

# Consistent model selection criteria and goodness-of-fit test for common time series models

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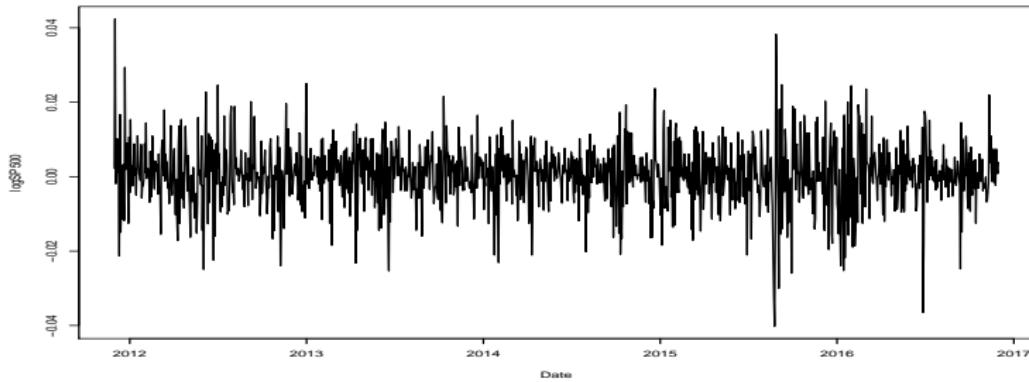
**2 June 2020**

# Outline

- 1 An example
- 2 Causal affine models
- 3 Gaussian Quasi-Maximum Likelihood Estimation
- 4 Consistency of a penalized QML criterion and goodness-of-fit test
- 5 Numerical results

## Example

Observe the trajectory of the logarithmic returns of S&P 500 :



⇒ **Two aims :**

- Chose an "optimal" model for these data ;
- Test its *goodness-of-fit*.

## Two intuitive definitions

Let  $(X_t)_{t \in \mathbb{Z}}$  be a time series (sequence of r.v. on  $(\Omega, \mathcal{A}, \mathbb{P})$ )

- $(X_t)_{t \in \mathbb{Z}}$  is a **stationary** process if  $\forall k \in \mathbb{N}^*, \forall (t_1, \dots, t_k) \in \mathbb{Z}^k$ ,

$$(X_{t_1}, \dots, X_{t_k}) \stackrel{\mathcal{L}}{\sim} (X_{t_1+h}, \dots, X_{t_k+h}) \quad \text{for all } h \in \mathbb{Z}.$$

- Assume that  $(\xi_t)_{t \in \mathbb{Z}}$  is a **white noise** (centered i.i.d.r.v.)

$(X_t)_{t \in \mathbb{Z}}$  **causal** process if  $\exists H : \mathbb{R}^{\mathbb{N}} \rightarrow \mathbb{R}$  such as  $X_t = H((\xi_{t-k})_{k \geq 0})$ .

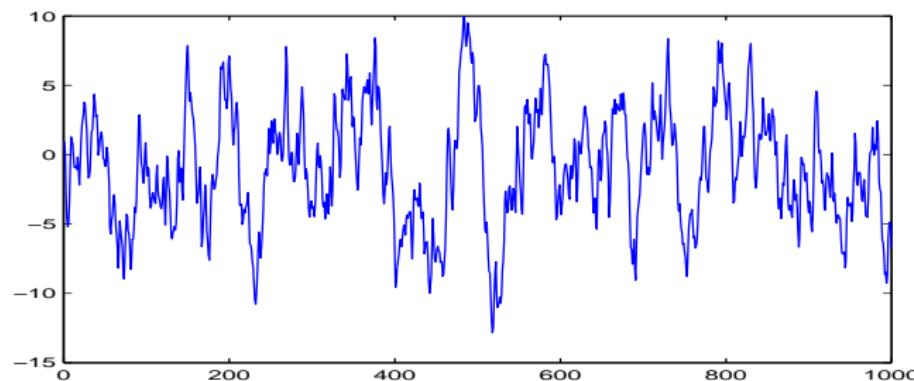
## ARMA processes (Whittle, 1951)

With  $(\xi_t)_{t \in \mathbb{Z}}$  a white noise,  $(a_i) \in \mathbb{R}^p$ ,  $(b_j) \in \mathbb{R}^q$

- ARMA( $p, q$ ) process : with  $a_p \neq 0$  and  $b_q \neq 0$ , for any  $t \in \mathbb{Z}$

$$X_t + a_1 X_{t-1} + \cdots + a_p X_{t-p} = \xi_t + b_1 \xi_{t-1} + \cdots + b_q \xi_{t-q}$$

- Stationarity and causality :  $1 + a_1 z + \cdots + a_p z^p \neq 0$  for any  $|z| \leq 1$ .



ARMA(1, 1)

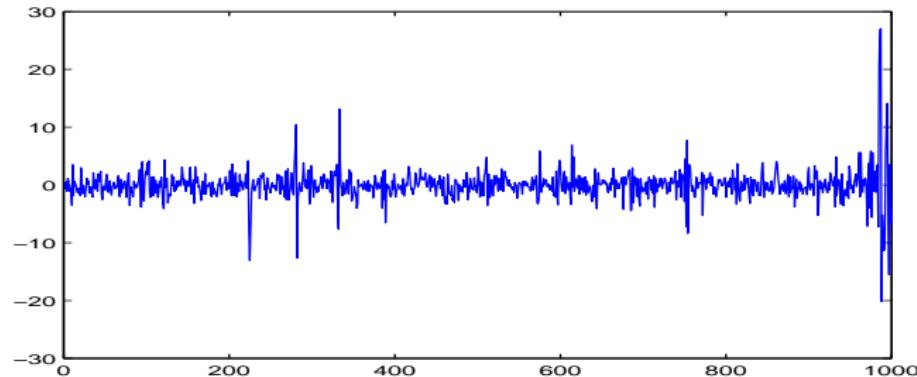
## GARCH processes (Engel, 1982) (Bollersev, 1986)

With  $(\xi_t)_{t \in \mathbb{Z}}$  a white noise,  $(c_i) \in \mathbb{R}_+^p$ ,  $(d_j) \in \mathbb{R}_+^q$

- GARCH( $p, q$ ) process : with  $c_0, c_p > 0$  and  $d_q > 0$ , for any  $t \in \mathbb{Z}$

$$\begin{cases} X_t = \sigma_t \xi_t, \\ \sigma_t^2 = c_0 + c_1 X_{t-1}^2 + \cdots + c_p X_{t-p}^2 + d_1 \sigma_{t-1}^2 + \cdots + d_q \sigma_{t-q}^2 \end{cases}$$

- $\sum_{j=1}^q d_j + \mathbb{E}(\xi_0^2) \sum_{i=1}^p c_i < 1 \implies$  Stationarity and causality



GARCH(1, 1)

# Model selection and Goodness-of-fit test

Consider a family  $\mathcal{M}$  of models. For instance,

$$\mathcal{M} = \{\text{ARMA}(p, q) \text{ or GARCH}(p', q'), \\ \text{with } 0 \leq p, p' \leq p_{\max}, 0 \leq q, q' \leq q_{\max}\}$$

We want to :

- Choose an "optimal" model in  $\mathcal{M}$  for  $(X_1, \dots, X_n)$ ;
- Estimate its parameters;
- Test its goodness-of-fit.

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## Examples : Causal AR[ $\infty$ ] and ARCH( $\infty$ ) models

With  $(\xi_t)_{t \in \mathbb{Z}}$  a white noise,

- AR( $\infty$ ) processes  $X_t = \sum_{i=1}^{\infty} \theta_i X_{t-i} + \xi_t$

$$\implies \text{Causal ARMA}(p, q) \text{ processes } X_t + \sum_{i=1}^p a_i X_{t-i} = \xi_t + \sum_{i=1}^q b_i \xi_{t-i}.$$

- ARCH( $\infty$ ) processes, (Robinson, 1991), with  $b_0 > 0$  and  $b_j \geq 0$

$$\begin{cases} X_t = \sigma_t \xi_t, \\ \sigma_t^2 = \phi_0 + \sum_{j=1}^{\infty} \phi_j X_{t-j}^2. \end{cases}$$

$\implies$  GARCH( $p, q$ ) processes, with  $c_0 > 0$ ,  $c_j, d_j \geq 0$ ,  $c_p, d_q > 0$

$$\begin{cases} X_t = \sigma_t \xi_t, \\ \sigma_t^2 = c_0 + \sum_{j=1}^p c_j X_{t-j}^2 + \sum_{j=1}^q d_j \sigma_{t-j}^2 \end{cases}$$

# A common frame for studying time series

A **common class** of models for AR, ARMA, ARCH and GARCH processes :

Causal affine models : class  $\mathcal{CA}(M, f)$

$$X_t = M(X_{t-1}, X_{t-2}, \dots) \xi_t + f(X_{t-1}, X_{t-2}, \dots), \quad \forall t \in \mathbb{Z}, \text{ a.s.}$$

- $M(\cdot)$  and  $f(\cdot)$  are real valued function on  $\mathbb{R}^{\mathbb{N}}$ ;
- $(\xi_t)_{t \in \mathbb{Z}}$  a white noise with  $\mathbb{E}(\xi_0) = 0$  and  $\mathbb{E}(|\xi_0|^r) < \infty$ ,  $r \geq 1$ .

## Extensions of univariate ARCH models

- TGARCH( $\infty$ ) processes, (Zakoïan, 1994), with  $b_0, b_j^+, b_j^- \geq 0$

$$\begin{cases} X_t = \sigma_t \xi_t, \\ \sigma_t = b_0 + \sum_{j=1}^{\infty} [b_j^+ \max(X_{t-j}, 0) - b_j^- \min(X_{t-j}, 0)] \end{cases}.$$

- APARCH( $\delta, p, q$ ) processes, (Ding *et al.*, 1993)

$$\begin{cases} X_t = \sigma_t \zeta_t, \\ \sigma_t^\delta = \omega + \sum_{j=1}^p \alpha_i (|X_{t-i}| - \gamma_i X_{t-i})^\delta + \sum_{j=1}^q \beta_j \sigma_{t-j}^\delta, \end{cases}$$

with  $\delta \geq 1$ ,  $\omega > 0$ ,  $-1 < \gamma_i < 1$  and  $\alpha_i, \beta_j \geq 0$ .

## Combinations of models

- ARMA-GARCH processes, (Ding *et al.*, 1993, Ling and McAleer, 2003)

$$\begin{cases} X_t = \sum_{i=1}^p a_i X_{t-i} + \varepsilon_t + \sum_{j=1}^q b_j \varepsilon_{t-j}, \\ \varepsilon_t = \sigma_t \zeta_t, \quad \text{with} \quad \sigma_t^2 = c_0 + \sum_{i=1}^{p'} c_i \varepsilon_{t-i}^2 + \sum_{j=1}^{q'} d_j \sigma_{t-j}^2 \end{cases}$$

- ARMA-APARCH processes, (Ding *et al.*, 1993)

$$\begin{cases} X_t = \sum_{i=1}^p a_i X_{t-i} + \varepsilon_t + \sum_{j=1}^q b_j \varepsilon_{t-j}, \\ \varepsilon_t = \sigma_t \zeta_t, \quad \text{with} \quad \sigma_t^\delta = \omega + \sum_{j=1}^{p'} \alpha_j (|X_{t-j}| - \gamma_j X_{t-j})^\delta + \sum_{j=1}^{q'} \beta_j \sigma_{t-j}^\delta \end{cases}$$

# Existence and stationarity of causal affine models

$$X_t = M(X_{t-1}, X_{t-2}, \dots) \xi_t + f(X_{t-1}, X_{t-2}, \dots), \quad \forall t \in \mathbb{Z},$$

We will assume that  $f$  and  $M$  satisfy Lipschitzian conditions :

$$\begin{cases} |f(x) - f(y)| & \leq \sum_{j=1}^{\infty} \alpha_j(f) |x_j - y_j| \\ |M(x) - M(y)| & \leq \sum_{j=1}^{\infty} \alpha_j(M) |x_j - y_j|. \end{cases}$$

for  $x = (x_j)_{j \in \mathbb{N}}$  and  $y = (y_j)_{j \in \mathbb{N}}$  two sequences of  $\mathbb{R}^{\infty}$ .

**Proposition** (from Doukhan and Wintenberger, 2007)

If  $\sum_{j=1}^{\infty} \alpha_j(f) + (\mathbb{E}(|\xi_0|^r))^{1/r} \sum_{j=1}^{\infty} \alpha_j(M) < 1$ , there exists a unique causal solution  $(X_t)_{t \in \mathbb{Z}}$  which is stationary, ergodic, such as  $\mathbb{E}(|X_0|^r) < \infty$ .

## Examples

Conditions on **stationarity** become :

- **Causal AR[ $\infty$ ]** :

$$X_t = \sum_{j=0}^{\infty} a_j \xi_{t-j} \implies \sum_{j=0}^{\infty} |a_j| < 1;$$

- **Causal ARCH[ $\infty$ ]** :

$$X_t = \xi_t \sqrt{c_0 + \sum_{j=1}^{\infty} c_j X_{t-j}^2} \implies (\mathbb{E}[|\xi_0|^r])^{1/r} \sum_{j=1}^{\infty} c_j < 1;$$

- **Causal TARCH[ $\infty$ ]** :

$$\begin{aligned} X_t &= \xi_t \left( b_0 + \sum_{j=1}^{\infty} [b_j^+ \max(X_{t-j}, 0) - b_j^- \min(X_{t-j}, 0)] \right) \\ &\implies (\mathbb{E}[|\xi_0|^r])^{1/r} \sum_{j=1}^{\infty} \max(b_j^-, b_j^+) < 1; \end{aligned}$$

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## Gaussian QMLE of causal affine model

Let  $(X_1, \dots, X_n)$  an **observed trajectory** of an  $\mathcal{CA}(M_{\theta^*}, f_{\theta^*})$

$$X_t = M_{\theta^*}(X_{t-1}, X_{t-2}, \dots) \xi_t + f_{\theta^*}(X_{t-1}, X_{t-2}, \dots), \quad \forall t \in \mathbb{Z}$$

- With  $f_\theta^t = f_\theta(X_{t-1}, X_{t-2}, \dots)$ ,  $M_\theta^t = M_\theta(X_{t-1}, X_{t-2}, \dots)$ ,

$$\text{Gaussian conditional log-density : } q_t(\theta) = -\frac{1}{2} \left[ \frac{(X_t - f_\theta^t)^2}{(M_\theta^t)^2} + \log(M_\theta^t)^2 \right]$$

- Let  $\widehat{f}_\theta^t = f_\theta(X_{t-1}, \dots, X_1, 0, \dots)$  and  $\widehat{M}_\theta^t = M_\theta(X_{t-1}, \dots, X_1, 0, \dots)$

$$\widehat{q}_t(\theta) = -\frac{1}{2} \left[ \frac{(X_t - \widehat{f}_\theta^t)^2}{(\widehat{M}_\theta^t)^2} + \log((\widehat{M}_\theta^t)^2) \right].$$

$$\implies \text{Gaussian QMLE : } \widehat{\theta}_n = \operatorname{argmax}_{\theta \in \Theta} \widehat{L}_n(\theta) \text{ with } \widehat{L}_n(\theta) = \sum_{t=1}^n \widehat{q}_t(\theta).$$

# Assumptions and strong consistency

We assume :

- **C0** :  $r \geq 2$  and  $\mathbb{E}(\xi_0^2) = 1$ ;
- **C1** :  $\Theta$  is a compact set included in

$$\Theta(r) = \left\{ \theta \in \mathbb{R}^d \mid \sum_{j=1}^{\infty} \alpha_j^{(0)}(f_\theta) + (\mathbb{E}(|\xi_0|^r))^{1/r} \sum_{j=1}^{\infty} \alpha_j^{(0)}(M_\theta) < 1 \right\}.$$

- **C2** :  $\exists M > 0$  such that  $M_\theta(x) \geq M$  for all  $\theta \in \Theta$ ,  $x \in \mathbb{R}^{\mathbb{N}}$ .
- **C3** :  $M_\theta$  and  $f_\theta$  are such that for all  $\theta_1, \theta_2 \in \Theta$ , then :

$$(M_{\theta_1} = M_{\theta_2} \quad \text{and} \quad f_{\theta_1} = f_{\theta_2}) \implies \theta_1 = \theta_2$$

- **A( $K_\theta, \Theta$ )** : There exists  $(\alpha_j(K_\theta, \Theta))_j$  such that  $\forall x, y \in \mathbb{R}^\infty$

$$\sup_{\theta \in \Theta} |K_\theta(x) - K_\theta(y)| \leq \sum_{j=1}^{\infty} \alpha_j(K_\theta, \Theta) |x_j - y_j|,$$

$$\text{with } \sum_{j=1}^{\infty} \alpha_j(K_\theta, \Theta) < \infty.$$

## Strong consistency

Théorème (Bardet and Wintenberger, 2009)

Assume  $r \geq 2$ ,  $\Theta \subset \Theta(2)$ , Conditions C0-3 and  $A(f_\theta, \Theta)$  and  $A(M_\theta, \Theta)$  with

$$\alpha_j(f_\theta, \Theta) + \alpha_j(M_\theta, \Theta) = O(j^{-\ell}) \text{ for some } \ell > \min(1, 3/r).$$

Then the QMLE  $\widehat{\theta}_n$  is strongly consistent, i.e.  $\widehat{\theta}_n \xrightarrow[n \rightarrow \infty]{a.s.} \theta^*$ .

# Asymptotic normality

Théorème (Bardet and Wintenberger, 2009)

Under conditions of SLLN, and if  $r \geq 4$ , if  $\theta^* \in \overset{\circ}{\Theta} \cap \Theta(4)$  and if  $\mathbf{A}(K_\theta, \Theta)$ ,  $\mathbf{A}(\partial_\theta K_\theta, \Theta)$  and  $\mathbf{A}(\partial_{\theta^2} K_\theta, \Theta)$  hold for  $K_\theta = f_\theta$  or  $M_\theta$ , and if

$$\alpha_j(\partial_\theta f_\theta, \Theta) + \alpha_j(\partial_\theta M_\theta, \Theta) = O(j^{-\ell'}) \text{ for some } \ell' > 1, \quad (1)$$

then the QMLE  $\widehat{\theta}_n$  is asymptotically normal, i.e., there exists matrix  $F(\theta^*)^{-1}$  and  $G(\theta^*)$  such that

$$\sqrt{n}(\widehat{\theta}_n - \theta^*) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}_d(0, F(\theta^*)^{-1} G(\theta^*) F(\theta^*)^{-1}). \quad (2)$$

- Could be applied to all cited processes ARMA, ARCH, APARCH,...
- But requires  $r \geq 4$  and **not very robust**.

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# Additivity of causal affine models

## Proposition

Let  $\Theta_1 \subset \mathbb{R}^{d_1}$ ,  $\Theta_2 \subset \mathbb{R}^{d_2}$ ,  $M_{\theta_1}^{(1)}, f_{\theta_1}^{(1)}, M_{\theta_2}^{(2)}, f_{\theta_2}^{(2)}$  for  $\theta_1 \in \Theta_1$ ,  $\theta_2 \in \Theta_2$ .

There exist  $\max(d_1, d_2) \leq d \leq d_1 + d_2$ ,  $\Theta \subset \mathbb{R}^d$ , and  $M_\theta, f_\theta$  with  $\theta \in \Theta$ , such as for any  $\theta_1 \in \Theta_1 \subset \mathbb{R}^{d_1}$  and  $\theta_2 \in \Theta_2 \subset \mathbb{R}^{d_2}$ ,

$$\left\{ \mathcal{CA}(M_{\theta_1}^{(1)}, f_{\theta_1}^{(1)}) \cup \mathcal{CA}(M_{\theta_2}^{(2)}, f_{\theta_2}^{(2)}) \right\} \subset \left\{ \mathcal{CA}(M_\theta, f_\theta) \right\}.$$

## Consequence :

- For any family  $\mathcal{M} = \bigcup_{i \in I} \mathcal{CA}(M_{\theta_i}^{(i)}, f_{\theta_i}^{(i)})$ ,  
$$\implies \mathcal{M} = \bigcup_{i \in I} \left\{ \mathcal{CA}(M_\theta, f_\theta) \right\}_{\theta \in \Theta_i \subset \mathbb{R}^{d_i}}$$
- $\mathcal{M}$  family of  $\mathcal{CA}$  models  $\Leftrightarrow \mathcal{M} \sim \{m \subset \{1, \dots, d\}\}$ ,  
$$\theta \in \Theta(m) \subset \{(x_1, \dots, x_d) \in \mathbb{R}^d, x_i = 0 \text{ if } i \notin m\}$$

# Penalized Quasi-Maximum Likelihood criterion

Let  $(X_1, \dots, X_n)$  an observed trajectory.

For  $m \in \mathcal{M}$ , define :

$$\begin{cases} \hat{\theta}(m) = \underset{\theta \in \Theta(m)}{\operatorname{argmax}} \hat{L}_n(\theta) \\ \hat{m} = \underset{m \in \mathcal{M}}{\operatorname{argmin}} \hat{C}(m) \quad \text{with} \quad \hat{C}(m) = -2\hat{L}_n(\hat{\theta}(m)) + |m| \kappa_n, \end{cases}$$

using

- $(\kappa_n)_n$  an increasing sequence of positive real numbers;
- $|m|$  denotes the cardinal of  $m$ , subset of  $\{1, \dots, d\}$ .

# Consistency

## Théorème

Let  $(X_1, \dots, X_n)$  be an observed trajectory of  $\mathcal{CA}(M_{\theta^*}, f_{\theta^*})$  where  $\theta^*$  unknown in  $\Theta \subset \Theta(r) \subset \mathbb{R}^d$  with  $r \geq 4$ . Under previous assumptions and if

$$\sum_{k \geq 1} \frac{1}{\kappa_k} \sum_{j \geq k} \alpha_j(f_\theta, \Theta) + \alpha_j(M_\theta, \Theta) + \alpha_j(\partial_\theta f_\theta, \Theta) + \alpha_j(\partial_\theta M_\theta, \Theta) < \infty,$$

then  $\mathbb{P}(\hat{m} = m^*) \xrightarrow[n \rightarrow +\infty]{} 1.$

## Consequence :

- If  $\alpha_j(f_\theta, \Theta) + \alpha_j(M_\theta, \Theta) + \alpha_j(\partial_\theta f_\theta, \Theta) + \alpha_j(\partial_\theta M_\theta, \Theta) = \mathcal{O}(\rho^j)$ ,  $|\rho| < 1$ ,  $\kappa_n \rightarrow \infty$  sufficient : BIC for ARMA, GARCH, APARCH,..., processes.
- If  $\alpha_j(f_\theta, \Theta) + \alpha_j(M_\theta, \Theta) + \alpha_j(\partial_\theta f_\theta, \Theta) + \alpha_j(\partial_\theta M_\theta, \Theta) = \mathcal{O}(j^{-\gamma})$ ,  $\gamma > 1$ ,  $\kappa_n = \mathcal{O}(n^\delta)$  with  $\delta > 2 - \gamma$  : not valid for BIC for AR( $\infty$ ), ARCH( $\infty$ ),...

# Estimation of the parameters

## Théorème

*Under the assumptions of the previous Theorem, then*

$$\sqrt{n} \left( (\hat{\theta}_n(\hat{m}))_i - (\theta^*)_i \right)_{i \in \hat{m}} \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}_d(0, F(\theta^*, m^*)^{-1} G(\theta^*, m^*) F(\theta^*, m^*)^{-1})$$

*where  $F$  and  $G$  are defined in CLT.*

⇒ Same convergence rate with or without the knowledge of the model

# Portmanteau goodness-of-fit test (1)

Define :

- Residuals :  $\hat{\xi}_k = \frac{X_k - \hat{f}_{\hat{\theta}(\hat{m})}^t}{\hat{M}_{\hat{\theta}(\hat{m})}^t}$
- Covariogram of square residuals :  $\hat{r}(k) = \frac{1}{n} \sum_{j=1}^{n-k} \hat{\xi}_j^2 \hat{\xi}_{j+k}^2 - 1$  ;
- Correlogram of square residuals :  $\hat{\rho}(k) = \frac{\hat{r}(k)}{\hat{r}(0)}$  ;

## Portmanteau goodness-of-fit test (2)

### Théorème

Under the assumptions of Theorem and if  $\mathbb{E}(\xi_0^3) = 0$  :

- ① With  $V(\theta^*)$  an explicit definite positive matrix, we have :

$$\sqrt{n} (\hat{\rho}(1), \dots, \hat{\rho}(K)) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}_K(0, V(\theta^*)).$$

- ② If we define  $\hat{Q}_K = n^{-t} (\hat{\rho}(1), \dots, \hat{\rho}(K)) (\hat{V}(\hat{\theta}(\hat{m})))^{-1} (\hat{\rho}(1), \dots, \hat{\rho}(K))$ ,

then  $\hat{Q}_K \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \chi^2(K)$ .

$$\implies \text{Test} \left\{ \begin{array}{l} H_0 : X \in \mathcal{AC}(M_{\theta^*}, f_{\theta^*}) \\ H_1 : X \notin \mathcal{AC}(M_{\theta^*}, f_{\theta^*}) \end{array} \right.$$

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## Simulation results for classical models

- ① Model 1, AR(2) :  $X_t = 0.4X_{t-1} + 0.4X_{t-2} + \xi_t$
- ② Model 2, ARMA(1,1) :  $X_t = 0.3X_{t-1} + \xi_t + 0.5\xi_{t-1}$
- ③ Model 3, ARCH(2) :  $X_t = \xi_t \sqrt{0.2 + 0.4X_{t-1}^2 + 0.2X_{t-2}^2}$

|    | n | 100      |            |                  | 500      |            |                  | 1000     |            |                  | 2000     |            |                  |
|----|---|----------|------------|------------------|----------|------------|------------------|----------|------------|------------------|----------|------------|------------------|
|    |   | $\log n$ | $\sqrt{n}$ | $\hat{\kappa}_n$ |
| M1 | W | 21.4     | 32.3       | 18.4             | 1.7      | 0.8        | 0.9              | 0.8      | 0.1        | 0.1              | 0.2      | 0          | 0                |
|    | T | 74.2     | 67.6       | 79.7             | 97.2     | 99.2       | 99.1             | 98.2     | 99.9       | 99.9             | 99.2     | 100        | 100              |
|    | O | 4.4      | 0.1        | 1.9              | 1.1      | 0          | 0                | 1.0      | 0          | 0                | 0.6      | 0          | 0                |
| M2 | W | 30.4     | 57.7       | 28.0             | 4.8      | 4.2        | 4.0              | 0.7      | 0.3        | 0.3              | 0.4      | 0          | 0                |
|    | T | 64.1     | 42.1       | 67.3             | 93.6     | 95.8       | 95.8             | 98.2     | 99.7       | 99.6             | 99.2     | 100        | 100              |
|    | O | 5.5      | 0.2        | 4.7              | 1.6      | 0          | 0.2              | 1.1      | 0          | 0.1              | 0.4      | 0          | 0                |
| M3 | W | 76.1     | 90.8       | 53.5             | 27.3     | 67.1       | 18.0             | 14.0     | 41.5       | 13.3             | 4.6      | 12.0       | 4.6              |
|    | T | 23.8     | 9.2        | 39.8             | 72.7     | 32.9       | 79.9             | 85.9     | 58.5       | 86.7             | 95.4     | 88.0       | 95.4             |
|    | O | 0.1      | 0          | 6.7              | 0        | 0          | 2.1              | 0.1      | 0          | 0                | 0        | 0          | 0                |

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- ③ Model 3, ARCH(2) :  $X_t = \xi_t \sqrt{0.2 + 0.4X_{t-1}^2 + 0.2X_{t-2}^2}$

| n       | 100     |       | 500  |       | 1000 |       | 2000 |       |      |
|---------|---------|-------|------|-------|------|-------|------|-------|------|
|         | size    | power | size | power | size | power | size | power |      |
| $K = 3$ | Model 1 | 3.3   | 10.9 | 6.2   | 52.2 | 3.5   | 84.8 | 5.0   | 98.2 |
|         | Model 2 | 3.3   | 7.0  | 4.8   | 23.3 | 6.2   | 42.4 | 4.9   | 70.4 |
|         | Model 3 | 4.6   | 6.4  | 8.4   | 44.1 | 14.3  | 81.0 | 36.9  | 99.4 |
| $K = 6$ | Model 1 | 2.9   | 9.1  | 4.9   | 42.0 | 4.4   | 76.3 | 4.5   | 97.6 |
|         | Model 2 | 3.0   | 6.3  | 5.2   | 18.0 | 5.1   | 35.1 | 4.6   | 60.2 |
|         | Model 3 | 4.5   | 12.6 | 11.1  | 64.4 | 14.7  | 92.5 | 27.9  | 99.9 |

# Simulation results for non hierarchical models

- ① Model 4 :  $X_t = 0.4X_{t-3} + 0.4X_{t-4} + \xi_t$ .

| n | 100      |            |                      | 500      |            |                      | 1000     |            |                      | 2000     |            |                      |
|---|----------|------------|----------------------|----------|------------|----------------------|----------|------------|----------------------|----------|------------|----------------------|
|   | $\log n$ | $\sqrt{n}$ | $\widehat{\kappa}_n$ |
| T | 70.4     | 67.3       | 71.0                 | 90       | 100        | 100                  | 93.2     | 100        | 100                  | 95.3     | 100        | 100                  |
| O | 25.0     | 1.6        | 28.8                 | 10       | 0          | 0                    | 6.8      | 0          | 0                    | 4.7      | 0          | 0                    |
| W | 4.6      | 31.1       | 0.2                  | 0        | 0          | 0                    | 0        | 0          | 0                    | 0        | 0          | 0                    |

# Numerical results for SP500 log-returns

Log-return of SP500 closing values from 11/2011 → 11/2016

Table – Results of the model selection and goodness-of-fit analysis on FTSE index.

| $\kappa_n = \log(n)$    | $\kappa_n = \sqrt{n}$ | $\kappa_n = \hat{\kappa}_n$ |
|-------------------------|-----------------------|-----------------------------|
| $\hat{m}$               | GARCH(1, 1)           | GARCH(1, 1)                 |
| $\hat{Q}_{10}(\hat{m})$ | 9.30                  | 9.30                        |
| $p - value$             | 0.50                  | 0.50                        |

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