



Stable limits for Markov chains and contractivity properties of transition operators

Joint work with M. El Machkouri and D. Volný (Rouen)

Probabilistic Limit Theorems for Dynamical Systems
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Motivations

The Markov
machinery

Contractivity
properties

Limit theorems

Principle of
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Motivations

- Consider an ARCH(1) Markov chain $\{X_n\}$ given by

$$X_{k+1} = \sqrt{\beta + \lambda X_k^2} Z_{k+1}, \quad k \geq 0,$$

where $\beta, \lambda > 0$ and $\{Z_n\}_{n \in \mathbb{N}}$ is a Gaussian standard i.i.d. sequence that is independent of X_0 .



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where $\beta, \lambda > 0$ and $\{Z_n\}_{n \in \mathbb{N}}$ is a Gaussian standard i.i.d. sequence that is independent of X_0 .

- The squares of ARCH(1) satisfy a stochastic recurrence equation - see a recent reference [Buraczewski, Damek, Mikosch \(2016\)](#).

$$X_{k+1}^2 = \beta Z_{k+1}^2 + \lambda Z_{k+1}^2 X_k^2 = A_{k+1} + B_{k+1} X_k^2, \quad k \geq 0.$$

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- If $\beta > 0$ and $\lambda \in (0, 2e^\gamma)$, then $\{X_k\}_{k \geq 0}$ is strictly stationary iff

$$X_0 \sim r_0 \sqrt{\beta \sum_{m=1}^{\infty} Z_m^2 \prod_{j=1}^{m-1} (\lambda Z_j^2)},$$

where r_0 is a Rademacher random variable ($P(r_0 = \pm 1) = 1/2$), independent of $\{Z_n\}$.



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- Under stationarity, $\{X_k\}_{k \geq 0}$ admit a power decay of tail probabilities.



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- Under stationarity, $\{X_k\}_{k \geq 0}$ admit a power decay of tail probabilities.
- Let $\beta > 0$ and $\lambda \in (0, 2e^\beta)$ and let $\kappa > 0$ be the unique positive solution of the equation

$$E(\lambda Z_1^2)^\kappa = 1.$$



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- Let $\beta > 0$ and $\lambda \in (0, 2e^\gamma)$ and let $\kappa > 0$ be the unique positive solution of the equation

$$E(\lambda Z_1^2)^u = 1.$$

- Then, as $x \rightarrow \infty$,

$$P(X_0 > x) \sim \frac{C_{\beta, \lambda}}{2} x^{-2\kappa},$$

where

$$C_{\beta, \lambda} = \frac{E[(\beta + \lambda X_0^2)^\kappa - (\lambda X_0^2)^\kappa]}{\kappa \lambda^\kappa E[(\lambda Z_1^2)^\kappa \ln(\lambda Z_1^2)]} \in (0, +\infty).$$

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- It follows that if $\kappa \in (0, 1)$ then the law of X_0 belongs to the domain of strict attraction of some strictly stable law.

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- It follows that if $\kappa \in (0, 1)$ then the law of X_0 belongs to the domain of strict attraction of some strictly stable law.
- In particular, if $\lambda \in (1, \lambda_0)$ then $2\kappa \in (1, 2)$ and $\{X_n\}$ is a stationary sequence of **martingale differences**.

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- Consider the normalized partial sums

$$S_n = \frac{X_1 + X_2 + \dots + X_n}{(nC_{\beta,\lambda})^{\frac{1}{2\kappa}}}, T_n = \frac{Y_1 + Y_2 + \dots + Y_n}{(nC_{\beta,\lambda})^{\frac{1}{2\kappa}}},$$

where $\{Y_k\}$ is an i.i.d. sequence with marginals $Y_n \sim X_n$.



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- Davis and Mikosch (AoP, 1998) proved that the limit of S_n is stable and Bartkiewicz, J., Mikosch and Wintenberger (PRTF, 2011) identified the parameters of the limit.

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- Davis and Mikosch (AoP, 1998) proved that the limit of S_n is stable and Bartkiewicz, J., Mikosch and Wintenberger (PRTF, 2011) identified the parameters of the limit.
- If $\exp(-C|\theta|^{2\kappa})$ is the characteristic function of the limit for T_n , then the characteristic function of the limit for S_n is of the form $\exp(-\tau C|\theta|^{2\kappa})$, where $1 > \tau = E[|1 + S_\infty|^{2\kappa} - |S_\infty|^{2\kappa}] > 0$ and the series

$$S_\infty = \sum_{j=1}^{\infty} \lambda^{j/2} \left[\prod_{k=1}^{j-1} |Z_k| \right] Z_j$$

converges a.s.

- The limit for S_n is **different** from the limit for T_n !
- **Unlike in the case of finite variance!**

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It is natural to ask **about extra conditions that guarantee the same behavior** of partial sums of Markov chains and the corresponding i.i.d. sequence.

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- Then they obtained a fractional diffusion (in fact: a stable Lévy process) as a scaled (both in time and space) limit of these solutions.



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- It was important that the **limit process was the same as if the summands were independent**, to allow for the clear interpretation of the parameters.



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- It was important that the **limit process was the same as if the summands were independent**, to allow for the clear interpretation of the parameters.
- Moreover, modeling with Markov chains provides **a physically acceptable solution**, while using independent random variables is physically meaningless.



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The Markovian machinery

- Let $(X_n)_{n \geq 0}$ be a Markov chain with a general state space $(\mathcal{S}, \mathcal{S})$ and the transition operator P .

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The Markovian machinery

- Let $(X_n)_{n \geq 0}$ be a Markov chain with a general state space $(\mathcal{S}, \mathcal{S})$ and the transition operator P .
- Recall that $Pf(x) = \int P(x, dy)f(y)$, where $P(x, dy)$ is the transition probability.

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- Let $\Psi : \mathcal{S} \rightarrow \mathbb{R}$ be such that $\pi \circ \Psi^{-1}$ belongs to the domain of attraction of a stable law μ_α ($0 < \alpha < 2$).



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- We will be interested in limit theorems of the form

$$\frac{\Psi(X_1) + \Psi(X_2) + \dots + \Psi(X_n)}{B_n} \xrightarrow{\mathcal{D}} \mu_\alpha.$$

(Possibly with explicit centering).



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- As if $\{\Psi(X_n)\}_{n \geq 0}$ were independent!



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Stable laws

- Recall that a *stable* distribution with exponent $\alpha \in (0, 2)$ has the characteristic function of the form

$$\hat{\mu}(\theta) = \exp \left(i\theta a^h + \int (e^{i\theta x} - 1 - i\theta x \mathbf{1}_{\{|x| \leq h\}}) \nu_{\alpha, c_+, c_-}(dx) \right),$$

where $a^h \in \mathbb{R}^1$, the Lévy measure ν_{α, c_+, c_-} has the density

$$\rho_{\alpha, c_+, c_-}(x) = \alpha \left(c_+ x^{-(\alpha+1)} \mathbf{1}_{\{x > 0\}} + c_- |x|^{-(\alpha+1)} \mathbf{1}_{\{x < 0\}} \right),$$

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and $h > 0$ is a fixed level of truncation.

- We will consider only the *strictly stable* limits μ_α of the form:

$$\hat{\mu}_{\alpha, c_+, c_-}(\theta) = \begin{cases} \exp \left(\int (e^{i\theta x} - 1) \nu_{\alpha, c_+, c_-}(dx) \right), & \alpha \in (0, 1); \\ \exp \left(\int (e^{i\theta x} - 1) \nu_{1, c, c}(dx) \right), & \alpha = 1; \\ \exp \left(\int (e^{i\theta x} - 1 - i\theta x) \nu_{\alpha, c_+, c_-}(dx) \right), & \alpha \in (1, 2). \end{cases}$$



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Domains of attraction

- Recall also that $\pi \circ \Psi^{-1}$ belongs to the domain of attraction of a stable law μ_{α, c_+, c_-} ($0 < \alpha < 2$), if

$$\pi(x; |\Psi(x)| > t) = t^{-\alpha} \ell(t),$$

where $\ell(t)$ is a slowly varying function as $t \rightarrow \infty$, and there exist the limits

$$\lim_{t \rightarrow \infty} \frac{\pi(x; \Psi(x) > t)}{\pi(x; |\Psi(x)| > t)} = \frac{c_+}{c_+ + c_-},$$

$$\lim_{t \rightarrow \infty} \frac{\pi(x; \Psi(x) < -t)}{\pi(x; |\Psi(x)| > t)} = \frac{c_-}{c_+ + c_-}.$$

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- A suitable choice of the norming constants B_n is

$$\frac{n}{B_n^\alpha} \ell(B_n) \rightarrow c_+ + c_-.$$

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The idea

- The idea consists in finding a possibly minimal form of **operator contractivity**.

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Example



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Example

- For $0 < |\rho| < 1$ set

$$P(x, dy) = \frac{1}{\sqrt{2\pi(1-\rho^2)}} e^{-\frac{(y-\rho x)^2}{2(1-\rho^2)}} dy.$$



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- For $0 < |\rho| < 1$ set

$$P(x, dy) = \frac{1}{\sqrt{2\pi(1-\rho^2)}} e^{-\frac{(y-\rho x)^2}{2(1-\rho^2)}} dy.$$

- Because $P(x, dy) = p(x, y)\pi(dy)$, where π is $\mathcal{N}(0, 1)$. and $\int \pi(dx)\pi(dy)p(x, y)^q < +\infty$, provided $2 < q < \frac{1+|\rho|}{|\rho|}$, we have

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- $P : L^2(\pi) \rightarrow L^q(\pi)$ is a bounded linear operator. This is **hyperboundedness!**



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- $P : L^2(\pi) \rightarrow L^q(\pi)$ is a bounded linear operator. This is **hyperboundedness!**
- Important: **there is neither ϕ -mixing nor ultraboundedness!**



Condition 2-U.I.

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Condition 2-U.I.

- Notions like “hyperboundedness” or “ultraboundedness” are known from the analysis of **Markov semigroups** and most of previously known examples were taken from the continuous time theory.



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- Notions like “hyperboundedness” or “ultraboundedness” are known from the analysis of **Markov semigroups** and most of previously known examples were taken from the continuous time theory.
- Examples in our paper show that such properties are quite common within the theory of Markov chains.



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- Examples in our paper show that such properties are quite common within the theory of Markov chains.
- Following Wu (JoFA, 2000) we will say that the transition operator P is **uniformly integrable in L^2 (or 2-U.I.)** if

$\{|Pf|^2; f \in L^2(\pi), \|f\|_2 \leq 1\}$ is uniformly π -integrable.

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- The hyperboundedness implies 2-U.I.
- We provide an example of a discrete in time and space Markov chain which satisfies our assumptions but **is not hyperbounded**.

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- As a consequence we are able to **weaken considerably the assumptions** of JKO (2009) and Cattiaux and Manou-Abi (ESAIM, 2014).

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- As a consequence we are able to **weaken considerably the assumptions** of JKO (2009) and Cattiaux and Manou-Abi (ESAIM, 2014).
- We believe that 2-U.I. is **the proper minimal form** for operator contractivity.

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L^2 -spectral gap and geometric ergodicity

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L^2 -spectral gap and geometric ergodicity

- The transition operator P is said to have an L^2 -spectral gap if there is a number $a < 1$ such that

$$\sup\{\|Pf\|_{L^2(\pi)}; \int_{\mathbb{S}} f(x)d\pi(x) = 0, \|f\|_{L^2(\pi)} \leq 1\} \leq a.$$



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- For reversible, ψ -irreducible and aperiodic Markov chains the spectral gap property is known to be equivalent to **geometric ergodicity**, i.e. existence of $0 < \rho < 1$ and $C : \mathbb{S} \rightarrow \mathbb{R}^+$ such that

$$\|P^n(x, \cdot) - \pi\|_{TV} \leq C(x)\rho^n, \quad \text{for } \pi\text{-a.e. } x \in \mathbb{S},$$

where $\|\cdot\|_{TV}$ is the total variance distance.

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$$\sup\{\|Pf\|_{L^2(\pi)}; \int_{\mathbb{S}} f(x)d\pi(x) = 0, \|f\|_{L^2(\pi)} \leq 1\} \leq a.$$

- For reversible, ψ -irreducible and aperiodic Markov chains the spectral gap property is known to be equivalent to **geometric ergodicity**, i.e. existence of $0 < \rho < 1$ and $C : \mathbb{S} \rightarrow \mathbb{R}^+$ such that

$$\|P^n(x, \cdot) - \pi\|_{TV} \leq C(x)\rho^n, \quad \text{for } \pi\text{-a.e. } x \in \mathbb{S},$$

where $\|\cdot\|_{TV}$ is the total variance distance.

- If $\{X_n\}$ is **irreversible**, then the spectral gap property implies the geometric ergodicity, but there are Markov chains that are geometrically ergodic and do not have an L^2 -spectral gap.

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- If $\{X_n\}$ is **irreversible**, then the spectral gap property implies the geometric ergodicity, but there are Markov chains that are geometrically ergodic and do not have an L^2 -spectral gap.
- Notice that **the central limit theorem need not hold** for such Markov chains!

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Theorem 1



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Theorem 1

Let $\{X_n\}$ be a Markov chain on $(\mathcal{S}, \mathcal{S})$, with P and π as above. We assume that P has an L^2 -spectral gap and satisfies the 2-U.I. condition.



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Suppose $\pi \circ \Psi^{-1}$ is in the domain of attraction of μ_{α, c_+, c_-} , $\alpha \in (0, 2)$. Let $B_n \rightarrow \infty$ be suitably chosen.



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If $\alpha \in (0, 1)$ or $\alpha = 1$ and $c_+ = c_- = c$, then

$$\frac{\Psi(X_1) + \Psi(X_2) + \dots + \Psi(X_n)}{B_n} \xrightarrow{\mathcal{D}} \mu_{\alpha, c_+, c_-} \quad (\mu_{1, c, c}).$$





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If $\alpha \in (1, 2)$, then

$$\frac{\sum_{j=1}^n \Psi(X_j) - \mathbb{E}(\Psi(X_j) | \mathcal{F}_{j-1})}{B_n} \xrightarrow{\mathcal{D}} \mu_{\alpha, c_+, c_-}.$$

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Comments on Theorem 1

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Comments on Theorem 1

- Let us notice that in the case $\alpha \in (1, 2)$ the tails of conditional expectations may **a priori** influence the form of the limit.



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Comments on Theorem 1

- Let us notice that in the case $\alpha \in (1, 2)$ the tails of conditional expectations may **a priori** influence the form of the limit. **But they do not.**

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Comments on Theorem 1

- Let us notice that in the case $\alpha \in (1, 2)$ the tails of conditional expectations may **a priori** influence the form of the limit. **But they do not.**
- It is worth stressing that for $\alpha = 1$ we need only that **the limit is symmetric** and not $\pi \circ \Psi^{-1}$ itself.



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Comments on Theorem 1

- Let us notice that in the case $\alpha \in (1, 2)$ the tails of conditional expectations may **a priori** influence the form of the limit. **But they do not.**
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Corollary

In assumptions of Theorem 1, if $\alpha \in (1, 2)$ and

$$\mathbb{E}(\Psi(X_1) | \mathcal{F}_0) = 0.$$

i.e. $\Psi(X_1), \Psi(X_2), \dots$ form a martingale difference sequence, then

$$\frac{\Psi(X_1) + \Psi(X_2) + \dots + \Psi(X_n)}{B_n} \xrightarrow{\mathcal{D}} \mu_{\alpha, c_+, c_-}.$$



Under the hyperboundedness

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Under the hyperboundedness

- As shown by JKO (2009) and CM-A (2014), we can get rid of centering by conditional expectations, when we assume the hyperboundedness.

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- As shown by JKO (2009) and CM-A (2014), we can get rid of centering by conditional expectations, when we assume the hyperboundedness.
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Theorem 2

In assumptions of Theorem 1 replace

- the 2-U.I. condition with **the hyperboundedness**;
- the L^2 -spectral gap property with **the strong mixing at geometric rate** (in particular: with the geometric ergodicity).





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In assumptions of Theorem 1 replace

- the 2-U.I. condition with **the hyperboundedness**;
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If $\alpha \in (0, 1)$ or $\alpha = 1$ and $c_+ = c_-$ or $\alpha \in (1, 2)$ and $\int \Psi(x)\pi(dx) = 0$, then

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Removing technicalities

- The improvement over the previous results consists also in removing technicalities.

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- $\pi \circ \Psi^{-1}$ is in the domain of attraction of μ_{α, c_+, c_-} , $\alpha \in (0, 2)$ (RIGHT).



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- $\pi \circ \Psi^{-1}$ is in the domain of attraction of μ_{α, c_+, c_-} , $\alpha \in (0, 2)$ (RIGHT).
- P has an L^2 -spectral gap (RIGHT).
- There exists a measurable family of Borel measures $Q(x, dy)$ and a measurable, nonnegative function $p(x, y)$ such that

$$P(x, dy) = p(x, y)\pi(dy) + Q(x, dy) \quad \text{for all } x \in E.$$

$$Q(x, [y : |\Psi(y)| \geq \lambda]) \leq C \int_{[|\Psi(y)| \geq \lambda]} p(x, y)\pi(dy), \lambda \geq 0;$$

$$C(2) := \sup_{y \in E} \int p^2(x, y)\pi(dx) < +\infty.$$

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- Observe that by the inequality in the second line the term $p(x, y)\pi(dy)$ is essential for properties of the transition operator P .

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- Let Rf be defined as

$$Rf(x) = \int p(x, y)f(y)\pi(dy).$$



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- Let Rf be defined as

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- So we have the **HYPERBOUNDEDNESS**.
- In particular we can ignore the auxiliary random kernel $Q(x, dy)$.



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Principle of Conditioning

- It is a new, efficient version of the Principle of Conditioning what allows us both to weaken assumptions used in JKO (2009) and CM-A (2014) and to remove the technicalities appearing in these papers.

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- It is a new, efficient version of the Principle of Conditioning what allows us both to weaken assumptions used in JKO (2009) and CM-A (2014) and to remove the technicalities appearing in these papers.
- The Principle of Conditioning (PoC) is a heuristic rule that allows us to produce limit theorems for dependent random variables given limit theorems for independent random variables.



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- For us it is interesting how the PoC gives a theorem on convergence to stable laws, valid for triangular arrays of adapted random variables.
- Let $\{X_{n,j}; j \in \mathbb{N}, n \in \mathbb{N}\}$ be an array of random variables, which are row-wise adapted to a sequence of filtrations $\{\{\mathcal{F}_{n,j}; j = 0, 1, \dots\}; n \in \mathbb{N}\}$.



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Theorem 3

$$\text{If } \max_{1 \leq j \leq k_n} \mathbb{P}(|X_{n,j}| > \varepsilon | \mathcal{F}_{n,j-1}) \xrightarrow{\mathcal{P}} 0, \quad \varepsilon > 0;$$

$$\sum_{j=1}^{k_n} \mathbb{P}(X_{n,j} > x | \mathcal{F}_{n,j-1}) \xrightarrow{\mathcal{P}} c_+ x^{-\alpha}, \quad \sum_{j=1}^{k_n} \mathbb{P}(X_{n,j} < -x | \mathcal{F}_{n,j-1}) \xrightarrow{\mathcal{P}} c_- |x|^{-\alpha}, \quad x > 0;$$

$$\sum_{j=1}^{k_n} \mathbb{E}(X_{n,j} \mathbf{1}_{\{|X_{n,j}| \leq h\}} | \mathcal{F}_{n,j-1}) \xrightarrow{\mathcal{P}} a^h;$$

$$\sum_{j=1}^{k_n} \mathbb{V}\text{ar}(X_{n,j} \mathbf{1}_{\{|X_{n,j}| \leq h\}} | \mathcal{F}_{n,j-1}) \xrightarrow{\mathcal{P}} \int_{\{|x| \leq h\}} x^2 \nu_{\alpha, c_+, c_-}(dx);$$

then

$$\sum_{j=1}^{k_n} X_{n,j} \xrightarrow{\mathcal{D}} \delta_{a^h} * c_h\text{-Pois}(\alpha, c_+, c_-).$$



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Principle of Conditioning

- In other words, the PoC says that if we replace in a limit theorem for row-wise independent summands:

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- In other words, the PoC says that if we replace in a limit theorem for row-wise independent summands:
 - the expectations by conditional expectations with respect to the past,

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- In other words, the PoC says that if we replace in a limit theorem for row-wise independent summands:
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- In other words, the PoC says that if we replace in a limit theorem for row-wise independent summands:
 - the expectations by conditional expectations with respect to the past,
 - the convergence of numbers by convergence in probability of random variables appearing in the conditions,then still the conclusion will hold.
- In fact, one can also replace the summation to constants by summation to stopping times.



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- Behind the verbal form of the PoC there is a result on convergence of conditional characteristic functions (J. 1980).

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Let the system $\{X_{n,j}, \mathcal{F}_{n,j}\}$ be as in Theorem 3.



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Theorem 4

Let the system $\{X_{n,j}, \mathcal{F}_{n,j}\}$ be as in Theorem 3. If for some $z \in \mathbb{C}, z \neq 0$,

$$\phi_n(\theta) = \prod_{j=1}^{k_n} \mathbb{E} \left(e^{i\theta X_{n,j}} | \mathcal{F}_{n,j-1} \right) \xrightarrow{\mathcal{P}} z,$$

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then also $\mathbb{E} \exp(i\theta \sum_{j=1}^{k_n} X_{n,j}) \longrightarrow z.$

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then also $\mathbb{E} \exp(i\theta \sum_{j=1}^{k_n} X_{n,j}) \longrightarrow z$.

In particular, if $\phi_n(\theta) \xrightarrow{\mathcal{P}} \hat{\mu}(\theta) \neq 0, \theta \in \mathbb{R}^1$, then

$$\sum_{j=1}^{k_n} X_{n,j} \xrightarrow{\mathcal{D}} \mu.$$

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Theorem 5

Let $\{X_{n,j}; j \in \mathbb{N}, n \in \mathbb{N}\}$ be an array of random variables, which are row-wise adapted to a sequence of filtrations $\{\{\mathcal{F}_{n,j}; j = 0, 1, \dots\}; n \in \mathbb{N}\}$.

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$$\sum_{j=1}^{k_n} |1 - \mathbb{E}(e^{i\theta X_{n,j}} | \mathcal{F}_{n,j-1})|^2 \xrightarrow{\mathcal{P}} 0, \quad \theta \in \mathbb{R}^1.$$



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Let A_n be arbitrary random variables and $\Phi(\theta) \in \mathbb{C}$ be a constant for each $\theta \in \mathbb{R}^1$.



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$$\sum_{j=1}^{k_n} |1 - \mathbb{E}(e^{i\theta X_{n,j}} | \mathcal{F}_{n,j-1})|^2 \xrightarrow{\mathcal{P}} 0, \quad \theta \in \mathbb{R}^1.$$

Let A_n be arbitrary random variables and $\Phi(\theta) \in \mathbb{C}$ be a constant for each $\theta \in \mathbb{R}^1$. The following conditions are equivalent:

$$\left(\sum_{j=1}^{k_n} (\mathbb{E}(e^{i\theta X_{n,j}} | \mathcal{F}_{n,j-1}) - 1) \right) - i\theta A_n \xrightarrow{\mathcal{P}} \Phi(\theta).$$

$$\left(\prod_{j=1}^{k_n} \mathbb{E}(e^{i\theta X_{n,j}} | \mathcal{F}_{n,j-1}) \right) e^{-i\theta A_n} \xrightarrow{\mathcal{P}} e^{\Phi(\theta)}.$$



Principle of Conditioning

SLfMC

Adam Jakubowski



Motivations

The Markov machinery

Contractivity properties

Limit theorems

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Theorem 5 - continued

In either case we have also

$$\mathbb{E} \exp(i\theta \left(\sum_{j=1}^{k_n} X_{n,j} - A_n \right)) \longrightarrow e^{\Phi(\theta)}.$$



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Theorem 5 - continued

In either case we have also

$$\mathbb{E} \exp(i\theta \left(\sum_{j=1}^{k_n} X_{n,j} - A_n \right)) \longrightarrow e^{\Phi(\theta)}.$$

In particular, if $e^{\Phi(\theta)} = \hat{\mu}(\theta)$, $\theta \in \mathbb{R}^1$, for some probability measure μ , then either of the equivalent conditions implies

$$\sum_{j=1}^{k_n} X_{n,j} - A_n \xrightarrow{\mathcal{D}} \mu.$$

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