

Set-valued risk measures of non-convex portfolios

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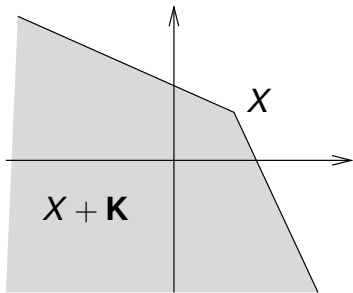
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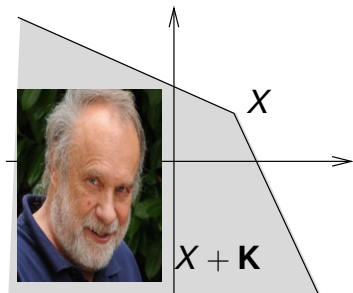
Kabanov's exchange cone model

- ▶ X is p -integrable random vector in \mathbb{R}^d (gains on d assets/currencies).
- ▶ \mathbf{K} is a random cone (e.g. generated by bid-ask exchange rates for currencies).
- ▶ \mathbf{K} is the family of portfolios available at price zero.
- ▶ \mathbf{K} describes transaction rules at the time when the gain X is assessed.

- ▶ Aim: measure the **risk** of X taking \mathbf{K} into account.



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Vector-valued risk

- ▶ Tempting to describe the risk of $X \in \mathbb{R}^d$ by a **vector** $r(X) \in \mathbb{R}^d$ (taking into account the cone K).
- ▶ Natural assumptions:
 - ▶ $r(X + a) = r(X) - a$,
 - ▶ if $X \leq Y$ coordinatewisely, then $r(X) \geq r(Y)$,
 - ▶ $r(cX) = cr(X)$,
 - ▶ $r(X + Y) \leq r(X) + r(Y)$ coordinatewisely.

Theorem (I.Cascos, IM, 2007)

In this case

$$r(X) = (r_1(X_1), \dots, r_d(X_d)),$$

that is, all vector-valued coherent risk measures marginalise.

Set-valued risk

- ▶ Capital $a \in \mathbb{R}^d$ that makes $X + a$ acceptable can be chosen in many **incomparable** ways.
- ▶ So the risk measure is a **set** in \mathbb{R}^d .
- ▶ The possible values of risk measures are **upper** sets, i.e. sets F such that with each x it contains all $y \geq x$ (coordinatewisely).
- ▶ Position is acceptable if the risk measure contains the origin.
- ▶ Larger set means lower risk.

Previous work

- ▶ Hamel & Heyde (2010) and Hamel et al. (2011, 2013) derived dual representations for risk measures of $X + \mathbf{K}$.
- ▶ Ben Tahar & Lepinette (2014) and Feinstein & Rudloff (2012,2013) worked out the dynamical setting.
- ▶ Molchanov and Cascos (2016): primal representation in terms of selections.
- ▶ All previous work in the **convex** setting.

Set-valued portfolio

- ▶ Portfolio \mathbf{X} is a random convex closed set such that $\mathbf{X} = \mathbf{X} + \mathbb{R}_-^d$ (lower set).
- ▶ Risk $R(\mathbf{X})$ is an upper set; utility is a lower set.
- ▶ \mathbf{X} is not necessarily convex.

Why set-valued portfolios?

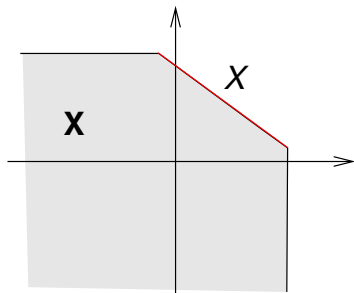
- ▶ \mathbf{X} incorporates rather general liquidity restrictions.
- ▶ In the simplest case, $\mathbf{X} = X + \mathbf{K}$ for a cone \mathbf{K} (Kabanov's model).
- ▶ In the dynamical setting the value of risk measure is a random set and it is used as the argument of another risk measure
 - ▶ numerical case $r_t(-r_s(X))$
 - ▶ set-valued setting $R_t(-R_s(\mathbf{X}))$, where

$$-F = \{-x : x \in F\}$$

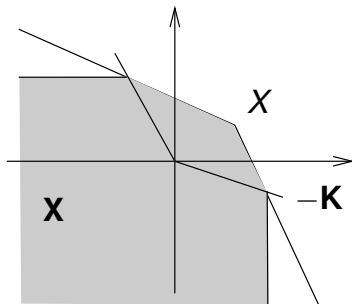
denotes the central symmetric set to $F \subset \mathbb{R}^d$.

Beyond Kabanov's model

1:1 transactions up to a certain amount

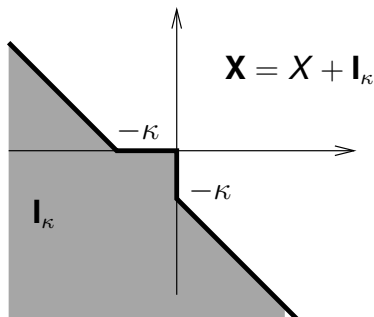


Only transactions that lead to solvent positions and/or disposal of assets are allowed

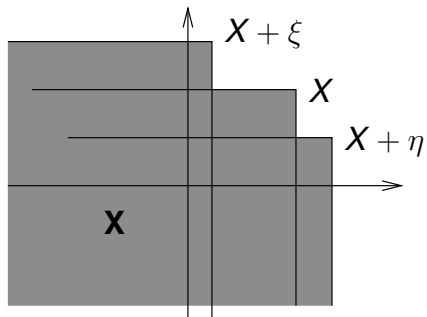


Non-convex portfolio: fixed transaction costs

- ▶ In case of each transaction, **fixed cost** κ is incurred.



Finite set of possible transactions



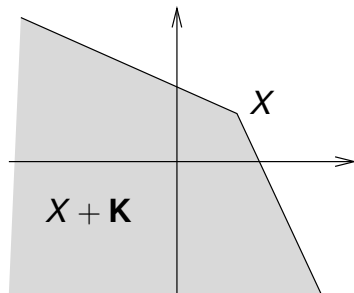
Selections and acceptability

- ▶ A random vector $\xi \in \mathbb{R}^d$ is called a **selection** of \mathbf{X} if $\xi \in \mathbf{X}$ a.s.
Assume that \mathbf{X} contains at least one p -integrable selection, i.e. the set $L^p(\mathbf{X})$ is not empty, $p \in [1, \infty]$.
- ▶ Consider d -tuple $\mathbf{r} = (r_1, \dots, r_d)$ of univariate **monetary** L^p -risk measures.
- ▶ Random set \mathbf{X} is **acceptable** if it possesses at least one acceptable selection ξ , meaning that

$$\mathbf{r}(\xi) = (r_1(\xi_1), \dots, r_d(\xi_d)) \leq \mathbf{0},$$

i.e. all individual coordinates of ξ are acceptable.

Example: cones



- ▶ $\mathbf{X} = X + \mathbf{K}$ has an acceptable selections exactly if there exists a **transfer** (selection) $\eta \in \mathbf{K}$ such that $\xi = X + \eta$ is acceptable.

Equivalent definition

- ▶ Let $\mathcal{A} \subset L^p(\mathbb{R}^d)$ be a family of acceptable random vectors in \mathbb{R}^d .
- ▶ Then portfolio \mathbf{X} is acceptable iff $L^0(\mathbf{X}, \mathfrak{F}) \cap \mathcal{A} \neq \emptyset$, equivalently,

$$L^0(-\mathbf{X}, \mathfrak{F}) + \mathcal{A} \ni 0.$$

Selection risk measure

- ▶ The **selection risk measure** $R(\mathbf{X})$ is the topological closure of the set

$$\{a \in \mathbb{R}^d : \mathbf{X} + a \text{ is acceptable}\}.$$

- ▶ Equivalently,

$$R(\mathbf{X}) = \text{cl} \bigcup_{\xi \in L^p(\mathbf{X})} \left(\mathbf{r}(\xi) + \mathbb{R}_+^d \right).$$

- ▶ This is the **primal representation** of the risk measure.
- ▶ In other words, the risk is the closed union of risks determined by singletons chosen from \mathbf{X} .

Duality-based approach

- ▶ Conical setting $\mathbf{X} = X + \mathbf{K}$: Hamel & Heyde (2010) and Hamel et al. (2011, 2013).
- ▶ Convex \mathbf{X} is the union of singletons (primal) and the intersection of half-spaces (dual).
- ▶ Portfolio \mathbf{X} is acceptable if all **half-spaces** containing \mathbf{X} are acceptable, that is,

$$\{\mathbf{x} \in \mathbb{R}^d : \langle \mathbf{x}, u \rangle \leq h(\mathbf{X}, u)\}$$

is acceptable for all (possibly random) u .

- ▶ The acceptability of such half-spaces is derived from the **support function** $h(\mathbf{X}, u)$.
- ▶ However, such approach converts \mathbf{X} to its convex hull.

Fixed points

- ▶ If all components of \mathbf{r} are essinf, that is, $\mathbf{r}(\xi) = \text{essinf}\xi$, then

$$\mathbf{R}(\mathbf{X}) = -F_{\mathbf{X}},$$

where

$$F_{\mathbf{X}} = \{x : \mathbf{P}\{x \in \mathbf{X}\} = 1\}$$

denotes the set of **fixed points**.

Proposition

For any selection risk measure, $-F_{\mathbf{X}} \subseteq \mathbf{R}(\mathbf{X})$.

Selection (Aumann) expectation

- ▶ The closure of the set of expectations of all integrable selections

$$\mathbf{EX} = \text{cl}\{\mathbf{E}\xi : \xi \in L^1(\mathbf{X})\}$$

is called the **selection (Aumann) expectation** of \mathbf{X} .

- ▶ If $r(\xi) = -\mathbf{E}\xi$, then

$$\mathbf{R}(\mathbf{X}) = -\mathbf{EX}$$

is a selection risk measure.

- ▶ It is **linear**

$$\mathbf{E}(\mathbf{X} + \mathbf{Y}) = \text{cl}(\mathbf{EX} + \mathbf{EY})$$

and \mathbf{EX} is always **convex** on non-atomic probability spaces, no matter if \mathbf{X} is convex or not.

- ▶ The primal and dual approaches yield the same set.

Non-linear functions constructed from expectation

- ▶ If $\mathbf{X}_1, \dots, \mathbf{X}_n$ are independent copies of \mathbf{X} , let

$$R_{\cap}(\mathbf{X}) = -\mathbf{E}(\mathbf{X}_1 \cap \dots \cap \mathbf{X}_n).$$

- ▶ It satisfies the property

$$R_{\cap}(\mathbf{X} + \mathbf{Y}) \supseteq R_{\cap}(\mathbf{X}) + R_{\cap}(\mathbf{Y}),$$

however, $0 \in R_{\cap}(\mathbf{X})$ does not imply the existence of an acceptable selection with respect to the underlying risk measure (expected minimum).

- ▶ The same applies to

$$R_{\mathcal{Z}}(\mathbf{X}) = \bigcap_{\zeta \in \mathcal{Z}} \mathbf{E}(-\zeta \mathbf{X}),$$

where \mathcal{Z} is a family of q -integrable non-negative random variables with expectation one.

Selection risk measure (reminder)

- ▶ The **selection risk measure** $R(\mathbf{X})$ is the topological closure of the set

$$\{a \in \mathbb{R}^d : \mathbf{X} + a \text{ is acceptable}\}.$$

- ▶ Equivalently,

$$R(\mathbf{X}) = \text{cl} \bigcup_{\xi \in L^p(\mathbf{X})} \left(\mathbf{r}(\xi) + \mathbb{R}_+^d \right).$$

Main properties

Theorem

The selection risk measure (in the non-convex setting) satisfies the following conditions

1. $R(\mathbf{X} + a) = R(\mathbf{X}) - a$ for all $a \in \mathbb{R}^d$ (cash invariance).
2. If $\mathbf{X} \subset \mathbf{Y}$ a.s., then $R(\mathbf{X}) \subset R(\mathbf{Y})$ (monotonicity).
3. If r is homogeneous, then $R(c\mathbf{X}) = cR(\mathbf{X})$ for all $c > 0$ (homogeneity).
4. If r is convex, then

$$R(\lambda\mathbf{X} + (1 - \lambda)\mathbf{Y}) \supseteq \lambda R(\mathbf{X}) + (1 - \lambda)R(\mathbf{Y})$$

(superadditivity for inclusion, larger set means lower risk).

Univariate case

- ▶ Consider $X \in L^p(\mathbb{R})$, and let $\mathbf{X} = (-\infty, X]$.
- ▶ All selections $\xi \in \mathbf{X}$ are dominated by X .
- ▶ Then the selection risk measure of \mathbf{X} is

$$R(\mathbf{X}) = [r(X), \infty).$$

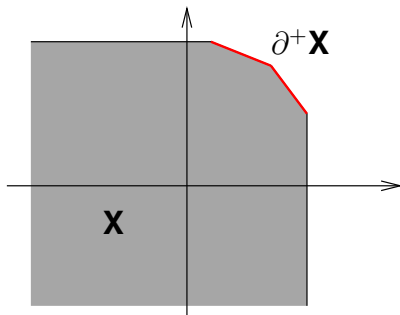
Finding acceptable selections

- ▶ $\partial^+ \mathbf{X}$ is the set of **Pareto optimal** points of \mathbf{X} .
- ▶ \mathbf{X} is called **quasi-bounded** if

$$\|\partial^+ \mathbf{X}\| = \sup\{\|x\| : x \in \partial^+ \mathbf{X}\}$$

is finite.

- ▶ Selections determining the risk should belong to $\text{cl } \partial^+ \mathbf{X}$.



Convexity: expectation

- ▶ $R(\mathbf{X}) = \mathbf{E}(-\mathbf{X})$ is a selection risk measure.
- ▶ It takes **convex** values if the underlying probability space is nonatomic, and then $R(\mathbf{X}) = R(\text{conv } \mathbf{X})$.
- ▶ This follows from **Lyapunov's theorem** on ranges of vector-valued measures.
- ▶ But this theorem generally does not hold for measures with values in infinite-dimensional Banach spaces.

Convexity: example

Example

If $\mathbf{X} = \{\xi, \eta\} + \mathbb{R}_-^d$, then $R(\mathbf{X})$ is convex if,

for each $t \in (0, 1)$, there exists $A \in \mathfrak{F}$ such that

$$t\mathbf{r}(\xi) + (1 - t)\mathbf{r}(\eta) \geq \mathbf{r}(\xi\mathbf{1}_A + \eta\mathbf{1}_{A^c}).$$

Convexity: general

- ▶ Assume that

$$\mathbf{r}(\xi) = \sup_{\zeta \in L^q(\mathbb{R}_+^d), \mathbf{E}\zeta=1} \left(\mathbf{E}(-\zeta\xi) - \alpha(\zeta) \right), \quad \xi \in L^p(\mathbb{R}^d),$$

where $\alpha(\zeta) = (\alpha_1(\zeta_1), \dots, \alpha_d(\zeta_d))$ and $\alpha_j : L^q(\mathbb{R}_+) \mapsto (-\infty, \infty]$ are the penalty functions corresponding to the components of \mathbf{r} .

Theorem

*Assume that the probability space is non-atomic and the penalty function α has all infinite components unless ζ belongs to a **finite family**. Then $\mathbf{R}(\mathbf{X})$ is convex.*

Convexity: deterministic sets

- ▶ F is **r-convex** if $R(F) = -F$.
- ▶ This is the case if and only if, for any $x, x' \in F$ and $A \in \mathfrak{F}$, we have

$$\mathbf{r}(x\mathbf{1}_A + x'\mathbf{1}_{A^c}) \in -F.$$

- ▶ Intersection of **r-convex** sets is **r-convex**.
- ▶ Each lower closed set is convex with respect to the **essinf** risk measure.
- ▶ The set \mathbf{I}_κ (fixed transaction costs) is convex with respect to the **Average Value-at-Risk** at level $\alpha \leq 1/2$.

Law invariance

Theorem

Assume that the probability space is nonatomic and that \mathbf{r} is Lebesgue continuous, that is, it is continuous on a.s. convergent uniformly p -integrably bounded sequences of random vectors.

Then $R(\mathbf{X})$ is law invariant on portfolios, such that $\|\partial^+ \mathbf{X}\|$ is p -integrable.

- ▶ For **convex** \mathbf{X} and **coherent** \mathbf{r} , we always have law invariance, see Molchanov & Cascos (2016).

Law invariance: proof

- ▶ If \mathbf{X} and \mathbf{X}' share the same distribution, then $\text{cl } \partial^+ \mathbf{X}$ and $\text{cl } \partial^+ \mathbf{X}'$ are p -integrably bounded and share the same distribution.
- ▶ Let $x \in \mathbf{r}(\xi) + \mathbb{R}_+^d$ for $\xi \in L^p(\text{cl } \partial^+ \mathbf{X})$.
- ▶ Since the weak closures of $L^0(\text{cl } \partial^+ \mathbf{X})$ and $L^0(\text{cl } \partial^+ \mathbf{X}')$ coincide, there is a sequence $\eta_n \in L^p(\text{cl } \partial^+ \mathbf{X}')$ converging weakly to ξ . Then $\|\eta_n\| \leq \|\text{cl } \partial^+ \mathbf{X}'\|$, and the latter random variable is integrable.
- ▶ Thus, $\{\eta_n, n \geq 1\}$ is relatively compact in $L^1(\mathbb{R}^d)$. By passing to a subsequence, it is possible to assume that $\eta_{n_k} \rightarrow \xi$ almost surely.
- ▶ The Lebesgue continuity property yields that $\mathbf{r}(\eta_{n_k}) \rightarrow \mathbf{r}(\xi)$. Thus, $\mathbf{r}(\xi) \in \mathbf{R}(\text{cl } \partial^+ \mathbf{X}')$, since the latter set is closed. Finally, $x \in \mathbf{R}(\mathbf{X}')$ since the latter set is upper.

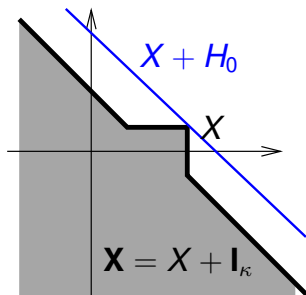
Fixed transaction costs: bounds

- ▶ Let $\mathbf{X} = X + \mathbf{I}_{\kappa}$, where $\mathbf{I}_{\kappa} = \mathbb{R}_-^d \cup H_{-\kappa}$, and

$$H_t = \{x \in \mathbb{R}^d : \sum_{i=1}^d x_i \leq t\}, \quad t \in \mathbb{R}.$$

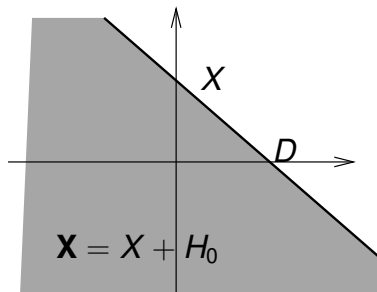
- ▶ Then

$$(\mathbf{r}(X) - \mathbf{I}_{\kappa}) \cup \mathbf{R}(X + H_{-\kappa}) \subset \mathbf{R}(X + \mathbf{I}_{\kappa}) \subset \mathbf{R}(X + H_0).$$



Selection risk of a half-space: coherent case

Let $D = X_1 + \dots + X_d$.



If \mathbf{r} is **coherent**, then $R(X + H_0) = H_{-r(D)}$.

Selection risk of a half-space

Let $D = X_1 + \dots + X_d$, and let $\mathbf{r} = (r_1, \dots, r_d)$.

Proposition

- i) If all components of \mathbf{r} are **identical convex** risk measures r , then $R(X + H_0) = -H_{-dr(D/d)}$.
- ii) If one of the components of \mathbf{r} is the **negative essential infimum** and all other are identical convex risk measures r , then $R(X + H_0) = -H_{-(d-1)r(\frac{D}{d-1})}$.
- iii) If one of components of \mathbf{r} is the **negative expectation** and all others are identical convex risk measures r such that $r(\xi) \geq -\mathbf{E}\xi$ for all $\xi \in L^1(\mathbb{R})$, then

$$R(X + H_0) = -H_{-\mathbf{E}D}.$$

Calculating the selection risk

- ▶ \mathbf{X} has too many selections.
- ▶ If $\mathbf{X} = X + F$ for p -integrable X and **deterministic** lower closed F , then

$$R(\mathbf{X}) \supseteq \mathbf{r}(X) + R(F)$$

assuming that \mathbf{r} is coherent.

Exact calculation: fixed transaction costs

- ▶ Let $\mathbf{X} = \mathbf{I}_\kappa$ (deterministic) in dimension 2, and let $\mathbf{r} = (r_1, r_2)$ have coherent components.
- ▶ Then the risk of \mathbf{I}_κ is determined by the set

$$B_{\mathbf{r}} = \{(r_1(\mathbf{1}_A), r_2(-\mathbf{1}_A)) : A \in \mathfrak{F}\},$$

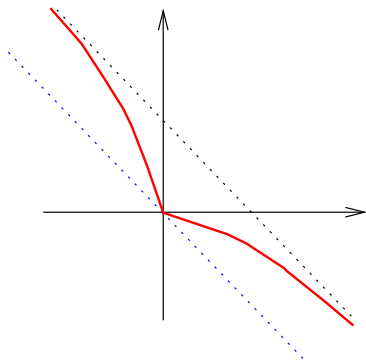
where $\mathbf{P}(A)$ is varying between 0 and 1.

- ▶ If \mathbf{r} is the Average Value-at-Risk at level $\alpha \leq 1/2$, then

$$R(\mathbf{I}_\kappa) = -\mathbf{I}_\kappa,$$

which is the set of fixed points.

Exact calculation: fixed transaction costs, $\alpha > 1/2$

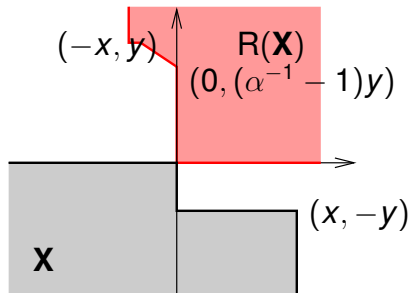


- ▶ The set $R(\mathbf{I}_\kappa)$ becomes $\text{conv}(-\mathbf{I}_\kappa) = \mathbf{E}(-\mathbf{I}_\kappa)$ if $\alpha = 1$.

Two admissible transactions

- ▶ Consider the set $\mathbf{X} = M + \mathbb{R}_-^2$, where $M = \{(0, 0), (x, -y)\}$ with $x, y > 0$.
- ▶ Let \mathbf{r} be the Average Value-at-Risk at level $\alpha > 1/2$.
- ▶ Consider selections $\xi = (x, y)\mathbf{1}_A$. Then

$$\mathbf{r}(\xi) = (xr(\mathbf{1}_A), yr(-\mathbf{1}_A)).$$



References

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