

Hörmander's theorem for semilinear SPDEs

Andris Gerasimovičs

Imperial College London

Marseille, April 25, 2019

Joint work with Martin Hairer

Framework

We consider a general semilinear Stratonovich SPDE

$$du_t = Lu_t dt + N(u_t)dt + \sum_{i=1}^d F_i(u_t) \circ dB_t^i, \quad u_0 \in \mathcal{H}, \quad (\text{SPDE})$$

1. L is a selfadjoint unbounded operator on a Hilbert space $\mathcal{H}$, that induces an analytic semigroup S_t and a family of interpolation spaces $\mathcal{H}_\alpha$ for $\alpha \in \mathbb{R}$.
2. B is d -dimensional Brownian motion.
3. $N \in C^\infty(\mathcal{H}, \mathcal{H}_{-\delta})$ for $0 \leq \delta < 1$, and $F_i \in C^\infty(\mathcal{H}, \mathcal{H})$.

Framework

We consider a general semilinear Stratonovich SPDE

$$du_t = Lu_t dt + N(u_t)dt + \sum_{i=1}^d F_i(u_t) \circ dB_t^i, \quad u_0 \in \mathcal{H}, \quad (\text{SPDE})$$

1. L is a selfadjoint unbounded operator on a Hilbert space $\mathcal{H}$, that induces an analytic semigroup S_t and a family of interpolation spaces $\mathcal{H}_\alpha$ for $\alpha \in \mathbb{R}$.
2. B is d -dimensional Brownian motion.
3. $N \in C^\infty(\mathcal{H}, \mathcal{H}_{-\delta})$ for $0 \leq \delta < 1$, and $F_i \in C^\infty(\mathcal{H}, \mathcal{H})$.

Framework

We consider a general semilinear Stratonovich SPDE

$\mathcal{H} = \mathcal{H}_0$ and for all $\alpha \geq \beta$ and every $\sigma \in [0, 1]$, one has

1. $\|S_t u\|_{\mathcal{H}_\alpha} \lesssim t^{\beta-\alpha} \|u\|_{\mathcal{H}_\beta} , \quad \|S_t u - u\|_{\mathcal{H}_{\beta-\sigma}} \lesssim t^\sigma \|u\|_{\mathcal{H}_\beta} .$

2. B is d -dimensional Brownian motion.

3. $N \in C^\infty(\mathcal{H}, \mathcal{H}_{-\delta})$ for $0 \leq \delta < 1$, and $F_i \in C^\infty(\mathcal{H}, \mathcal{H})$.

Framework

We consider a general semilinear Stratonovich SPDE

$$du_t = Lu_t dt + N(u_t)dt + \sum_{i=1}^d F_i(u_t) \circ dB_t^i, \quad u_0 \in \mathcal{H}, \quad (\text{SPDE})$$

1. L is a selfadjoint unbounded operator on a Hilbert space $\mathcal{H}$, that induces an analytic semigroup S_t and a family of interpolation spaces $\mathcal{H}_\alpha$ for $\alpha \in \mathbb{R}$.
2. B is d -dimensional Brownian motion.
3. $N \in C^\infty(\mathcal{H}, \mathcal{H}_{-\delta})$ for $0 \leq \delta < 1$, and $F_i \in C^\infty(\mathcal{H}, \mathcal{H})$.

Framework

We consider a general semilinear Stratonovich SPDE

$$du_t = Lu_t dt + N(u_t)dt + \sum_{i=1}^d F_i(u_t) \circ dB_t^i, \quad u_0 \in \mathcal{H}, \quad (\text{SPDE})$$

1. L is a selfadjoint unbounded operator on a Hilbert space $\mathcal{H}$, that induces an analytic semigroup S_t and a family of interpolation spaces $\mathcal{H}_\alpha$ for $\alpha \in \mathbb{R}$.
2. B is d -dimensional Brownian motion.
3. $N \in C^\infty(\mathcal{H}, \mathcal{H}_{-\delta})$ for $0 \leq \delta < 1$, and $F_i \in C^\infty(\mathcal{H}, \mathcal{H})$.

Examples

Navier-Stokes equation in 2 dimensions:

$$dw_t = \Delta w_t dt + \nabla \cdot (w_t \mathcal{K}(w_t)) dt + \sum_{j=1}^d (f_j + g_j w_t) \circ dB_t^j.$$

$$w_0 \in L^2(\mathbb{T}^2, \mathbb{R}), \mathcal{K} = \text{curl} \Delta^{-1}, f_j, g_j \in C^\infty(\mathbb{T}^2, \mathbb{R})$$

Reaction-Diffusion equations:

$$du_t(x) = \Delta u_t dt + p_0(u_t(x)) dt + \sum_{j=1}^d f_j(x) p_j(u_t(x)) \circ dB_t^j.$$

$$u_0 \in H^1(\mathbb{T}, \mathbb{R}), p_i \text{ are polynomials, } f_j \in C^\infty(\mathbb{T}, \mathbb{R}).$$

Examples

Navier-Stokes equation in 2 dimensions:

$$dw_t = \Delta w_t dt + \nabla \cdot (w_t \mathcal{K}(w_t)) dt + \sum_{j=1}^d (f_j + g_j w_t) \circ dB_t^j.$$

$$w_0 \in L^2(\mathbb{T}^2, \mathbb{R}), \mathcal{K} = \text{curl } \Delta^{-1}, f_j, g_j \in C^\infty(\mathbb{T}^2, \mathbb{R})$$

Reaction-Diffusion equations:

$$du_t(x) = \Delta u_t dt + p_0(u_t(x)) dt + \sum_{j=1}^d f_j(x) p_j(u_t(x)) \circ dB_t^j.$$

$$u_0 \in H^1(\mathbb{T}, \mathbb{R}), p_i \text{ are polynomials, } f_j \in C^\infty(\mathbb{T}, \mathbb{R}).$$

Malliavin calculus

Let $\Omega = C([0, T], \mathbb{R}^d)$ be a Wiener space for the Brownian motion. Denote by $\mathcal{CM} = H^1([0, T], \mathbb{R}^d)$ a Cameron Martin space of the Wiener measure.

Malliavin derivative $\mathcal{D}u_t : \Omega \rightarrow \mathcal{CM} \otimes \mathcal{H}$ of the solution to (SPDE) is defined for every $h \in \mathcal{CM}$ as a limit in probability:

$$\langle \mathcal{D}u_t(\omega), h \rangle_{\mathcal{CM}} = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-1} (u_t(\omega + \varepsilon h) - u_t(\omega)) .$$

Malliavin matrix $\mathcal{M}_t : \mathcal{H} \rightarrow \mathcal{H}$ of the solution is a positive semi-definite operator defined by

$$\mathcal{M}_t = \langle \mathcal{D}u_t, \mathcal{D}u_t \rangle_{\mathcal{CM}} .$$

Malliavin calculus

Let $\Omega = C([0, T], \mathbb{R}^d)$ be a Wiener space for the Brownian motion. Denote by $\mathcal{CM} = H^1([0, T], \mathbb{R}^d)$ a Cameron Martin space of the Wiener measure.

Malliavin derivative $\mathcal{D}u_t : \Omega \rightarrow \mathcal{CM} \otimes \mathcal{H}$ of the solution to (SPDE) is defined for every $h \in \mathcal{CM}$ as a limit in probability:

$$\langle \mathcal{D}u_t(\omega), h \rangle_{\mathcal{CM}} = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-1} (u_t(\omega + \varepsilon h) - u_t(\omega)) .$$

Malliavin matrix $\mathcal{M}_t : \mathcal{H} \rightarrow \mathcal{H}$ of the solution is a positive semi-definite operator defined by

$$\mathcal{M}_t = \langle \mathcal{D}u_t, \mathcal{D}u_t \rangle_{\mathcal{CM}} .$$

Malliavin calculus

Let $\Omega = C([0, T], \mathbb{R}^d)$ be a Wiener space for the Brownian motion. Denote by $\mathcal{CM} = H^1([0, T], \mathbb{R}^d)$ a Cameron Martin space of the Wiener measure.

Malliavin derivative $\mathcal{D}u_t : \Omega \rightarrow \mathcal{CM} \otimes \mathcal{H}$ of the solution to (SPDE) is defined for every $h \in \mathcal{CM}$ as a limit in probability:

$$\langle \mathcal{D}u_t(\omega), h \rangle_{\mathcal{CM}} = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-1} (u_t(\omega + \varepsilon h) - u_t(\omega)) .$$

Malliavin matrix $\mathcal{M}_t : \mathcal{H} \rightarrow \mathcal{H}$ of the solution is a positive semi-definite operator defined by

$$\mathcal{M}_t = \langle \mathcal{D}u_t, \mathcal{D}u_t \rangle_{\mathcal{CM}} .$$

Smooth Densities

Theorem: Let X be Malliavin smooth $\mathbb{R}^n$ valued random variable, such that $\mathcal{D}^k X$ has moments of all orders for all $k \in \mathbb{N}$. Moreover assume that Malliavin Matrix $\mathcal{M} = \langle \mathcal{D}X, \mathcal{D}X \rangle_{\mathcal{CM}}$ is almost surely invertible and has inverse moments of all orders. Then the law of X has a smooth density with respect to Lebesgue measure on $\mathbb{R}^n$.

Hörmander's theorem

Theorem (G. & Hairer 2018): Let u be a solution to (SPDE) and assume that $\mathbb{E}\|u_t\|^p < \infty$ for all $t > 0$ and $p \geq 1$. Assume in addition that L, N, F_i satisfy Hörmander's condition. Then for every finite dimensional projection $\Pi : \mathcal{H} \rightarrow \mathcal{H}$ and for every $t > 0$

$$\mathbb{P}\left(\inf_{\|\Pi\varphi\|=1} \frac{\langle \mathcal{M}_t \varphi, \varphi \rangle}{\|\varphi\|^2} \leq \varepsilon\right) \leq C_p \varepsilon^p.$$

Corollary: Every finite dimensional projection of the solution Πu_t has a smooth density with respect to Lebesgue measure on $\Pi(\mathcal{H})$.

Hörmander's theorem

Theorem (G. & Hairer 2018): Let u be a solution to (SPDE) and assume that $\mathbb{E}\|u_t\|^p < \infty$ for all $t > 0$ and $p \geq 1$. Assume in addition that L, N, F_i satisfy Hörmander's condition. Then for every finite dimensional projection $\Pi : \mathcal{H} \rightarrow \mathcal{H}$ and for every $t > 0$

$$\mathbb{P}\left(\inf_{\|\Pi\varphi\|=1} \frac{\langle \mathcal{M}_t \varphi, \varphi \rangle}{\|\varphi\|^2} \leq \varepsilon\right) \leq C_p \varepsilon^p.$$

Corollary: Every finite dimensional projection of the solution Πu_t has a smooth density with respect to Lebesgue measure on $\Pi(\mathcal{H})$.

Duhamel's formula

The Jacobian $J_{t,s}$ of the solution satisfies the following equation

$$\begin{cases} dJ_{t,s} = LJ_{t,s}dt + DN(u_t)J_{t,s}dt + \sum_{i=1}^d DF_i(u_t)J_{t,s} \circ dB_t^i, \\ J_{s,s} = \text{id}. \end{cases}$$

DN, DF_i are Fréchet derivatives.

One can derive an SPDE for the Malliavin derivative and use Duhamel's formula to obtain for $\varphi \in \mathcal{H}$:

$$\langle \mathcal{M}_t \varphi, \varphi \rangle = \sum_{i=1}^d \int_0^t \langle J_{t,s} F_i(u_s), \varphi \rangle^2 ds.$$

Duhamel's formula

The Jacobian $J_{t,s}$ of the solution satisfies the following equation

$$\begin{cases} dJ_{t,s} = LJ_{t,s}dt + DN(u_t)J_{t,s}dt + \sum_{i=1}^d DF_i(u_t)J_{t,s} \circ dB_t^i, \\ J_{s,s} = \text{id}. \end{cases}$$

DN, DF_i are Fréchet derivatives.

One can derive an SPDE for the Malliavin derivative and use Duhamel's formula to obtain for $\varphi \in \mathcal{H}$:

$$\langle \mathcal{M}_t \varphi, \varphi \rangle = \sum_{i=1}^d \int_0^t \langle J_{t,s} F_i(u_s), \varphi \rangle^2 ds.$$

Sketch of the proof

Aim: for all $p \geq 1$, $\varepsilon > 0$: $\mathbb{P}\left(\inf_{\|\Pi\varphi\|=1} \frac{\langle \mathcal{M}_t \varphi, \varphi \rangle}{\|\varphi\|^2} \leq \varepsilon\right) \leq C_p \varepsilon^p$.

Denote $F_0 = L + N$ and formally differentiate $\langle J_{t,s} F_i(u_s), \varphi \rangle$:

$$d\langle J_{t,s} F_i(u_s), \varphi \rangle = \langle J_{t,s} [F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s} [F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

where $[A, B](u) = DB(u)A(u) - DA(u)B(u)$ is a Lie bracket.

Define the iterated Lie brackets:

$$\mathcal{A}_0 = \{F_i : 1 \leq i \leq d\}, \quad \mathcal{A}_{k+1} = \mathcal{A}_k \cup \{[F_i, A] : A \in \mathcal{A}_k, 0 \leq i \leq d\}.$$

Sketch of the proof

Aim: if $\|\Pi\varphi\| = 1$ then $\mathbb{P}\left(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small} \right)$ is small.

Denote $F_0 = L + N$ and formally differentiate $\langle J_{t,s} F_i(u_s), \varphi \rangle$:

$$d\langle J_{t,s} F_i(u_s), \varphi \rangle = \langle J_{t,s} [F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s} [F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

where $[A, B](u) = DB(u)A(u) - DA(u)B(u)$ is a Lie bracket.

Define the iterated Lie brackets:

$$\mathcal{A}_0 = \{F_i : 1 \leq i \leq d\}, \quad \mathcal{A}_{k+1} = \mathcal{A}_k \cup \{[F_i, A] : A \in \mathcal{A}_k, 0 \leq i \leq d\}.$$

Sketch of the proof

$$\sum_{i=1}^d \int_0^t \langle J_{t,s} F_i(u_s), \varphi \rangle^2 ds =$$

Aim: if $\|\Pi\varphi\| = 1$ then $\mathbb{P}\left(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small}\right)$ is small.

Denote $F_0 = L + N$ and formally differentiate $\langle J_{t,s} F_i(u_s), \varphi \rangle$:

$$d\langle J_{t,s} F_i(u_s), \varphi \rangle = \langle J_{t,s} [F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s} [F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

where $[A, B](u) = DB(u)A(u) - DA(u)B(u)$ is a Lie bracket.

Define the iterated Lie brackets:

$$\mathcal{A}_0 = \{F_i : 1 \leq i \leq d\}, \quad \mathcal{A}_{k+1} = \mathcal{A}_k \cup \{[F_i, A] : A \in \mathcal{A}_k, 0 \leq i \leq d\}.$$

Sketch of the proof

$$\sum_{i=1}^d \int_0^t \langle J_{t,s} F_i(u_s), \varphi \rangle^2 ds =$$

Aim: if $\|\Pi\varphi\| = 1$ then $\mathbb{P}\left(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small}\right)$ is small.

Denote $F_0 = L + N$ and formally differentiate $\langle J_{t,s} F_i(u_s), \varphi \rangle$:

$$d\langle J_{t,s} F_i(u_s), \varphi \rangle = \langle J_{t,s} [F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s} [F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

where $[A, B](u) = DB(u)A(u) - DA(u)B(u)$ is a Lie bracket.

Define the iterated Lie brackets:

$$\mathcal{A}_0 = \{F_i : 1 \leq i \leq d\}, \quad \mathcal{A}_{k+1} = \mathcal{A}_k \cup \{[F_i, A] : A \in \mathcal{A}_k, 0 \leq i \leq d\}.$$

Sketch of the proof

$$\sum_{i=1}^d \int_0^t \langle J_{t,s} F_i(u_s), \varphi \rangle^2 ds =$$

Aim: if $\|\Pi\varphi\| = 1$ then $\mathbb{P}\left(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small}\right)$ is small.

Denote $F_0 = L + N$ and formally differentiate $\langle J_{t,s} F_i(u_s), \varphi \rangle$:

$$d\langle J_{t,s} F_i(u_s), \varphi \rangle = \langle J_{t,s} [F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s} [F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

where $[A, B](u) = DB(u)A(u) - DA(u)B(u)$ is a Lie bracket.

Define the iterated Lie brackets:

$$\mathcal{A}_0 = \{F_i : 1 \leq i \leq d\}, \quad \mathcal{A}_{k+1} = \mathcal{A}_k \cup \{[F_i, A] : A \in \mathcal{A}_k, 0 \leq i \leq d\}.$$

Sketch of the proof

$$\sum_{i=1}^d \int_0^t \langle J_{t,s} F_i(u_s), \varphi \rangle^2 ds =$$

Aim: if $\|\Pi\varphi\| = 1$ then $\mathbb{P}\left(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small}\right)$ is small.

Denote $F_0 = L + N$ and formally differentiate $\langle J_{t,s} F_i(u_s), \varphi \rangle$:

$$d\langle J_{t,s} F_i(u_s), \varphi \rangle = \langle J_{t,s} [F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s} [F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

where $[A, B](u) = DB(u)A(u) - DA(u)B(u)$ is a Lie bracket.

Define the iterated Lie brackets:

$$\mathcal{A}_0 = \{F_i : 1 \leq i \leq d\}, \quad \mathcal{A}_{k+1} = \mathcal{A}_k \cup \{[F_i, A] : A \in \mathcal{A}_k, 0 \leq i \leq d\}.$$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$
Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Sketch of the proof

"Hörmander's condition": For every $u \in \mathcal{H}$, span of $\bigcup_{k \geq 0} \{A(u) : A \in \mathcal{A}_k\}$ is dense in $\mathcal{H}$.

"Norris's Lemma": If for a semi martingale Y , a (Stratonovich) integral $\int_0^t X_s ds + \int_0^t Y_s \circ dB_s$ is small then X_s and Y_s are small.

$\langle \mathcal{M}_t \varphi, \varphi \rangle$ is small $\implies \langle J_{t,s} F_i(u_s), \varphi \rangle$ is small for $i = 1, \dots, d$

Norris's lemma + induction $\implies \langle J_{t,s} A(u_s), \varphi \rangle$ is small for every $A \in \bigcup_{k \geq 0} \mathcal{A}_k$

Hörmander's condition $\implies \langle J_{t,s} A(u_s), \varphi \rangle \sim 1$ for some $A \in \bigcup_{k \geq 0} \mathcal{A}_k$.

Contradiction $\implies \mathbb{P}(\langle \mathcal{M}_t \varphi, \varphi \rangle \text{ being small})$ is small. $\square$

Itô calculus doesn't work (here)

To apply Norris's lemma in

$$d\langle J_{t,s}F_i(u_s), \varphi \rangle = \langle J_{t,s}[F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j ,$$

one needs $\langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle$ to be a semi martingale. **Which is not** because of the "future" t .

Even worse the integral $\int_0^\cdot \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j$ can not be defined as Itô integral because integrand is not adapted.

Need another notion of the integral and a version of Norris's lemma for it.

Itô calculus doesn't work (here)

To apply Norris's lemma in

$$d\langle J_{t,s}F_i(u_s), \varphi \rangle = \langle J_{t,s}[F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j ,$$

one needs $\langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle$ to be a semi martingale. **Which is not** because of the "future" t .

Even worse the integral $\int_0^\cdot \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j$ can not be defined as Itô integral because integrand is not adapted.

Need another notion of the integral and a version of Norris's lemma for it.

Itô calculus doesn't work (here)

To apply Norris's lemma in

$$d\langle J_{t,s}F_i(u_s), \varphi \rangle = \langle J_{t,s}[F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j,$$

one needs $\langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle$ to be a semi martingale. **Which is not** because of the "future" t .

Even worse the integral $\int_0^\cdot \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j$ can not be defined as Itô integral because integrand is not adapted.

Need another notion of the integral and a version of Norris's lemma for it.

Itô calculus doesn't work (here)

To apply Norris's lemma in

$$d\langle J_{t,s}F_i(u_s), \varphi \rangle = \langle J_{t,s}[F_0, F_i](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j ,$$

one needs $\langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle$ to be a semi martingale. **Which is not** because of the "future" t .

Even worse the integral $\int_0^\cdot \langle J_{t,s}[F_j, F_i](u_s), \varphi \rangle \circ dB_s^j$ can not be defined as Itô integral because integrand is not adapted.

Need another notion of the integral and a version of Norris's lemma for it.

Rough paths

$\gamma \in (\frac{1}{3}, \frac{1}{2}]$, a pair $(X_t, \mathbb{X}_{t,s}) \in \mathbb{R}^d \times \mathbb{R}^{d \times d}$ is $\mathcal{C}^\gamma$ rough path if

$$|X_t - X_s| \lesssim |t - s|^\gamma, \quad |\mathbb{X}_{t,s}| \lesssim |t - s|^{2\gamma}$$

$$\mathbb{X}_{t,s} - \mathbb{X}_{u,s} - \mathbb{X}_{t,u} = (X_t - X_u) \otimes (X_u - X_s)$$

$\mathbb{X}_{t,s}$ postulates a value of the integral $\int_s^t (X_r - X_s) dX_r$ which is not defined classically.

For B - Brownian motion setting $\mathbb{B}_{t,s}^{\text{Strat}} := \int_s^t (B_r - B_s) \circ dB_r$ defines a rough path $(B, \mathbb{B}^{\text{Strat}}) \in \mathcal{C}^\gamma$ for every $\gamma \in (\frac{1}{3}, \frac{1}{2})$.

Rough paths

$\gamma \in (\frac{1}{3}, \frac{1}{2}]$, a pair $(X_t, \mathbb{X}_{t,s}) \in \mathbb{R}^d \times \mathbb{R}^{d \times d}$ is $\mathcal{C}^\gamma$ rough path if

$$|X_t - X_s| \lesssim |t - s|^\gamma, \quad |\mathbb{X}_{t,s}| \lesssim |t - s|^{2\gamma}$$

$$\mathbb{X}_{t,s} - \mathbb{X}_{u,s} - \mathbb{X}_{t,u} = (X_t - X_u) \otimes (X_u - X_s)$$

$\mathbb{X}_{t,s}$ postulates a value of the integral $\int_s^t (X_r - X_s) dX_r$ which is not defined classically.

For B - Brownian motion setting $\mathbb{B}_{t,s}^{\text{Strat}} := \int_s^t (B_r - B_s) \circ dB_r$ defines a rough path $(B, \mathbb{B}^{\text{Strat}}) \in \mathcal{C}^\gamma$ for every $\gamma \in (\frac{1}{3}, \frac{1}{2})$.

Rough paths

$\gamma \in (\frac{1}{3}, \frac{1}{2}]$, a pair $(X_t, \mathbb{X}_{t,s}) \in \mathbb{R}^d \times \mathbb{R}^{d \times d}$ is $\mathcal{C}^\gamma$ rough path if

$$|X_t - X_s| \lesssim |t - s|^\gamma, \quad |\mathbb{X}_{t,s}| \lesssim |t - s|^{2\gamma}$$
$$\mathbb{X}_{t,s} - \mathbb{X}_{u,s} - \mathbb{X}_{t,u} = (X_t - X_u) \otimes (X_u - X_s)$$

$\mathbb{X}_{t,s}$ postulates a value of the integral $\int_s^t (X_r - X_s) dX_r$ which is not defined classically.

For B - Brownian motion setting $\mathbb{B}_{t,s}^{\text{Strat}} := \int_s^t (B_r - B_s) \circ dB_r$ defines a rough path $(B, \mathbb{B}^{\text{Strat}}) \in \mathcal{C}^\gamma$ for every $\gamma \in (\frac{1}{3}, \frac{1}{2})$.

Rough integrals

$(y, y') \in C^\gamma([0, T], \mathcal{B}) \times C^\gamma([0, T], \mathcal{B}^d)$, where $\mathcal{B}$ is Banach space, is controlled by $(X, \mathbb{X})$ if

$$\|y_t - y_s - y'_s(X_t - X_s)\|_{\mathcal{B}} \lesssim |t - s|^{2\gamma}$$

If (y, y') is controlled by $(X, \mathbb{X})$ then the following integral can be defined

$$\int_s^t y_r d\mathbf{X}_r := \lim_{|\mathcal{P}| \rightarrow 0} \sum_{[u,v] \in \mathcal{P}} (y_u(X_v - X_u) + y'_u \mathbb{X}_{v,u})$$

"Rough Norris's Lemma" (Hairer & Pillai 2010): If (y, y') is controlled by $(B, \mathbb{B}^{\text{Strat}})$, and integral $\int_0^t v_s ds + \int_0^t y_s dB_s$ is small then v_s and y_s are small.

Rough integrals

$(y, y') \in C^\gamma([0, T], \mathcal{B}) \times C^\gamma([0, T], \mathcal{B}^d)$, where $\mathcal{B}$ is Banach space, is controlled by $(X, \mathbb{X})$ if

$$\|y_t - y_s - y'_s(X_t - X_s)\|_{\mathcal{B}} \lesssim |t - s|^{2\gamma}$$

If (y, y') is controlled by $(X, \mathbb{X})$ then the following integral can be defined

$$\int_s^t y_r d\mathbf{X}_r := \lim_{|\mathcal{P}| \rightarrow 0} \sum_{[u,v] \in \mathcal{P}} (y_u(X_v - X_u) + y'_u \mathbb{X}_{v,u})$$

"Rough Norris's Lemma" (Hairer & Pillai 2010): If (y, y') is controlled by $(B, \mathbb{B}^{\text{Strat}})$, and integral $\int_0^t v_s ds + \int_0^t y_s dB_s$ is small then v_s and y_s are small.

Rough integrals

$(y, y') \in C^\gamma([0, T], \mathcal{B}) \times C^\gamma([0, T], \mathcal{B}^d)$, where $\mathcal{B}$ is Banach space, is controlled by $(X, \mathbb{X})$ if

$$\|y_t - y_s - y'_s(X_t - X_s)\|_{\mathcal{B}} \lesssim |t - s|^{2\gamma}$$

If (y, y') is controlled by $(X, \mathbb{X})$ then the following integral can be defined

$$\int_s^t y_r d\mathbf{X}_r := \lim_{|\mathcal{P}| \rightarrow 0} \sum_{[u,v] \in \mathcal{P}} (y_u(X_v - X_u) + y'_u \mathbb{X}_{v,u})$$

"Rough Norris's Lemma" (Hairer & Pillai 2010): If (y, y') is controlled by $(B, \mathbb{B}^{\text{Strat}})$, and integral $\int_0^t v_s ds + \int_0^t y_s dB_s$ is small then v_s and y_s are small.

Rough PDEs

Theorem (G. & Hairer 18; Gubinelli & Tindel 10): Let $u_0 \in \mathcal{H}$ and $(X, \mathbb{X}) \in \mathcal{C}^\gamma$. Let $N : \mathcal{H} \rightarrow \mathcal{H}_{-\delta}$ be Lipschitz and $F_j : \mathcal{H} \rightarrow \mathcal{H}$ be C^3 . Then there exists $\tau > 0$ and a unique $u \in C([0, \tau), \mathcal{H})$ which is a local in time, mild solution to:

$$u_t = S_t u_0 + \int_0^t S_{t-r} N(u_r) dr + \int_0^t S_{t-r} F_j(u_r) d\mathbf{X}_r^j \quad (\text{RPDE}),$$

for all $t \leq \tau$.

RPDE is well-posed: the solution to the above equation depends continuously on $(X, \mathbb{X})$ and u_0 .

Rough PDEs

Theorem (G. & Hairer 18; Gubinelli & Tindel 10): Let $u_0 \in \mathcal{H}$ and $(X, \mathbb{X}) \in \mathcal{C}^\gamma$. Let $N : \mathcal{H} \rightarrow \mathcal{H}_{-\delta}$ be Lipschitz and $F_j : \mathcal{H} \rightarrow \mathcal{H}$ be C^3 . Then there exists $\tau > 0$ and a unique $u \in C([0, \tau), \mathcal{H})$ which is a local in time, mild solution to:

$$u_t = S_t u_0 + \int_0^t S_{t-r} N(u_r) dr + \int_0^t S_{t-r} F_j(u_r) d\mathbf{X}_r^j \quad (\text{RPDE}),$$

for all $t \leq \tau$.

RPDE is well-posed: the solution to the above equation depends continuously on $(X, \mathbb{X})$ and u_0 .

What remains to show?

To proceed as before it remains to show equation

$$d\langle J_{t,s}A(u_s), \varphi \rangle = \langle J_{t,s}[L + N, A](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, A](u_s), \varphi \rangle d\mathbf{X}_s^j,$$

and use "Rough Norris's Lemma" to proceed same as before.

Problem: only have mild equations for $J_{t,s}$ and u_s and can't "differentiate" the above.

Idea: Rewrite $\langle J_{t,s}A(u_s), \varphi \rangle = \langle A(u_s), J_{t,s}^*\varphi \rangle$, derive mild equation for $A(u_s)$ and $J_{t,s}^*$ and plug thus in.

What remains to show?

To proceed as before it remains to show equation

$$d\langle J_{t,s}A(u_s), \varphi \rangle = \langle J_{t,s}[L + N, A](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, A](u_s), \varphi \rangle d\mathbf{X}_s^j,$$

and use "Rough Norris's Lemma" to proceed same as before.

Problem: only have mild equations for $J_{t,s}$ and u_s and can't "differentiate" the above.

Idea: Rewrite $\langle J_{t,s}A(u_s), \varphi \rangle = \langle A(u_s), J_{t,s}^* \varphi \rangle$, derive mild equation for $A(u_s)$ and $J_{t,s}^*$ and plug thus in.

What remains to show?

To proceed as before it remains to show equation

$$d\langle J_{t,s}A(u_s), \varphi \rangle = \langle J_{t,s}[L + N, A](u_s), \varphi \rangle ds + \langle J_{t,s}[F_j, A](u_s), \varphi \rangle d\mathbf{X}_s^j,$$

and use "Rough Norris's Lemma" to proceed same as before.

Problem: only have mild equations for $J_{t,s}$ and u_s and can't "differentiate" the above.

Idea: Rewrite $\langle J_{t,s}A(u_s), \varphi \rangle = \langle A(u_s), J_{t,s}^*\varphi \rangle$, derive mild equation for $A(u_s)$ and $J_{t,s}^*$ and plug thus in.

Mild Itô's formula for RPDEs

Theorem (G. & Hairer 18): Let $u \in C([0, T], \mathcal{H})$ solve mild (RPDE) and $A \in C^2(\mathcal{H}, \mathcal{H})$ then $A(u_t)$ satisfies:

$$\begin{aligned} A(u_t) = & S_t A(u_0) + \int_0^t S_{t-r} (DA(u_r) N(u_r) + [L, A](u_r)) dr \\ & + \int_0^t S_{t-r} DA(u_r) F_j(u_r) d\mathbf{X}_r^j \\ & + \frac{1}{2} \int_0^t S_{t-r} D^2 A(u_r) (F_i(u_r), F_k(u_r)) d[\mathbf{X}]_r^{i,k}, \end{aligned}$$

where $[\mathbf{X}]_t = X_t \otimes X_t - 2 \text{Sym}(\mathbb{X}_{t,0})$ is a bracket of rough path.

Backwards equations and $J_{t,s}^*$

Proposition (G. & Hairer 18): Let $u \in C([0, T], \mathcal{H})$ solve mild (RPDE) then for all $\varphi \in \mathcal{H}$ there exists a unique solution $K_{t,s}\varphi$ to the backwards rough PDE:

$$\begin{aligned} K_{t,s}\varphi = & S_{t-s}\varphi + \int_s^t S_{r-s}DN^*(u_r)K_{t,r}\varphi dr \\ & + \int_s^t S_{r-s}DF_i^*(u_r)K_{t,r}\varphi d\mathbf{X}_r^i, \end{aligned}$$

and such K is an adjoint of the Jacobian: $K_{t,s} = J_{t,s}^*$.

Rough Fubini Theorem

Plugging in the mild equations for $A(u_s)$ and $J_{t,s}^*$ into $\langle A(u_s), J_{t,s}^* \varphi \rangle$ creates double integrals that we want to get rid of.

Theorem (G. & Hairer 18): Let $Y_{t,s}$ be such that both $Y_{\cdot,s}$ and $Y_{t,\cdot}$ are controlled by $(X, \mathbb{X}) \in \mathcal{C}^\gamma$ with the corresponding Gubinelli derivatives being $Y_{\cdot,s}^1$ and $Y_{t,\cdot}^2$. In addition assume that $Y_{\cdot,s}^1$ and $Y_{\cdot,s}^2$ are controlled by $(X, \mathbb{X})$ and have the same Gubinelli derivative $Y_{t,s}^{1,2} = Y_{t,s}^{2,1}$ then the following change of integrals formula holds:

$$\int_0^t \int_0^r Y_{r,s} d\mathbf{X}_s d\mathbf{X}_r - \int_0^t \int_s^t Y_{r,s} d\mathbf{X}_r d\mathbf{X}_s = \int_0^t Y_{s,s} d[\mathbf{X}]_s .$$

Proof: approximate X with the smooth functions.

Rough Fubini Theorem

Plugging in the mild equations for $A(u_s)$ and $J_{t,s}^*$ into $\langle A(u_s), J_{t,s}^* \varphi \rangle$ creates double integrals that we want to get rid of.

Theorem (G. & Hairer 18): Let $Y_{t,s}$ be such that both $Y_{\cdot,s}$ and $Y_{t,\cdot}$ are controlled by $(X, \mathbb{X}) \in \mathcal{C}^\gamma$ with the corresponding Gubinelli derivatives being $Y_{\cdot,s}^1$ and $Y_{t,\cdot}^2$. In addition assume that $Y_{t,\cdot}^1$ and $Y_{\cdot,s}^2$ are controlled by $(X, \mathbb{X})$ and have the same Gubinelli derivative $Y_{t,s}^{1,2} = Y_{t,s}^{2,1}$ then the following change of integrals formula holds:

$$\int_0^t \int_0^r Y_{r,s} d\mathbf{X}_s d\mathbf{X}_r - \int_0^t \int_s^t Y_{r,s} d\mathbf{X}_r d\mathbf{X}_s = \int_0^t Y_{s,s} d[\mathbf{X}]_s .$$

Proof: approximate X with the smooth functions.

Rough Fubini Theorem

Plugging in the mild equations for $A(u_s)$ and $J_{t,s}^*$ into $\langle A(u_s), J_{t,s}^* \varphi \rangle$ creates double integrals that we want to get rid of.

Theorem (G. & Hairer 18): Let $Y_{t,s}$ be such that both $Y_{\cdot,s}$ and $Y_{t,\cdot}$ are controlled by $(X, \mathbb{X}) \in \mathcal{C}^\gamma$ with the corresponding Gubinelli derivatives being $Y_{\cdot,s}^1$ and $Y_{t,\cdot}^2$. In addition assume that $Y_{t,\cdot}^1$ and $Y_{\cdot,s}^2$ are controlled by $(X, \mathbb{X})$ and have the same Gubinelli derivative $Y_{t,s}^{1,2} = Y_{t,s}^{2,1}$ then the following change of integrals formula holds:

$$\int_0^t \int_0^r Y_{r,s} d\mathbf{X}_s d\mathbf{X}_r - \int_0^t \int_s^t Y_{r,s} d\mathbf{X}_r d\mathbf{X}_s = \int_0^t Y_{s,s} d[\mathbf{X}]_s .$$

Proof: approximate X with the smooth functions.

Final remarks

This finishes the proof (in the case of $[X] \equiv 0$) of the equation

$$d\langle A(u_s), J_{t,s}^* \varphi \rangle = \langle [L + N, A](u_s), J_{t,s}^* \varphi \rangle ds + \langle [F_j, A](u_s), J_{t,s}^* \varphi \rangle d\mathbf{X}_s^j.$$

This equation allows us to use Hörmander's condition and Rough Norris's Lemma (in the case of $(B, \mathbb{B}^{\text{Strat}})$) to carry out the same arguments as in the finite dimensional case.

This finishes the proof of the Hörmander's theorem for semilinear SPDEs.

Final remarks

This finishes the proof (in the case of $[X] \equiv 0$) of the equation

$$d\langle A(u_s), J_{t,s}^* \varphi \rangle = \langle [L + N, A](u_s), J_{t,s}^* \varphi \rangle ds + \langle [F_j, A](u_s), J_{t,s}^* \varphi \rangle d\mathbf{X}_s^j.$$

This equation allows us to use Hörmander's condition and Rough Norris's Lemma (in the case of $(B, \mathbb{B}^{\text{Strat}})$) to carry out the same arguments as in the finite dimensional case.

This finishes the proof of the Hörmander's theorem for semilinear SPDEs.

Final remarks

This finishes the proof (in the case of $[X] \equiv 0$) of the equation

$$d\langle A(u_s), J_{t,s}^* \varphi \rangle = \langle [L + N, A](u_s), J_{t,s}^* \varphi \rangle ds + \langle [F_j, A](u_s), J_{t,s}^* \varphi \rangle d\mathbf{X}_s^j.$$

This equation allows us to use Hörmander's condition and Rough Norris's Lemma (in the case of $(B, \mathbb{B}^{\text{Strat}})$) to carry out the same arguments as in the finite dimensional case.

This finishes the proof of the Hörmander's theorem for semilinear SPDEs.

Thank you for your attention!

Thank you for your attention!

Example of the vector fields satisfying Hörmander's condition.

Let $\mathcal{H} = L^2(\mathbb{T}, \mathbb{R})$, $B = (B^1, B^2)$ and

$F_1(u) = \sin(x) + u(x) \cos(x)$ and $F_2(u) = \cos(x) - u(x) \sin(x)$

$$[F_1, F_2](u) = \cos^2(x) + \sin^2(x) = 1,$$

$$[[F_1, F_2], F_1] = \cos(x), \quad [[F_1, F_2], F_2] = -\sin(x),$$

$$[[[F_1, F_2], F_1], F_1] = \cos^2(x), \quad [[[F_1, F_2], F_2], F_1] = -\sin(x) \cos(x) \dots$$

Can produce any term of the form $\sin^k(x) \cos^\ell(x)$, which creates a basis for $L^2(\mathbb{T}, \mathbb{R})$ thus span of all iterated Lie brackets is dense in $L^2(\mathbb{T}, \mathbb{R})$.

Example of the vector fields satisfying Hörmander's condition.

Let $\mathcal{H} = L^2(\mathbb{T}, \mathbb{R})$, $B = (B^1, B^2)$ and

$$F_1(u) = \sin(x) + u(x) \cos(x) \text{ and } F_2(u) = \cos(x) - u(x) \sin(x)$$

$$[F_1, F_2](u) = \cos^2(x) + \sin^2(x) = 1,$$

$$[[F_1, F_2], F_1] = \cos(x), \quad [[F_1, F_2], F_2] = -\sin(x),$$

$$[[[F_1, F_2], F_1], F_1] = \cos^2(x), \quad [[[[F_1, F_2], F_2], F_1] = -\sin(x) \cos(x) \dots$$

Can produce any term of the form $\sin^k(x) \cos^\ell(x)$, which creates a basis for $L^2(\mathbb{T}, \mathbb{R})$ thus span of all iterated Lie brackets is dense in $L^2(\mathbb{T}, \mathbb{R})$.

Example of the vector fields satisfying Hörmander's condition.

Let $\mathcal{H} = L^2(\mathbb{T}, \mathbb{R})$, $B = (B^1, B^2)$ and

$F_1(u) = \sin(x) + u(x) \cos(x)$ and $F_2(u) = \cos(x) - u(x) \sin(x)$

$$[F_1, F_2](u) = \cos^2(x) + \sin^2(x) = 1,$$

$$[[F_1, F_2], F_1] = \cos(x), \quad [[F_1, F_2], F_2] = -\sin(x),$$

$$[[[F_1, F_2], F_1], F_1] = \cos^2(x), \quad [[[F_1, F_2], F_2], F_1] = -\sin(x) \cos(x) \dots$$

Can produce any term of the form $\sin^k(x) \cos^\ell(x)$, which creates a basis for $L^2(\mathbb{T}, \mathbb{R})$ thus span of all iterated Lie brackets is dense in $L^2(\mathbb{T}, \mathbb{R})$.

Example of the vector fields satisfying Hörmander's condition.

Let $\mathcal{H} = L^2(\mathbb{T}, \mathbb{R})$, $B = (B^1, B^2)$ and

$F_1(u) = \sin(x) + u(x) \cos(x)$ and $F_2(u) = \cos(x) - u(x) \sin(x)$

$$[F_1, F_2](u) = \cos^2(x) + \sin^2(x) = 1,$$

$$[[F_1, F_2], F_1] = \cos(x), \quad [[F_1, F_2], F_2] = -\sin(x),$$

$$[[[F_1, F_2], F_1], F_1] = \cos^2(x), \quad [[[F_1, F_2], F_2], F_1] = -\sin(x) \cos(x) \dots$$

Can produce any term of the form $\sin^k(x) \cos^\ell(x)$, which creates a basis for $L^2(\mathbb{T}, \mathbb{R})$ thus span of all iterated Lie brackets is dense in $L^2(\mathbb{T}, \mathbb{R})$.

Example of the vector fields satisfying Hörmander's condition.

Let $\mathcal{H} = L^2(\mathbb{T}, \mathbb{R})$, $B = (B^1, B^2)$ and

$F_1(u) = \sin(x) + u(x) \cos(x)$ and $F_2(u) = \cos(x) - u(x) \sin(x)$

$$[F_1, F_2](u) = \cos^2(x) + \sin^2(x) = 1,$$

$$[[F_1, F_2], F_1] = \cos(x), \quad [[F_1, F_2], F_2] = -\sin(x),$$

$$[[[F_1, F_2], F_1], F_1] = \cos^2(x), \quad [[[F_1, F_2], F_2], F_1] = -\sin(x) \cos(x) \dots$$

Can produce any term of the form $\sin^k(x) \cos^\ell(x)$, which creates a basis for $L^2(\mathbb{T}, \mathbb{R})$ thus span of all iterated Lie brackets is dense in $L^2(\mathbb{T}, \mathbb{R})$.