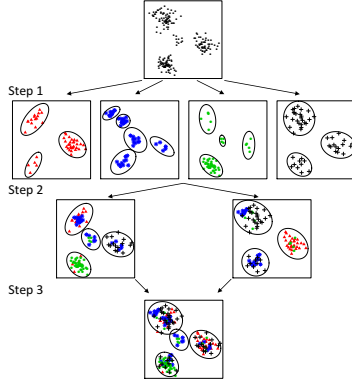


Scalable Bayesian Nonparametric Clustering and Classification

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www.math.utexas.edu/users/pmueller/cirm.pdf

1 Data

1.1 Examples

Health Records Data

Data: $n = 85,021$ patients

Variables y_i : fasting blood glucose, white blood cell count, red blood cell count, hemoglobin, platelets, low density lipoproteins, total cholesterol, triglycerides, triketopurine, high density lipoproteins, serum creatinine, serum glutamic oxaloacetic transaminase, total bilirubin, gender, height, weight, blood pressure and waist

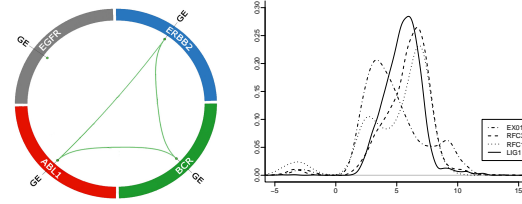
Outcome: diabetes

Goal: clustering, classification & prediction

Zodiac Data

Data: gene-gene interactions of
 $n = 19,304$ genes with all other genes.

Data on gene-gene interactions from Zodiac (Zhu et al., 2015) with TCGA data.



Goal: cluster genes by distribution of interactions (with all other $n - 1$ genes).

1.2 Clustering

Clustering large data

Problem: clustering large (not “Big”) data, $y_i, i = 1, \dots, n$

Random partition: exchangeable partition of $[n] \equiv \{1, \dots, n\} \Leftrightarrow$ ties under sampling from discrete random prob measure (Kingman, 1978)

$$\theta_i \sim G \text{ and } G \sim H(G)$$

cluster membership $s_i = j \Leftrightarrow \theta_i = \theta_j^*$ for j th unique value θ_j^* ; BNP prior $H(G)$, e.g. DP

\rightarrow “BNP clustering”,

Sampling model: together with $y_i \sim f(y_i | \theta_i)$, e.g., normal kernel, BNP mixture:

$$y_i \sim \int f(y_i | \theta) dG(\theta) \text{ and } G \sim \text{DP},$$

or any other BNP mixture model.

Computation: full posterior simulation becomes challenging with $n > 1000$;

Variational Bayes: DP mixture (Lin, 2013 NIPS; Tank, Foti & Fox, 2015 AISTATS) – on-line learning;

Parallelize algorithm: Williamson, Dubey & Xing (2013, ICML) exploit representation of the DP as normalized Ga process to parallelize inference.

Predictive recursion: Newton, Quintana & Zhang (1998) use approximate predictive recursion, to approximate $p(y_{n+1} | \mathbf{y})$ under DP mixture model. Similar idea in Wang & Dunson (2011, JCGS) who sequentially build up clusters by assigning $(i + 1)$ to a cluster in a partition of $[i]$ (SUGS)

1.3 Predictive recursion clustering

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Predictive recursion clustering (PRC)

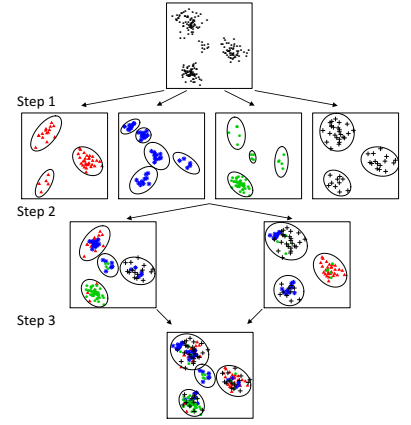
Predictive recursion clustering: Zuanetti et al., (2018 StatComp); use predictive recursion like Newton et al. (98), approximating the posterior predictive $p(\theta_{i+1} \mid y_1, \dots, y_{i-1}) \approx g_i(\theta)$:

$$g_i(\theta) = (1 - w_i)g_{i-1}(\theta) + w_i \frac{f(y_i \mid \theta)g_{i-1}(\theta)}{c(y_i, g_{i-1})},$$

exact for $i = 1$ (and $w_i = 1/(1 + \alpha)$), and approx beyond.

Clustering: g_i builds up as a mixture model, which implicitly defines a random partition (with some computational simplifications, like dropping terms with very small weight, etc.)

1. split data into “shards”;
2. subset posterior on shards;
3. split clusters into shards \rightarrow Step 2 with clusters as the new units;
4. stop when only one shard is left.



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Clustering of clusters

In Step 2, 3, ...: clustering of clusters; similar notion in Argiento et al. (2014) and Malsiner-Walli, Frühwirth-Schnatter & Grün (2017) (for mixture of non-Gaussian dists).

Notation: let $\tilde{s}_i = j$ if i th cluster (of original units) joins the j th cluster of clusters.

Prior prob: exchangeable prior $\Leftrightarrow p(\rho) = f(n_1, \dots, n_C)$ for C clusters with cardinalities $n_c \Rightarrow$

$$p(\tilde{s}_i = c \mid \tilde{\mathbf{s}}^{-i}) \propto \frac{p(\rho^{+c})}{p(\rho^{-i})}$$

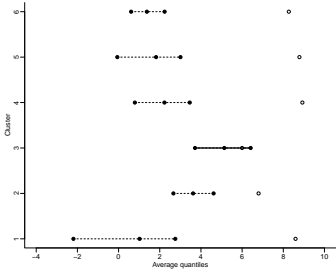
for any BNP prior – easy;

Transdim MCMC: Neal’s (2000) Algorithm 8 for new singleton clusters

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GE-GE Interactions

Summarize each gene histogram by Jacobi polynomials \rightarrow clustering of $y_i \in \mathbb{R}^8$;



PRC clusters. Top (more than 1% of the genes) 6 clusters: average 25%, 50% and 75% quantiles (solid bullets) and average $10f_{0i}$ (empty circle).

Cluster 3 are the genes of interest.

2 SIGN algorithm for BNP clustering

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SIGN algorithm for BNP clustering

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Approximation

Partition: $s_i = k$ if i th unit in k th cluster; alternatively use indicators $\delta_{ij} = I(s_i = s_j)$.

Subset posteriors: Let $[n] = A \cup B$ denote two shards;
 $\delta_A = (\delta_{ij}, i, j \in A)$, same for δ_B ,
 $\delta_{AB} = (\delta_{ij}, i \in A, j \in B)$

$$p(\delta \mid \mathbf{y}) \approx q(\delta \mid \mathbf{y}) \equiv p(\delta_A \mid \mathbf{y}_A) p(\delta_B \mid \mathbf{y}_B) p(\delta_{AB} \mid \delta_A, \delta_B, \mathbf{y})$$

Summary: judge approximation by

$$F_{.1} = \% \text{ pairs with } |E_q(\delta_{ij}) - E(\delta_{ij} \mid \mathbf{y})| > 0.1$$

3 Simulation

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Simulations

Simulation I: simple mixture of $C_0 = 5$ (truth) normals; comparison with PY mixture (full MCMC) and DBSCAN (Ester et al., 1996)

	SIGN	SIGN-VI	PYM	DBSCAN
C	4.94 (0.31)	4.90 (0.30)	5.08 (0.27)	3.64 (0.63)
MISC	0.08 (0.03)	0.09 (0.03)	0.04 (0.01)	0.41 (0.11)
MSE	0.01 (0.01)	0.01 (0.01)	0.01 (0.00)	0.49 (0.18)

MISC=misclassification rate; MSE=estimation of cluster-specific means

Predictive $p(x_{n+1}, y_{n+1} | \mathbf{x}, \mathbf{y})$ implies regression; conditional regression or density regression (Park & Dunson, 2010; M & al, 1996).

PPMx: define more general $p(\rho | \mathbf{x})$, avoiding explicit modeling of a covariate distribution

Estimated partition at the end of each step: need estimated clusters after each step; use Dahl (2006) summary.
Alternatively, variation of information loss (SIGN-VI)

Classification: AUC.

Comparison with full MCMC (“PPMx”), BART, random forest (RF), logistic regression (LR) and SVM

	Simulation III	Simulation IV
SIGN	0.808 (0.067)	0.838 (0.067)
PPMx	0.824 (0.060)	0.841 (0.063)
BART	0.755 (0.062)	0.866 (0.050)
RF	0.793 (0.059)	0.838 (0.067)
LR	0.600 (0.091)	0.524 (0.073)
SVM	0.622 (0.077)	0.585 (0.077)

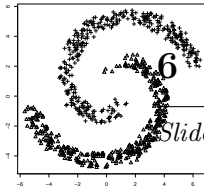
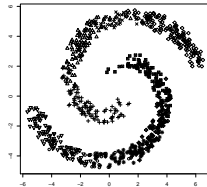
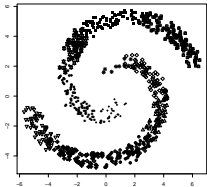
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Simulation II: two spirals

full MCMC

SIGN

DBSCAN



$\hat{C} = 14.10(1.37)$

9.28(.93)

1.98(0.14)

The reduced \hat{C} under the SIGN approximation is typical. Clusters from early steps can be merged, but never split.

4 Classification

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Prediction

Density estimation: BNP clustering,

$$p(\rho) p(\boldsymbol{\theta} | \rho) p(\mathbf{y}_i | \rho, \boldsymbol{\theta}),$$

implies density estimation $p(y_{n+1} | \mathbf{y})$.

Regression & prediction: to be useful for regression, need conditioning in $p(\rho | \mathbf{x})$, on covariates x_i ; $p(y_{n+1} | x_{n+1}, \mathbf{y}, \mathbf{x})$ defines desired regression.

Augmented model: augment response to $z_i = (x_i, y_i)$ and proceed as before

$$p(\rho) p(\boldsymbol{\theta} | \rho) p(\mathbf{z}_i | \rho, \boldsymbol{\theta}).$$

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EHR – Results

AUC for classification by diabetes:

EHR

Results

Response y_i : indicator for diabetes

Covariates x_i : white blood cell count (WBC), red blood cell count (RBC), hemoglobin (HGB), platelets (PLT), fasting blood glucose (FBG), low density lipoproteins (LDL), total cholesterol (TC), triglycerides (Trig), triketopurine (TriK), high density lipoproteins (HDL), serum creatinine (SCr), serum glutamic oxaloacetic transaminase (SGOT), and total bilirubin (TB); sex, height, weight, blood pressure, and waist.

Data: $n = 85,021$ patients

SIGN: $M_1 = 250$ shards \rightarrow 1351 local clusters;
 $M_2 = 5$ shards \rightarrow 25 regional clusters;
Algorithm stops at step $K = 3$

	EHR	Bank
SIGN	0.880	0.825
PPMx	-	-
BART	0.867	0.792
RF	0.869	0.786
LR	0.856	0.781
SVM	0.856	0.761

(“Bank” is another data set, on success of telemarketing)

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GAN

GAN: Chinese policy requires “China first” publication;
We use a “Generative Adversarial Network” (GAN)
(Goodfellow et al. 2014) to generate a hypothetical
repeat

- One network does density estimation $p(x_i, y_i)$ and predictive simulation of n fake data,
 $i = n + 1, \dots, n + n$;
pass the augmented data to a second network:
- A second network tries to discriminate original
versus fake data.
- Iterate until discrimination is impossible.

We comply with Chinese law, but statistical inference is
identical

7 Variations

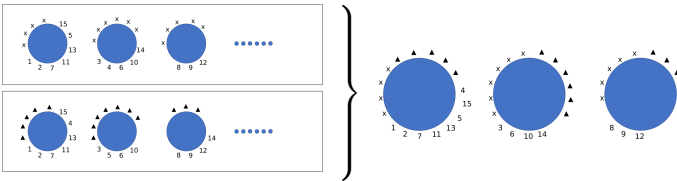
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Variations: Overlapping Shards

Simplification: replace clustering of clusters (and beyond)
by deterministic match and merge.

Clustering: Split data into shards *with common overlap*

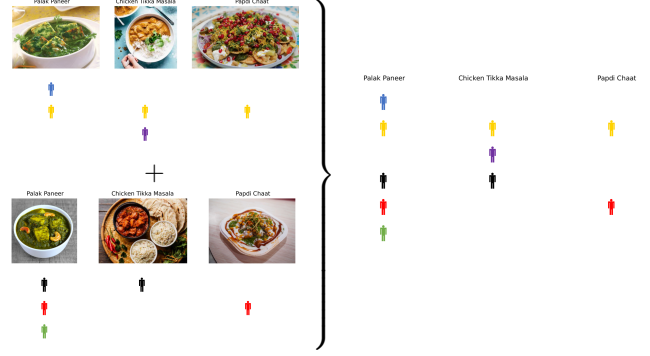
Consensus: Merge clusters C_1, C_2 with m_{12} common
members if $\min \left\{ \frac{m_{12}}{|C_1|}, \frac{m_{12}}{|C_2|} \right\} > \lambda$



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Random subsets (feature allocation)

Feature allocation: Merge features F_1, F_2 if
feature-specific parameters are close, $d(F_1, F_2) < \lambda$.



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Example: Tumor heterogeneity

- experimental unites = mutations $i = 1, \dots, n$;
- features = homogeneous subclones $F_j \subseteq [n]$,
subsets of mutations;
- Each subclone is linked with a set of weights, w_j ,
for observed tissue samples,
use $d(w_j, w_\ell)$ to decide merging

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Double feature allocation

Double feature allocation: two sets of experimental
units, $i = 1, \dots, n$ (e.g., patients) and $s = 1, \dots, S$ (e.g.,
symptoms);
each feature $F_j \subseteq [n]$ (e.g., disease) is associated with a
subset $S_j \subseteq [S]$.

Clustering of clusters: Same – merge features F_1, F_2 if
feature-specific parameters S_1, S_2 are close,
 $d(S_1, S_2) < \lambda$.

Example: EHR, features = “disease”, $F_j \subseteq [n]$, subsets of
patients;
Each disease is linked to a set S_j of symptoms,
 $d(S_j, S_\ell) = |S_j \cap S_\ell| / |S_j \cup S_\ell|$.

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Summary

- Model-based clustering (feature allocation, double FA)
is more flexible than purely algorithmic methods, but
computationally challenging for large n (also for large p)
- Several algorithms, using predictive recursion,
approximation, parallelization, subset posteriors
(consensus MC)

- Approximate posterior uncertainties important for decision problems (e.g., phenotype discovery in EHR data)