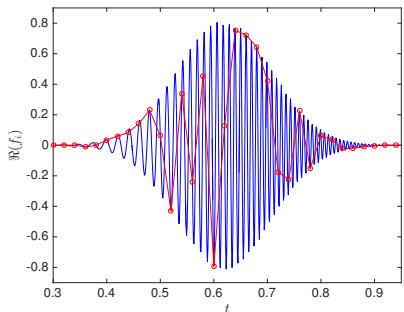
Error curves as a function of Δt 

Error with respect to Δt for $\epsilon \in \{1, 0.1, 0.01, 0.001, 0.0001, 0.00001, 0.000001\}$.
 $N_x = 128, N_{p_x} = 128$.

Error curves as a function of ε 

Error with respect to ε for various values of Δt : $\Delta t = 2^{-k} \times 10^{-2}, k = 0, \dots, 5$.

Oscillations



For $\varepsilon = 0.005$: $\Re(f)(t, -2.16, -1.18)$ as a function of t .

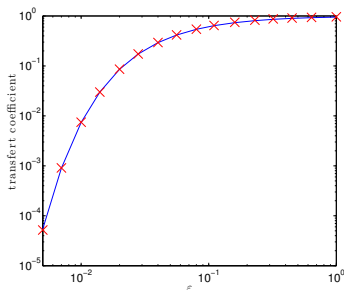
Blue: reference solution, Red: solution computed with our scheme. The right figure is a zoom of the left figure. $N_x = 64$, $N_{p_x} = 128$, $\Delta t = 0.02$.

Landau-Zener transition rate

We plot the transition rate as a function of ε , and compare with the theoretical Landau-Zener transition rate:

$$f_+(0, x, p_x) = \frac{4}{\pi} e^{-4(x+2)^2 - 4(p_x - 1.3)^2}, \quad f_-(0, x, p_x) = 0, \quad f_i(0, x, p_x) = 0.$$

$$T = \frac{\int f_-(t_f, x, p_x) dx dp_x}{\int f_+(0, x, p_x) dx dp_x}, \quad T_{\text{Landau-Zener}} = \exp\left(-\frac{\pi p_y^2}{\varepsilon E}\right).$$



Landau-Zener probability. Red crosses=numerically computed transfert coefficient.
Blue curve=theoretical coefficient. $N_x = 64, N_{p_x} = 64, \Delta t = 0.005$.

Computing Φ_θ by a derivative-free algorithm

$$\frac{du}{dt} = f_{t/\varepsilon}(u), \quad u(t) = \Phi_{t/\varepsilon} \circ \Psi_t \circ (\Phi_0)^{-1}(u_0).$$

➤ Equation on Φ_θ^ε

$$\begin{aligned} \partial_\theta \Phi_\theta(u) &= -\varepsilon \partial_u \Phi_\theta(u) K^\varepsilon(u) + \varepsilon f_\theta \circ \Phi_\theta(u), \\ K^\varepsilon &= \langle \partial_u \Phi_\theta(u) \rangle^{-1} \langle f_\theta \circ \Phi_\theta(u) \rangle. \end{aligned}$$

➤ Integrating this equation with $\langle \Phi_\theta \rangle = \text{id}$,

$$\begin{aligned} \Phi_\theta^{[0]} &= \text{id}, \quad \Phi_\theta^{[n+1]} = \text{id} + \varepsilon \int_0^\theta \left(f_\tau \circ \Phi_\tau^{[n]} - \partial_u \Phi_\tau^{[n]} K^{[n]} \right) d\tau \\ &\quad - \varepsilon \left\langle \int_0^\theta \left(f_\tau \circ \Phi_\tau^{[n]} - \partial_u \Phi_\tau^{[n]} K^{[n]} \right) d\tau \right\rangle \\ K^{[0]} &= \langle f \rangle, \quad K^{[n+1]} = \langle f \circ \Phi^{[n+1]} \rangle. \end{aligned}$$

A free derivative recursive formula

- Computing the explicit form of $\partial_u \Phi_\theta^{[n]}$ becomes very complicated for large k as it involves high-order derivatives of $f_\theta(u)$. Necessity to have at our disposal the derivatives of f_θ
- To overcome this, we replace the derivatives $\partial_u g$ by the following

$$D_\eta g(u) = \frac{1}{\eta} (g(u + \eta v) - g(u)), \quad \eta = \varepsilon^n,$$

and get the following iterative scheme ,

$$\begin{aligned} \tilde{\Phi}_\theta^{[0]} = \text{id}, \quad \tilde{\Phi}_\theta^{[n+1]} = \text{id} + \varepsilon \int_0^\theta \left(f_\tau \circ \tilde{\Phi}_\tau^{[n]} - D_{\varepsilon^n} \tilde{\Phi}_\tau^{[n]} \tilde{K}^{[n]} \right) d\tau \\ - \varepsilon \left\langle \int_0^\theta \left(f_\tau \circ \tilde{\Phi}_\tau^{[n]} - D_{\varepsilon^n} \tilde{\Phi}_\tau^{[n]} \tilde{K}^{[n]} \right) d\tau \right\rangle \end{aligned}$$

$$\tilde{K}^{[0]} = \langle f \rangle \quad \tilde{K}^{[n+1]} = \langle f \circ \tilde{\Phi}^{[n+1]} \rangle.$$

- Note that $\tilde{\Phi}_\theta^{[0]} = \Phi_\theta^{[0]}$ and $\tilde{\Phi}_\theta^{[1]} = \Phi_\theta^{[1]}$.
- Online code in a Julia package : YVES MOCQUARD, PIERRE NAVARO ET N. CROUSEILLES :
<https://github.com/ymocquar/HOODESolver.jl>

Conclusion

- Several strategies based on averaging techniques have been briefly presented : they provide uniformly accurate (UA) schemes for highly oscillatory models.
- Usual averaging techniques do not work in the case of vanishing frequency : the fast and the slow variable strongly interact in the asymptotics. Stationary-phase like computations are needed.
- **Systematic derivation** and **structure** of asymptotic models in this case is **an open question**.
- This a first step towards the development of efficient methods for more "realistic" quantum-kinetic models: **quantum transition rates in 2D graphene for example**.
- Other applications in Fluid Mechanics : **rotating fluids, vibrating traps or bubbles**
...

THANK YOU FOR YOUR ATTENTION