Adaptation to a gradual environment - Research of lineages

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# Climate change adaptation

- One observes rapid phenotypic changes in invasive or natural populations that are subject to environmental changes.
- Such fast evolution may result in adaptation of these populations facing changing environment.

### Our aim:

- To model the response of a population to a gradual change in environment, based on an individual-based model.
- To capture the dynamics in the past of the lineage (genetic history) of an individual chosen at random at a fixed time.

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# The population process

- Each individual is characterized by a quantitative genetic or phenotypic real parameter, usually called trait.
- The parameter K scales the population size. It will be large.
- Population of  $N^{K}(t)$  individuals weighted by  $\frac{1}{K}$  and traits

 $(X_t^1,\cdots,X_t^{N^K(t)})\in\mathbb{R}^{N^K(t)}.$ 

• The population is described by the point measure

$$\nu_t^K = \frac{1}{K} \sum_{i=1}^{N^K(t)} \delta_{X_t^i}.$$

$$\int \varphi(x)\nu_t^K(dx) = \frac{1}{K}\sum_{i=1}^{N^K(t)}\varphi(X_t^i) \quad ; \quad \int \nu_t^K(dx) = \frac{N^K(t)}{K}$$

• The population process  $(\nu_t^K, t \ge 0)$  is a Markov process with values in  $\mathbb{D}(\mathbb{R}_+, \mathcal{M}_F(\mathbb{R})).$ 

# The transitions

### BIRTH

Clonal reproduction at rate 1 from each individual of trait x: the offsprings inherits of x.

#### MUTATION: two different modeling

1) During its life time, the trait of the individual is submitted to many very small centered mutations.

Its behavior is modeled by a Brownian motion with variance  $\sigma^2$ .

2) At rate 1, there is a reproduction event with mutation. The offspring of an individual with trait x will inherit the trait  $x + \sigma h$ , where h is distributed according to a symmetric law G(h)dh. (Ex: G(h)dh is a centered reduced Gaussian law).

# The mortality rate

• Without environmental effect: mutation-selection balance



Each individual with trait x dies at rate

$$\frac{x^2}{2} + \frac{N^{K}(t)}{K} = \frac{x^2}{2} + \int \nu_t^{K}(dx) dx$$

The intrinsic death rate  $\frac{x^2}{2}$  depends on the trait *x* of the individual.  $\frac{1}{K}$ : competition pressure between two individuals. The term  $\int \nu_t^K (dx)$  represents the interaction between individuals.

# Effect of the environment

• The environment evolves linearly in time at the velocity  $\sigma c$ .

• The optimal trait is driven by the environment: the optimal trait at time t will be  $\sigma ct$ .

- In our modeling, we will replace the death rate  $x^2/2$  by  $(x \sigma ct)^2/2$ .
- Moving optimal trait:  $x = \sigma ct$ .

# The stochastic population process

The population process  $\nu^{\kappa}$  is solution of a stochastic differential equation driven by Poisson point measures governing birth and death events and Brownian motions or Poisson processes governing mutations.

Semi-martingale decomposition.

$$\int \varphi(x)\nu_t^K(dx) = \int \varphi(x)\nu_0^K(dx) + M_t^K(\varphi) + \int_0^t \int \left(1 - \frac{(x - \sigma cs)^2}{2} - \int \nu_s^K(dx)\right)\varphi(x)\nu_s^K(dx)ds + \begin{cases} \int_0^t \int \frac{\sigma^2}{2}\varphi''(x)\nu_s^K(dx)ds \\ \int_0^t \int \int \varphi(x + \sigma h) - \varphi(x))G(h)dh\nu_s^K(dx)ds \end{cases}$$

where  $M^{\kappa}(\varphi)$  is a square integrable martingale with

$$\mathbb{E}((M_t^{K}(\varphi))^2) = \frac{C(\varphi, t)}{K}.$$

## Large population approximation

**Proposition:** Let T > 0. Under appropriate assumptions, the population process  $\nu^{K}$  is approximated on [0, T] by the unique weak solution of

$$\partial_t u(t,x) = \left(1 - \frac{(x - \sigma ct)^2}{2} - \int u(t,x) dx\right) u(t,x) \\ + \begin{cases} \frac{\sigma^2}{2} \partial_{xx}^2 u(t,x) \\ \int (u(t,x + \sigma h) - u(t,x)) G(h) dh \end{cases}$$

That means that  $\forall \varepsilon > 0, \forall \varphi \in C_b^2$ ,

$$\lim_{K\to+\infty} \mathbb{P}(\sup_{t\leq T} | \int \varphi(x)\nu_t^K(dx) - \int \varphi(x)u(t,x)dx | > \varepsilon) = 0.$$

In particular,

$$\lim_{K\to+\infty}\mathbb{P}(\sup_{t\leq T}|\int \nu_t^K(dx)-\int u(t,x)dx|>\varepsilon)=0.$$

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# **Moving Framework - Gaussian case** Let us define $\widetilde{Z}^{\kappa}$ as the image-measure of $\nu^{\kappa}$ by the map $x \longrightarrow x - \sigma ct$ . Then for all $C_b^2$ function $\varphi$ ,

$$\begin{split} \int \varphi(x) \widetilde{Z}_{t}^{K}(dx) &= \int \varphi(x) \nu_{0}^{K}(dx) + \widetilde{M}_{t}^{K}(\varphi) \\ &+ \int_{0}^{t} \int \left( \left(1 - \frac{x^{2}}{2} - \int \widetilde{Z}_{s}^{K}(dx)\right) \varphi(x) - \sigma c \varphi'(x) + \frac{\sigma^{2}}{2} \varphi''(x) \right) \widetilde{Z}_{s}^{K}(dx) ds. \end{split}$$

where  $\widetilde{M}^{K}(\varphi)$  is a square integrable martingale with second order moment of the form  $\frac{C(T,\varphi)}{K}$ .

The macroscopic approximation when *K* is large is given by the density profile  $f(t, x) = u(t, x + \sigma ct)$ , solution of

$$\partial_t f(t,x) = \left(1 - \frac{x^2}{2} - \int f(t,x) dx\right) f(t,x) + \sigma c \partial_x f(t,x) + \frac{\sigma^2}{2} \partial_{xx}^2 f(t,x).$$

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with  $f(0, x) = u_0(x)$ .

### Theorem: Gaussian case.

There is a unique positive stationary distribution, solution of

$$\frac{\sigma^2}{2}F^{\prime\prime}+\sigma cF^\prime+\Big(1-\frac{x^2}{2}-\int F\Big)F=0,$$

if and only if

$$1-\frac{\sigma}{2}-\frac{c^2}{2}>0.$$

It is given by

$$F(x) = rac{\lambda}{\sqrt{2\pi\sigma}} \exp\left(-rac{(x+c)^2}{2\sigma}
ight) ext{ and } \int F(x) dx = \lambda = 1 - rac{\sigma}{2} - rac{c^2}{2}.$$

**Remark**: If  $u_0 = F$ , then for any  $\varepsilon > 0$ ,

$$\lim_{K\to+\infty} \mathbb{P}(\sup_{t\leq T} |\int \widetilde{Z}_t^K(dx) - \lambda| > \varepsilon) = 0.$$

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The population follows the optimum that moves to the right at the constant speed  $\sigma c$ .

The shape of the wave that follows this movement "stabilizes" to become

 $u(x,t)=F(x-\sigma ct).$ 

In the Gaussian case, F has its maximum in -c in the moving reference frame. The population is always "behind" its environment.



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# Stationary dynamics - Research of genetic lineages in a gradual environment

Assume that the population is at equilibrium in the moving reference frame.

Question: what is the internal dynamics in the stationary distribution?



time  $\rightarrow$ 

The grey background is the stationary density of individuals *F*. The *y* axis represents the phenotype *z* in the moving frame (z = x - ct).

The maladaptive individuals of yesterday have become more adapted today and these phylogenies can be seen as a "trace" of past environmental change.

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## The associated branching-diffusion process: the nonlinearity is frozen

We construct on the same probability space a branching-diffusion process  $(Z_t^{K}, t \ge 0)$ , issued from the same initial condition where the nonlinearity is fixed to  $\lambda = ||F||_1$ .

For any  $\varphi \in C^2_b(\mathbb{R})$ ,

$$\int \varphi(x) Z_t^{\kappa}(dx) = \int \varphi(x) \nu_0^{\kappa}(dx) + M_t^{\kappa}(\varphi) \\ + \int_0^t \int \left( \left(1 - \frac{x^2}{2} - \lambda\right) \varphi(x) - \sigma c \varphi'(x) + \frac{\sigma^2}{2} \varphi''(x) \right) Z_s^{\kappa}(dx) ds.$$

• We assume that  $\nu_0^K$  converges in law to F. (For example, the r.v.  $X_0^i$  are independent with law F).

Then

$$\lim_{K \to +\infty} \mathbb{E} \Big( \sup_{t \leq T} \Big| \int \varphi(x) Z_t^K(dx) - \int \varphi(x) \widetilde{Z}_t^K(dx) \Big|^2 \Big) = 0$$

We will approximate the nonlinear process by the branching-diffusion process which has beautiful properties based on the branching property.

In particular, it's enough to consider one initial individual taking  $K_{\pm} = 1$ .

## An auxiliary one-dimensional process

### One initial individual and K = 1.

We can easily observe (using Itô's Formula) that for any bounded continuous function  $\varphi$ , for  $t \ge 0$  and  $x \in \mathbb{R}$ ,

$$\mathbb{E}_{\delta_{x}}\left[\int \varphi(x)Z_{t}(dx)\right] = \mathbb{E}_{x}\left[\exp\left(\int_{0}^{t}\left(1-\frac{1}{2}Y_{s}^{2}-\lambda\right)ds\right)\varphi(Y_{t})\right],$$

where Y is the drifted Brownian motion

 $dY_t = \sigma(dB_t - cdt).$ 

Then,  $m_t(x) = \mathbb{E}_{\delta_x} \left[ \int Z_t(dx) \right]$  satisfies

$$m_t(x) = \mathbb{E}_x \Big[ \exp \Big( \int_0^t \left( 1 - \frac{1}{2} Y_s^2 - \lambda \right) ds \Big) \Big],$$

and then  $m \in C_b^{1,\infty}([0,T] \times \mathbb{R})$ .

From Feynman-Kac formula, we deduce that  $(m_t(x), x \in \mathbb{R}, t \ge 0)$  is the unique strong solution of

$$\begin{cases} \partial_t m = \frac{\sigma^2}{2} \partial_{xx} m - \sigma c \partial_x m + (1 - \frac{x^2}{2} - \lambda)m \\ m_0(x) = 1. \end{cases}$$

That implies that for any  $t \ge 0$ ,

$$\int m_t(x)F(x)dx = \int F(x)dx = \lambda.$$

Moreover, following Fitzsimmons-Pitman-Yor arguments using Girsanov's transform, one can explicitely compute  $m_t$ :

$$m_t(x) = \sqrt{1 + \tanh(\sigma t)} \exp\left(-\frac{\left(x + e^{-\sigma t}c\right)^2}{2\sigma} \left(1 + \tanh(\sigma t)\right) + \frac{\left(x + c\right)^2}{2\sigma}\right).$$

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## The historical particle system

We extend the previous formula to the historical system until a fixed (observation) time T.

•  $V_T$  denotes the set of individuals alive at time T.

• Let us take  $i \in V_T$  and t < T.

 $X^{i}(t)$  denotes the historical lineage of the individual *i* in the following sense:

If the individual *i* was born at time *t*, then  $X^{i}(t)$  denotes the trait of *i* at *t*. But if the individual *i* was not born at time *t*, then  $X^{i}(t) = X^{j}(t)$  where *j* is the most recent ancestor of *i* living at time *t*.

We write  $(j, t) \leq (i, T)$ .

**Theorem:** For any  $t_1 < t_2 < \cdots < t_n \leq T$ , for any  $x \in \mathbb{R}$ ,

$$\mathbb{E}_{\delta_{X}}\left[\sum_{i\in V_{T}}\varphi(X_{t_{1}}^{i},\ldots,X_{t_{n}}^{i})\right] = \mathbb{E}_{X}\left[\exp\left(\int_{0}^{T}\left(1-\frac{1}{2}Y_{s}^{2}-\lambda\right)ds\right)\varphi(Y_{t_{1}},\ldots,Y_{t_{n}})\right].$$



# The spinal approach - the typical trajectory

#### Theorem:

For  $x \in \mathbb{R}$  and  $\Phi$  a continuous bounded function on  $\mathcal{C}([0, T], \mathbb{R})$ , we have

$$\lim_{K \to +\infty} \mathbb{E}_{K\delta_{X}} \left[ \frac{1}{N_{T}^{K}} \sum_{i \in V_{T}^{K}} \Phi(X_{s}^{i}, s \leq T) \right] = \frac{1}{m_{T}(x)} \mathbb{E}_{\delta_{X}} \left[ \sum_{i \in V_{T}} \Phi(X_{s}^{i}, s \leq T) \right]$$
$$= \mathbb{E}_{X} \left[ \Phi(\widetilde{Y}_{s}, s \leq T) \right],$$

where  $\widetilde{Y}$  is an inhomogeneous Markov Process (depending on T) with infinitesimal generator given for  $f \in C_b^2(\mathbb{R})$  by

$$\mathcal{G}_t f(x) = \frac{L(m_{T-t}f)(x) - f(x)Lm_{T-t}(x)}{m_{T-t}(x)}$$

where L is the infinitesimal generator of the drifted Brownian Y.

The process  $\widetilde{Y}$  describes the behavior of the phenotypic trajectory of an individual uniformly sampled among the individuals alive at time T, in a large population.

## The biaised initial distribution

Taking s = 0, we obtain that the initial value of  $\tilde{Y}$  is not distributed according to  $\frac{1}{\lambda}F$  but according to the biaised distribution  $\frac{1}{\lambda}m_T F$ .

**Proof**: (Cf. A. Marguet). Markov property and Itô's Formula applied to  $f(Y_t)m_{T-t}(Y_t)$ .

Using the explicit value of  $m_t(x)$ , we deduce that for  $0 \le t \le T$ ,

$$\widetilde{Y}_{t} = \frac{\cosh(\sigma(T-t))}{\cosh(\sigma T)} \widetilde{Y}_{0} + c \cosh(\sigma(T-t)) (\tanh(\sigma(T-t)) - \tanh(\sigma T)) \\ + \sigma \cosh(\sigma(T-t)) \int_{0}^{t} \frac{dB_{s}}{\cosh(\sigma(T-s))}.$$

- For any  $t \ge 0$ , the random variable  $\widetilde{Y}_t$  is a Gaussian variable.
- Computation gives that for any  $0 \le t \le T$ ,

$$\widetilde{Y}_t \sim \mathcal{N}\Big(-c \, e^{-\sigma(T-t)}, rac{\sigma}{1+ anh(\sigma(T-t))}\Big)$$

• Then the density p(t, y) of  $\widetilde{Y}_t$  satisfies

$$\partial_{y} \log p(t, y) = -\frac{x + c e^{-\sigma(T-t)}}{\sigma} (1 + \tanh(\sigma(T-t))).$$

# Time-reversion of the process: the phenotypic lineage equation to the ancestor

We can now apply a result of Haussmann and Pardoux.

The reverse-time process of a diffusion  $b(t, \tilde{Y}_t)dt + \sigma dB_t$  is a diffusion process whose drift is given by

$$b^{r}(t, y) = -b(T - t, y) + \sigma^{2} \partial_{y} \log p(T - t, y)$$

and the diffusion part stays unchanged.

Here we obtain that the time-reverse diffusion process of  $\widetilde{Y}$  is the Ornstein-Uhlenbeck process

 $dX_t = -\sigma X_t dt + \sigma dB_t,$ 

which is homogeneous and independent of  $T \parallel$ 





The grey background is the stationary density of individuals *F*. The *y* axis represents the phenotype *z* in the moving frame (z = x - ct).

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Dominant trait: -c. Optimal trait: 0. In this case, we have seen that the pde is

$$\partial_t f(t,x) = \int \left( f(t,x+\sigma h) - f(t,x) \right) G(h) dh + \left( 1 - \frac{x^2}{2} - \int f(t,x) dx \right) f(t,x) \\ + \sigma c \partial_x f(t,x)$$

with  $f(0, x) = u_0(x)$ .

In what follows, we will denote by  $G_{\sigma} * f$  the operator

$$G_{\sigma} * f(x) = \int f(x + \sigma h) G(h) dh.$$

## The stationary distribution

Theorem: (Coville-Hamel, Velleret)

Let us define the operator A for any smooth function f by

$$Af = f - G_{\sigma} * f - c\sigma \partial_x f + \frac{1}{2}x^2 f.$$

Then

(i) There exists a unique  $\lambda \ge 0$  and a unique positive function  $\phi \in H^1(\mathbb{R})$  satisfying  $\int \phi = 1$  and  $x^2 \phi \in L^2$  satisfying that

$$A\phi = \lambda\phi.$$

In addition, the function  $\phi$  is a smooth function.

(ii) There exists a unique non zero stationary distribution F for our non local problem if and only if

 $\lambda < 1$ .

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Moreover,  $\int F = 1 - \lambda$ .

A part of the previous approach stays valid but without explicit computations.

The auxiliary process is now

$$dY_t = \sigma(-cdt + \int hN(dt, dh)),$$

with *N* a Poisson point measure on  $\mathbb{R}_+ \times \mathbb{R}$  with intensity G(h)dh dt.

• Approach based on additive functionals (Dynkin) and reverse time for general Markov processes (Reinhard-Roynette).

Let  $(P_t)$  the semigroup defined by

$$P_t \varphi(x) = \mathbb{E}_x \Big[ \exp \Big( \int_0^t \left( 1 - \frac{1}{2} Y_s^2 - \lambda \right) ds \Big) \varphi(Y_t) \Big].$$

• One can show that since F is stationary, then

 $P_t^*F = F$ .

We deduce that the law of  $\tilde{Y}_t$  issued from  $m_T F$  is  $m_{T-t} \cdot F$ . Moreover, using reverse time technics, we obtain that the semigroup of the reverse time process of  $\tilde{Y}$  satisfies

$$P_t^{\mathsf{R}}\varphi=\frac{P_t^*(F\varphi)}{F}.$$

This semigroup does not depend on  $m_t$ !

# Thank you for your attention!



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