Learning Rough Volatility

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CIRM Luminy, 6th September 2018

Innovative Research in Mathematical Finance dedicated to the 70th birthday of Yuri Kabanov

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- Rough volatility models have been around since October 2014 (see the Rough Volatility website for a chronicle of developments)
- These models have repeatedly proven to be superior to standard models in many areas: in volatility forecasting, in option pricing, close fits to the implied vol surface, ...



- Rough volatility models have been around since October 2014 (see the Rough Volatility website for a chronicle of developments)
- These models have repeatedly proven to be superior to standard models in many areas: in volatility forecasting, in option pricing, close fits to the implied vol surface, ...
- ► Relaxing the assumption of independence of volatility increments was crucial for the superior performance of rough volatility models ⇒ but: several standard pricing methods no longer available & naive Monte Carlo methods slow
- Calibration time has been a bottleneck for rough volatility several advances have been made to speed up the calibration process [BLP '15, MP '17, HJM '17].

Today's talk:

Speedups for rough volatility models along two lines:

- 1. in pricing of vanilla options based on faster Monte Carlo approximations for a family of rough stochastic volatility models. [H-Jacquier-Muguruza '17])
- 2. in calibration by means of machine learning (ongoing with A. Sani, A. Muguruza and with M. Tomas).

Framework



$$\begin{split} \mathrm{d} X_t &= -\frac{1}{2} V_t \mathrm{d} t + \sqrt{V_t} \mathrm{d} W_t, \quad X_0 = 0, \\ V_t &= \Phi \left(\int_0^t g(t-s) \mathrm{d} Y_s \right), \quad V_0 > 0, \; \alpha \in (-1/2, 1/2), \\ dY_t &= b(Y_t) \mathrm{d} t + \sigma(Y_t) \mathrm{d} Z_t, \quad \mathrm{d} Z_t \mathrm{d} W_t = \rho \mathrm{d} t. \end{split}$$

where $\Phi \in C^1$, $g \in \mathcal{L}^{\alpha} := \left\{ u^{\alpha} L(u) : L \in \mathcal{C}_b^1([0, T]), \alpha \in \left(-\frac{1}{2}, \frac{1}{2}\right) \right\}$ and Y satisfies Yamada-Watanabe conditions for path-wise uniqueness.

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FCLT for Hölder cont. processes:



Generalised Fractional Operators \mathcal{G}^{lpha}

Definition

Let $g \in \mathcal{L}^{\alpha} := \left\{ u^{\alpha} L(u) : L \in \mathcal{C}^{1}_{b}([0, T]), \alpha \in \left(-\frac{1}{2}, \frac{1}{2}\right) \right\}$ and fix $\lambda \in (0, 1)$. The GFO for $f \in \mathcal{C}^{\lambda}([0, T])$ is

$$(\mathcal{G}^{lpha}f)(t):= \left\{ egin{array}{c} \int_{0}^{t}f(s)rac{\mathrm{d}}{\mathrm{d}t}g(t-s)\mathrm{d}s, & ext{for }lpha\in[0,1), \ rac{\mathrm{d}}{\mathrm{d}t}\int_{0}^{t}f(s)g(t-s)\mathrm{d}s, & ext{for }lpha\in(-\lambda,0). \end{array}
ight.$$

Remark: If $g(u) = u^{\alpha}$, then GFO=Riemann-Liouville fractional operators

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Theorem (rough Donsker theorem)

Consider the sequence $(W_n(t))_{n\geq 1}$ and W its weak limit in $(\mathcal{C}^{1/2}([0, T]), \|\cdot\|_{1/2})$. Then $(\mathcal{G}^{\alpha}W_n)_{n\geq 1}$ converges weakly to $\int_0^{\cdot} g(\cdot - s) dW_s$ in $(\mathcal{C}^{\alpha+1/2}([0, T]), \|\cdot\|_{\alpha+1/2})$ for $\alpha \in (-\frac{1}{2}, \frac{1}{2})$.



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FCLT for rough volatility models



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FCLT for rough volatility models Define recursively in time, for any $n \ge 1$, $t \in [0, T]$, $t_k = \frac{k}{N}$

$$X_n(t) := -\frac{1}{2} \frac{T}{n} \sum_{k=1}^{\lfloor nt \rfloor} \Phi\left(\left(\mathcal{G}^{\alpha} Y_n\right)(t_k)\right) + \sqrt{\frac{T}{\sigma n}} \sum_{k=1}^{\lfloor nt \rfloor} \sqrt{\Phi\left(\left(\mathcal{G}^{\alpha} Y_n\right)(t_k)\right)} \left(W_n(t_{k+1}) - W_n(t_k)\right)$$



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Theorem (rDonsker for rough volatility models)

 $(X_n)_{n\geq 1}$, converges weakly to X in $(\mathcal{C}^{1/2-}(\mathbb{T}), \|\cdot\|_{1/2-}),$

$$\begin{aligned} \mathrm{d}X_t &= -\frac{1}{2}V_t\mathrm{d}t + \sqrt{V_t}\mathrm{d}W_t, \quad X_0 = 0, \\ V_t &= \Phi\left(\int_0^t g(t-s)\mathrm{d}Y_s\right), \quad V_0 > 0, \; \alpha \in (-1/2, 1/2) \\ dY_t &= b(Y_t)\mathrm{d}t + \sigma(Y_t)\mathrm{d}Z_t, \quad \mathrm{d}Z_t\mathrm{d}W_t = \rho\mathrm{d}t. \end{aligned}$$

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FCLT for Hölder cont. processes:



Examples in this framework

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Rough Bergomi:

$$\begin{split} \mathrm{d} X_t &= -\frac{1}{2} V_t \mathrm{d} t + \sqrt{V_t} \mathrm{d} W_t, \qquad X_0 = 0 \\ V_t &= \xi_0(t) \mathcal{E} \left(2\nu C_H \int_0^t \frac{dZ_u}{(t-u)^{1/2-H}} \right), \quad \nu, \xi_0(\cdot) > 0 \\ dZ_t dW_t &= \rho dt, \qquad \rho \in (0,1) \end{split}$$

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Rough Heston:

$$dX_t = -\frac{1}{2}V_t dt + \sqrt{V_t} dW_t, \qquad X_0 = 0,$$

$$Y_t = \int_0^t \kappa(\theta - Y_s) dt + \int_0^t \xi \sqrt{Y_s} dZ_s \quad V_0, \kappa, \xi, \theta > 0, \ 2\kappa\theta > \xi^2$$

$$V_t = \eta + \int_0^t (t-s)^\alpha dY_s, \qquad \eta > 0, \ \alpha \in (-1/2, 1/2).$$

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Example: rough Bergomi smiles



Figure 1: Implied volatilities of rDonsker with left-point and variance matching evaluation and the Hybrid scheme with $5 \cdot 10^5$ simulations. Parameters: $\nu = 1, \rho = -0.7, \xi_0 = 0.04, n = 468$

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Example: rough Bergomi smiles



Figure 2: Parameters: $\nu = 1, \rho = -0.7, \xi_0 = 0.04$, n = 468 steps

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Conclusion



▶ rDonsker is 1.25× faster than Hybrid scheme (because we omit the Cholesky bit)



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- Part 2: in calibration by means of machine learning techniques (ongoing with A. Sani, A. Muguruza and with M. Tomas).

Part 2: Speed-ups on calibration

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Part 2: Speed-ups on calibration

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one step away from of-the-shelf optimizers to explore the parameter space more efficiently, limiting the number of function evaluations for calibration. Tested for variance options in a "weighted rough Bergomi" framework (De Marco, Guyon)

$$dS_t = -\frac{1}{2}V_t dt + \sqrt{V_t} dW_t \quad V_t = \xi_0(t) \left(\gamma \nu_t + (1-\gamma)\eta_t\right)$$
$$\nu_t = \mathcal{E}\left(\nu\sqrt{2H} \int_0^t (t-s)^{H-1/2} dZ_s\right) \quad \eta_t = \mathcal{E}\left(\eta\sqrt{2H} \int_0^t (t-s)^{H-1/2} dZ_s\right)$$

(w Amir Sani and Aitor Muguruza) and

approximation by neural networks (w Mehdi Thomas and Aitor Muguruza)

Optimizers to minimize nr. fn eval

- Limited-memory Bounded BroydenFletcherGoldfarbShanno (L-BFGS-B)
- Truncated Newton (TNC)
- Sequential Least-Squares Quadratic Programming (SLSQP)
- 2-stage Minimization

Stage 1: Classifier-Directed Global Minimizer (2-min Time Budget) Stage 2: Local Minimizer initialized with Stage 1 x_0 Imperial College

(Ongoing work) General setup: two parts of the network:

- 1. Generator: Input (parameters) Output (implied volatilities)
- 2. Calibrator: Input (implied volatilities) Output (*optimal* parameters).

Both feed-forward neural networks for the generator three hidden layers (1000-800-600)-nodes. Calibrator 1 layer on top.

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General setup: two parts of the network:

1 Generator (approximation of IV surfaces via NN)

In order to train the network we first need to build a training set (supervised learning).



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General setup: two parts of the network:

1 Generator (approximation of IV surfaces via NN)

In order to train the network we first need to build a training set (supervised learning).

- For this we can use numerical valuation functions (Bergomi model, Rough Bergomi, Heston, ... Part 1): We generate 20,000 surfaces for each model, using a fixed grid of strikes and tenors.
- Though training time consuming, it can be done offline.
- We sample uniformly points in the parameter set θ ∈ Θ, then compute and save f(θ). Those samples will constitute our training set. We repeat this procedure until we reach enough samples for our surrogate function to be a good approximation.

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General setup: two parts of the network:

2 Calibrator

In order to train the network we first need to build a training set. Conclusions:



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General setup: two parts of the network:

2 Calibrator

In order to train the network we first need to build a training set. Conclusions:

- ▶ This can be done online, fast (within range of ~ 1 second already unoptimized)
- Evaluation of parameters now more direct than via Monte Carlo. One minimizes now the distance between the (approximator) surrogate functions $\hat{f}(\theta^*)$ and the volatility surface.

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We see that after learning, calibrating many parameters is fast



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We see that after learning, calibrating many parameters is fast \Rightarrow approximate several models at the same time.



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We see that after learning, calibrating many parameters is fast \Rightarrow approximate several models at the same time. New learning procedure:

- Train the generator on several models at the same time (here Parameters from Heston and Bergomi parameters) in Monte Carlo experiments as before.
- ► Calibrate several models at the same time ⇒ determine the best-fit model to a given data (flag).
- ► Controlled experiments: train on both Bergomi and Heston ⇒ test on data generated by Heston.

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Conclusions and further steps

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- 1. Adding further rough volatility models to the library to determine which model describes best the given set of data.
- Calibration of Implied volatility gives an ideal objective function for learning (data ⇔ models).
- 3. Or: optimising the distribution of distributions directly (bypassing IV)

Thank you and Happy Birthday Yuri!



FCLT for Hölder continuous processes



FCLT for Hölder continuous processes

Define for any $\omega \in \Omega$, $n \geq 1$, $t \in [0, T]$, the approximating sequence

$$W_n(t,\omega) := \frac{1}{\sigma\sqrt{n}} \sum_{k=1}^J \xi_k(\omega) + \frac{nt-j}{\sigma\sqrt{n}} \xi_{j+1}(\omega), \quad \text{whenever } t \in \left[\frac{j}{n}, \frac{j+1}{n}\right), \text{ for } j = 0, \dots, n-1.$$

where the family $(\xi_i)_{i\geq 1}$ forms an iid sequence of centered random variables with finite moments of all orders and $\mathbb{E}(\xi_1^2) = \sigma^2 > 0$.



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where the family $(\xi_i)_{i\geq 1}$ forms an iid sequence of centered random variables with finite moments of all orders and $\mathbb{E}(\xi_1^2) = \sigma^2 > 0$.

Theorem (Donsker-Lamperti Theorem)

The sequence $(W_n)_{n\geq 1}$ converges weakly to a Brownian motion in $(\mathcal{C}^{\alpha}([0, T]), \|\cdot\|_{\alpha})$ for all $\alpha < \frac{1}{2}$.

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The left-point approximation may be modified e.g.

$$\int_0^{\frac{Ti}{n}} g\left(\frac{Ti}{n}-s\right) \mathrm{d}W_s \approx \frac{1}{\sqrt{n\sigma}} \sum_{k=1}^{j-1} g\left(t_k^*\right) \xi_k, \quad j=0,\ldots,n$$

where t_k^* is chosen optimally to match first and second moments





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$$g(t_k^*) = \sqrt{n\int_{rac{T(k-1)}{n}}^{rac{Tk}{n}}g(t-s)^2\mathrm{d}s}, \quad k=1,\ldots,n.$$





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- This simple trick improves substantially the simulation (specially when α is close to -1/2)
- The hybrid scheme also admits this trick

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