

A. Its.

$\varphi(z), z \in \mathbb{C} : |z|=1$  

$T_n[\varphi] = \{ \varphi_{j-k} \}_{j,k=0, \dots, n-1}$  truncated Toeplitz matrices

$D_n = \det T_n$

Multiple integral representation:

$$D_n = \frac{1}{(2\pi i)^n n!} \int_{\mathbb{C}} \dots \int_{\mathbb{C}} \prod_{j < k} |z_j - z_k|^2 \prod_{j=1}^n \frac{\varphi(z_j)}{z_j} dz_j$$

Also,  $D_n = \prod_{k=0}^{n-1} h_k$ , where  $h_n$  is related to OPUC:

Given the symbol  $\varphi$ , we can define monic orthogonal polynomials  $\{ P_n(z) \}_{n=0}^{\infty}$ ,  $P_n(z) = z^n + \dots$  such that

$$\int_{\mathbb{C}} z^{-k} P_n(z) \varphi(z) \frac{dz}{2\pi i z} = 0, \quad k=0, 1, \dots, n-1.$$

or  $\int_{\mathbb{C}} z^{-k} P_n(z) \varphi(z) \frac{dz}{2\pi i z} = \boxed{h_n} \delta_{nk}, \quad k=0 \dots n.$

We also define  $Q_n(z) = -\frac{z^n}{h_n} \widehat{P}_n(z^{-1})$ , where

$$\int_{\mathbb{C}} \widehat{P}_n(z^{-1}) z^k \varphi(z) \frac{dz}{2\pi i z} = \widehat{h}_n \delta_{nk}, \quad k=0 \dots n.$$

Additionally,  $\int_{\mathbb{C}} P_n(z) \widehat{P}_n(z^{-1}) \varphi(z) \frac{dz}{2\pi i z} = h_n \delta_{nk}$

Classical situation:  $\varphi(z) = \overline{\varphi(1/z)}$ , then  $\widehat{P}(z^{-1}) = \overline{P(z)}$   
and  $\widehat{P}(z|\varphi) = \overline{P(\bar{z}|\bar{\varphi})}$

Obs.  $\ln D_n(z) = - \int_0^1 \left[ \int_C (P_n'(z|\gamma) Q_{n-1}(z|\gamma) - P_n(z|\gamma) Q_{n-1}'(z|\gamma)) z^{-n} \frac{\varphi(z)-1}{2\pi i} dz \right] d\gamma$

where  $P_n(z|\gamma) = \varphi_\gamma = \gamma\varphi + 1 - \gamma$ , and

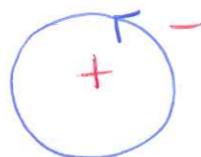
$$Q_n(z) = \frac{1}{h_n} z^n \widehat{P}_n(z^{-1}).$$

Riemann-Hilbert representation of OPUC  
(Beike-Deift-Johansson).

Define  $Y(z) = \begin{pmatrix} P_n(z) & \int_C \frac{P_n(s) s^{-n} \varphi(s)}{s-z} \frac{ds}{2\pi i} \\ Q_{n-1}(z) & \int_C \frac{Q_{n-1}(s) s^{-n} \varphi(s)}{s-z} \frac{ds}{2\pi i} \end{pmatrix}$

it satisfies

$\mathbb{I} \circ Y(z) \in \mathcal{H}(\mathbb{C} \setminus C)$



$\mathbb{II} \circ Y_+(z) = Y_-(z) \begin{pmatrix} 1 & z^{-n} \varphi(z) \\ 0 & 1 \end{pmatrix}$

$\mathbb{III} \circ Y(z) = (\mathbb{I} + \mathcal{O}(\frac{1}{z})) \begin{pmatrix} z^n & 0 \\ 0 & z^{-n} \end{pmatrix}$  as  $z \rightarrow \infty$ .

Obs.  $Y(z) = \begin{pmatrix} z^n & \mathcal{O}(z^{-n-1}) \\ \mathcal{O}(z^{n-1}) & z^{-n} + \mathcal{O}(z^{-n-1}) \end{pmatrix}$

(1,2) entry:  $\int_C \frac{P_n(s) s^{-n} \varphi(s)}{s-z} \frac{ds}{2\pi i}$   
 $= - \sum_{k=0}^{\infty} \frac{1}{z^{k+1}} \int_C P_n(s) s^{k-n+1} \varphi(s) \frac{ds}{2\pi i}$

But  $\int_C P_n(z) z^{-k} \varphi(z) \frac{dz}{2\pi i z} = 0$ , so

orthogonality gives  $Y_{12}(z) = O(z^{-n-1})$  as  $z \rightarrow \infty$ .

Obs 1) let  $Y(z) = 1$

2) Suppose that  $\tilde{Y}(z)$  satisfies I-III, then take

$\tilde{Y}(z)Y^{-1}(z)$ , this is identity, so I-III determines

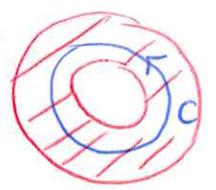
$Y(z)$  uniquely.

Taking I-III as definition of  $Y$ , we can try to obtain large  $n$  asymptotics, and then  $P_n(z) = Y_n(z)$  and  $h_n = Y_{12}(0)$ .

We rewrite :

$$\ln D_n(z) = - \int_0^1 \left[ \int_C (Y_{11}'(z) Y_{21}(z) - Y_n(z) Y_{21}'(z)) z^{-n} \frac{\varphi(z)-1}{2\pi i} dz \right] dr$$

Assume that  $\varphi(z)$  is analytic in an annulus :



$\varphi(z) = e^{V(z)}$ , where

$$V(z) = \sum_{k=-\infty}^{\infty} V_k z^k \quad (\text{convergent Laurent series})$$

First transformation :  $Y(z) \mapsto T(z) = Y(z) \begin{cases} z^{n\sigma_3}, & |z| > 1 \\ I, & |z| < 1 \end{cases}$

so for  $T(z)$  we have the jump:

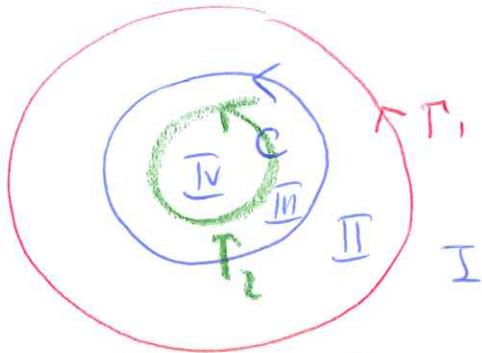
$$T_+(z) = T_-(z) \begin{pmatrix} z^n & \varphi(z) \\ 0 & z^{-n} \end{pmatrix}$$

*Oscillatory matrix!*

and the asymptotics  $T(\infty) = I$ .

Now,

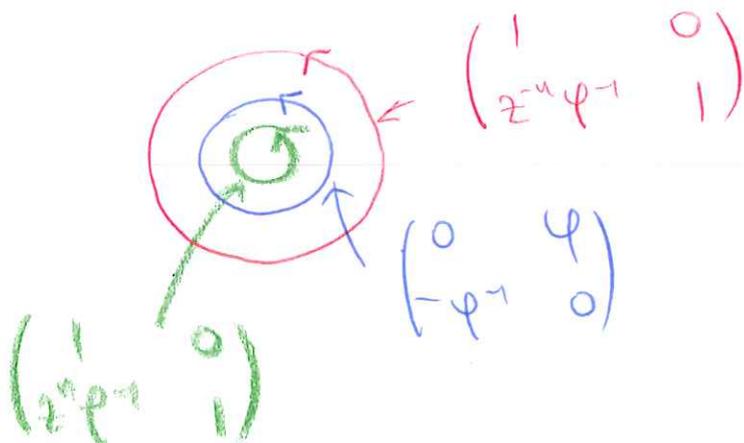
$$\begin{pmatrix} z^n & \varphi \\ 0 & z^{-n} \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ z^{-n}\varphi^{-1} & 1 \end{pmatrix}}_{\text{Deform to outer contour}} \begin{pmatrix} 0 & \varphi \\ -\varphi^{-1} & 0 \end{pmatrix} \underbrace{\begin{pmatrix} 1 & 0 \\ z^n\varphi^{-1} & 1 \end{pmatrix}}_{\text{Deform to inner contour}}$$



Second transformation:

$$T \rightarrow S(z) = T(z) \begin{cases} \begin{pmatrix} 1 & 0 \\ z^{-n}\varphi^{-1} & 1 \end{pmatrix}, & z \in \text{II} \\ \begin{pmatrix} 1 & 0 \\ -z^n\varphi^{-1} & 1 \end{pmatrix}, & z \in \text{III} \\ \text{I}, & z \in \text{I} \cup \text{IV} \end{cases}$$

So  $S$  satisfies the RHP on three contours:



plus identity at infinity. The jumps on  $T_1 \cup T_2$  are exponentially close to identity, so we expect that as  $n \rightarrow \infty$ ,  $S(z) \sim S^{(\infty)}$ , where  $S^{(\infty)}$  satisfies a RHP with a jump on  $\mathbb{C}$  only:

$$S_+^{(\infty)} = S_-^{(\infty)} \begin{pmatrix} 0 & \varphi \\ -\varphi^{-1} & 0 \end{pmatrix}, \quad z \in \mathbb{C}$$

## Szegő function:

(3)

$D(z) = \exp \left\{ \frac{1}{2\pi i} \int_C \frac{\ln \varphi(s)}{s-z} ds \right\}$ , which solves the following scalar problem:  $D_+ = D_- \varphi$  on  $C$ , so

$$S^{(\infty)}(z) = D^{\sigma_3}(z) \begin{cases} I, & |z| > 1 \\ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, & |z| < 1 \end{cases}$$

Tracing back the transformations, we obtain for the first column

$$[Y(z)]_1 \cong D_+^{\sigma_3}(z) \begin{pmatrix} \varphi^{-1} z^n \\ -1 \end{pmatrix} + O(\varphi^{-n}), \quad |\varphi| > 1.$$

Obs.  $\varphi = \varphi_\gamma$ , deformation of the original symbol

$$\varphi_\gamma \equiv \gamma \varphi(z) + 1 - \gamma$$

$$\text{Now, } Y_{11} = D_+ \varphi_\gamma^{-1} z^n$$

$$Y_{21} = -D_+^{-1}, \quad \text{and therefore}$$

$$Y_{11}' Y_{21} - Y_{11} Y_{21}' = -2 D_+^{-1} D_+^{-1} \varphi_\gamma^{-1} z^n + \varphi_\gamma^{-2} \varphi_\gamma' z^n - n \varphi_\gamma^{-1} z^{n-1},$$

and then

$$\ln D_n \cong I_1 + I_2 + I_3, \quad \text{where}$$

$$I_1 = \int_0^1 \int_C D_+^{-1} D_+^{-1} \varphi_\gamma^{-1} \frac{\varphi_\gamma^{-1}}{2\pi i} dz d\gamma$$

$$I_2 = - \int_0^1 \int_C \varphi_\gamma^{-2} \varphi_\gamma' \frac{\varphi_\gamma^{-1}}{2\pi i} dz d\gamma$$

$$I_3 = n \int_0^1 \int_C \varphi_\gamma^{-1} \frac{\varphi_\gamma^{-1}}{2\pi i} \frac{dz}{z} d\gamma$$

Obs  $\psi_r - 1 = \frac{d\psi_r}{dr}$ , so

$$I_3 = n \int_0^1 \int_C \frac{d}{dr} \ln \psi_r \frac{dz}{2\pi i z} dr$$

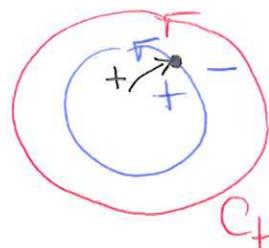
$$= n \int_C \ln \psi \frac{dz}{2\pi i z} = n (\ln \psi)_0.$$

We can check that  $I_2 = 0$ , integrating with respect to  $z$  for each fixed  $r$  (winding 0 for any  $r$ )

Now,  $D_+(z) = \exp\left(\frac{1}{2\pi i} \int_C \frac{\ln \psi_r(s)}{s-z} ds\right)$

$$= \exp\left(\frac{1}{2\pi i} \int_{C_+} \frac{\ln \psi_r(s)}{s-z} ds\right)$$

↑  
by analyticity of  $\psi_r$ .



So  $D_+^{-1} D_+^{-1} = \frac{1}{2\pi i} \int \frac{\ln \psi_r(s)}{(s-z)^2} ds$ , and then

$$I_1 = 2 \int_0^1 \int_C \int_{C_+} \frac{\ln \psi_r(s)}{(s-z)^2} \frac{d}{dr} \ln \psi_r \frac{ds dz}{(2\pi i)^2}$$

$$= \int_0^1 \int_C \int_{C_+} \frac{\ln \psi_r(s) \frac{d}{dr} \ln \psi_r(z) + \ln \psi_r(z) \frac{d}{dr} \ln \psi_r(s)}{(s-z)^2} \frac{ds dz}{(2\pi i)^2}$$

+ (residue when switching  $C$  and  $C_+$ )  
||  
○ (exercise)

$$= \int_C \int_{C_+} \frac{\ln \psi_r(s) \ln \psi_r(z)}{(z-s)^2} \frac{ds dz}{(2\pi i)^2}$$

$$\begin{aligned}
 &= \int_C \ln \psi(z) \frac{d}{dz} \int_{C_+} \frac{\ln \psi(s)}{s-z} \frac{ds dz}{(2\pi i)^2} \\
 &= \int_C \ln \psi(z) \left( \underbrace{\sum_{k=1}^{\infty} k z^{k-1} \int_{C_+} \ln \psi(s) s^{-k-1} \frac{ds}{2\pi i}}_{(\ln \psi(z))_k} \right) \frac{dz}{2\pi i} \\
 &= \sum_{k=1}^{\infty} k (\ln \psi)_k \int_C \ln \psi(z) z^{k-1} \frac{dz}{2\pi i} \\
 &= \sum_{k=1}^{\infty} k (\ln \psi)_k (\ln \psi)_k.
 \end{aligned}$$



Fisher-Hartwig symbols

$$\psi(z) = e^{V(z)} \underbrace{|z-1|^{2\alpha}}_{\text{root}} \underbrace{z^\beta e^{-\beta \pi i}}_{\text{jump}}, \quad \begin{matrix} 2\alpha > -1 \\ 0 < \arg z < 2\pi \end{matrix}$$

In this case

$$\ln D_n = n V_0 + \underbrace{\sum_{k=1}^{\infty} k V_k V_{-k}}_{\text{regular part (SSLT)}} - (\alpha - \beta) \sum_{k=1}^{\infty} V_k - (\alpha + \beta) \sum_{k=1}^{\infty} V_{-k}$$

$$+ \underbrace{(\alpha^2 - \beta^2) \ln n}_{\text{power-type behaviour}} + \ln \frac{\Gamma(1+\alpha-\beta) \Gamma(1+\alpha+\beta)}{\Gamma(1+2\alpha)} + o(1),$$

where  $\Gamma(x)$  is the Barnes  $\Gamma$ -function,  $\Gamma(x+1) = \Gamma(x) \Gamma(x)$

Obs. We can write

$$\psi(z) = e^{V(z)} (z-1)^{2\alpha} z^{-\alpha+\beta} e^{-\pi i(\alpha+\beta)}, \quad \text{since}$$

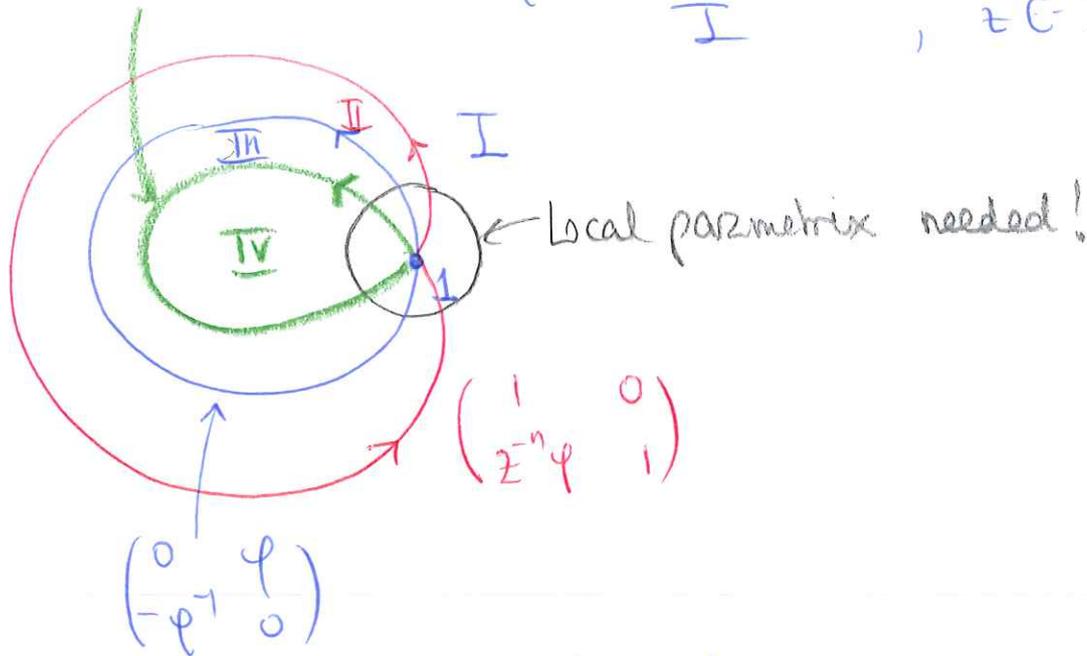
$$|z-1|^{2\alpha} = (z-1)^{2\alpha} z^{-\alpha} e^{-\pi i \alpha} \quad \begin{matrix} (z-1)^{2\alpha} \\ z^{-\alpha} \end{matrix}$$

Check:  $|z-1|^{2\alpha} = (z-1)^\alpha (\bar{z}-1)^\alpha$   
 $= (z-1)^\alpha \left(\frac{1}{z}-1\right)^\alpha$

$$Y(z) \rightarrow T(z) = Y(z) \begin{cases} z^{-n\sigma_3} & , |z| > 1 \\ I & , |z| < 1 \end{cases}$$

with  $T_+ = T_- \begin{pmatrix} z^n & \varphi \\ 0 & z^{-n} \end{pmatrix} = T_- \begin{pmatrix} 1 & 0 \\ z^{-n}\varphi^{-1} & 1 \end{pmatrix} \begin{pmatrix} 0 & \varphi \\ -\varphi^{-1} & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ z^n\varphi^{-1} & 1 \end{pmatrix}$

then  $T \rightarrow S = T \begin{cases} \begin{pmatrix} z^n\varphi & 0 \\ 1 & 1 \end{pmatrix} & , z \in \text{II} \\ \begin{pmatrix} 1 & 0 \\ -z^n\varphi & 1 \end{pmatrix} & , z \in \text{III} \\ I & , z \in \text{I} \cup \text{IV} \end{cases}$



Global parametrix:  $S^{(\infty)} = P^{(\infty)}(z)$ , which satisfies

$$P_+^{(\infty)} = P_-^{(\infty)} \begin{pmatrix} 0 & \varphi \\ -\varphi^{-1} & 0 \end{pmatrix}, \quad z \in \mathbb{C}, \quad P^{(\infty)}(\infty) = I,$$

and again

$$P^{(\infty)}(z) = \mathcal{D}^{\sigma_3}(z) \begin{cases} I & , |z| > 1 \\ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} & , |z| < 1. \end{cases}$$

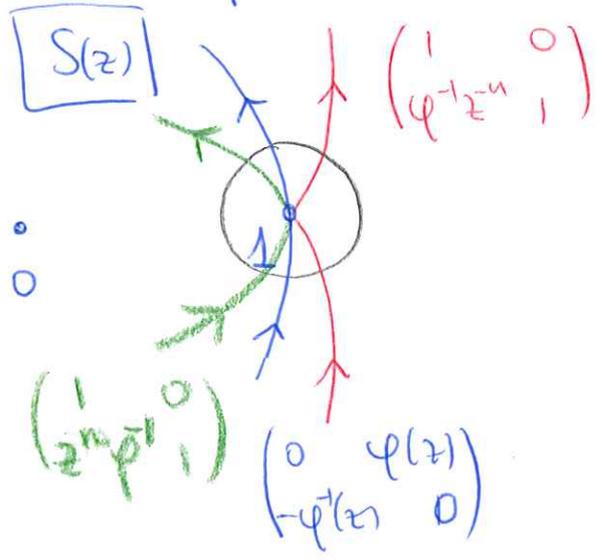
If we write

$$V(z) = V_+ + V_- = \sum_{k=0}^{\infty} z^k V_k + \sum_{k=-\infty}^{-1} z^k V_k, \text{ then}$$

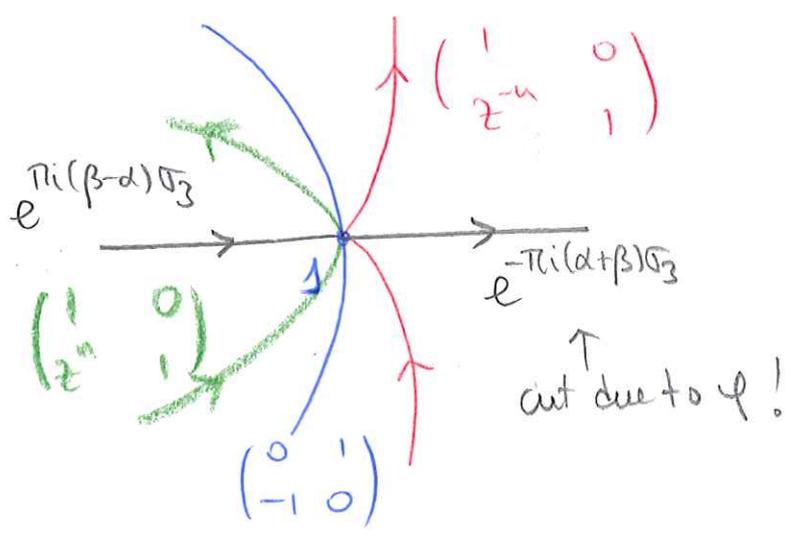
$$D(z) = \begin{cases} e^{V_+} (z-1)^{\alpha+\beta} e^{-i\pi(\alpha+\beta)}, & |z| < 1 \\ e^{-V_-} \left(\frac{z-1}{z}\right)^{-\alpha+\beta}, & |z| > 1 \end{cases}$$

as explicit factorisation ( $D_+ = D_- \varphi$ ).

Local parameatrix?

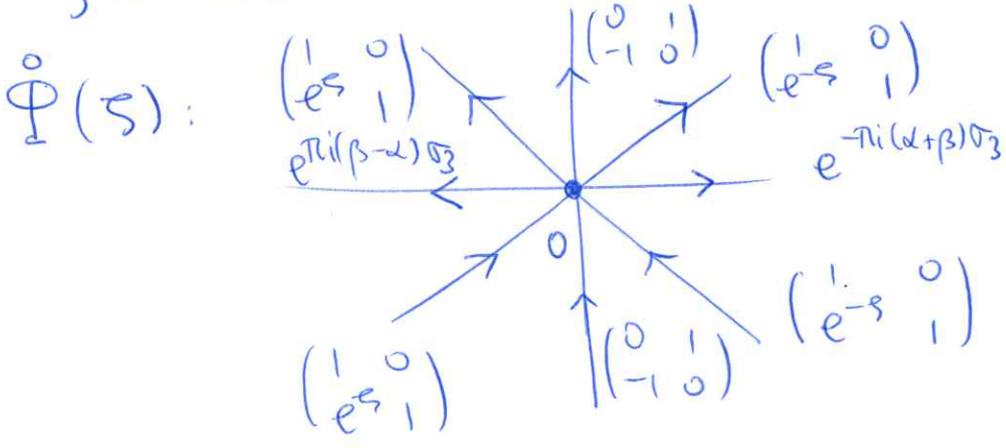


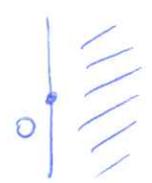
Define  $\tilde{S}(z) = S(z) \varphi^{\sigma_2/2}$ , then

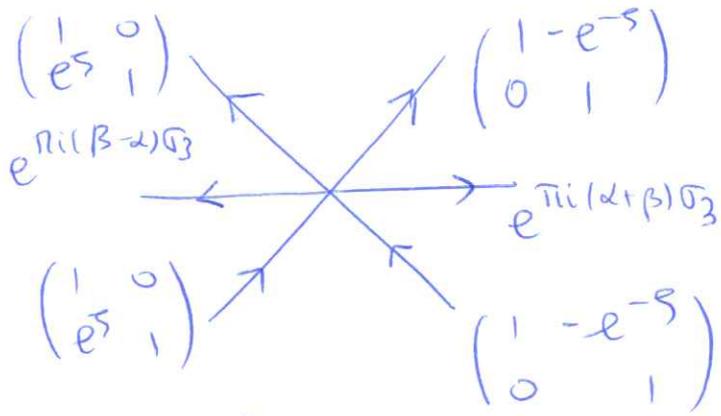


Local variable:

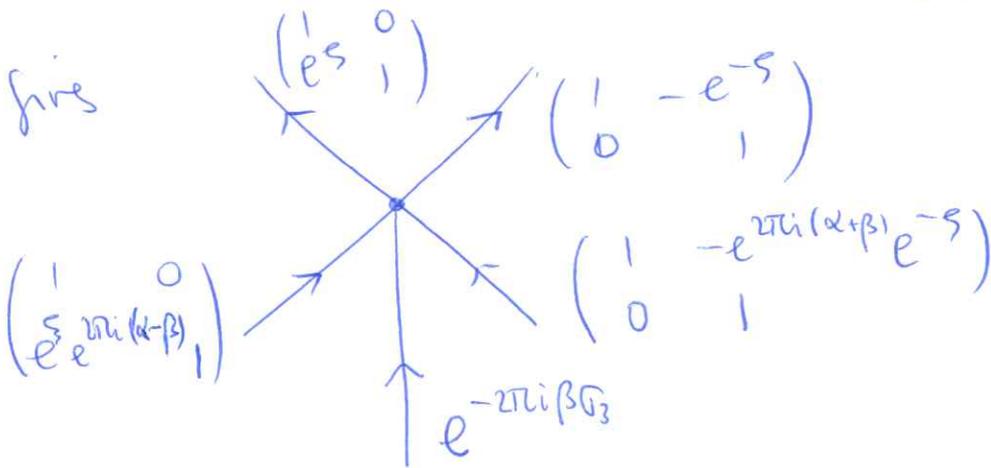
$$\varphi = n \cdot \ln z = n(z-1) + \dots, \quad z \rightarrow 1$$



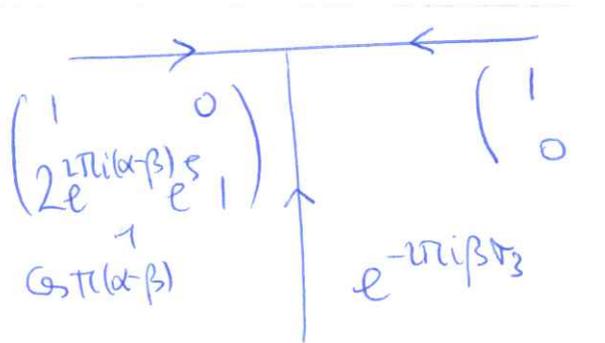
Then  $\dot{\Phi} \rightarrow \overset{1}{\Phi}(\varsigma) = \dot{\Phi}(\varsigma) \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  



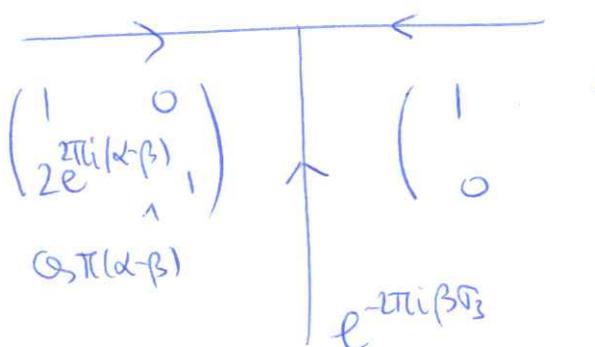
Now  $\overset{1}{\Phi}(\varsigma) \rightarrow \overset{2}{\Phi}(\varsigma) = \overset{1}{\Phi}(\varsigma) \cdot \begin{cases} e^{\pi i (\alpha + \beta) \sigma_3} \\ e^{-\pi i (\beta - \alpha) \sigma_3} \end{cases}$  



Next,  $\overset{2}{\Phi}(\varsigma) \rightarrow \overset{3}{\Phi}(\varsigma) \rightarrow \overset{3}{\Psi}(\varsigma) = \overset{3}{\Phi}(\varsigma) e^{-\frac{\varsigma}{2} \sigma_3}$



$\begin{pmatrix} 1 & 0 \\ 2e^{2\pi i (\alpha - \beta) s} e^s & 1 \end{pmatrix}$   $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$   $-e^{-\varsigma} 2 e^{-\pi i (\alpha + \beta)} \cos(\pi(\alpha + \beta))$   $\overset{3}{\Phi}(\varsigma)$



$\begin{pmatrix} 1 & 0 \\ 2e^{\pi i (\alpha - \beta) s} & 1 \end{pmatrix}$   $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$   $-2 e^{-\pi i (\alpha + \beta)} \cos \pi(\alpha + \beta)$   $\overset{3}{\Psi}(\varsigma)$

Also,  $\hat{\Psi}(s) = (I + O(1/s)) e^{-\frac{s}{2}\sqrt{3}} s^{-\beta\sqrt{3}}$ ,  $s \rightarrow \infty$  (6)

and  $\hat{\Psi}(s) = \hat{\mathbb{I}}(s) s^{\alpha\sqrt{3}}$  (Cj) Constant matrices depending on different regions

Notation:  $\Psi(s) \equiv \hat{\Psi}(s)$ , and consider

$\frac{d\Psi}{ds} \Psi^{-1}$  is holomorphic in  $\mathbb{C} \setminus \{0\}$  (no jumps)

$$\left| \frac{d\Psi}{ds} \Psi^{-1} = -\frac{1}{2}\sqrt{3} + \frac{1}{s} A_0 \right|, \text{ where } A_0 = \begin{pmatrix} -\beta & a \\ b & \beta \end{pmatrix}, \text{ and}$$

if  $\Psi(s) = (I + \frac{m}{s} + \dots) e^{-\frac{s}{2}\sqrt{3}} s^{-\beta\sqrt{3}}$ , then  $\downarrow$  eig.  $\pm \alpha$

$$a = 2(m)_{12}, \quad b = -2(m)_{21}.$$

So  $\frac{d\Psi}{ds} = \left( -\frac{1}{2}\sqrt{3} + \frac{1}{s} A_0 \right) \Psi$ , linear ODE with rational coeffs. with irregular sing. at  $\infty$  and regular sing. at 0.

Monodromy data:  $M = \{ S_1, S_2, C \}$ , with Stokes matrices  $S_1 = \begin{pmatrix} 1 & 0 \\ s_1 & 1 \end{pmatrix}$ ,  $S_2 = \begin{pmatrix} 1 & s_2 \\ 0 & 1 \end{pmatrix}$ , with the relation  $S_1 S_2 = 2e^{-2\pi i \beta} (\cos 2\pi \alpha - \cos 2\pi \beta)$ .

Obs  $\dim M = \dim A$ .

(a, b)  $\leftrightarrow$  (s<sub>1</sub>, s<sub>2</sub>) (Direct/inverse monodromy problem)

First component:

$$\xi \Upsilon_{11}'' + \Upsilon_{11}' + \left( \frac{1}{2} - \frac{\xi}{4} - \frac{\alpha^2}{\xi} - \beta \right) \Upsilon_{11} = 0$$

We can write  $\Upsilon_{11} = \xi^\alpha w(\xi)$ , which gives

$$\xi w'' + (2\alpha+1)w' + \left( \frac{1}{2} - \beta - \frac{\xi}{4} \right) w = 0$$

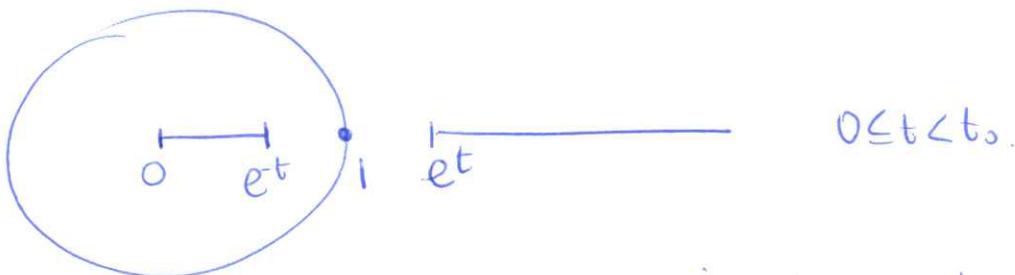
best transformation:  $w(\xi) = e^{-\xi/2} v(\xi)$ , then

$$\xi v'' + (2\alpha+1-\xi)v' - (\alpha+\beta)v = 0$$

Confluent hypergeometric function,  $v = \mathcal{F}(\alpha+\beta, 1+2\alpha; \xi)$ .

Transition asymptotics

$$\psi(z) = e^{v(z)} (z - e^{-t})^{\alpha+\beta} (z - e^t)^{\alpha-\beta} z^{-\alpha+\beta} e^{-\pi i(\alpha+\beta)}$$



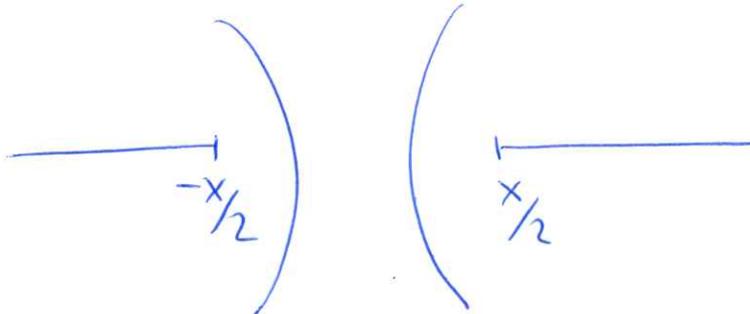
Monodromy theory and Painlevé equations

$$\frac{d\Upsilon}{d\xi} = \left[ -\frac{\beta_3}{2} + \frac{A_0}{\xi} \right] \Upsilon \rightarrow \text{Confluent hypergeometric}$$

We add one more singularity

$$\frac{d\Upsilon}{d\xi} = \left[ -\frac{\beta_3}{2} + \frac{A_0}{\xi} + \frac{1}{\xi-x} A_x \right] \Upsilon \rightarrow \text{Painlevé II}$$

Now  $\dim \mathcal{M} = \dim \mathcal{A} - 1$ , so there is a one-parameter family of equations with the same monodromy data.



We can say that  $P_{\square}$  is a non-linear confluent hypergeometric function.

$$\frac{dY}{dS} = [S A_1 + A_0] Y \rightarrow \text{Parabolic cylinder function}$$

$$\frac{dY}{dS} = [S^2 A_2 + S A_1 + A_0] Y \rightarrow P_{\square} \text{ (one parameter)}$$

But also  $\frac{dY}{dS} = [S A_1 + A_0 + \frac{A_{-1}}{S}] Y \rightarrow P_{\square}$   
*(two parameters)*

*A<sub>2</sub> nilpotent  $\rightarrow$  P<sub>I</sub>*

Bessel:  $\frac{dY}{dS} = [A_1 + \frac{A_0}{S}] Y$  and then

$$\frac{dY}{dS} = [A_1 + \frac{A_0}{S} + \frac{A_2}{S^2}] Y \rightarrow P_{\square}$$

Hypergeometric  $\frac{dY}{dS} = (\frac{A_1}{S} + \frac{A_2}{S-1}) Y$  and then

$$\frac{dY}{dS} = (\frac{A_1}{S} + \frac{A_2}{S-1} + \frac{A_3}{S-x}) Y \rightarrow P_{\square}$$

