

Excluded Minor Results For Vf-Safe Delta–Matroids

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Quick recap 1.

Definition (Bouchet)

(E, \mathcal{F}) form a Δ -matroid if

- 1 $\mathcal{F} \neq \emptyset$.
- 2 For all $F_1, F_2 \in \mathcal{F}$ and $e \in F_1 \Delta F_2$, there exists $f \in F_1 \Delta F_2$ such that $F_1 \Delta \{e, f\} \in \mathcal{F}$.

We allow $e = f$ in the definition.

\mathcal{F} is the set of feasible sets.

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The set of quasi-trees of a ribbon graph form the feasible sets of a **ribbon-graphic** Δ -matroid.

Quick recap 2.

Let $D = (E, \mathcal{F})$ be a Δ -matroid and $A \subseteq E$. Then the **partial dual** $D * A$ is the Δ -matroid such that F is feasible in $D * A$ if and only if $F \triangle A$ is feasible in D .

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Partial (local) duality of ribbon graphs is consistent with that of Δ -matroids.

Binary Δ -matroids 1.

A symmetric binary matrix

$$\begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

The non-singular principal sub-matrices

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Proposition (Bouchet)

The collection of (sets of column indices of) non-singular, principal sub-matrices of a symmetric binary matrix M form the feasible sets of a Δ -matroid $D(M)$.

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These Δ -matroids are (confusingly) called **graphic**.

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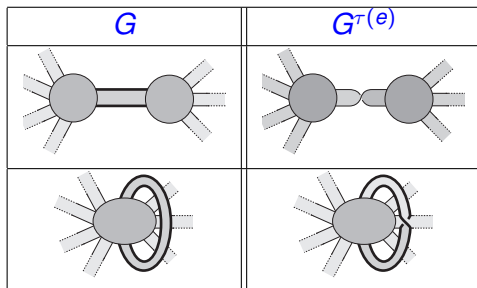
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Proposition (Bouchet)

- 1 *Every normal binary Δ -matroid is graphic.*
- 2 *Every binary matroid is a binary Δ -matroid.*
- 3 *Every ribbon-graphic Δ -matroid is binary.*

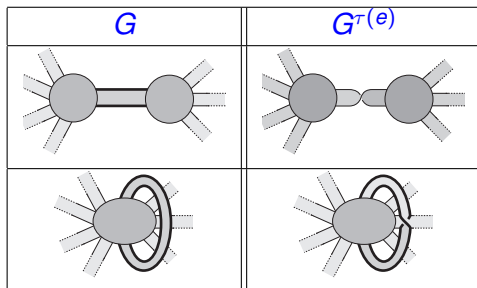
Half-Twists

A natural ribbon graph operation is the **partial Petrial**: apply a half-twist to an edge e to get $G^{\tau(e)}$.



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Extends to sets of edges: $G^{\tau(A)}$ denotes G with half-twists added to the edges of A .

Loop complementation

If M is a symmetric binary matrix, then $M + e$ is formed from M by replacing $M_{e,e}$ by $1 - M_{e,e}$.

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Proposition (Chun, Moffatt, N, Rueckriemen)

- 1 If $e \notin F$, then $F \in \mathcal{F}(D(G^{\tau(e)})) \Leftrightarrow F \in \mathcal{F}(D(G))$.
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Open Question

What are the excluded minors for the class of vf-safe Δ -matroids?

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What are the excluded minors for the class of vf-safe Δ -matroids?

Theorem

A matroid is vf-safe if and only if it has no minor isomorphic to $U_{2,6}$, $U_{4,6}$, P_6 , F_7^- or $(F_7^-)^$.*

Vf-safe Δ -matroids

The operations $+e$ and $*e$ act on set systems like two transpositions in Sym_3 .

Definition (Brijder and Hoogeboom)

If a set system S' may be obtained from S by a sequence of $+$ and $*$ operations, then S' is a **twisted dual** of S .

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- All three types of minor can be defined for arbitrary set systems.
- The order of operations matters, but not if we take care to avoid contracting loops, deleting coloops etc.
- So there is a well-defined notion of 3-minors.

Vf-safe Δ -matroids

Theorem (Bonin, C. Chun, N)

A set system is a vf-safe Δ -matroid if and only if it contains no 3-minor isomorphic to a twisted dual of S_3 .

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Proof.

Each member of $\mathcal{S} \cup \mathcal{T}$ contains a twisted dual of S_3 as a 3-minor. \square

Vertex minors 1.

Recall normal, binary Δ -matroids are graphic.

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Two graphs are **locally equivalent** if one can be obtained from the other by a sequence of the following:

- adding / removing loops (loop complementations).
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G is a **vertex minor** of H if G may be obtained from H by a sequence of local / loop complementations and deleting vertices.

Vertex minors 2.

“Vertex minors and 3-minors are equivalent”.

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Proposition

- If G is a vertex minor of H , then $D(G)$ is a twisted dual of a 3-minor of $D(H)$.
- If D_1 is a 3-minor of a binary Δ -matroid D_2 , then there are graphs G_1 and G_2 with $D(G_i)$ a twisted dual of D_i and G_1 a vertex minor of G_2 .

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Up to partial duals there are 5 excluded minors for the class of binary Δ -matroids within the class of Δ -matroids.

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Corollary (Bonin, Chun, N)

A vf-safe Δ -matroid is binary if and only if it has no 3-minor isomorphic to a twisted dual of

$$B = (\{a, b, c\}, \{\emptyset, \{a, b\}, \{a, c\}, \{b, c\}, \{a, b, c\}\}).$$

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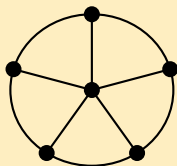
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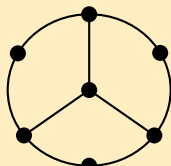
Ribbon graphs

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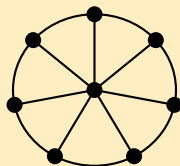
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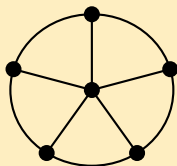


G_3

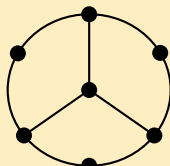
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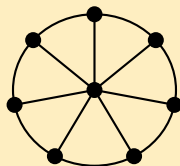
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A set system is a ribbon graphic Δ -matroid if and only if it has no 3-minor isomorphic to a twisted dual of S_3 , B_1 , $D(G_1)$, $D(G_2)$ or $D(G_3)$.