Uniform generation of infinite concurrent runs The case of trace monoids

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- 2 Simulating Bernoulli distributions
- 3 Step-by-step simulation and pyramids

4 Conclusion

Heap of pieces

Trace monoid

• Pieces:

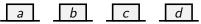


• Alphabet:

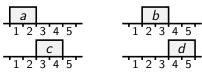
$$\Sigma = \{a, b, c, d\}$$

Heap of pieces

• Pieces:



• Horizontal layout:



• Vertical heaps:





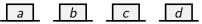
Trace monoid

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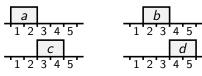
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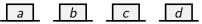
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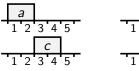
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Heap of pieces

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• Horizontal layout:





Vertical heaps:





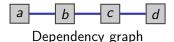
Trace monoid

Alphabet:

$$\Sigma = \{a, b, c, d\}$$

- Dependence relation:
 D={{a,b},{b,c},{c,d}}
- Trace monoid:

 $\mathcal{M} = \langle a, b, c, d | ac = ca, ad = da, bd = db \rangle^+$

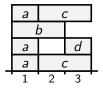


Heaps of pieces and dependency graph



Heap of pieces

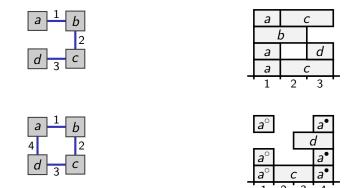




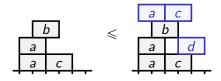
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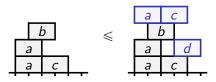
Heap of (disconnected) pieces



Heap of pieces



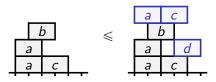
Heap of pieces



Can you pick one infinite heap uniformly at random?

- Objective terms of the second seco
- **2** Study uniform distributions on traces of length k: what if $k \to \infty$?

Heap of pieces

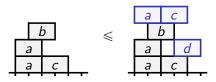


Can you pick one infinite heap uniformly at random?

- Heap length = #pieces in the heap
- Weak convergence of distributions:

$$\mu_k \to \nu \Leftrightarrow (\forall x \in \mathcal{M}^+, \mathbb{P}_{\mu_k}[x \leqslant \xi] \to \mathbb{P}_{\nu}[x \leqslant \xi])$$

Heap of pieces



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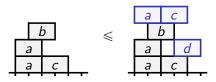
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Theorem (Abbes & Mairesse 2015)

If μ_k is the unifom measure on $\mathcal{M}_k = \{\zeta \in \mathcal{M} : |\zeta| = k\}$, ν exists and is the critical Bernoulli distribution of \mathcal{M} .

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Heap of pieces



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Theorem (Abbes & Mairesse 2015) — not constructive! If μ_k is the unifom measure on $\mathcal{M}_k = \{\zeta \in \mathcal{M} : |\zeta| = k\}, \nu$ exists and is the critical Bernoulli distribution of \mathcal{M} .

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Definition

A probability measure μ on ${\cal M}$ is:

- Bernoulli if $\forall x \in \mathcal{M}, \forall \sigma \in \Sigma, \mathbb{P}_{\mu}[x \sigma \leq \zeta \mid x \leq \zeta] = \mathbb{P}_{\mu}[\sigma \leq \zeta]$
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Uniform Bernoulli $\Rightarrow \mathbb{P}_{\mu}[x \leq \zeta] = p^{|x|} \Rightarrow \mathbb{P}_{\mu}[x = \zeta] \propto p^{|x|}.$

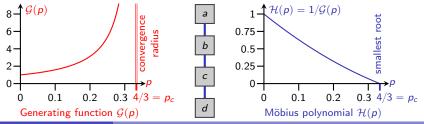
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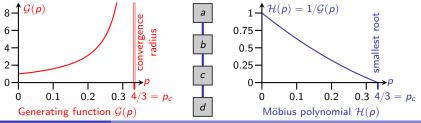
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(requires **infinite** heaps)

Which are the **possible values** of the parameter p? $0 \le p \le p_c$

Uniform Bernoulli
$$\Rightarrow \mathbb{P}_{\mu}[x \leq \zeta] = p^{|x|} \Rightarrow \mathbb{P}_{\mu}[x = \zeta] \propto p^{|x|} \stackrel{?}{=} p^{|x|}\mathcal{H}(p).$$



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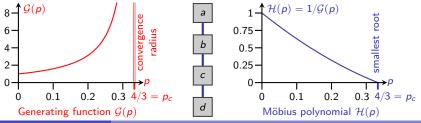
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Infinite heaps

Heap of pieces



Infinite heaps



 $\overline{\mathcal{M}}$ is the **compactification** of \mathcal{M} for the topology induced by $\Uparrow \mathbf{x} = \{\zeta : \mathbf{x} \leq \zeta\}$

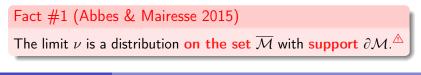
Reminder:
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Infinite heaps



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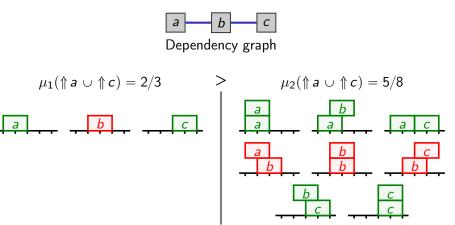
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Idea #1: Pick $\zeta_k \sim \mu_k$, pick a piece x wisely and set $\zeta_{k+1} = \zeta_k \cdot x$

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Example in the monoid $\langle a, b, c \mid ac = ca \rangle^+$



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Simulating the limit $\boldsymbol{\nu}$

Idea #2: Simulate $\zeta \sim \nu$, floor by floor





Fact #2 (Abbes & Mairesse 2015) This approach works because ν is **Bernoulli**!

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Simulating the limit $\boldsymbol{\nu}$

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Fact #2 (Abbes & Mairesse 2015)

This approach works because ν is **Bernoulli**!

Problems: Huge state space (exponential number of possible floors) Adding one floor implies synchronising many pieces

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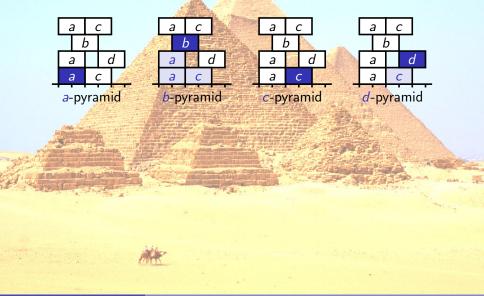
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Simulating the limit ν piece by piece Idea #3: Decompose heaps recursively by using pyramids

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Simulating the limit ν piece by piece

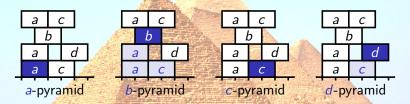
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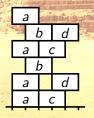
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Simulating the limit ν piece by piece

Idea #3: Decompose heaps recursively by using pyramids

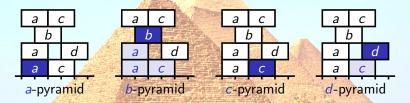


Example: Recursive decomposition using b-pyramids

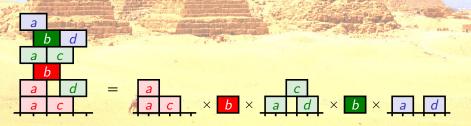


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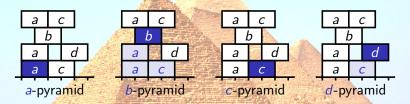


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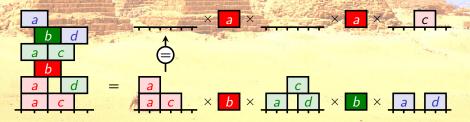


Uniform generation in infinite concurrent runs - The case of trace monoids

Idea #3: Decompose heaps recursively by using pyramids



Example: Recursive decomposition using b-pyramids, then a-pyramids...



Uniform generation in infinite concurrent runs - The case of trace monoids

Idea #3: Decompose heaps recursively by using independent pyramids

Theorem – continued (Abbes & J. 2017)

If $\mathbf{a} \in \Sigma$ and ν is **Bernoulli** on $\overline{\mathcal{M}}(\Sigma)$, then



where right-hand side random variables are independent.

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Theorem – continued (Abbes & J. 2017)

If $X \subseteq \Sigma$, $\mathbf{a} \in \Sigma$ and ν is **Bernoulli** on $\overline{\mathcal{M}}(\Sigma)$, then





- if ν has support $\partial \mathcal{M}$, $\xi = \text{infinite sequence of a-pyramids}$ $(k \leftarrow \infty)$
- a-pyramid = (a-free sequence ξ with $S(\xi) \subseteq D(a)$) \cdot a

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$$\mathbf{S}(\mathbf{a} \cdot \zeta) \subseteq X \Rightarrow \mathbf{S}(\zeta) \subseteq X$$

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Auxiliary goal: Generate a heap $\xi \in \mathcal{M}$ with $\mathbf{S}(\xi) \subseteq X$:

- **(**) Generate an **a**-free heap $\zeta \in \mathcal{M}$ with $\mathbf{S}(\zeta) \subseteq X$
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▶ if $k \ge 1$ and $S(\mathbf{a} \cdot \zeta) \nsubseteq X$: go back to step #1 (anticipated rejection)

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- ▶ if $k \ge 1$ and $S(\mathbf{a} \cdot \zeta) \subseteq X$: generate **a**-pyramids ζ_1, \ldots, ζ_k and output $\xi = \zeta_1 \cdot \zeta_2 \cdots \zeta_k \cdot \zeta$

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if k ≥ 1 and S(a·ζ) ⊆ X: generate a-pyramids ζ₁,...,ζ_k and output ξ = ζ₁·ζ₂···ζ_k·ζ

Variant: Choose $\mathbf{a} \in X$ and avoid rejection

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Running time/piece: n q or n Read-only memory usage: n or 2^n where $\mathcal{M}' = \mathcal{M}(\Sigma \setminus \{a\})$ and $q = \mathcal{G}_{\mathcal{M}'}(p_c) \leq 1/p_c^n$ $(q = n^{\Theta(n)} \text{ is possible})$

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A distributed simulation algorithm

Algorithm based on:

- precomputing and storing Möbius polynomials of sub-monoids
- decomposing heaps into independent pyramids/heaps in sub-monoids
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Very efficient on graphs with:

- few cycles (small storage/high efficiency for a mix between variants)
- small tree-width (no preprocessing/storage)



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