

Stochastic differential equations with singular perturbations

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Liéanard Oscillator

We consider the Liéanard Oscillator driven by random force given by the second order stochastic differential equation

$$\varepsilon \ddot{z}_t + \dot{z}_t - h(z_t) = \delta \dot{w}_t,$$

where $0 < \varepsilon < 1$, $\delta > 0$ are some parameters, \dot{w}_t is the white noise. This model arises in the description of the motion of a small particle in a viscous media. Setting $x_t^\varepsilon = z_t$ and $y_t^\varepsilon = \dot{z}_t$ we can represent this physical model in the stochastic calculus form

$$\left\{ \begin{array}{l} \frac{dx_t^\varepsilon}{dt} = y_t^\varepsilon, \quad x_0^\varepsilon = x^0; \\ \varepsilon dy_t^\varepsilon = -y_t^\varepsilon + h(x_t^\varepsilon) + \delta dw_t, \quad y_0^\varepsilon = y^0, \end{array} \right.$$

where $(w_t)_{0 \leq t \leq T}$ is the Wiener process.

Stochastic volatility models

Fouque, Papanicolaou and Sircar (2000) considered the financial markets (B, S) in which the bond $B = (B_t^\varepsilon)_{0 \leq t \leq T}$ and the stock $S = (S_t^\varepsilon)_{0 \leq t \leq T}$ are defined as

$$\left\{ \begin{array}{l} dB_t^\varepsilon = r(y_t^\varepsilon) B_t^\varepsilon dt, \quad B_0^\varepsilon = 1; \\ dS_t^\varepsilon = \mu(y_t^\varepsilon) S_t^\varepsilon dt + \sigma(y_t^\varepsilon) S_t^\varepsilon dw_t^s, \quad S_0^\varepsilon = S^0; \\ \varepsilon dy_t^\varepsilon = F(y_t^\varepsilon) dt + \beta \sqrt{\varepsilon} G(y_t^\varepsilon) dw_t^y, \quad y_0^\varepsilon = y^0, \end{array} \right.$$

where the market coefficients $r(\cdot)$, $\mu(\cdot)$, $\sigma(\cdot)$ are some functions, $(w_t^s)_{0 \leq t \leq T}$ and $(w_t^y)_{0 \leq t \leq T}$ are two Wiener processes, $F(\cdot)$ and $G(\cdot)$ satisfy some conditions for which one can study the behavior of the process $(y_t^\varepsilon)_{0 \leq t \leq T}$.

Singular perturbations for ODE

The system

$$\left\{ \begin{array}{l} \frac{dx_t^\varepsilon}{dt} = f(t, x_t^\varepsilon, y_t^\varepsilon), \quad x_0^\varepsilon = x^0; \\ \varepsilon \frac{dy_t^\varepsilon}{dt} = F(t, x_t^\varepsilon, y_t^\varepsilon), \quad y_0^\varepsilon = y^0. \end{array} \right.$$

The "slow" variable $x_t^\varepsilon \in \mathbb{R}^k$ and the "fast" variable $y_t^\varepsilon \in \mathbb{R}^n$, $0 < \varepsilon < 1$ is a small parameter.

The problem is to study the limit behavior for the solutions $(x_t^\varepsilon)_{0 \leq t \leq T}$ and $(y_t^\varepsilon)_{0 \leq t \leq T}$ when $\varepsilon \rightarrow 0$?

Limit form

We define now the following system

$$\frac{dx_t}{dt} = f(t, x_t, \varphi(t, x_t)), \quad x_0 = x^0,$$

where the $[0, T] \times \mathbb{R}^k \rightarrow \mathbb{R}^n$ function φ is the stable root

$$F(t, x, \varphi(t, x)) = 0.$$

Theorem (Tikhonov, 1952)

$$\lim_{\varepsilon \rightarrow 0} \sup_{0 \leq t \leq T} |x_t^\varepsilon - x_t| = 0 \quad \text{and} \quad \lim_{\varepsilon \rightarrow 0} \sup_{t_0 \leq t \leq T} |y_t^\varepsilon - \varphi(t, x_t)| = 0$$

for any fixed $0 < t_0 < T$.

Stochastic systems

The system

$$\left\{ \begin{array}{l} dx_t^\varepsilon = f(t, x_t^\varepsilon, y_t^\varepsilon)dt + g(t, x_t^\varepsilon, y_t^\varepsilon) dw_t^x, \quad x_0^\varepsilon = x^0; \\ \varepsilon dy_t^\varepsilon = F(t, x_t^\varepsilon, y_t^\varepsilon)dt + \beta\sqrt{\varepsilon} G(t, x_t^\varepsilon, y_t^\varepsilon)dw_t^y, \quad y_0^\varepsilon = y^0, \end{array} \right.$$

where $\beta = \beta_\varepsilon = o(1/|\ln \varepsilon|)$ as $\varepsilon \rightarrow 0$.

The coefficients satisfy some technical conditions under which this system has an unique strong solution for any $\varepsilon > 0$.

The problem is to study the asymptotic behavior of the solution when $\varepsilon \rightarrow 0$.

Limit form

To describe the limit form for the slow variables we set

$$dx_t = f(t, x_t, \varphi(t, x_t))dt + g(t, x_t, \varphi(t, x_t))dw_t^x, \quad x_0 = x^0.$$

Theorem (Kabanov and Pergamenchtchikov, 1990)

$$\mathbf{P} - \lim_{\varepsilon \rightarrow 0} \sup_{0 \leq t \leq T} |x_t^\varepsilon - x_t| = 0 \quad \text{and} \quad \mathbf{P} - \lim_{\varepsilon \rightarrow 0} \sup_{t_0 \leq t \leq T} |y_t^\varepsilon - \varphi(t, x_t)| = 0$$

for any fixed $0 < t_0 < T$.

Fast processes

We consider the fast process

$$\varepsilon dy_t^\varepsilon = F(y_t^\varepsilon)dt + \beta\sqrt{\varepsilon}G(y_t^\varepsilon)dw_t, \quad y_0^\varepsilon = y^0.$$

Main condition:

There exists a stable root φ_∞ of the equation $F(y) = 0$, i.e. such that the continuous derivative matrix $F'(\cdot)$ exists and the real parts of all eigenvalues $A = F'(\varphi_\infty)$ are strictly negative

$$\mathbf{P} - \lim_{\varepsilon \rightarrow 0} \sup_{t_0 \leq t \leq T} |y_t^\varepsilon - \varphi_\infty| = 0$$

for any fixed $0 < t_0 < T$.

Boundary layer

To study the correction we need to consider the following system

$$\frac{d\tilde{y}_t}{dt} = F(\tilde{y}_t), \quad \tilde{y}_0 = y^0.$$

Vasil'eva and Butusov (1973)

$$\tilde{y}_t = \varphi_\infty + \Pi(t)$$

the boundary layer function $\Pi(\cdot)$ is such that $\Pi(0) = y^0 - \varphi_\infty$ and for some positive constants $\mathbf{c} > 0$ and $\gamma > 0$

$$|\Pi(t)| \leq \mathbf{c} e^{-\gamma t}$$

for any $t \geq 0$.

First order correction

In the neighborhood of zero:

$$y_t^\varepsilon = \tilde{y}_r + \beta \tilde{\eta}_r + \beta \tilde{\Delta}_t^\varepsilon, \quad r = t/\varepsilon,$$

where

$$d\tilde{\eta}_s = F'(\tilde{y}_s)\tilde{\eta}_s ds + G(\tilde{y}_s)d\tilde{w}_s, \quad \tilde{\eta}_0 = 0$$

and

$$\tilde{w}_s = \frac{1}{\sqrt{\varepsilon}} w_{s/\varepsilon}.$$

The rest term

$$\mathbf{P} - \lim_{\varepsilon \rightarrow 0} \max_{0 \leq t \leq T} |\tilde{\Delta}_t^\varepsilon| = 0.$$

First order correction

In the outside of any neighborhood of zero:

$$y_t^\varepsilon = \varphi_\infty + \beta \eta_r + \beta \Delta_t^\varepsilon, \quad r = t/\varepsilon,$$

where

$$d\eta_s = A\eta_s ds + B d\tilde{w}_s, \quad \eta_0 = 0$$

$A = F'(\varphi_\infty)$, $B = G(\varphi_\infty)$ and the rest term

$$\mathbf{P} - \lim_{\varepsilon \rightarrow 0} \max_{t_0 \leq t \leq T} |\Delta_t^\varepsilon| = 0$$

for any fixed $0 < t_0 < T$.

Uniform metric

To describe the large deviation in the uniform metric we need to introduce the following $\mathcal{C}(\mathbb{R}_+) \rightarrow \mathbb{R}_+$ functional. For any $y \in \mathcal{C}^1(\mathbb{R}_+)$ this functional is defined as

$$S(y) := \frac{1}{2} \int_0^\infty |\Sigma^{-1/2}(y_s) (\dot{y}_s - F(y_s))|^2 ds,$$

where $\Sigma(y) = G(y)G'(y)$. Moreover, we set $S(y) = +\infty$ for $y \notin \mathcal{C}^1(\mathbb{R}_+)$.

This is the well-known Freidlin - Wentzell functional on the interval $[0, +\infty]$.

Uniform metric

We remind that for the process $\tilde{y}_r^\varepsilon = y_{r\varepsilon}^\varepsilon$

$$d\tilde{y}_r^\varepsilon = F(\tilde{y}_r^\varepsilon)dr + \beta G(\tilde{y}_r^\varepsilon)d\tilde{w}_r, \quad \tilde{w}_r = \frac{1}{\sqrt{\varepsilon}} w_{r/\varepsilon}$$

and $y_0^\varepsilon = y^0$.

In this case for $0 \leq r \leq T/\varepsilon$

$$\tilde{y}_r^\varepsilon = \tilde{y}_r + \beta\tilde{\eta}_r + \dots$$

where

$$\frac{d\tilde{y}_r}{dr} = F(\tilde{y}_r), \quad \tilde{y}_0 = y^0.$$

Uniform metric

Theorem

For any $\nu > 0$

$$\lim_{\varepsilon \rightarrow 0} \beta^2 \ln \mathbf{P} \left(\max_{0 \leq r \leq T/\varepsilon} |\tilde{y}_r^\varepsilon - \tilde{y}_r| > \nu \right) = - \inf_{y \in \mathbf{B}(\nu)} S(y),$$

where

$$\mathbf{B}(\nu) = \left\{ y \in \mathbf{C}(\mathbb{R}_+) : \sup_{r \geq 0} |y_r - \tilde{y}_r| > \nu, y_0 = y^0 \right\}$$

Deviation in the metric $L_2[0, T]$

To describe the deviation in the integral metric we need to define $C[0, T] \rightarrow \mathbb{R}_+$ as

$$\check{S}_T(y) := \frac{1}{2} \int_0^T |\Sigma^{-1/2}(y_t) F(y_t)|^2 dt,$$

where $\Sigma(y) = G(y)G'(y)$. Remind that the usually for regular perturbations Freidlin - Wentzell functional is defined as

$$S_T(y) := \frac{1}{2} \int_0^T |\Sigma^{-1/2}(y_t) (\dot{y}_t - F(y_t))|^2 dt.$$

Deviation in the metric $\mathbf{L}_2[0, T]$

Theorem

For any $\nu > 0$

$$\lim_{\varepsilon \rightarrow 0} \beta^2 \varepsilon \ln \mathbf{P} \left(\int_0^T |y_t^\varepsilon - \varphi_\infty|^2 dt > \nu \right) = - \inf_{y \in \check{\mathbf{B}}(\nu)} \check{S}_T(y),$$

where

$$\check{\mathbf{B}}(\nu) = \left\{ y \in \mathbf{C}[0, T] : \int_0^T |y_t - \varphi_\infty|^2 dt > \nu \right\}.$$

Applications PDEs

Let us consider the following Cauchy problem:

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} v^\varepsilon(t, x) = \frac{\beta^2}{\varepsilon} G^2(x) \frac{\partial^2}{(\partial x)^2} v^\varepsilon(t, x) + \frac{1}{\varepsilon} F(x) \frac{\partial}{\partial x} v^\varepsilon(t, x) \\ \quad + r(x) v^\varepsilon(t, x) + h(x); \\ v^\varepsilon(0, x) = \mathbf{b}(x), \quad x \in \mathbb{R}. \end{array} \right.$$

The limit equation for $t > 0$

$$\frac{\partial}{\partial x} v(t, x) = 0.$$

Applications PDEs

Using the "fast" process

$$\varepsilon dy_t^{x,\varepsilon} = F(y_t^{x,\varepsilon})dt + \beta\sqrt{\varepsilon}G(y_t^{x,\varepsilon})dw_t, \quad y_0^{x,\varepsilon} = x,$$

we can represent the PDE solution as

$$v^\varepsilon(t, x) = \mathbf{E} \mathbf{b}(y_t^{x,\varepsilon}) e^{\int_0^t r(y_u^{x,\varepsilon})du} + \mathbf{E} \int_0^t h(y_u^{x,\varepsilon}) e^{\int_0^u r(y_v^{x,\varepsilon})dv} du.$$

If the equation $F(x) = 0$ has unique stable root φ_∞ then for any $t > 0$ and any $x \in \mathbb{R}$

$$\lim_{\varepsilon \rightarrow 0} v^\varepsilon(t, x) = \mathbf{b}_\infty e^{r_\infty t} + h_\infty \frac{e^{r_\infty t} - 1}{r_\infty},$$

where $\mathbf{b}_\infty = \mathbf{b}(\varphi_\infty)$, $r_\infty = r(\varphi_\infty)$ and $h_\infty = h(\varphi_\infty)$.

Applications PDEs

Let us consider now the following problem:

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} v^\varepsilon(t, z) = \mathcal{L}^\varepsilon v^\varepsilon(t, z); \\ v^\varepsilon(0, z) = \mathbf{b}(z), \end{array} \right.$$

where $z = (x, y) \in \mathbb{R}^2$ and

$$\begin{aligned} \mathcal{L}^\varepsilon := & g^2(t, z) \frac{\partial^2}{\partial x^2} + \frac{\beta^2}{\varepsilon} G^2(t, z) \frac{\partial^2}{\partial y^2} \\ & + f(t, z) \frac{\partial}{\partial x} + \frac{1}{\varepsilon} F(t, z) \frac{\partial}{\partial y}. \end{aligned}$$

Applications PDEs

By the probability representation we can write that

$$v^\varepsilon(t, z) = v^\varepsilon(t, x, y) = \mathbf{E} \mathbf{b}(X_t^{x,\varepsilon}, Y_t^{y,\varepsilon}),$$

where

$$\left\{ \begin{array}{l} dX_t^\varepsilon = f(t, X_t^{x,\varepsilon}, Y_t^{y,\varepsilon})dt + g(t, X_t^{x,\varepsilon}, Y_t^{y,\varepsilon})dw_t^x, \quad X_0^{x,\varepsilon} = x; \\ \varepsilon dY_t^\varepsilon = F(t, X_t^{x,\varepsilon}, Y_t^{y,\varepsilon})dt + \beta\sqrt{\varepsilon}G(t, X_t^{x,\varepsilon}, Y_t^{y,\varepsilon})dw_t^y, \quad Y_0^{y,\varepsilon} = y. \end{array} \right.$$

Applications PDEs

The stochastic Tikhonov theorem implies that

$$\lim_{\varepsilon \rightarrow 0} v^\varepsilon(t, x, y) = v_0(t, x),$$

where

$$v_0(t, x) = \mathbf{E} \mathbf{b}(t, X_t^x, \varphi(t, X_t^x))$$

and

$$dX_t^x = f(t, X_t^x, \varphi(t, X_t^x))dt + g(t, X_t^x, \varphi(t, X_t^x))dw_t^x, \quad X_0^x = x.$$

Applications PDEs

Using the probability representation we obtain that

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} v_0(t, x) = g^2(t, \varphi(t, x)) \frac{\partial^2}{\partial x^2} v_0(t, x) + f(t, \varphi(t, x)) \frac{\partial}{\partial x} v_0(t, x); \\ v_0(0, x) = \mathbf{b}(0, x, \varphi(0, x)). \end{array} \right.$$

Example. Let consider the stochastic volatility model, i.e. $B \equiv 1$ and

$$\left\{ \begin{array}{l} dS_t^\varepsilon = \sigma(y_t^\varepsilon) S_t^\varepsilon dw_t^s, \quad S_0^\varepsilon = S^0; \\ \varepsilon dy_t^\varepsilon = F(y_t^\varepsilon) dt + \beta \sqrt{\varepsilon} G(y_t^\varepsilon) dw_t^y, \quad y_0^\varepsilon = y^0 \end{array} \right.$$

Stable root: $F(\varphi_\infty) = 0$.

Pricing problem

Consider now the european option with the payoff h

$$\frac{\partial}{\partial t} v_\varepsilon(t, x, y) + \mathcal{L}^\varepsilon v_\varepsilon(t, x, y) = 0, \quad v_\varepsilon(T, x) = h(x)$$

and

$$\mathcal{L}^\varepsilon := \sigma^2(y) \frac{\partial^2}{\partial x^2} + \frac{1}{\varepsilon} F(y) \frac{\partial}{\partial y} + \frac{\beta^2}{\varepsilon} G^2(y) \frac{\partial^2}{\partial y^2}$$

If we change the variable variable $s = T - t$ we obtain the initial Cauchy problem and by making use the previous convergence we obtain that

$$\lim_{\varepsilon \rightarrow 0} v_\varepsilon(t, x, y) = v_0(t, x),$$

where $v_0(t, x)$ is the option price for the Black-Scholes market with the volatility $\sigma(\varphi_\infty)$.

Filtering of Nearly Observed processes

Let us consider the model described by two processes $x_t \in \mathbb{R}^n$ (unobservable signal) and $y_t^\varepsilon \in \mathbb{R}^n$ (observations), both given by

$$\begin{cases} dx_t = f_t dt + g dw_t^x, & x_0^\varepsilon = x^0; \\ dy_t^\varepsilon = x_t dt + \varepsilon dw_t^y, & y_0^\varepsilon = y^0, \end{cases}$$

where $w_t^x \in \mathbb{R}^m$ and $w_t^y \in \mathbb{R}^n$ are independent Wiener processes and g is $n \times m$ nonrandom known. We use the filter \hat{x}^ε defined as

$$d\hat{x}_t^\varepsilon = \hat{f}_t^\varepsilon dt - \varepsilon^{-1} A (dy_t^\varepsilon - \hat{x}_t^\varepsilon dt),$$

where \hat{f}_t^ε is measurable with respect to $\sigma\{y_u, 0 \leq u \leq t\}$ and A is symmetric negative defined matrix. For example, we can take $A = -\kappa I_n$ (I_n is the identity matrix of order n) or $A = -(gg')^{1/2}$.

Filtering accuracy

We study the deviation $\Delta_t^\varepsilon = \widehat{x}_t^\varepsilon - x_t$. We obtain that

$$d\Delta_t^\varepsilon = \varepsilon^{-1} A \Delta_t^\varepsilon dt + (\widehat{f}_t^\varepsilon - f_t) dt + G d\tilde{w}_t,$$

where the matrix $G = (AA' + gg')^{1/2}$. Assume that the function f_t is linear, i.e.

$$f_t = b_t + D_t x_t,$$

where b_t is unknown and D_t is known. In this case we chose $\widehat{f}_t^\varepsilon = D_t \widehat{x}_t^\varepsilon$ and, therefore,

$$d\widehat{x}_t^\varepsilon = D_t \widehat{x}_t^\varepsilon dt - \varepsilon^{-1} A (dy_t^\varepsilon - \widehat{x}_t^\varepsilon dt) .$$

Filtering accuracy

Therefore, in the linear case

$$d\Delta_t^\varepsilon = \varepsilon^{-1}A\Delta_t^\varepsilon dt + (D_t\Delta_t^\varepsilon - b_t)dt + Gd\tilde{w}_t.$$

Asymptotically, as $\varepsilon \rightarrow 0$, the accuracy $\Delta_t^\varepsilon \approx \eta_t^\varepsilon$, where

$$d\eta_t^\varepsilon = \varepsilon^{-1}A\eta_t^\varepsilon dt + Gd\tilde{w}_t.$$

In this case $\varphi_\infty = 0$, $\beta = \sqrt{\varepsilon}$ and

$$\check{S}_T(y) = \frac{1}{2} \int_0^T y_t' A (A^2 + gg')^{-1} A y_t dt.$$

Filtering accuracy

For any $\nu > 0$

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^2 \ln \mathbf{P} \left(\int_0^T |\Delta_t^\varepsilon|^2 dt > \nu \right) = - \inf_{y \in B(\eta)} \check{S}_T(y)$$

where

$$\check{B}(\nu) = \left\{ y \in \mathbf{C}[0, T] : \int_0^T |y_t|^2 dt > \nu \right\}.$$

In this case

$$\inf_{y \in B(\eta)} \check{S}_T(y) = \frac{\nu}{2} \lambda_{\min}(A(A^2 + gg')^{-1}A),$$

and $\lambda_{\min}(B)$ is minimal eigenvalue of the matrix B .

Filtering accuracy

For any $\nu > 0$

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^2 \ln \mathbf{P} \left(\int_0^T |\Delta_t^\varepsilon|^2 dt > \nu \right) = -\frac{\nu}{2} \lambda_{\min}(A(A^2 + gg')^{-1}A).$$

Note that if $n = m = 1$ and $A = -\kappa$ we obtain that for any $\nu > 0$

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^2 \ln \mathbf{P} \left(\int_0^T |\Delta_t^\varepsilon|^2 dt > \nu \right) = -\frac{\kappa^2 \nu}{2(\kappa^2 + g^2)}.$$

Signal estimation

If in the model $g = 0$ we obtain that for any $\nu > 0$

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^2 \sup_{x \in \Theta} \ln \mathbf{P} \left(\int_0^T |\hat{x}_t^\varepsilon - x_t|^2 dt > \nu \right) = -\frac{\nu}{2}.$$

This is the best estimator in the sense that for any estimator $(\tilde{x}_t)_{0 \leq t \leq T}$

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^2 \sup_{x \in \Theta} \ln \mathbf{P} \left(\int_0^T |\tilde{x}_t^\varepsilon - x_t|^2 dt > \nu \right) \geq -\frac{\nu}{2}.$$

Conclusion

- The stochastic version of the Tikhonov theorem is shown. The boundary layer and the asymptotic expansions are studied.
- The large deviations methods for the fast variables in the uniform metric and in the metric $L_2[0, T]$ are developed. The rate functions are found.
- Applications of the stochastic singular perturbation method: statistic of stochastic processes, financial markets, optimal control, PDE analysis.

Thanks

**THANK YOU VERY MUCH
FOR YOUR ATTENTION
HAPPY BIRTHDAY YOURI !!!**