## Beyond the Hörmander Condition

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CIRM, September 2018

### Motivation

- Why studying UFG processes?
- Examples of SDEs which are UEG but do not satisfy the Hörmander condition
- General Setting
- The Hörmander condition
  - PDE Theory and probability
  - Geometric Control Theoretical point of view

#### UFG condition

- "Obtuse angle condition"
- non-autonomous (hypoelliptic) processes "

  "UFG diffusions"
- Some results on the long-time behaviours of UFG diffusions.

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- Non-ergodic theory???
- Multi-agent systems

 $\partial_t f_t + v \partial_x f_t + \partial_v \left[ (G(M_t(t, x)) - v) f_t \right] - \sigma \partial_{w} f_t = 0$  $f_t = f_t(x, v)$  particle density,

$$M(t, \mathbf{x}) = \frac{\int_{\mathbf{x}} d\mathbf{y} \int_{\mathbf{x}} d\mathbf{w} \, h(\mathbf{y}, \mathbf{w}) \varphi(\mathbf{x} - \mathbf{y}) \mathbf{w}}{\int_{\mathbf{x}} d\mathbf{y} \int_{\mathbf{x}} d\mathbf{w} \, h(\mathbf{y}, \mathbf{w}) \varphi(\mathbf{x} - \mathbf{y})}$$

[Butta, Flandoli, Ottobre, Zegarlinski, arxiv, 2018]

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▶ (Smooth) Vector field in  $\mathbb{R}^N$ , i.e. map  $V : \mathbb{R}^N \to \mathbb{R}^N$ , with

$$V(x) = (V^1(x), \ldots, V^j(x), \ldots, V^N(x)) \quad x \in \mathbb{R}^N$$

Identified with first order differential operator

$$V(x) = \sum_{j} V^{j}(x) \partial_{j}$$

For a collection of fields

$$V_0(x), V_1(x), \ldots, V_d(x)$$

Example: in R<sup>3</sup> consider

$$V:=\partial_x-rac{y}{2}\partial_x$$
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▶ SDE in  $\mathbb{R}^N$ 

## $dX_t = V_0(X_t)dt + V_1(X_t) \circ dW_t, \quad X_0 = x$

$$dX_l = V_0(X_l)dl + \sum_{t=1}^d V_t(X_t) \circ dW_t^l, \quad X_0 = x$$

Take  $\mathbb{E}I(X_t|X_0 = x) =: u(t, x)$ . Then  $\partial_t u(t, x) = \mathcal{L}u(t, x)$ 

u(0,x)=f(x)

▶ Operator *L* in *Hörmander's "Sum of squares" form* 

$$\mathcal{L} = V_0 + rac{1}{2}\sum_{l=1}^d V_l^2$$

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# Warning

I will use the word *distribution* in geometric sense i.e. as a map

$$M \ni x \xrightarrow{\mathcal{D}}$$
 vector space  $\subseteq T_x M$ 

This can be produced by assigning a set of vector fields on *M* 

 $M \ni x \xrightarrow{\mathcal{V}} \operatorname{span}\{V_0(x), V_1(x), \ldots, V_d(x)\}$ 

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$$M \ni x \xrightarrow{\mathcal{D}} \operatorname{span} \{ V_0(x), V_1(x), \ldots, V_d(x) \}$$

- Let  $V_0, V_1, \ldots, V_d$  be d + 1 vector fields on  $\mathbb{R}^N$
- Consider the following Lie Algebras

 $\Delta_0(\mathbf{x}) = \operatorname{span}Lie\{V_0(\mathbf{x}), V_1(\mathbf{x}), \dots, V_d(\mathbf{x})\}$  $\Delta_0(\mathbf{x}) = \operatorname{span}Lie\{V_1(\mathbf{x}), \dots, V_d(\mathbf{x}), [V_0, V_1](\mathbf{x}), \dots, [V_0, V_d](\mathbf{x})\} \subseteq \Delta_0(\mathbf{x}).$ 

- If ∆<sub>0</sub>(x) = ℝ<sup>N</sup> for every x ∈ ℝ<sup>N</sup> then L is hypoelliptic (on ℝ<sup>N</sup>) analytic viewpoint
- If ∆(x) = ℝ<sup>N</sup> for every x ∈ ℝ<sup>N</sup> then ∂<sub>t</sub> − L is hypoelliptic (on ℝ<sub>+</sub> × ℝ<sup>N</sup>) and the process X<sub>t</sub> has a density − probabilistic perspective

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- ▶ If  $\Delta(x) = \mathbb{R}^N$  for every  $x \in \mathbb{R}^N$  then  $\partial_t \mathcal{L}$  is hypoelliptic (on  $\mathbb{R}_+ \times \mathbb{R}^N$ ) and the process  $X_t$  has a density – probabilistic perspective

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Hörmander Condition

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$$V_0(x) = V_0^{(\Delta)}(x) + V_0^{(\perp)}(x)$$

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$$\begin{aligned} \Delta_{n+1}(x) &= \operatorname{span}Lie\{V_0(x), V_1(x), \dots, V_d(x)\} \\ \Delta_n(x) &= \operatorname{span}Lie\{V_1(x), \dots, V_d(x), [V_0, V_1](x), \dots, [V_0, V_d](x)\} \subseteq \Delta_{n+1}(x) \end{aligned}$$

$$V_0(x) = V_0^{(\Delta_n)}(x) + V_0^{(\perp)}(x)$$

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# The HC in PDE Theory

Under the PHC one can make sense of the PDE

$$\partial_t u(t, x) = \mathcal{L}u(t, x)$$
  
 $u(0, x) = f(x)$ 

as u(t, x) is smooth in both arguments (even when f is just continuous and bounded)

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In particular u(t, x) is differentiable in the direction ∂t, V<sub>0</sub>, in all the directions {V<sub>i</sub>}<sup>a</sup><sub>i=1</sub> and in the directions belonging to the Lie algebra.

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The Control-Theoretical viewpoint

▶ In control theory the Hörmander condition is known as Chow's Condition:

If 
$$|span(Lie\{V_0(x), V_1(x), \dots, V_d(x)\}) = \mathbb{R}^N$$
 for all  $x \in \mathbb{R}^N$ 

then any two points of  $\mathbb{R}^N$  are connected by integral curves of the fields  $V_0(x), V_1(x), \ldots, V_d(x)$  (*reachability*)
The HC implies reachability, it *does not* imply that the corresponding stochastic dynamics goes everywhere (controllable)! E. g.:

$$dX_t = -sin(X_t)dt + cos(X_t) \circ dW_t, \quad X_t \in \mathbb{R}$$

Solution of apparent contradiction.

 $dX_t = -sin(X_t)dt + cos(X_t)u(t)dt$ 

versus

 $dX_t = -\sin(X_t)\tilde{u}(t)dt + \cos(X_t)u(t)dt$ 

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The Lie algebra

 $\Delta(x) = Lie\{V_1(x), \dots, V_d(x), [V_0, V_1], \dots, [V_0, V_d]\}$  is finitely generated

That is,

Level 1	$\mathfrak{V}_0 = \{V_1, \ldots, V$	/ <sub>d</sub> }
Level 2	$\mathfrak{V}_1 = \{ [V_i, V], $	$0 \leq i \leq d, V \in \mathfrak{V}_0$
Level 3	$\mathfrak{V}_2 = \{ [V_i, V],$	$0 \leq i \leq d, V \in \mathfrak{V}_1$
÷		
Level m		

 No assumption on the rank of the Lie algebra! the rank does not even need to be constant (and indeed, it is in general not constant)

► A bit more formally

$$V_{[\alpha]}(\mathbf{x}) = \sum_{eta \in \mathcal{A}_m} \varphi^{eta}_{\alpha}(\mathbf{x}) V_{[eta]}(\mathbf{x}) \,.$$

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 $\Delta(x) = Lie\{V_1(x), \dots, V_d(x), [V_0, V_1], \dots, [V_0, V_d]\}$  is finitely generated

That is,

Level 1	$\mathfrak{V}_0 = \{V_1, \ldots, V_n\}$	V <sub>d</sub> }	
Level 2	$\mathfrak{V}_1 = \{ [V_i, V], $	$0 \leq i \leq d, V \in \mathfrak{V}_0$	
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No assumption on the rank of the Lie algebra! the rank does not even need to be constant (and indeed, it is in general not constant)

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### PDE

$$\blacktriangleright \mathbb{E}f(X_t|X_0=x) =: u(t,x)$$

$$\partial_t u(t,x) = V_0 u(t,x) + \frac{1}{2} \sum_{i=1}^d V_i^2 u(t,x)$$

Rewrite the above as

$$(\partial_t - V_0)u(t, x) = \frac{1}{2}\sum_{i=1}^n V_i^2 u(t, x)$$

Suppose we can prove differentiability in the direction  $\mathcal{V}:=\partial_t-V_0$ . Then we can still make sense of the above (Strook, Kusuoka, Crisan, Delarue)

Extreme example of UFG condition: 1D transport equation

$$\begin{cases} \partial_t u(t, x) = \partial_x u(t, x) \\ u(0, x) = f(x) \end{cases} \Rightarrow u(t, x) = f(x+t)$$

Solution is smooth in direction  $\partial_t - \partial_x$  as  $(\partial_t - \partial_x)u(t, x) \equiv 0$ 

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## Stochastic Geodesic Equation

$$dz_t = V_0(z_t)dt + V_1(z_t) \circ dW_t, \quad z = (u, v) \in \mathbb{R}^6$$
  
 $V_0 = (v, -|v|^2 u), \quad V_1 = (0, u \times v).$ 

 $z_t \in T\mathbb{S}^2 := \{(u, v) : |u| = 1, v \perp u\}$ 

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#### Known facts from theory of finitely generated distributions

- Under the UFG condition the space  $\mathbb{R}^N$  is partitioned into manifolds  $\mathcal{M}$ .
- Each manifold *M* is the integral manifold of the distribution

#### $\Delta_0(x) = \operatorname{span} Lie\{V_0, V_1, \ldots, V_d\}$

#### ▶ The rank of $\Delta_0(x)$ is constant on $\mathcal{M}$ .

- The orbits of the vector fields V<sub>0</sub>,..., V<sub>σ</sub> coincide with the integral manifolds of Δ
- + Strook and Varadhan control theorem
  - If the process X<sub>t</sub> starts on one manifold M it will stay on M for every positive t:

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- ► exponential decay of derivatives (+ some control theory) ⇒ uniqueness of invariant measure (on the manifold)
- Obtuse Angle condition

## $\left[V_{lpha}, V_{0} ight] f(x) \cdot V_{lpha} f(x) \leq -\lambda \left|V_{lpha} f(x) ight|^{2}$

Obtuse angle condition implies

 $|V_lpha P_l f(x)| \leq c e^{-\lambda t}$ 

Suppose you know  $(P_t f)(x) \to v$ 

$$\begin{split} P_{l}f)(y) &= (P_{l}f)(y) - (P_{l}f)(x) + (P_{l}f)(x) - \nu \\ &= \int_{0}^{T} V_{\alpha}(P_{l}f)(\gamma(s))ds + (P_{l}f)(x) - \nu \end{split}$$

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Beyond the Hörmander Condition

Under the UFG condition there is a change of coordinates such that locally one can always express the SDE

$$dX_t = V_0(X_t)dt + \sum_{i=1}^d V_i(X_t) \circ dW_t^i, \quad X_0 = x$$

in the form "ODE + SDE":  $\tilde{X}_t = (Z_t, \zeta_t)$ 

$$dZ_t = U_0(Z_t, \zeta_t) dt + \sum_{j=1}^d U_j(Z_t, \zeta_t) \circ dW_t^j$$
$$d\zeta_t = U(\zeta_t) dt \qquad \text{one-dimensional OI}$$

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## Non-autonomous hypoelliptic systems

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- Either  $\zeta_l \to \pm \infty$  or  $\zeta_l \to$
- ▶ Let  $\overline{\zeta}$  be a stationary point of U and suppose  $\zeta_t \to \overline{\zeta}$
- ▶ Reasonable guess:  $X_t = (Z_t, \zeta_t) \to (\overline{Z}_t, \overline{\zeta})$  where

$$d\hat{Z}_t = U_0(\hat{Z}_t,\hat{\zeta}) dt + \sum_{j=1}^d U_j(\hat{Z}_t,\hat{\zeta}) \circ dW_t^j$$

▶ Notice that in this case  $V_0^{(\perp)}(x) = (0, ..., 0, U(z))$  hence

the curve  $t o e^{r \zeta_0^{(\perp)}}(x)^{\,\prime\prime} = {}^{*} \zeta_t$  is driving the dynamics

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Beyond the Hörmander Condition

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- Let  $\bar{\zeta}$  be a stationary point of U and suppose  $\zeta_t \to \bar{\zeta}$
- Reasonable guess:  $X_t = (Z_t, \zeta_t) \rightarrow (\overline{Z}_t, \overline{\zeta})$  where

$$dar{Z}_t = U_0(ar{Z}_t,ar{\zeta}) dt + \sum_{j=1}^d U_j(ar{Z}_t,ar{\zeta}) \circ dW_t^j$$

► Notice that in this case  $V_0^{(\perp)}(x) = (0, ..., 0, U(z))$  hence

the curve  $t \to e^{tV_0^{(\perp)}}(x)$  " = "  $\zeta_t$  is driving the dynamics

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## Example 1

UFG- Heisenberg diffusion

$$dY_t = -Y_t dt + \sqrt{2} dW_t^2$$
  

$$dZ_t = -2Z_t dt - \sqrt{2} Y_t \circ dW_t^1 + \sqrt{2} \zeta_t \circ dW_t^2$$
  

$$d\zeta_t = -\zeta_t dt$$

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# Example 2 (less cheating)

Random circles

$$dX_t = -Y_t dt + \sqrt{2}X_t \circ dB_t$$
$$dY_t = X_t dt + \sqrt{2}Y_t \circ dB_t.$$

$$V_0 = (-y, x), \quad V_1 = (x, y)$$

After the change of coordinates one obtains

 $d\zeta_l = dt$  $dZ_l = \sqrt{2}dW_l$ 

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## Example 2 (less cheating)

Random circles

$$dX_t = -Y_t dt + \sqrt{2}X_t \circ dB_t$$
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After the change of coordinates one obtains

$$d\zeta_t = dt$$
  
 $dZ_t = \sqrt{2}dW$ 





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