

Properties and error analysis of the effective dynamics for diffusion processes

Wei Zhang

Zuse Institute Berlin

joint work with Carsten Hartmann, Tony Lelièvre, Christof Schütte



Outline

- Effective dynamics
- Properties of effective dynamics on time scales
- Pathwise error estimates

Diffusion process

SDE on \mathbb{R}^n

$$dx(s) = -a \nabla V ds + \frac{1}{\beta} (\nabla \cdot a) ds + \sqrt{2\beta^{-1}} \sigma dw(s), \quad s \geq 0.$$

Infinitesimal generator

$$\begin{aligned} \mathcal{L} &= -a \nabla V \cdot \nabla + \frac{1}{\beta} (\nabla \cdot a) \cdot \nabla + \frac{1}{\beta} a : \nabla^2 \\ &= \frac{e^{\beta V}}{\beta} \sum_{1 \leq i, j \leq n} \frac{\partial}{\partial x_i} \left(e^{-\beta V} a_{ij} \frac{\partial}{\partial x_j} \right). \end{aligned}$$

Invariant measure

$$d\mu = \rho(x) dx, \quad \rho(x) = \frac{1}{Z} e^{-\beta V},$$

where $Z = \int_{\mathbb{R}^n} e^{-\beta V} dx$.

Assumptions: smooth coefficients, $a = \sigma \sigma^T$ is elliptic, \dots

Effective dynamics

Reaction coordinate: $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

Effective dynamics

Reaction coordinate: $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

Ito's formula

$$d\xi_I(x(s)) = \mathcal{L}\xi_I(x(s))ds + \sqrt{2\beta^{-1}} \sum_{i=1}^n \sum_{j=1}^d \frac{\partial \xi_I}{\partial x_i} \sigma_{ij}(x(s)) dw_j(s).$$

Effective dynamics

Reaction coordinate: $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

Ito's formula

$$d\xi_l(x(s)) = \mathcal{L}\xi_l(x(s))ds + \sqrt{2\beta^{-1}} \sum_{i=1}^n \sum_{j=1}^d \frac{\partial \xi_l}{\partial x_i} \sigma_{ij}(x(s)) dw_j(s).$$

This motivates the effective dynamics¹

$$dz(s) = \tilde{b}(z(s)) ds + \sqrt{2\beta^{-1}} \tilde{\sigma}(z(s)) dw(s).$$

For $z \in \mathbb{R}^m$, $1 \leq l, k \leq m$,

$$\tilde{b}_l(z) = \mathbf{E}_{\mu_z}(\mathcal{L}\xi_l),$$

$$(\tilde{a})_{lk}(z) = (\tilde{\sigma}\tilde{\sigma}^T)_{lk}(z) = \mathbf{E}_{\mu_z} \left(\sum_{i,j=1}^n a_{ij} \frac{\partial \xi_l}{\partial x_i} \frac{\partial \xi_k}{\partial x_j} \right).$$

Effective dynamics

Reaction coordinate: $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

Ito's formula

$$d\xi_l(x(s)) = \mathcal{L}\xi_l(x(s))ds + \sqrt{2\beta^{-1}} \sum_{i=1}^n \sum_{j=1}^d \frac{\partial \xi_l}{\partial x_i} \sigma_{ij}(x(s)) dw_j(s).$$

This motivates the effective dynamics¹

$$dz(s) = \tilde{b}(z(s)) ds + \sqrt{2\beta^{-1}} \tilde{\sigma}(z(s)) dw(s).$$

For $z \in \mathbb{R}^m$, $1 \leq l, k \leq m$,

$$\tilde{b}_l(z) = \mathbf{E}_{\mu_z}(\mathcal{L}\xi_l),$$

$$(\tilde{a})_{lk}(z) = (\tilde{\sigma}\tilde{\sigma}^T)_{lk}(z) = \mathbf{E}_{\mu_z} \left(\sum_{i,j=1}^n a_{ij} \frac{\partial \xi_l}{\partial x_i} \frac{\partial \xi_k}{\partial x_j} \right).$$

$$\iff \tilde{b} = \mathbf{E}_{\mu_z}(\mathcal{L}\xi), \quad \tilde{\sigma} = [\mathbf{E}_{\mu_z}(\nabla \xi \mathbf{a} \nabla \xi^T)]^{\frac{1}{2}}.$$

1. Legoll and Lelièvre, Nonlinearity, 2010.

Conditional expectation μ_z

On the level set $\Sigma_z = \{x \in \mathbb{R}^n \mid \xi(x) = z\}$, given by

$$d\mu_z(x) = \frac{1}{Q(z)} \rho(x) \left[\det(\nabla \xi \nabla \xi^T)(x) \right]^{-\frac{1}{2}} d\nu_z(x).$$

Conditional expectation μ_z

On the level set $\Sigma_z = \{x \in \mathbb{R}^n \mid \xi(x) = z\}$, given by

$$d\mu_z(x) = \frac{1}{Q(z)} \rho(x) \left[\det(\nabla \xi \nabla \xi^T)(x) \right]^{-\frac{1}{2}} d\nu_z(x).$$

$\forall f : \mathbb{R}^n \rightarrow \mathbb{R}$, co-area formula gives

$$\begin{aligned} \int_{\mathbb{R}^n} f(x) \rho(x) dx &= \int_{\mathbb{R}^m} \left(\int_{\Sigma_z} f(x) d\mu_z \right) Q(z) dz \\ &= \int_{\mathbb{R}^m} \left(\int_{\mathbb{R}^n} f(x) \rho(x) \delta(\xi(x) - z) dx \right) dz \end{aligned}$$

Conditional expectation μ_z

On the level set $\Sigma_z = \{x \in \mathbb{R}^n \mid \xi(x) = z\}$, given by

$$d\mu_z(x) = \frac{1}{Q(z)} \rho(x) \left[\det(\nabla \xi \nabla \xi^T)(x) \right]^{-\frac{1}{2}} d\nu_z(x).$$

$\forall f : \mathbb{R}^n \rightarrow \mathbb{R}$, co-area formula gives

$$\begin{aligned} \int_{\mathbb{R}^n} f(x) \rho(x) dx &= \int_{\mathbb{R}^m} \left(\int_{\Sigma_z} f(x) d\mu_z \right) Q(z) dz \\ &= \int_{\mathbb{R}^m} \left(\int_{\mathbb{R}^n} f(x) \rho(x) \delta(\xi(x) - z) dx \right) dz \end{aligned}$$

$$\begin{aligned} \implies \mathbf{E}_{\mu_z}(f) &= \int_{\Sigma_z} f(x) d\mu_z \\ &= \frac{1}{Q(z)} \int_{\mathbb{R}^n} f(x) \rho(x) \delta(\xi(x) - z) dx \\ &= \mathbf{E}_{\mu}(f \mid \xi(x) = z). \end{aligned}$$

Outline

- Effective dynamics
- Properties of effective dynamics on time scales
- Pathwise error estimates

Generator of effective dynamics

$$\tilde{\mathcal{L}} = \sum_{l=1}^m \tilde{b}_l \frac{\partial}{\partial z_l} + \frac{1}{\beta} \sum_{l,l'=1}^m \tilde{a}_{ll'} \frac{\partial^2}{\partial z_l \partial z_{l'}} .$$

Generator of effective dynamics

$$\tilde{\mathcal{L}} = \sum_{l=1}^m \tilde{b}_l \frac{\partial}{\partial z_l} + \frac{1}{\beta} \sum_{l,l'=1}^m \tilde{a}_{ll'} \frac{\partial^2}{\partial z_l \partial z_{l'}}.$$

Suppose $f(x) = \tilde{f}(\xi(x))$, $g(x) = \tilde{g}(\xi(x))$. Using chain rules,

$$\mathcal{L}f = \sum_{l=1}^m (\mathcal{L}\xi_l) \frac{\partial \tilde{f}}{\partial x_l} + \frac{1}{\beta} \sum_{l,l'=1}^m \left(\sum_{i,j=1}^n a_{ij} \frac{\partial \xi_l}{\partial x_i} \frac{\partial \xi_{l'}}{\partial x_j} \right) \frac{\partial^2 \tilde{f}}{\partial z_l \partial z_{l'}}$$

$$\implies \int_{\mathbb{R}^n} (\mathcal{L}f) g \rho dx = \int_{\mathbb{R}^m} \mathbf{E}_{\mu_z}(\mathcal{L}f) \tilde{g} Q(z) dz = \int_{\mathbb{R}^m} (\tilde{\mathcal{L}}\tilde{f}) \tilde{g} Q(z) dz.$$

Generator of effective dynamics

$$\tilde{\mathcal{L}} = \sum_{l=1}^m \tilde{b}_l \frac{\partial}{\partial z_l} + \frac{1}{\beta} \sum_{l,l'=1}^m \tilde{a}_{ll'} \frac{\partial^2}{\partial z_l \partial z_{l'}}.$$

Suppose $f(x) = \tilde{f}(\xi(x))$, $g(x) = \tilde{g}(\xi(x))$. Using chain rules,

$$\mathcal{L}f = \sum_{l=1}^m (\mathcal{L}\xi_l) \frac{\partial \tilde{f}}{\partial x_l} + \frac{1}{\beta} \sum_{l,l'=1}^m \left(\sum_{i,j=1}^n a_{ij} \frac{\partial \xi_l}{\partial x_i} \frac{\partial \xi_{l'}}{\partial x_j} \right) \frac{\partial^2 \tilde{f}}{\partial z_l \partial z_{l'}}$$

$$\implies \int_{\mathbb{R}^n} (\mathcal{L}f) g \rho dx = \int_{\mathbb{R}^m} \mathbf{E}_{\mu_z}(\mathcal{L}f) \tilde{g} Q(z) dz = \int_{\mathbb{R}^m} (\tilde{\mathcal{L}} \tilde{f}) \tilde{g} Q(z) dz.$$

Proposition 1

The effective dynamics is both reversible and ergodic. And the invariant measure $\tilde{\mu}$ is given by $d\tilde{\mu} = Q(z) dz$.

Time scales

Let φ_i be the orthonormal eigenfunctions of operator $-\mathcal{L}$, i.e., $-\mathcal{L}\varphi_i = \lambda_i\varphi_i$, with eigenvalues

$$0 = \lambda_0 < \lambda_1 \leq \lambda_2 \leq \dots .$$

Similarly, let $\tilde{\varphi}_i$ be the orthonormal eigenfunctions of operator $-\tilde{\mathcal{L}}$ corresponding to eigenvalues $\tilde{\lambda}_i$, where

$$0 = \tilde{\lambda}_0 < \tilde{\lambda}_1 \leq \tilde{\lambda}_2 \leq \dots .$$

Time scales

Let φ_i be the orthonormal eigenfunctions of operator $-\mathcal{L}$, i.e., $-\mathcal{L}\varphi_i = \lambda_i\varphi_i$, with eigenvalues

$$0 = \lambda_0 < \lambda_1 \leq \lambda_2 \leq \dots .$$

Similarly, let $\tilde{\varphi}_i$ be the orthonormal eigenfunctions of operator $-\tilde{\mathcal{L}}$ corresponding to eigenvalues $\tilde{\lambda}_i$, where

$$0 = \tilde{\lambda}_0 < \tilde{\lambda}_1 \leq \tilde{\lambda}_2 \leq \dots .$$

Theorem 1 (Min-Max)

$$\lambda_i = \min_{H_{i+1}} \max_{f \in H_{i+1}, \|f\|_\mu=1} \langle -\mathcal{L}f, f \rangle_\mu ,$$

for $i \geq 0$, where H_{i+1} is $(i + 1)$ -dimensional subspaces.

Time scales

Proposition 2

$$\lambda_i \leq \tilde{\lambda}_i \leq \lambda_i + \frac{1}{\beta} \langle \mathbf{a} \nabla(\varphi_i - \tilde{\varphi}_i \circ \xi), \nabla(\varphi_i - \tilde{\varphi}_i \circ \xi) \rangle_{\mu}.$$

Time scales

Proposition 2

$$\lambda_i \leq \tilde{\lambda}_i \leq \lambda_i + \frac{1}{\beta} \langle \mathbf{a} \nabla(\varphi_i - \tilde{\varphi}_i \circ \xi), \nabla(\varphi_i - \tilde{\varphi}_i \circ \xi) \rangle_{\mu}.$$

Particularly, if

$$\begin{aligned} \varphi(\mathbf{x}) &= (\varphi_1(\mathbf{x}), \varphi_2(\mathbf{x}), \dots, \varphi_m(\mathbf{x})) \in \mathbb{R}^m, \\ \xi(\mathbf{x}) &= \mathbf{F} \circ \varphi(\mathbf{x}) \in \mathbb{R}^m, \end{aligned}$$

we have

$$\tilde{\lambda}_i = \lambda_i, \quad 0 \leq i \leq m.$$

1. Zhang, Hartmann and Schütte, Faraday Discuss., 2016.
2. Nüske, 2018.

Reaction rate

Disjoint sets $A, B \subset \mathbb{R}^n$.

k_{AB} : transition rate between A and B in TPT theory ^{1,2} :

$$k_{AB} = \frac{1}{\beta} \int_{(A \cup B)^c} \sum_{i,j=1}^n a_{ij}(x) \frac{\partial q(x)}{\partial x_i} \frac{\partial q(x)}{\partial x_j} \rho(x) dx ,$$

where q is the committor satisfying

$$\begin{aligned} \mathcal{L}q &= 0, & x \in (A \cup B)^c \\ q|_A &= 0, & q|_B = 1, \end{aligned}$$

1. Vanden-Eijnden, 2006.

2. E and Vanden-Eijnden, Annu. Rev. Phys. Chem. , 2010.

Reaction rate

Suppose $A = \xi^{-1}(\tilde{A})$, $B = \xi^{-1}(\tilde{B})$.

$\tilde{k}_{\tilde{A}\tilde{B}}$: reaction rate of effective dynamics.

Reaction rate

Suppose $A = \xi^{-1}(\tilde{A})$, $B = \xi^{-1}(\tilde{B})$.

\tilde{k}_{AB} : reaction rate of effective dynamics.

Proposition 3

$$k_{AB} \leq \tilde{k}_{AB} = k_{AB} + \frac{1}{\beta} \int_{(A \cup B)^c} \sum_{i,j=1}^n a_{ij} \frac{\partial(q - \tilde{q} \circ \xi)}{\partial x_i} \frac{\partial(q - \tilde{q} \circ \xi)}{\partial x_j} \rho \, dx,$$

where \tilde{q} is committor of effective dynamics.

Again, if $\xi(x) = q(x)$, then $\tilde{k}_{AB} = k_{AB}$.

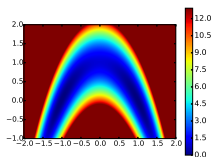
1. Lu and Vanden-Eijnden, J. Chem. Phys., 2014.
2. Zhang, Hartmann and Schütte, Faraday Discuss., 2016.

Simple 2D Example

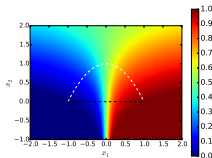
$$V_\epsilon(x_1, x_2) = (x_1^2 - 1)^2 + \frac{1}{\epsilon} (x_1^2 + x_2 - 1)^2,$$

$$\xi_1(x_1, x_2) = x_1 \exp(-2x_2) \quad \text{and} \quad \xi_2(x_1, x_2) = x_1$$

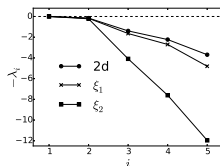
$$\beta = 2.0, \quad \epsilon = 0.1.$$



(a) Potential



(b) Committor



(c) Eigenvalues

| k_{AB} | ξ_1 | ξ_2 |
|----------------------|----------------------|----------------------|
| 3.0×10^{-2} | 3.3×10^{-2} | 4.8×10^{-2} |

Table: Reaction rate k_{AB}

Outline

- Effective dynamics
- Properties of effective dynamics on time scales
- Pathwise error estimates

Pathwise error estimates

Aim: compare $\xi(x(s))$ and $z(s)$,
when ξ is nonlinear, multi-dimensional ($m > 1$).

Pathwise error estimates

Aim: compare $\xi(x(s))$ and $z(s)$,
when ξ is nonlinear, multi-dimensional ($m > 1$).

$$d\xi(x(s)) = (\mathcal{L}\xi)(x(s)) ds + \sqrt{2\beta^{-1}}(\nabla\xi\sigma)(x(s)) dw(s),$$

$$\begin{aligned} dz(s) &= \tilde{b}(z(s)) ds + \sqrt{2\beta^{-1}}\tilde{\sigma}(z(s)) d\tilde{w}(s) \\ &= \mathbf{E}_{\mu_z}(\mathcal{L}\xi)(z(s)) ds + \sqrt{2\beta^{-1}}[\mathbf{E}_{\mu_z}(\nabla\xi a \nabla\xi^T)]^{\frac{1}{2}}(z(s)) d\tilde{w}(s). \end{aligned}$$

Two guiding examples: linear case 1

Linear reaction coordinate:

$$\xi(x) = (x_1, x_2, \dots, x_m)^T = z, \quad x = (z, y) \in \mathbb{R}^m \times \mathbb{R}^{n-m}.$$

Choose

$$V(z, y) = V_0(z, y) + \frac{1}{\epsilon} V_1(y), \quad 0 < \epsilon \ll 1$$

$$a = \sigma = I_{n \times n}$$

Two guiding examples: linear case 1

Linear reaction coordinate:

$$\xi(x) = (x_1, x_2, \dots, x_m)^T = z, \quad x = (z, y) \in \mathbb{R}^m \times \mathbb{R}^{n-m}.$$

Choose

$$V(z, y) = V_0(z, y) + \frac{1}{\epsilon} V_1(y), \quad 0 < \epsilon \ll 1$$

$$a = \sigma = I_{n \times n}$$

\implies SDE becomes

$$dz_i(s) = - \frac{\partial V_0}{\partial z_i}(z(s), y(s)) ds + \sqrt{2\beta^{-1}} dw_i(s),$$

$$dy_j(s) = - \frac{\partial V_0}{\partial y_j}(z(s), y(s)) ds - \frac{1}{\epsilon} \frac{\partial V_1}{\partial y_j}(y(s)) ds + \sqrt{2\beta^{-1}} dw_j(s).$$

Two guiding examples: linear case 2

Linear reaction coordinate:

$$\xi(x) = (x_1, x_2, \dots, x_m)^T = z, \quad x = (z, y) \in \mathbb{R}^m \times \mathbb{R}^{n-m}.$$

Choose

$$\sigma \equiv \begin{pmatrix} I_{m \times m} & 0 \\ 0 & \frac{1}{\sqrt{\delta}} I_{(n-m) \times (n-m)} \end{pmatrix}, \quad 0 < \delta \ll 1$$

Two guiding examples: linear case 2

Linear reaction coordinate:

$$\xi(x) = (x_1, x_2, \dots, x_m)^T = z, \quad x = (z, y) \in \mathbb{R}^m \times \mathbb{R}^{n-m}.$$

Choose

$$\sigma \equiv \begin{pmatrix} I_{m \times m} & 0 \\ 0 & \frac{1}{\sqrt{\delta}} I_{(n-m) \times (n-m)} \end{pmatrix}, \quad 0 < \delta \ll 1$$

\implies SDE becomes

$$\begin{aligned} dz_i(s) &= -\frac{\partial V}{\partial z_i}(z(s), y(s)) ds + \sqrt{2\beta^{-1}} dw_i(s), \\ dy_j(s) &= -\frac{1}{\delta} \frac{\partial V}{\partial y_j}(z(s), y(s)) ds + \sqrt{\frac{2\beta^{-1}}{\delta}} dw_j(s). \end{aligned}$$

Two guiding examples: linear case 2

$$\begin{aligned} dz_i(s) &= - \frac{\partial V}{\partial z_i}(z(s), y(s)) ds + \sqrt{2\beta^{-1}} dw_i(s), \\ dy_j(s) &= - \frac{1}{\delta} \frac{\partial V}{\partial y_j}(z(s), y(s)) ds + \sqrt{\frac{2\beta^{-1}}{\delta}} dw_j(s). \end{aligned} \tag{1}$$

(1) is the “**averaging system**” in the study of multiscale dynamics.

Two guiding examples: linear case 2

$$\begin{aligned} dz_i(s) &= -\frac{\partial V}{\partial z_i}(z(s), y(s)) ds + \sqrt{2\beta^{-1}} dw_i(s), \\ dy_j(s) &= -\frac{1}{\delta} \frac{\partial V}{\partial y_j}(z(s), y(s)) ds + \sqrt{\frac{2\beta^{-1}}{\delta}} dw_j(s). \end{aligned} \tag{1}$$

(1) is the “**averaging system**” in the study of multiscale dynamics.

Facts:

1. $\mathbb{R}^n = \mathbb{R}^m \times \mathbb{R}^{n-m}$.
2. $\rho_z(y) \propto e^{-\beta V(z,y)}$ is the density used to perform “averaging”, for fixed z .
3. $\mathcal{L} = \frac{1}{\delta} \mathcal{L}_0 + \mathcal{L}_1$, s.t. $\int_{\mathbb{R}^{n-m}} (\mathcal{L}_0 f) \rho_z dy = 0$, $\forall f$ on \mathbb{R}^{n-m} .
4. δ : time scale separation.

General case

For a general mapping $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$, we have

1. $\Sigma_z = \{x \in \mathbb{R}^n \mid \xi(x) = z\}$.
2. $d\mu_z(x) = \frac{1}{Q(z)} \rho(x) \left[\det(\nabla \xi \nabla \xi^T)(x) \right]^{-\frac{1}{2}} d\nu_z(x)$.

General case

For a general mapping $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$, we have

1. $\Sigma_z = \{x \in \mathbb{R}^n \mid \xi(x) = z\}$.
2. $d\mu_z(x) = \frac{1}{Q(z)} \rho(x) \left[\det(\nabla \xi \nabla \xi^T)(x) \right]^{-\frac{1}{2}} d\nu_z(x)$.
3. $\mathcal{L} = \mathcal{L}_0 + \mathcal{L}_1$, where

$$\mathcal{L}_0 = \frac{e^{\beta V}}{\beta} \sum_{1 \leq i, j \leq n} \frac{\partial}{\partial x_i} \left(e^{-\beta V} (a\Pi)_{ij} \frac{\partial}{\partial x_j} \right),$$

$$\Pi = I - \sum_{1 \leq i, j \leq m} (\Phi^{-1})_{ij} \nabla \xi_i \otimes (a \nabla \xi_j), \quad \Phi = \nabla \xi a \nabla \xi^T.$$

$$\implies \int_{\Sigma_z} (\mathcal{L}_0 f) d\mu_z = 0, \quad \forall f : \Sigma_z \rightarrow \mathbb{R}.$$

General case

For a general mapping $\xi : \mathbb{R}^n \rightarrow \mathbb{R}^m$, we have

1. $\Sigma_z = \{x \in \mathbb{R}^n \mid \xi(x) = z\}$.
2. $d\mu_z(x) = \frac{1}{Q(z)} \rho(x) \left[\det(\nabla \xi \nabla \xi^T)(x) \right]^{-\frac{1}{2}} d\nu_z(x)$.
3. $\mathcal{L} = \mathcal{L}_0 + \mathcal{L}_1$, where

$$\mathcal{L}_0 = \frac{e^{\beta V}}{\beta} \sum_{1 \leq i, j \leq n} \frac{\partial}{\partial x_i} \left(e^{-\beta V} (a\Pi)_{ij} \frac{\partial}{\partial x_j} \right),$$

$$\Pi = I - \sum_{1 \leq i, j \leq m} (\Phi^{-1})_{ij} \nabla \xi_i \otimes (a \nabla \xi_j), \quad \Phi = \nabla \xi a \nabla \xi^T.$$

$$\implies \int_{\Sigma_z} (\mathcal{L}_0 f) d\mu_z = 0, \quad \forall f : \Sigma_z \rightarrow \mathbb{R}.$$

4. $\mathcal{E}_z(f, h) = - \int_{\Sigma_z} (\mathcal{L}_0 f) h d\mu_z = \frac{1}{\beta} \int_{\Sigma_z} (a \Pi \nabla f) \cdot (\Pi \nabla h) d\mu_z$.

Pathwise error estimates: Assumptions

1. $|\tilde{\mathbf{b}}(z) - \tilde{\mathbf{b}}(z')| \leq L_b |z - z'|$, $\|\tilde{\sigma}(z) - \tilde{\sigma}(z')\|_F \leq L_\sigma |z - z'|$.

2. Define $\mathbf{A} = (\nabla_\xi \mathbf{a} \nabla_\xi^T)^{\frac{1}{2}}$, and

$$\kappa_1^2 := \sum_{i=1}^m \int_{\mathbb{R}^n} (\Pi \nabla \mathcal{L} \xi_i) \cdot (\mathbf{a} \Pi \nabla \mathcal{L} \xi_i) d\mu < +\infty,$$

$$\kappa_2^2 := \sum_{1 \leq i, j \leq m} \int_{\mathbb{R}^n} (\Pi \nabla \mathbf{A}_{ij}) \cdot (\mathbf{a} \Pi \nabla \mathbf{A}_{ij}) d\mu < +\infty.$$

3. μ_Z and \mathcal{E}_Z satisfy the Poincaré inequality with a uniform constant $\rho > 0$, i.e.,

$$\int_{\Sigma_Z} f^2 d\mu_Z - \left(\int_{\Sigma_Z} f d\mu_Z \right)^2 \leq \frac{1}{\rho} \mathcal{E}_Z(f, f), \quad \forall f : \Sigma_Z \rightarrow \mathbb{R}.$$

Pathwise error estimates

Theorem 2

$x(s)$ satisfies

$$dx(s) = -a \nabla V ds + \frac{1}{\beta} (\nabla \cdot a) ds + \sqrt{2\beta^{-1}} \sigma dw(s), \quad s \geq 0,$$

starting from $x(0) \sim \mu$, and $z(s)$ is the effective dynamics

$$dz(s) = \tilde{b}(z(s)) ds + \sqrt{2\beta^{-1}} \tilde{\sigma}(z(s)) d\tilde{w}(s),$$

with $z(0) = \xi(x(0))$. For all $t \geq 0$,

$$\mathbf{E} \left(\sup_{0 \leq s \leq t} |\xi(x(s)) - z(s)|^2 \right) \leq \frac{3t}{\beta\rho} \left(\frac{27\kappa_1^2}{2\rho} + \frac{32\kappa_2^2}{\beta} \right) e^{Lt},$$

where $L = 3L_b^2 + \frac{48L_\sigma^2}{\beta} + 1$.

Pathwise error estimates: proof

1. Coupling of noise: $d\tilde{w}(s) = (A^{-1}\nabla\xi\sigma)(x(s)) dw(s)$,
 $A = (\nabla\xi a \nabla\xi^T)^{\frac{1}{2}}$.

Pathwise error estimates: proof

1. Coupling of noise: $d\tilde{w}(s) = (A^{-1}\nabla\xi\sigma)(x(s)) dw(s)$,
 $A = (\nabla\xi a \nabla\xi^T)^{\frac{1}{2}}$.

2. $\varphi(x) = (\mathcal{L}\xi)(x) - \tilde{b}(\xi(x))$, $\forall x \in \mathbb{R}^n$.

$$\begin{aligned} & d(\xi(x(s)) - z(s)) \\ &= \varphi(x(s)) ds + [\tilde{b}(\xi(x(s))) - \tilde{b}(z(s))] ds + \sqrt{2\beta^{-1}} [A(x(s)) - \tilde{\sigma}(z(s))] d\tilde{w}(s). \end{aligned}$$

1. Legoll, Lelièvre and Olla, Stoch. Process. Appl., 2017.

2. Lyons and Zhang, Ann. Probab., 1994.

Pathwise error estimates: proof

1. Coupling of noise: $d\tilde{w}(s) = (A^{-1}\nabla\xi\sigma)(x(s)) dw(s)$,
 $A = (\nabla\xi a \nabla\xi^T)^{\frac{1}{2}}$.

2. $\varphi(x) = (\mathcal{L}\xi)(x) - \tilde{b}(\xi(x))$, $\forall x \in \mathbb{R}^n$.

$$\begin{aligned} & d(\xi(x(s)) - z(s)) \\ &= \varphi(x(s)) ds + [\tilde{b}(\xi(x(s))) - \tilde{b}(z(s))] ds + \sqrt{2\beta^{-1}} [A(x(s)) - \tilde{\sigma}(z(s))] d\tilde{w}(s). \end{aligned}$$

3. Forward-backward Martingale approach^{1,2}

$$\implies \mathbf{E} \left[\sup_{0 \leq t' \leq t} \left| \int_0^{t'} \varphi(x(s)) ds \right|^2 \right] \leq \frac{27\kappa_1^2 t}{2\beta\rho^2}.$$

1. Legoll, Lelièvre and Olla, Stoch. Process. Appl., 2017.

2. Lyons and Zhang, Ann. Probab., 1994.

Pathwise error estimates: proof

1. Coupling of noise: $d\tilde{w}(s) = (A^{-1}\nabla\xi\sigma)(x(s)) dw(s)$,
 $A = (\nabla\xi a \nabla\xi^T)^{\frac{1}{2}}$.

2. $\varphi(x) = (\mathcal{L}\xi)(x) - \tilde{b}(\xi(x))$, $\forall x \in \mathbb{R}^n$.
 $d(\xi(x(s)) - z(s))$
 $= \varphi(x(s)) ds + [\tilde{b}(\xi(x(s))) - \tilde{b}(z(s))] ds + \sqrt{2\beta^{-1}} [A(x(s)) - \tilde{\sigma}(z(s))] d\tilde{w}(s)$.

3. Forward-backward Martingale approach^{1,2}

$$\implies \mathbf{E} \left[\sup_{0 \leq t' \leq t} \left| \int_0^{t'} \varphi(x(s)) ds \right|^2 \right] \leq \frac{27\kappa_1^2 t}{2\beta\rho^2}.$$

4. $\tilde{\sigma} = [\mathbf{E}_{\mu_z}(A^2)]^{\frac{1}{2}}$. Lieb's concavity theorem

$$\implies \mathbf{E}_{\mu_z} \|A - \tilde{\sigma} \circ \xi\|_F^2 \leq 2 \mathbf{E}_{\mu_z} \|A - (\mathbf{E}_{\mu_z} A) \circ \xi\|_F^2.$$

1. Legoll, Lelièvre and Olla, Stoch. Process. Appl., 2017.

2. Lyons and Zhang, Ann. Probab., 1994.

Pathwise error estimates: linear cases

Corollary 3

Let $x = (z, y)$ and $\xi(x) = z$. $L = 3L_b^2 + \frac{48L_\sigma^2}{\beta} + 1$.

1. (Case 1) Potential $V = V_0 + \frac{1}{\epsilon} V_1$. $\exists \epsilon_0 \geq 0$, s.t. when $\epsilon \leq \epsilon_0$,

$$\mathbf{E} \left(\sup_{0 \leq s \leq t} |\xi(x(s)) - z(s)|^2 \right) \leq \frac{C_2 \epsilon^2 t}{K^2} e^{Lt},$$

for some $C_2 > 0$ independent of ϵ and K .

2. (Case 2) We have

$$\mathbf{E} \left(\sup_{0 \leq s \leq t} |\xi(x(s)) - z(s)|^2 \right) \leq \frac{C_2 \delta t}{\rho_0^2} e^{Lt},$$

for some $C_2 > 0$ independent of δ and ρ_0 .

Conclusion

Summary

1. effective dynamics
2. properties on eigenvalues and reaction rates
3. pathwise estimates (nonlinear, vector-valued ξ)

Related topics

1. numerical methods
2. non-reversible case (U. Sharma)

Conclusion

Summary

1. effective dynamics
2. properties on eigenvalues and reaction rates
3. pathwise estimates (nonlinear, vector-valued ξ)

Related topics

1. numerical methods
2. non-reversible case (U. Sharma)

Thank you !