

Asymptotic preserving scheme for Lévy Fokker Planck equation with fractional diffusion limit

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Kinetic equations: from modeling computation to analysis

Centre International de Rencontres Mathématiques

March 22–26, 2021

Joint with **Wuzhe Xu**

Outline

- 1 Introduction
- 2 Numerical methods
- 3 Numerical examples
- 4 Conclusion

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Lévy Fokker Planck equation

$$\begin{cases} \partial_t f + v \cdot \nabla_x f = \underbrace{\nabla_v \cdot (vf) - (-\Delta_v)^s f}_{:= \mathcal{L}^s(f)}, & s \in (0, 1), \\ f(0, x, v) = f_{in}(x, v), \end{cases}$$

- fractional Laplacian:

$$(-\Delta_v)^s f(v) := C_{s,d} \text{P.V.} \int_{\mathbb{R}^d} \frac{f(v) - f(w)}{|v - w|^{d+2s}} dw, \quad C_{s,d} = \frac{4^s \Gamma(d/2 + s)}{\pi^{d/2} |\Gamma(-s)|}$$

$$(-\Delta_v)^s f(v) := \mathcal{F} [|k|^{2s} \mathcal{F}[f](k)] (v)$$

- $s = 1$ reduces to the classical Fokker-Planck operator
- application: nonlocal effect in plasma turbulence

Properties of \mathcal{L}^s

- conservation of mass
- equilibrium

$$\mathcal{L}^s(\mathcal{M}) = 0, \quad \int_{\mathbb{R}^d} \mathcal{M}(v) dv = 1, \quad \mathcal{M}(v) \sim \frac{C_0}{|v|^{d+2s}} \text{ as } |v| \rightarrow \infty.$$

- entropy dissipation: $\partial_t f = \mathcal{L}^s f$ ¹

$$G_{\mathcal{M}}^{\Phi}(f) := \int_{\mathbb{R}^d} \Phi(f) \mathcal{M} dv - \Phi \left(\int_{\mathbb{R}^d} f \mathcal{M} dv \right)$$

$$E_{\Phi}(t) = G_{\mathcal{M}}^{\Phi} \left(\frac{f}{\mathcal{M}} \right), \quad E_{\Phi}(t) \leq e^{-\frac{t}{c}} E_{\Phi}(0), \quad t \geq 0$$

¹Gentil, Imbert, Asymptotic Analysis 2008.

Fractional diffusion limit

$$x \mapsto \varepsilon x, \quad t \mapsto \varepsilon^{2s} t$$

$$\begin{cases} \varepsilon^{2s} \partial_t f^\varepsilon + \varepsilon v \cdot \nabla_x f^\varepsilon = \nabla_v \cdot (v f^\varepsilon) - (-\Delta_v)^s f^\varepsilon, \\ f^\varepsilon(0, x, v) = f_{in}(x, v). \end{cases}$$

Q: why anomalous scaling?

$$\varepsilon^2 \partial_t f^\varepsilon + \varepsilon v \cdot \nabla_x f^\varepsilon = \nabla_v \cdot (v f^\varepsilon) + \Delta_v f^\varepsilon$$

$$\varepsilon \rightarrow 0 \implies f \rightarrow \rho e^{-\frac{|v|^2}{2}}$$

$$\int_{\mathbb{R}^N} dv \implies \partial_t \rho + \frac{1}{\varepsilon} \nabla_x \cdot j = 0$$

$$\int_{\mathbb{R}^N} v \cdot dv \implies \varepsilon \partial_t j + \nabla_x \cdot \int_{\mathbb{R}^N} v \otimes v f dv = -\frac{1}{\varepsilon} j$$

$$\implies \partial_t \rho + \nabla_x \cdot (D \nabla_x \rho) = 0, \quad D = \int v \otimes v e^{-\frac{|v|^2}{2}} dv$$

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Theorem (Cesbron, Mellet, Trivisa 2012)

Assume that $f_0 \in L^2(\mathbb{R}^N, \mathcal{M}(v)^{-1} dv dx)$, where $\mathcal{M}(v)$ is the unique normalized equilibrium distribution. Then, up to a subsequence, the solution f^ε converges weakly in $L^\infty(0, T; L^2(\mathbb{R}^{2d}, \mathcal{M}(v)^{-1} dv dx))$ to $\rho(t, x) \mathcal{M}(v)$ as $\varepsilon \rightarrow 0$, where $\rho(t, x)$ solves

$$\begin{cases} \partial_t \rho + (-\Delta_x)^s \rho = 0, \\ \rho(0, x) = \rho_{in}(x) := \int_{\mathbb{R}^d} f_{in}(x, v) dv. \end{cases}$$

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- $f^\varepsilon(t, x, v) \rightharpoonup \rho(t, x) \mathcal{M}(v)$ weakly in $L^2_{\mathcal{M}^{-1}}(\mathbb{R}^N \times (0, \infty))$, $\rho = \int f dv$
- consider a test function $\phi(t, x, v) = \varphi(t, x + \varepsilon v)$

$$\begin{aligned} \int f^\varepsilon [\varepsilon^{2s} \partial_t \phi + \varepsilon v \cdot \nabla_x \phi - v \cdot \nabla_v \phi + (-\Delta_v)^s \phi] dx dv dt \\ + \varepsilon^{2s} \int f_0(x, v) \phi(0, x, v) dx dv = 0 \end{aligned}$$

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$$\int f^\varepsilon \left[\varepsilon^{2s} \partial_t \varphi + \underbrace{\varepsilon v \cdot \nabla_x \varphi - v \cdot \nabla_v \varphi}_{=0} + \underbrace{(-\Delta_v)^s \phi}_{\varepsilon^{2s} (-\Delta_x)^s \varphi} \right] dx dv dt$$

$$+ \varepsilon^{2s} \int f_0(x, v) \phi(0, x, v) dx dv = 0$$

$$\implies \int f^\varepsilon [\partial_t \varphi + (-\Delta_x)^s \varphi] dx dv dt + \int f_0(x, v) \varphi(0, x + \varepsilon v) dx dv = 0$$

$$\xrightarrow{\varepsilon \rightarrow 0} \int \rho(t, x) [\partial_t \varphi + (-\Delta_x)^s \varphi](t, x) dx dt + \int \rho_0(x) \varphi(0, x) dx = 0$$

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Numerical challenges

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$$\begin{cases} \partial_t \rho + (-\Delta_x)^s \rho = 0 \\ \rho(0, x) = \int f_{in}(x, v) dv \end{cases}$$

- Nonlocality $(-\Delta_v)^s \frac{1}{|v|^{d+2s}}$
 - finite difference/finite element + domain truncation
[Huang, Oberman, 2014] [Zhang, Deng, Karniadakis, 2018]
 - spectral method
[Mao, Shen, 2017] *Hermite polynomial*
[Cayama, Cuesta, Hoz, 2019] *mapped Chebyshev polynomial*
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Computation of $(-\Delta_v)^s$

[Cayama, Cuesta, Hoz, 2019]

- mapping $v \mapsto \xi$

$$\xi = \frac{v}{\sqrt{L_v^2 + v^2}} \in (-1, 1) \iff v = \frac{L_v \xi}{\sqrt{1 - \xi^2}} \in (-\infty, \infty),$$

- Chebyshev polynomials

$$T_k(\xi) = \cos(k \arccos(\xi)), \quad \xi \in [-1, 1]$$

- further change of variable $q = \arccos(\xi) \in [0, \pi]$

$$T_k(\xi) = \cos(kq)$$

- In the new variable q ($v = \frac{L_v \xi}{\sqrt{1 - \xi^2}} = L_v \cot(q)$)

$$(-\Delta_q)^s f(q) = \begin{cases} -\frac{1}{L_v \pi} \int_0^\pi \frac{f'(p)}{\cot(q) - \cot(p)} dp, & s = \frac{1}{2}, \\ \frac{C_{s,d}}{2L_v^{2s} s(1-2s)} \int_0^\pi \frac{\sin^2(p) f''(p) + 2 \sin(p) \cos(p) f'(p)}{|\cot(q) - \cot(p)|^{2s-1}} dp, & s \neq \frac{1}{2}. \end{cases}$$

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Computation of $(-\Delta_v)^s$

- even extension

$$\tilde{f}(q) = \begin{cases} f(q), & q \in [0, \pi] \\ f(2\pi - q), & q \in [\pi, 2\pi] \end{cases}$$

- discrete Fourier transform

$$f(q_j) = \sum_{k=-N_v}^{N_v-1} \hat{f}_k e^{ikq_j}, \quad q_j = \frac{\pi(2j+1)}{2N_v}, \quad 0 \leq j \leq N_v - 1$$

- compute $(-\Delta_v)^s f$

$$(-\Delta_q)^s f(q_j) = \sum_{k=-N_v}^{N_v-1} \hat{f}_k (-\Delta_q)^s e^{ikq_j}, \quad j = 0, \dots, 2N_v - 1.$$

- compute $(-\Delta_v)^s (e^{imq})$

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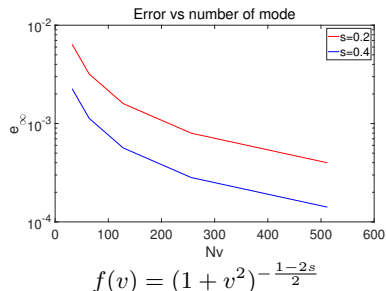
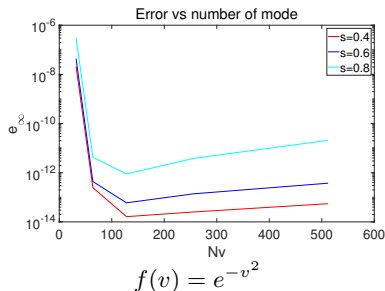
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Computation of \mathcal{L}^s

- Examples: $(-\Delta_v)^s f$

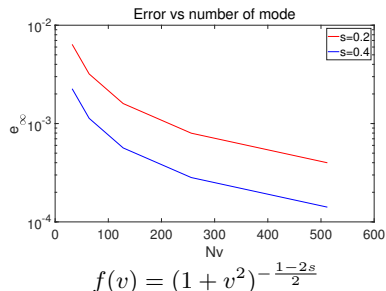
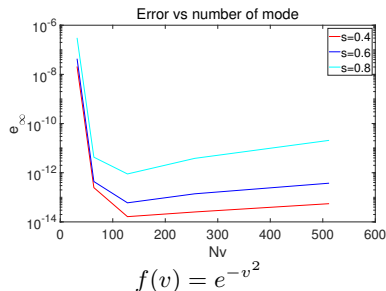


- \mathcal{L} in new variable q

$$\mathcal{L}_q^s(f) := f - \cos(q) \sin(q) \partial_q f - (-\Delta_q)^s f$$

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- Examples: $(-\Delta_v)^s f$



- \mathcal{L} in new variable q

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System decomposition

- Micro-macro decomposition

$$f(t, x, v) = \eta(t, x, v)\mathcal{M}(v) + g(t, x, v)$$

$$\eta(t, x, v) = h(t, x + \varepsilon v)$$

- Plug the decomposition to the equation

$$\begin{aligned} \varepsilon^{2s} \partial_t(\eta\mathcal{M} + g) + \varepsilon v \partial_x(\eta\mathcal{M} + g) &= \mathcal{L}^s(g) + \mathcal{L}^s(\eta\mathcal{M}) \\ &= \mathcal{L}^s(g) + v\mathcal{M} \cdot \partial_v \eta - \mathcal{M}(-\Delta_v)^s \eta - I(\eta, \mathcal{M}) + \eta \mathcal{L}^s(\mathcal{M}) \end{aligned}$$

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$$\begin{aligned} I(f, g) &= (-\Delta_v)^s(fg) - g(-\Delta_v)^s f - f(-\Delta_v)^s g \\ &= C_{1,s} \int_{\mathbb{R}^d} \frac{(f(v) - f(w))(g(w) - g(v))}{|v - w|^{d+2s}} dw. \end{aligned}$$

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- Split system

$$\begin{cases} \varepsilon^{2s} \partial_t g + \varepsilon v \partial_x g = \mathcal{L}^s(g) - I(\eta, \mathcal{M}), \\ \partial_t \eta = -(-\Delta_x)^s \eta, \end{cases}$$

- Initial data

$$\eta_{in}(x, v) = \rho_{in}(x + \varepsilon v) \quad g_{in}(x, v) = f_{in}(x, v) - \eta_{in}(x, v)\mathcal{M}(v).$$

System decomposition

- Micro-macro decomposition

$$f(t, x, v) = \eta(t, x, v)\mathcal{M}(v) + g(t, x, v)$$

$$\eta(t, x, v) = h(t, x + \varepsilon v)$$

- Plug the decomposition to the equation

$$\begin{aligned} \varepsilon^{2s} \partial_t(\eta\mathcal{M} + g) + \varepsilon v \partial_x(\eta\mathcal{M} + g) &= \mathcal{L}^s(g) + \mathcal{L}^s(\eta\mathcal{M}) \\ &= \mathcal{L}^s(g) + v\mathcal{M} \cdot \partial_v \eta - \underbrace{\mathcal{M}(-\Delta_v)^s \eta}_{\varepsilon^{2s} \mathcal{M}(-\Delta_x)^s \eta} - I(\eta, \mathcal{M}) + \underbrace{\eta \mathcal{L}^s(\mathcal{M})}_{=0} \\ \varepsilon^{2s} \partial_t(\eta\mathcal{M} + g) + \varepsilon v \partial_x g &= \mathcal{L}^s(g) - \varepsilon^{2s} (-\Delta_x)^s \eta \mathcal{M} - I(\eta, \mathcal{M}) \end{aligned}$$

- Split system

$$\begin{cases} \varepsilon^{2s} \partial_t g + \varepsilon v \partial_x g = \mathcal{L}^s(g) - I(\eta, \mathcal{M}), \\ \partial_t \eta = -(-\Delta_x)^s \eta, \end{cases}$$

- Initial data

$$\eta_{in}(x, v) = \rho_{in}(x + \varepsilon v) \quad g_{in}(x, v) = f_{in}(x, v) - \eta_{in}(x, v)\mathcal{M}(v).$$

System decomposition

- Micro-macro decomposition

$$f(t, x, v) = \eta(t, x, v)\mathcal{M}(v) + g(t, x, v)$$

$$\eta(t, x, v) = h(t, x + \varepsilon v)$$

- Plug the decomposition to the equation

$$\begin{aligned} \varepsilon^{2s} \partial_t(\eta\mathcal{M} + g) + \varepsilon v \partial_x(\eta\mathcal{M} + g) &= \mathcal{L}^s(g) + \mathcal{L}^s(\eta\mathcal{M}) \\ &= \mathcal{L}^s(g) + v\mathcal{M} \cdot \partial_v \eta - \underbrace{\mathcal{M}(-\Delta_v)^s \eta}_{\varepsilon^{2s} \mathcal{M}(-\Delta_x)^s \eta} - I(\eta, \mathcal{M}) + \underbrace{\eta \mathcal{L}^s(\mathcal{M})}_{=0} \\ \varepsilon^{2s} \partial_t(\eta\mathcal{M} + g) + \varepsilon v \partial_x g &= \mathcal{L}^s(g) - \varepsilon^{2s} (-\Delta_x)^s \eta \mathcal{M} - I(\eta, \mathcal{M}) \end{aligned}$$

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Energy stability

Proposition

If (η, g) solves split system, then $f = \eta\mathcal{M} + g$ solves the original equation. Both system has the energy dissipation property. That is, define the total energy

$$E_f^2 = \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{f^2}{\mathcal{M}} dv dx = \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{(\eta\mathcal{M} + g)^2}{\mathcal{M}} dv dx,$$

then $\frac{dE_f}{dt} \leq 0$.

Proposition

$$E_\eta^2 = \int_{\mathbb{R}} \int_{\mathbb{R}} \eta^2 \mathcal{M} dx dv, \quad E_g^2 = \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{g^2}{\mathcal{M}} dx dv$$

are both uniformly bounded in time.

Semi-discrete scheme

To solve

$$\begin{cases} \varepsilon^{2s} \partial_t g + \varepsilon v \partial_x g = \mathcal{L}^s(g) - I(\eta, \mathcal{M}) \\ \partial_t \eta = -(-\Delta_x)^s \eta \end{cases}$$

we propose

$$\begin{cases} \frac{\varepsilon^{2s}}{\Delta t} (g^* - g^n) = \mathcal{L}^s(g^*) - \gamma g^* - I(\eta^n, \mathcal{M}) \\ \frac{\varepsilon^{2s}}{\Delta t} (g^{n+1} - g^*) + \varepsilon v \partial_x g^{n+1} = \gamma g^{n+1} \\ \frac{1}{\Delta t} (\eta^{n+1} - \eta^n) = -(-\Delta_x)^s \eta^n \end{cases}$$

Compare to $\frac{\varepsilon^{2s}}{\Delta t} (g^{n+1} - g^n) + \varepsilon v \partial_x g^{n+1} = \mathcal{L}^s(g^{n+1}) - I(\eta^n, \mathcal{M})$

- alleviate ill-conditioning

	$Cond(A_0)$	$Cond(A_{\frac{1}{2}})$	$Cond(A_1)$
$s = 0.4, \varepsilon = 1$	4.73	4.54	4.36
$s = 0.6, \varepsilon = 1$	4.93	4.73	4.55
$s = 0.8, \varepsilon = 1$	13.28	12.66	12.11
$s = 0.4, \varepsilon = 1e-3$	7.74e3	158	52
$s = 0.6, \varepsilon = 1e-3$	1.24e5	187.42	63.44
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$s = 0.4, \varepsilon = 1e-5$	3.57e5	181.66	55.84
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- alleviate ill-conditioning
- reduce computational cost
- asymptotic property

Semi-discrete scheme

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AP property

Proposition

The numerical solution $\rho^n = \langle f^n \rangle = \langle \eta^n \mathcal{M} + g^n \rangle$ satisfies

$$\frac{\rho^{n+1} - \rho^n}{\Delta t} = (-\Delta_x)^s \rho^n, \quad \text{as } \varepsilon \rightarrow 0.$$

- From the reconstruction formula

$$\begin{aligned} \frac{\rho^{n+1} - \rho^n}{\Delta t} &= \left\langle \frac{\eta^{n+1} - \eta^n}{\Delta t} \mathcal{M} \right\rangle + \left\langle \frac{g^{n+1} - g^n}{\Delta t} \right\rangle \\ &= - \langle (-\Delta_x)^s \eta^n \mathcal{M} \rangle + \left\langle \frac{g^{n+1} - g^n}{\Delta t} \right\rangle \\ &= (-\Delta_x)^s \langle f^n - g^n \rangle + \left\langle \frac{g^{n+1} - g^n}{\Delta t} \right\rangle \\ &= (-\Delta_x)^s \rho^n - (-\Delta_x)^s \langle g^n \rangle + \left\langle \frac{g^{n+1} - g^n}{\Delta t} \right\rangle \end{aligned}$$

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- $\left(\frac{\varepsilon^{2s}}{\Delta t} + \gamma + \mathcal{L}^s \right) g^* = \frac{\varepsilon^{2s}}{\Delta t} g^n - I(\eta^n, \mathcal{M})$
 $\|g^*(x, \cdot)\|_{L_v^\infty} \lesssim \|I(\eta^n, \mathcal{M})\|_{L_v^\infty} + \frac{\varepsilon^{2s}}{\Delta t} \|g^n\|_{L_v^\infty}$
- $\frac{\varepsilon^{2s}}{\Delta t} (g^{n+1} - g^*) + \varepsilon v \partial_x g^{n+1} = \gamma g^{n+1}$
 $|g^{n+1}(x, v)| \leq \frac{2\varepsilon^{2s}}{\Delta t} \|g^*(\cdot, v)\|_{L_x^\infty}$

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Long time behavior

$$\partial_t f = \partial_v(vf) - (-\Delta_v)^s f, \quad f(0, v) = e^{-v^2}$$

$$s = 0.5, \quad \mathcal{M}(v) = \pi^{-0.5}(1+v^2)^{-1}:$$

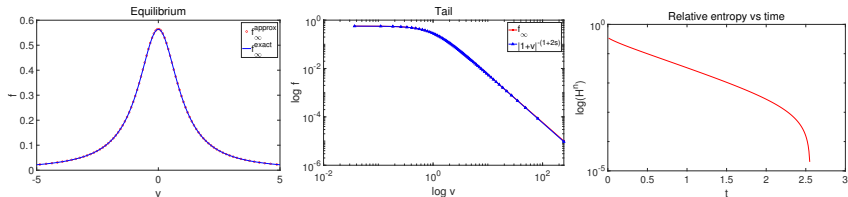


Figure: Here $\Delta t = 0.01$ and $N_v = 128$

Long time behavior

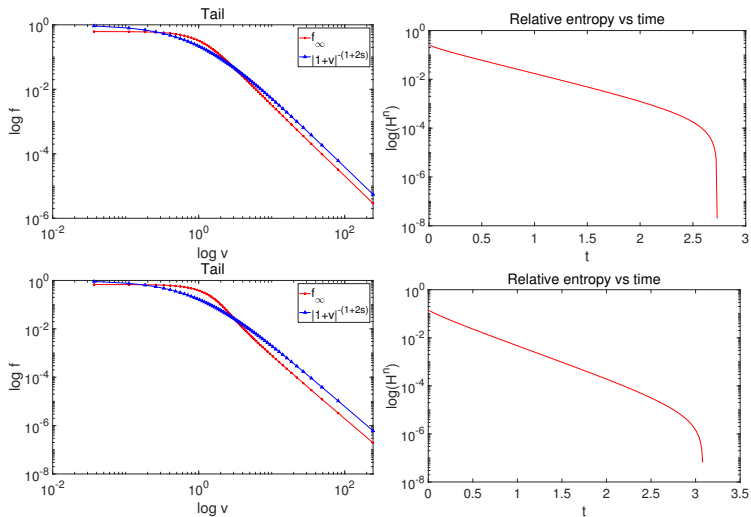


Figure: Here use $N_v = 128$, $\Delta t = 0.01$. top: $s = 0.6$. bottom: $s = 0.8$.

Uniform accuracy in time

$$\begin{cases} \partial_t f + v \cdot \nabla_x f = \nabla_v \cdot (vf) - (-\Delta_v)^s f := \mathcal{L}^s(f), & s \in (0, 1) \\ f(0, x, v) = \pi^{-0.5} e^{-15x^2} e^{-v^2}, & x \in [-5, 5] \end{cases}$$

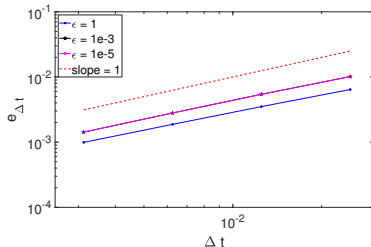
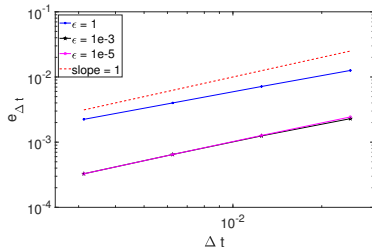


Figure: Convergence test for $s = 0.4$ (left) and $s = 0.8$ (right). $L_x = 5$, $N_x = 200$, $L_v = 3$ and $N_v = 128$, $\Delta t = 0.025, 0.0125, 0.00625, 0.003125, 0.0015625$.

Stability

$$E_f = \sum_{i=1}^{N_x} \sum_{j=1}^{N_v} \frac{f_{i,j}^2}{\mathcal{M}_j} w_j \Delta q \Delta x, \quad w_j = \frac{L_v}{(\sin(q_j))^2}$$

$$E_g = \sum_{i=1}^{N_x} \sum_{j=1}^{N_v} \frac{g_{i,j}^2}{\mathcal{M}_j} w_j \Delta q \Delta x, \quad E_\eta = \sum_{i=1}^{N_x} \sum_{j=1}^{N_v} \eta_{i,j}^2 \mathcal{M}_j w_j \Delta q \Delta x.$$

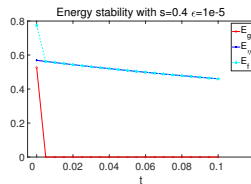
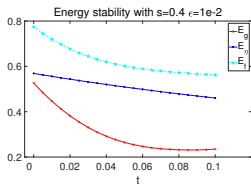
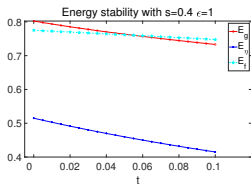


Figure: $L_x = 5$, $L_v = 3$, $N_x = 100$, $N_v = 128$, $\Delta t = 0.01$.

Kinetic regime

Reference solution:

$$\begin{cases} \frac{f^* - f^n}{\Delta t} + v \partial_x f^n = 0, \\ \frac{f^{n+1} - f^*}{\Delta t} = \partial_v (v f^{n+1}) - (-\Delta_v)^s f^{n+1}. \end{cases}$$

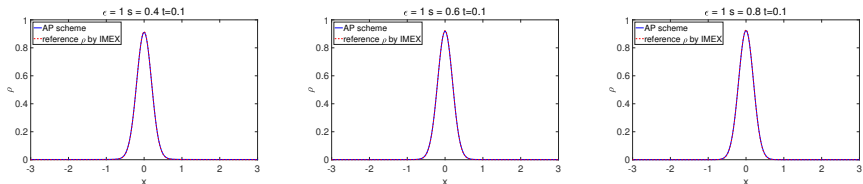


Figure: For our AP scheme, $N_x = 200$, $N_v = 128$, $\Delta t = 0.01$. For reference solution, $N_x = 800$, $N_v = 256$, $\Delta t = 1e - 4$.

Diffusive regime

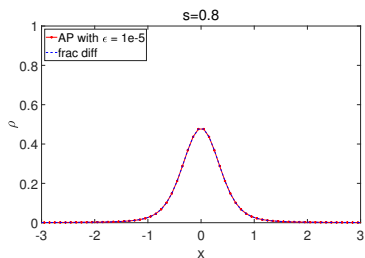
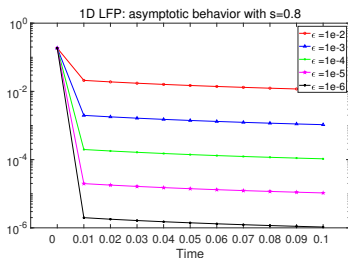
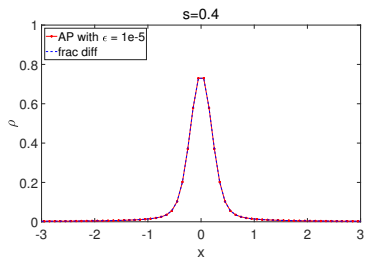
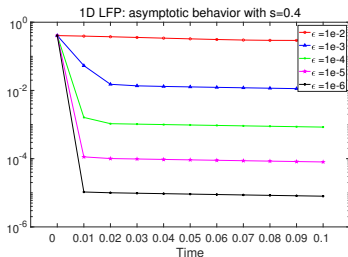


Figure: $T = 0.1$, $N_x = 100$, $\Delta t = 0.01$, $N_v = 128$.

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We have developed an *asymptotic preserving* scheme for Lévy Fokker Planck equation with *fractional* diffusion limit.

Key ideas:

- spectral method with nonlocal basis
- a new macro-micro decomposition
- an operator splitting

Thank you!

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