Christian Klingenberg

Mathematics Dept., Würzburg University, Germany

An inverse problem for a model of cell motion and chemotaxis



An inverse problem for a model of cell motion and chemotaxis Christian Klingenberg Mathematics Dept., Würzburg University, Germany jointly with: Kathrin Hellmuth Würzburg University, Germany Ru-yu Lai Univ. of Wisc. in Madison, USA Qin Li Marlies Pirner Würzburg University, Germany Min Tang Shanghai Jiao Tong Univ., China

- Univ. of Minnesota, Minneapolis, USA

  - and others

### I will now describing the context of this topic













 $10^{-2}$  m

kinetic equations Boltzmann-type equations mesoscopic description



![](_page_9_Figure_1.jpeg)

time

scale

### **Microscopic description**

System of N interacting particles Newton's equations

![](_page_10_Figure_1.jpeg)

### **Mesoscopic description**

Large system of particles with negligible size **Boltzmann's kinetic equation** 

![](_page_11_Figure_1.jpeg)

![](_page_11_Figure_3.jpeg)

Continuous fluid Equations of hydrodynamics (Euler, Navier-Stokes...)

 $T_{collision} << T_{observation}$ Fast relaxation limit

### **Mesoscopic description**

Large system of particles with negligible size **Boltzmann's kinetic equation** 

![](_page_11_Picture_9.jpeg)

![](_page_12_Figure_1.jpeg)

Laure

![](_page_13_Figure_1.jpeg)

### we shall focus on

![](_page_14_Figure_1.jpeg)

### kinetic neutron transport equation:

### example

 $\partial_t f + \frac{1}{\varepsilon} v \cdot \nabla_x f = \frac{\sigma_T}{\varepsilon^2} \left( \frac{1}{2} \int_{-1}^1 f dv' - f \right)$ 

### kinetic neutron transport equation:

 $\partial_t f + \frac{1}{\varepsilon} v \cdot \nabla_x f = \frac{\sigma_T}{\varepsilon^2} \left(\frac{1}{2} \int_{-1}^1 f dv' - f\right)$ 
$$\begin{split} \epsilon &\to 0 \\ \text{macroscopic diffusion equ } \epsilon \partial_t f(v) + v \partial_x f(v) = \frac{\sigma(x,z)}{\epsilon} \left[ \frac{1}{2} \int_{-1}^1 f(v') \, dv' - f(v) \right] \\ \end{split}$$
 $\overset{\sigma(x,z)}{\rho_t} = \partial_x \left( \frac{1}{3\sigma_T} \partial_x \rho \right)$ 

![](_page_16_Picture_3.jpeg)

### example

with  $\rho(t,x) = \frac{1}{2} \int_{-1}^{1} f(v') dv'$ 

![](_page_16_Picture_7.jpeg)

![](_page_16_Picture_8.jpeg)

### kinetic neutron transport equation:

 $\partial_t f + \frac{1}{\varepsilon} v \cdot \nabla_x f = \frac{\sigma_T}{\varepsilon^2} \left(\frac{1}{2} \int_{-1}^1 f dv' - f\right)$ 
$$\begin{split} \epsilon &\to 0 \\ \text{macroscopic diffusion equ } \epsilon \partial_t f(v) + v \partial_x f(v) = \frac{\sigma(x,z)}{\epsilon} \left[ \frac{1}{2} \int_{-1}^1 f(v') \, dv' - f(v) \right] \\ \end{split}$$
equ  $\sigma(x,z) = \partial_x \left(\frac{1}{3\sigma_T}\partial_x \rho\right)$ 

![](_page_17_Picture_3.jpeg)

### example

with  $\rho(t,x) = \frac{1}{2} \int_{-1}^{1} f(v') dv'$ 

![](_page_17_Picture_7.jpeg)

![](_page_17_Picture_8.jpeg)

one would like to prove well-posedness of this solution  $f_{\epsilon}$ 

![](_page_18_Picture_3.jpeg)

one would like to prove well-posedness of this solution  $f_{e}$ 

$$\partial_t f + \frac{1}{\varepsilon} v \cdot \nabla_x f =$$

 $=\frac{\sigma_T}{\varepsilon^2}\left(\frac{1}{2}\int_{-1}^{1}fdv'-f\right)$ 

![](_page_19_Picture_5.jpeg)

one would like to prove well-posedness of this solution  $f_{e}$ 

given the corresponding PDE model at the macroscopic level with given initial and boundary data

one would like to prove well-posedness of this solution  $\rho$ 

one would like to prove well-posedness of this solution  $f_{e}$ 

given the corresponding PDE model at the macroscopic level with given initial and boundary data

one would like to prove well-posedness of this solution  $\rho$ 

 $\rho_t = \partial_x \left( \frac{\partial_x \rho}{3\sigma_T} \right)$ 

given a PDE model at the *mesoscopic* level with given initial and boundary data

one would like to prove well-posedness of this solution  $f_{e}$ 

given the corresponding PDE model at the macroscopic level with given initial and boundary data

one would like to prove well-posedness of this solution  $\rho$ 

finally one would like to prove convergence under the appropriate scaling (  $f_{\epsilon}dv \rightarrow \rho$  )

## rigorous proof of this limit is difficult

![](_page_23_Figure_1.jpeg)

 $\partial_t(\varrho v) + \operatorname{div}_x(\varrho v)$ 

there are huge difficulties in showing well-posedness of the 2-d compressible Euler equations

$$\partial_t \varrho + \operatorname{div}_x(\varrho v) = 0$$
  
 $\otimes v) + \nabla_x [p(\varrho)] = 0$ 

### consider this initial value problem in 2 space dimensions

![](_page_25_Picture_1.jpeg)

![](_page_25_Picture_2.jpeg)

### Two shocks

# for example: Standard solution consists of just one shock

![](_page_26_Figure_1.jpeg)

 $ho_+, V_+$ 

- X<sub>2</sub>

![](_page_27_Picture_1.jpeg)

Klingenberg, Simon Markfelder: "The Riemann problem for the multidimensional isentropic system of gas dynamics is ill-posed if it contains a shock" Archive for Rational Mechanics and Analysis (2018)

in addition to the standard solution there are many "wild solutions"

X

### const.

![](_page_27_Picture_6.jpeg)

![](_page_27_Picture_7.jpeg)

### this is the standard solution

Ī

![](_page_28_Picture_1.jpeg)

const.

### Riemann data

X

![](_page_29_Picture_1.jpeg)

### all of these many solutions are entropy solutions

E. Feireisl; C. Klingenberg; S. Markfelder, "On the density of 'wild' initial data for the compressible Euler system", Calculus of Variations (2020)

Riemann data

![](_page_29_Picture_6.jpeg)

as long as we don't know well-posedness of the limit of Boltzmann for  $\epsilon \to 0$  in the hyperbolic scaling (namely the Euler equations) it is difficult to prove this limit

### example of a well-posedness proof for a kinetic equation

### a *multi-species* kinetic model

$$\partial_t f_1 + v \cdot \nabla_x f_1 + \frac{F_1}{m_1} \cdot \nabla_v f_2$$
$$\partial_t f_2 + v \cdot \nabla_x f_2 + \frac{F_2}{m_2} \cdot \nabla_v f_2$$

# $f_1 = Q_{11}(f_1, f_1) + Q_{12}(f_1, f_2)$

 $f_2 = Q_{22}(f_2, f_2) + Q_{21}(f_2, f_1)$ 

modeled by **two** interaction terms

![](_page_32_Picture_5.jpeg)

### we use the BGK approximation

 $\partial_t f_1 + \nabla_x \cdot (vf_1) + \frac{F_1}{m_1} \nabla_v f_1 = \nu_{11} n_1 (M_1 - f_1) + \nu_{12} n_2 (M_{12} - f_1)$  $\partial_t f_2 + \nabla_x \cdot (vf_2) + \frac{F_2}{m_2} \nabla_v f_2 = \nu_{22} n_2 (M_2 - f_2) + \nu_{21} n_1 (M_{21} - f_2)$ 

we use the BGK approximation  $\partial_t f_1 + \nabla_x \cdot (vf_1) + \frac{F_1}{m_1} \nabla_v f_1 = \nu_{11} n_1 (M_1 - f_1) + \nu_{12} n_2 (M_{12} - f_1)$  $\partial_t f_2 + \nabla_x \cdot (vf_2) + \frac{F_2}{m_2} \nabla_v f_2 = \nu_{22} n_2 (M_2 - f_2) + \nu_{21} n_1 (M_{21} - f_2)$ 

![](_page_34_Figure_1.jpeg)

$$M_{12}(x,v,t) = \frac{n_{12}}{\sqrt{2\pi \frac{T_{12}}{m_1}^3}} \exp\left(-\frac{|v - u_{12}|^2}{2\frac{T_{12}}{m_1}}\right)$$

$$M_{21}(x,v,t) = \frac{n_{21}}{\sqrt{2\pi \frac{T_{21}}{m_2}^3}} \exp\left(-\frac{|v - u_{21}|^2}{2\frac{T_{21}}{m_2}}\right)$$

we use the BGK approximation  $\partial_t f_1 + \nabla_x \cdot (vf_1) + \frac{F_1}{m_1} \nabla_v f_1 =$  $\partial_t f_2 + \nabla_x \cdot (vf_2) + \frac{F_2}{m_2} \nabla_v f_2 =$ 

![](_page_35_Figure_1.jpeg)

- Klingenberg, C., Pirner, M., Puppo, G.: "A consistent kinetic model for a two component mixture with an application to plasma", Kinetic and Related Models Vol. 10, No. 2, pp. 445–465 (2017)

$$\nu_{11}n_1(M_1 - f_1) + \nu_{12}n_2(M_{12} - f_1)$$
$$\nu_{22}n_2(M_2 - f_2) + \nu_{21}n_1(M_{21} - f_2)$$

$$M_{12}(x,v,t) = \frac{n_{12}}{\sqrt{2\pi \frac{T_{12}}{m_1}^3}} \exp\left(-\frac{|v - u_{12}|^2}{2\frac{T_{12}}{m_1}}\right)$$
$$M_{21}(x,v,t) = \frac{n_{21}}{\sqrt{2\pi \frac{T_{21}}{m_2}^3}} \exp\left(-\frac{|v - u_{21}|^2}{2\frac{T_{21}}{m_2}}\right)$$

can determine these coefficients such that conservation properties, H-theorem holds

![](_page_35_Figure_7.jpeg)
#### we can show well-posedness of this model

$$\partial_t f_1 + \nabla_x \cdot (vf_1) + \frac{F_1}{m_1} \nabla_v f_1 = \\ \partial_t f_2 + \nabla_x \cdot (vf_2) + \frac{F_2}{m_2} \nabla_v f_2 =$$

- Klingenberg, C. & Pirner, M.: "Existence, Uniqueness and Positivity of solutions for BGK models for mixtures", Journal of Differential Equations, 264, pp. 207-227 (2019)

> $\nu_{11}n_1(M_1 - f_1) + \nu_{12}n_2(M_{12} - f_1)$  $\nu_{22}n_2(M_2 - f_2) + \nu_{21}n_1(M_{21} - f_2)$

#### next we consider uncertainties in the kinetic context

#### examples:

\_

## when deriving the collision kernel from measurements there might be uncertainties (with variable z):

 $\epsilon \partial_t f(v) + v \partial_x f(v) =$ 



$$= \frac{\sigma(x,z)}{\epsilon} \left[ \frac{1}{2} \int_{-1}^{1} f(v') dv' - f(v) \right]$$

#### next we consider uncertainties in the kinetic context

# examples:

 $\epsilon \partial_t f(v) + v \partial_x f(v) =$ 

-----



when deriving the collision kernel from measurements there might be uncertainties (with variable z):

$$= \frac{\sigma(x,z)}{\epsilon} \left[ \frac{1}{2} \int_{-1}^{1} f(v') dv' - f(v) \right]$$

the measurements of the initial and boundary data might be uncertain

 $\epsilon \partial_t f(v) + v \partial_x f(v) = \frac{\sigma(x, z)}{\epsilon} \left[ \frac{1}{2} \int_{-1}^1 f(v') \, dv' - f(v) \right]_{\text{text}}$ 

 $\sigma(x,z)$ 

#### examples:

#### - the diffusivity coefficient my be known only with uncertainty

 $\rho(t,x)$ 



 $\epsilon \partial_t f(v) + v \partial_x f(v) = \frac{\partial(w, z)}{\epsilon} \left[ \frac{1}{2} \int_{-1}^{1} f(v') dv' - f(v) \right]$ 

 $\sigma(x,z)$ nere coulo also pe uncertainties in the hulo context

### examples: $\rho(t,x)$ the diffusivity coefficient my be known only with uncertainty — $\rho_t = \partial_x \left| \frac{1}{3\sigma(x,z)} \partial_x \rho \right|$

## 



the measurements of the initial and boundary data might be uncertain



#### numerics of uncertainties in the kinetic context

generalized polynomial chaos stochastic Galerkin method (gPC)



- we consider a set of orthonorr space of random functions

### - we consider a set of orthonormal basis function $\{\phi_j(z)\}$ for the

we consider a set of orthonorr
space of random functions

- we expand the functions into a Fourier series w.r.t. this basis  $f(z) = \Sigma f_j \phi_j(z)$ 

### - we consider a set of orthonormal basis function $\{\phi_j(z)\}$ for the

space of random functions

- we expand the functions into a Fourier series w.r.t. this basis

- truncate this series

- substitute into the stochastic system to obtain a deterministic system for the first N gPC coefficients

### - we consider a set of orthonormal basis function $\{\phi_i(z)\}$ for the

## $f(z) = \sum f_j \phi_j(z)$

#### one would like to show accuracy of the gPC method

#### one would like to show accuracy of the gPC method

for this one checks the boundedness or the decay in time of the derivatives

#### one would like to show accuracy of the gPC method

for this one checks the boundedness or the decay in time of the derivatives

this can be deduced from hypocoercivity

 $\partial_t f + v \partial_x f = \sigma(z) \left( \mathcal{M} - f \right)$ 

#### one attempts to prove decay in time for f and its derivatives

 $\partial_t f + v \partial_x f = \sigma(z) \left( \mathcal{M} - f \right)$ 

one attempts to prove decay in time for f and its derivatives

Li, Q., & Wang, L. Uniform regularity for linear kinetic equations with random input based on hypocoercivity. SIAM/ASA Journal on Uncertainty Quantification, 5(1), (2017)

 $\partial_t f + v \partial_x f = \sigma(z) \left( \mathcal{M} - f \right)$ 

#### for the linearized BGK equation decay in f has been done in



#### for the linearized BGK equation decay in f has been done in

Li, Q., & Wang, L. Uniform regularity for linear kinetic equations with random input based on hypocoercivity. SIAM/ASA Journal on Uncertainty Quantification, 5(1), (2017)

#### we generalize this result and show decay for all derivatives in z by using Liapunov techniques from

Franz Achleitner, Anton Arnold, and Eric A. Carlen. On multi-dimensional hypocoerciv BGK models. Kinetic & Related Models, 11(4), (2018)

 $\partial_t f + v \partial_x f = \sigma(z) \left( \mathcal{M} - f \right)$ 

one attempts to prove decay in time for f and its derivatives



### write $f = \mathcal{M} + \epsilon h$

## write $f = \mathcal{M} + \epsilon h$ substituting gives

### $\partial_t h + v \partial_x h = \sigma(z)(\mathcal{M} - h)$

h = h(t, x, v, z)

## write $f = \mathcal{M} + \epsilon h$ substituting gives $\partial_t h + v \partial_x h = \sigma(z)(\mathcal{M} - h)$

we can show

#### $\|\partial_z^l h\| \leq Ce^{-\lambda t}$ $l \in \mathcal{N}$

Herzing, T., Klingenberg, C., Pirner, M.: "Hypocoercivity of the linearized BGK-equation with stochastic coefficients", submitted (2021)

h = h(t, x, v, z)

Black-Scholes equation:

 $\frac{\partial V(S,t)}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V(S,t)}{\partial S^2} + rS \frac{\partial V(S,t)}{\partial S} - rV(S,t) = 0$ 



(time inverted) Black-Scholes equation: deterministic diffusion coefficient (volatility)

 $\frac{\partial V(S,t)}{\partial t} - \frac{1}{2} \frac{\sigma^2 S^2}{\sigma^2} \frac{\partial^2 V(S,t)}{\partial S^2} + rS \frac{\partial V(S,t)}{\partial S} - rV(S,t) = 0$ 



(time inverted) Black-Scholes equation:  $\frac{\partial V(S,t)}{\partial t} - \frac{1}{2} \frac{\sigma^2 S^2}{\delta S^2} \frac{\partial^2 V(S,t)}{\partial S^2} + rS \frac{\partial V(S,t)}{\partial S} - rV(S,t) = 0$ deterministic diffusion coefficient (volatility)  $\frac{\partial V(S,t,\Theta)}{\partial t} - \frac{1}{2} \Sigma(\Theta)^2 S^2 \frac{\partial^2 V(S,t,\Theta)}{\partial S^2} + rS \frac{\partial V(S,t,\Theta)}{\partial S} - rV(S,t,\Theta) = 0$ stochastic diffusion coefficient (volatility)





#### in financial applications the diffusion coefficient depends on finitely many stochastic variables

 $\Sigma(\Theta_1, ..., \Theta_L)$ 



#### the stochastic Galerkin approach is computationally costly

in financial applications the diffusion coefficient depends on finitely many stochastic variables

 $\Sigma(\Theta_1, ..., \Theta_L)$ 



the stochastic Galerkin approach is computationally costly

hence we improve computational efficiency using a machine learning (bi-fidelity) approach

L. Liu and X. Zhu, A bi-fidelity method for the multiscale Boltzmann equation with random parameters, Journal of Computational Physics 402 (2020)

in financial applications the diffusion coefficient depends on finitely many stochastic variables

 $\Sigma(\Theta_1, ..., \Theta_L)$ 







Comparing the stochastic Black-Scholes model to real market data

Hellmuth, K., Klingenberg, C.: "Computing Black Scholes with uncertain volatility - a machine learning approach, manuscript (2021)



in the forward problem we are given a collision kernel and study the effect of this on the solution

in the forward problem we are given a collision kernel and study the effect of this on the solution

But there are situations where the parameters of the collision kernel needs to be inferred from the solution



in the forward problem we are given a collision kernel and study the effect of this on the solution

But there are situations where the parameters of the collision kernel needs to be inferred from the solution

given (parts of) the solution to the kinetic problem, find the coefficients



in the forward problem we are given a collision kernel and study the effect of this on the solution

But there are situations where the parameters of the collision kernel needs to be inferred from the solution

given (parts of) the solution to the kinetic problem, find the coefficients

this is the inverse problem for kinetic equations



#### we shall illustrate this

#### radiative transfer equation

$$\partial_t u + \theta \cdot \nabla_x u = -\mu u + \int_{\mathbb{S}^{n-1}} \Phi(\theta', \theta) u(t, x, \theta') \, d\theta' + \sigma$$
$$\partial_t T = \Delta_x T - \sigma T^4 + \mu \frac{1}{|\mathbb{S}^{n-1}|} \int_{\mathbb{S}^{n-1}} u(t, x, \theta) \, d\theta \,,$$

 $u \equiv u(t, x, \theta)$  describes the radiation intensity T is the temperature  $\mu \equiv \mu(x)$  is a given absorption coefficient  $\sigma$  given emission coefficient

 $\Phi(\theta', \theta)$  given kernel, describing scattering of photons






# forward problem

# solve u and T inside the body

- with given values u and T on the boundary,



# - the kernel $\Phi( heta', heta)$ , emission $m{\sigma}$ and absorbtion $\mu$ are known



### inverse problem

reconstruct emission coefficient  $\sigma$ 

- given the incoming data  $u_{|\Gamma_-}$
- given the outgoing measurement  $u_{|\Gamma_{\perp}}$

- given the kernel  $\Phi(\theta', \theta)$ , and absorption  $\mu$ - temperature **T** is given on the whole boundary

# inverse problem



stationary case, set scattering  $\Phi = 0$ 

 $\theta \cdot \nabla_x u + \overset{\text{given}}{\mu} u = \sigma T^4 \quad \text{in } \Omega \times \mathbb{S}^{n-1}$ 

# we prove that the emission coefficient $\sigma$

- exists
- IS UNIQUE

Klingenberg, C., Lai, R., Li, Q.: "Reconstruction of the emission coefficient in the nonlinear radiative transfer equation", SIAM Journal on Applied Mathematics, Vol. 81, 1 (2021)

# - depends continuously on the data



### now consider the limit to the macroscopic equation

this (stationary) kinetic model in the parabolic scaling leads to an elliptic problem

# the related problem for the corresponding macroscopic fluid equation is ill-posed, similar to the Calderon problem

# $\nabla \cdot \sigma \nabla u = 0 \text{ in } \Omega,$ $u|_{\partial \Omega} = f.$

conductivity (in the kinetic case emission)  $\sigma$ 

Calderon problem: recover  $\sigma$  from knowledge of solution on the boundary





we propose to solve it by approximating the inverse problem via the kinetic equation





- we propose to solve it by approximating the inverse problem via the kinetic equation
  - so instead of a Tychonov regularization we suggest a "kinetic regularization"





- we propose to solve it by approximating the inverse problem via the kinetic equation
  - so instead of a Tychonov regularization we suggest a "kinetic regularization"

we will illustrate this for chemotaxis





# consider another kinetic model: chemotaxis

bacteria move by either "running" in a straight line and at random times rotating and the moving on



# consider another kinetic model: chemotaxis

# bacteria move by either "running" in a straight line and at random times rotating and the moving on

**Tumbling mode** 



Running mode



counter-clockwise rotation of flagella



electron microscope



# Chemotaxis

# these bacteria like to move in the direction of a chemical attractant





### chemotaxis



Chalub, F. A., Markowich, P. A., Perthame, B., & Schmeiser, C.: Kinetic models for chemotaxis and their drift-diffusion limits. In *Nonlinear Differential Equation Models, (2004)* 

B. Perthame, M. Tang, N. Vauchelet, Derivation of the bacterial run-and-tumble kinetic equation from a model with biochemical pathway Journal of Mathematical Biology, Vol. 73, No. 5, (2016)

$$-\int_{V} (T_{\varepsilon}^{*}[S]f - T_{\varepsilon}[S]f')dv'$$

$$\rho_{\varepsilon} = \int_{V} f_{\varepsilon} dv$$

$$f_{\varepsilon} = \frac{1}{4\pi} \int_{\mathbb{R}^{3}} \frac{\rho_{\varepsilon}(y,t)}{|x-y|} dy$$

om a

# one can consider the limit of this mesoscopic model to a macroscopic model, called Keller-Segel model

 $\nabla c = -\lambda_d \, \frac{x}{|x|^d} \star \varrho,$ 

# $\frac{\partial}{\partial t}\varrho - \Delta \varrho + \operatorname{div}(\varrho \chi \nabla c) = 0, \quad t \ge 0, \ x \in \mathbb{R}^d,$

Chalub, F. A., Markowich, P. A., Perthame, B., & Schmeiser, C.: Kinetic models for chemotaxis and their drift-diffusion limits. In Nonlinear Differential Equation Models, (2004)

solution of the kinetic chemotaxis problem

so solutions of the forward problems converge (kinetic -> macroscopic)

# IN

it is proven

# $\rightarrow$ (as $\epsilon \rightarrow 0$ ) to solution of macroscopic Keller-Segel model



the solution to the inverse problem for the macroscopic equation is ill posed

given a situation where the solution to the inverse problem for the kinetic equation is well-posed





# for the inverse problem

### the *well-posed* solution to the inverse problem of the kinetic chemotaxis equation **?** (as $\epsilon \rightarrow 0$ ) to an *ill posed* solution of the inverse problem to the Keller-Segel



in practice only noisy data is available thus we use the probabilistic setting



in practice only noisy data is available thus we use the probabilistic setting

we consider the inverse problem in a Bayesian setting



in practice only noisy data is available thus we use the probabilistic setting

we consider the solution of the inverse problem both in the kinetic and macroscopic setting

we consider the inverse problem in a Bayesian setting





in practice only noisy data is available

thus we use the probabilistic setting

- we consider the inverse problem in a Bayesian setting
- we consider the solution of the inverse problem both in the kinetic and macroscopic setting
- we consider the convergence of one to the other in a norm suitable to this context





# we prove convergence in the Bayesian setting, in an appropriate norm

Helmuth, K., Klingenberg, C., Li, Q., Tank, M.: "Multiscale convergence of the inverse problem for chemotaxis in the Bayesian setting", manuscript (2021)



# in applications certain modeling parameters of PDE models are not known accurately

the uncertainty quantification paradigm was to assume they are given stochastic functions

Conclusion

in applications certain modeling parameters of PDE models are not known accurately



- in applications certain modeling parameters of PDE models are not known accurately
- the uncertainty quantification paradigm was to assume they are given stochastic functions
  - we suggest to determine these modeling parameters by solving an inverse problem





- in applications certain modeling parameters of PDE models are not known accurately
- the uncertainty quantification paradigm was to assume they are given stochastic functions
  - we suggest to determine these modeling parameters by solving an inverse problem
- it seems natural that this question leads to looking at inverse problems in the Bayesian setting



- in applications certain modeling parameters of PDE models are not known accurately
- the uncertainty quantification paradigm was to assume they are given stochastic functions
  - we suggest to determine these modeling parameters by solving an inverse problem
- it seems natural that this question leads to looking at inverse problems in the Bayesian setting
  - in future work we plan to devise efficient machine learning algorithms for these inverse problems



# Thank you for your attention !