

Exact Enumeration of Planar Eulerian Orientations

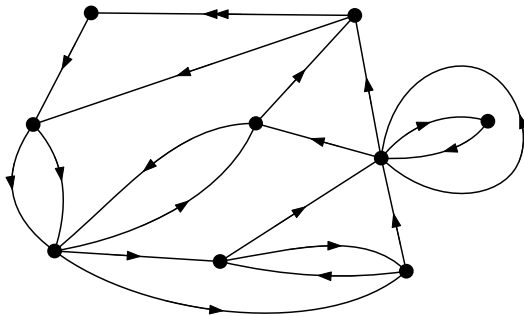
Andrew Elvey Price

Joint work with Mireille Bousquet-Mélou

The University of Melbourne and Université de Bordeaux

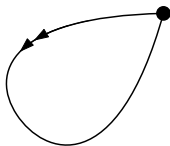
12/03/2018

ROOTED PLANAR EULERIAN ORIENTATIONS



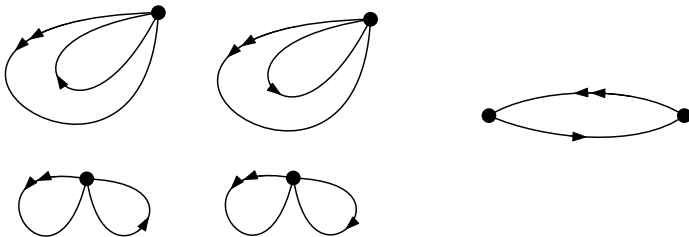
Each vertex has equally many incoming as outgoing edges.

ONE EDGE ROOTED PLANAR EULERIAN ORIENTATIONS



There is 1 planar rooted Eulerian orientations with one edge.

TWO EDGE ROOTED PLANAR EULERIAN ORIENTATIONS



There are 5 planar rooted Eulerian orientations with two edges.

COUNTING ROOTED PLANAR EULERIAN ORIENTATIONS

- Let g_n be the number of rooted planar Eulerian orientations with n edges.

COUNTING ROOTED PLANAR EULERIAN ORIENTATIONS

- Let g_n be the number of rooted planar Eulerian orientations with n edges.
- $g_1 = 1$.

COUNTING ROOTED PLANAR EULERIAN ORIENTATIONS

- Let g_n be the number of rooted planar Eulerian orientations with n edges.
- $g_1 = 1$.
- $g_2 = 5$.

COUNTING ROOTED PLANAR EULERIAN ORIENTATIONS

- Let g_n be the number of rooted planar Eulerian orientations with n edges.
- $g_1 = 1$.
- $g_2 = 5$.
- Aim: Find a formula for g_n .

BACKGROUND ON THE PROBLEM

- In 2016, Bonichon, Bousquet-Mélou, Dorbec and Pennarun posed the problem of enumerating planar rooted Eulerian orientations with a given number of edges.

BACKGROUND ON THE PROBLEM

- In 2016, Bonichon, Bousquet-Mélou, Dorbec and Pennarun posed the problem of enumerating planar rooted Eulerian orientations with a given number of edges.
- They computed the number g_n of these orientations for $n \leq 15$.

BACKGROUND ON THE PROBLEM

- In 2016, Bonichon, Bousquet-Mélou, Dorbec and Pennarun posed the problem of enumerating planar rooted Eulerian orientations with a given number of edges.
- They computed the number g_n of these orientations for $n \leq 15$.
- They also proved that the growth rate

$$\mu = \lim_{n \rightarrow \infty} \sqrt[n]{g_n}$$

exists and lies in the interval $(11.56, 13.005)$

QUARTIC PLANAR ROOTED EULERIAN ORIENTATIONS

- *quartic*: Each vertex has degree 4.

QUARTIC PLANAR ROOTED EULERIAN ORIENTATIONS

- *quartic*: Each vertex has degree 4.
- Let q_n be the number of quartic rooted planar Eulerian orientations with n vertices.

QUARTIC PLANAR ROOTED EULERIAN ORIENTATIONS

- *quartic*: Each vertex has degree 4.
- Let q_n be the number of quartic rooted planar Eulerian orientations with n vertices.
- Bonichon et al. also posed the problem of enumerating these.

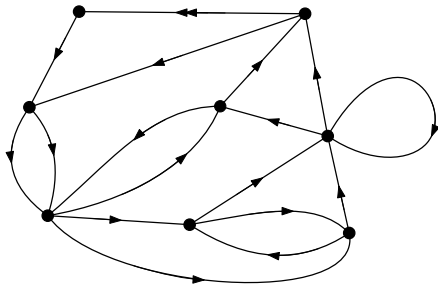
QUARTIC PLANAR ROOTED EULERIAN ORIENTATIONS

- *quartic*: Each vertex has degree 4.
- Let q_n be the number of quartic rooted planar Eulerian orientations with n vertices.
- Bonichon et al. also posed the problem of enumerating these.
- In physics, this is equivalent to the ice type model on a random lattice studied by Zinn-Justin and Kostov.

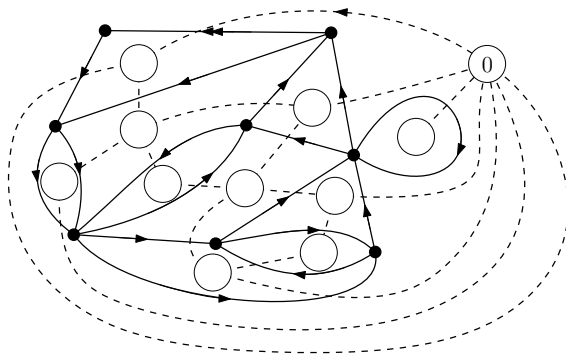
QUARTIC PLANAR ROOTED EULERIAN ORIENTATIONS

- *quartic*: Each vertex has degree 4.
- Let q_n be the number of quartic rooted planar Eulerian orientations with n vertices.
- Bonichon et al. also posed the problem of enumerating these.
- In physics, this is equivalent to the ice type model on a random lattice studied by Zinn-Justin and Kostov.
- Also, $6q_n$ is the number of properly three coloured quadrangulations with n faces.

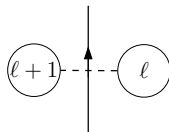
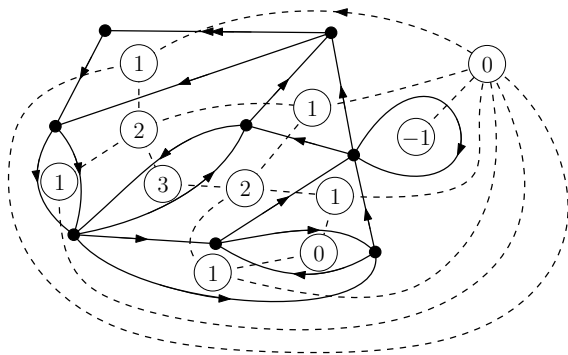
BIJECTION TO LABELLED MAPS



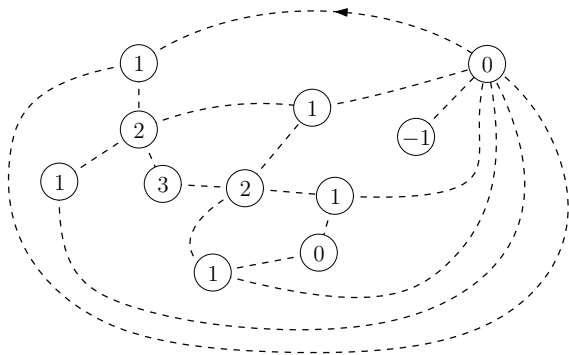
BIJECTION TO LABELLED MAPS



BIJECTION TO LABELLED MAPS

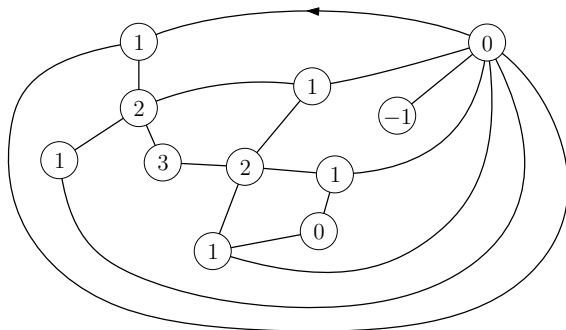


BIJECTION TO LABELLED MAPS



LABELLED MAPS

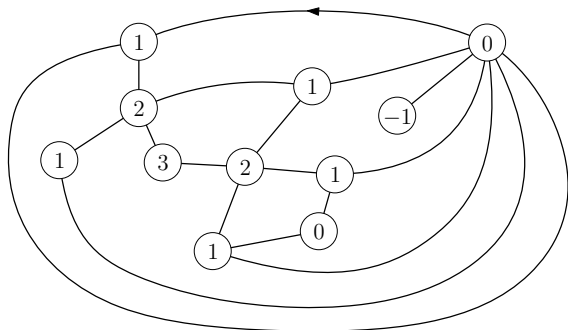
Labelled maps are rooted planar maps with labelled vertices such that:



LABELLED MAPS

Labelled maps are rooted planar maps with labelled vertices such that:

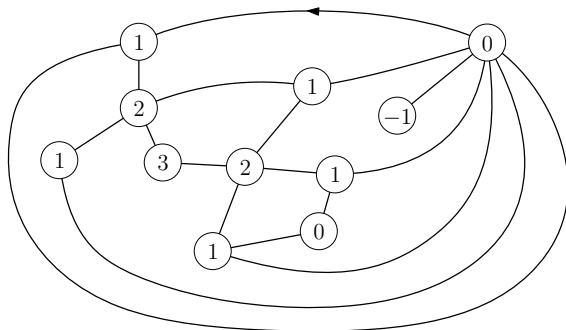
- The root edge is labelled from 0 to 1.



LABELLED MAPS

Labelled maps are rooted planar maps with labelled vertices such that:

- The root edge is labelled from 0 to 1.
- Adjacent labels differ by 1.

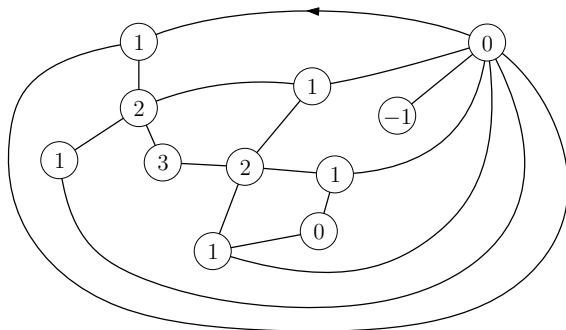


LABELLED MAPS

Labelled maps are rooted planar maps with labelled vertices such that:

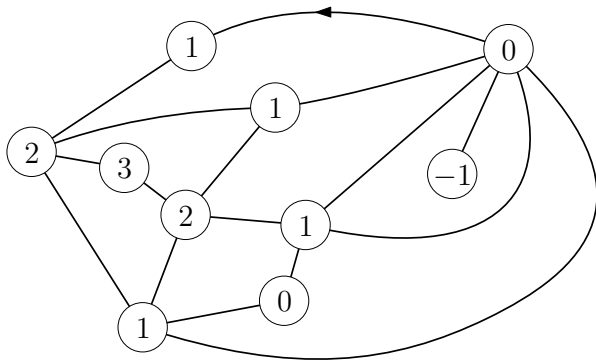
- The root edge is labelled from 0 to 1.
- Adjacent labels differ by 1.

By the bijection, g_n is the number of labelled maps with n edges.



LABELLED QUADRANGULATIONS

By our bijection, q_n (the number of quartic eulerian orientations with n vertices) is the number of labelled quadrangulations with n faces.



COUNTING LABELLED QUADRANGULATIONS

By generalising the problem, we deduce a system of functional equations which defines q_n :

COUNTING LABELLED QUADRANGULATIONS

By generalising the problem, we deduce a system of functional equations which defines q_n :

$$q_n = [yt^n]P(t, y)$$

$$P(t, y) = \frac{1}{y}[x^1]C(t, x, y)$$

$$D(t, x, y) = \frac{1}{1 - C\left(t, \frac{1}{1-x}, y\right)}$$

$$D(t, x, y) = 1 + yD(t, x, y)[y^1]D(t, x, y) + y[x^{\geq 0}] \frac{1}{x} P\left(t, \frac{1}{x}\right) D(t, x, y)$$

$$[y^1]D(t, x, y) = \frac{1}{1-x}(1 + 2t[y^2]D(t, x, y) - t([y^1]D(t, x, y))^2).$$

COUNTING LABELLED QUADRANGULATIONS

By generalising the problem, we deduce a system of functional equations which defines q_n :

$$q_n = [yt^n]P(t, y)$$

$$P(t, y) = \frac{1}{y}[x^1]C(t, x, y)$$

$$D(t, x, y) = \frac{1}{1 - C\left(t, \frac{1}{1-x}, y\right)}$$

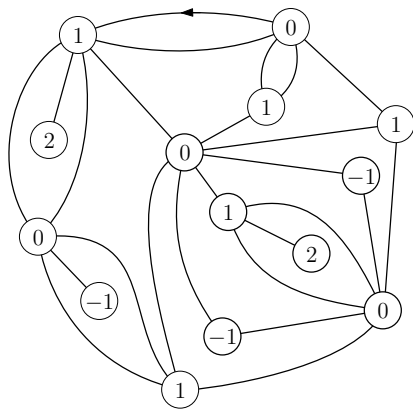
$$D(t, x, y) = 1 + yD(t, x, y)[y^1]D(t, x, y) + y[x^{\geq 0}] \frac{1}{x} P\left(t, \frac{1}{x}\right) D(t, x, y)$$

$$[y^1]D(t, x, y) = \frac{1}{1-x}(1 + 2t[y^2]D(t, x, y) - t([y^1]D(t, x, y))^2).$$

I will show one element of the proof.

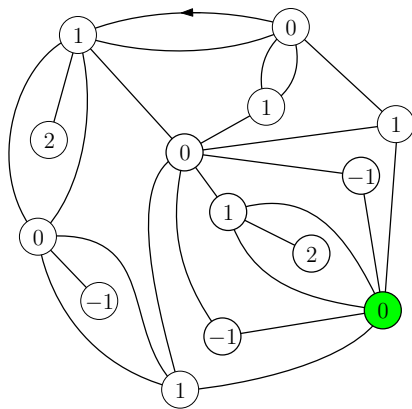
D-PATCHES

D-patch: Digons are allowed next to the root vertex and the outer face may have any degree.



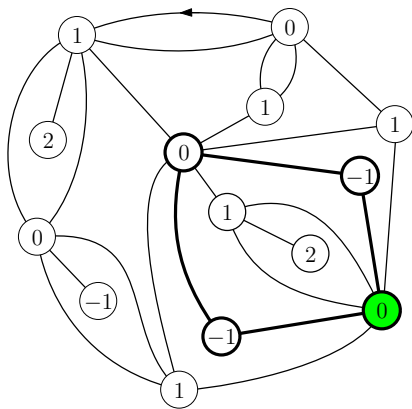
DECOMPOSITION OF D-PATCHES

Colour the vertex two places clockwise from the root vertex around the outer face.



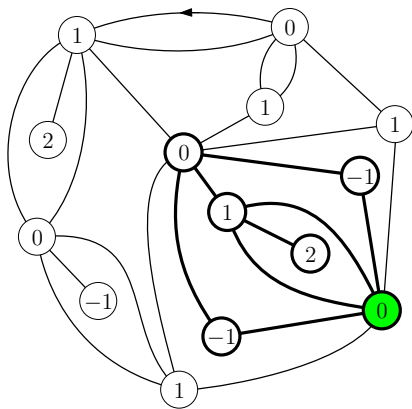
DECOMPOSITION OF D-PATCHES

Highlight the maximal connected subgraph of nonpositive labels, containing the coloured vertex.



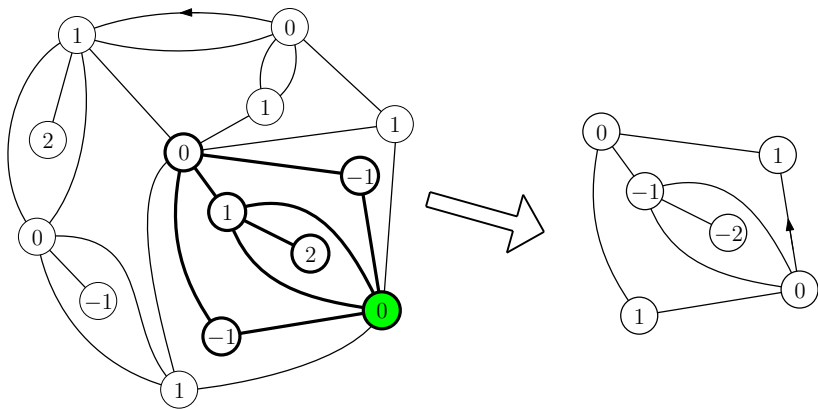
DECOMPOSITION OF D-PATCHES

Add to the subgraph all vertices and edges contained in its inner face(s).



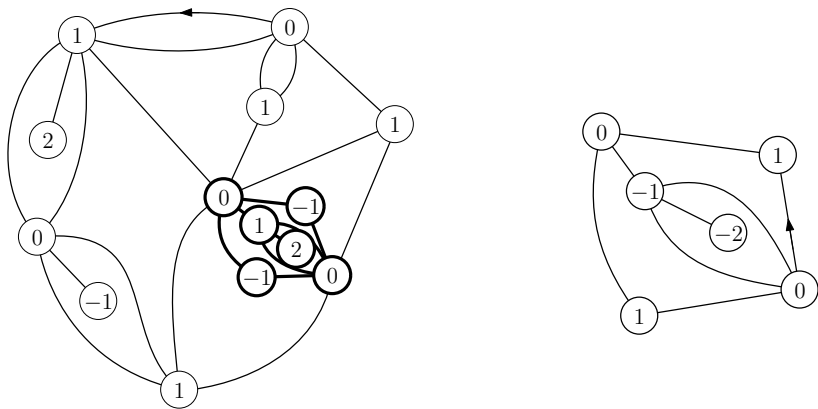
DECOMPOSITION OF D-PATCHES

Record the subgraph with inverted labels.



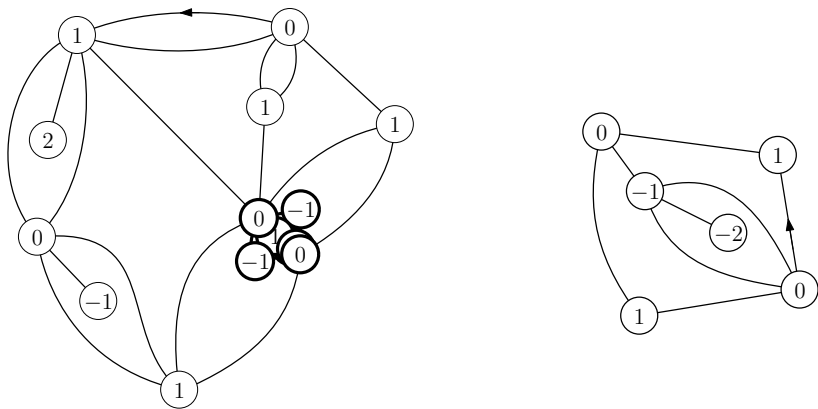
DECOMPOSITION OF D-PATCHES

Contract the highlighted map to a single vertex (labelled 0).



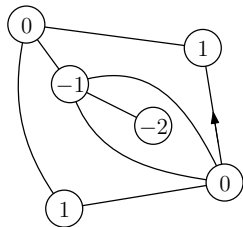
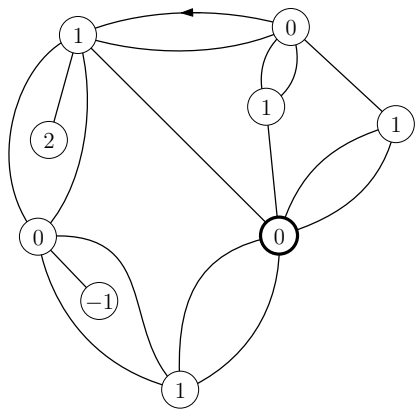
DECOMPOSITION OF D-PATCHES

Contract the highlighted map to a single vertex (labelled 0).



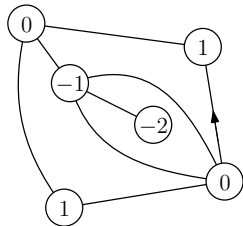
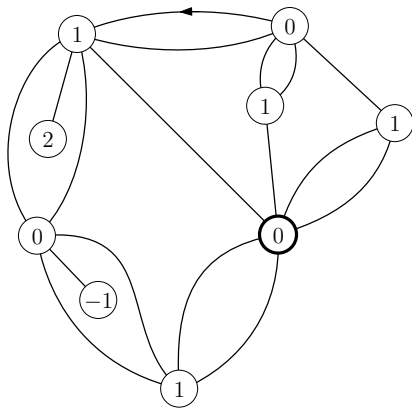
DECOMPOSITION OF D-PATCHES

Contract the highlighted map to a single vertex (labelled 0).



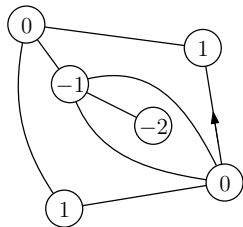
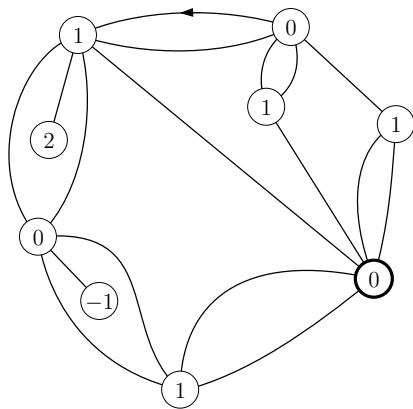
DECOMPOSITION OF D-PATCHES

Contract the highlighted map to a single vertex (labelled 0). The new vertex may be adjacent to digons.



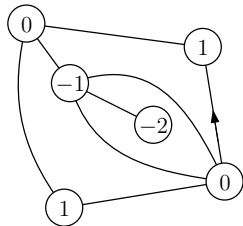
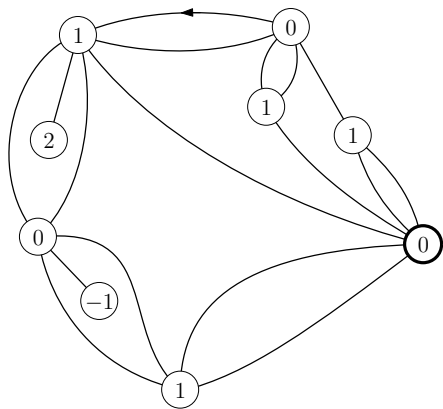
DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex.



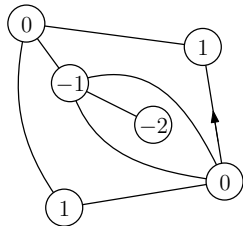
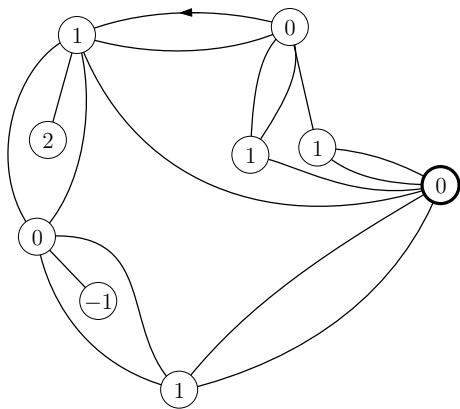
DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex.



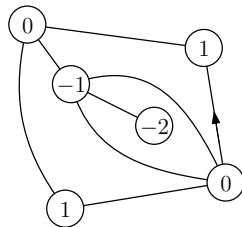
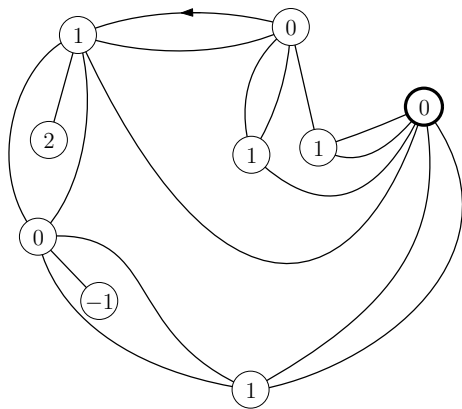
DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex.



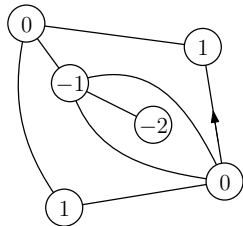
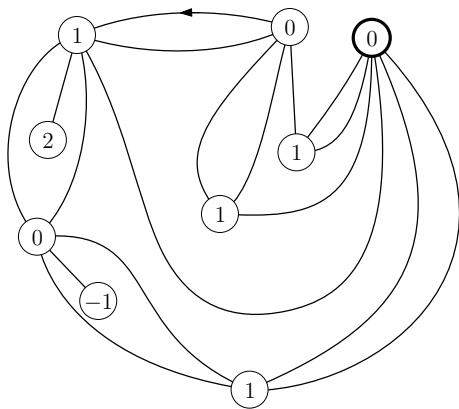
DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex.



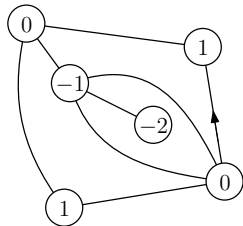
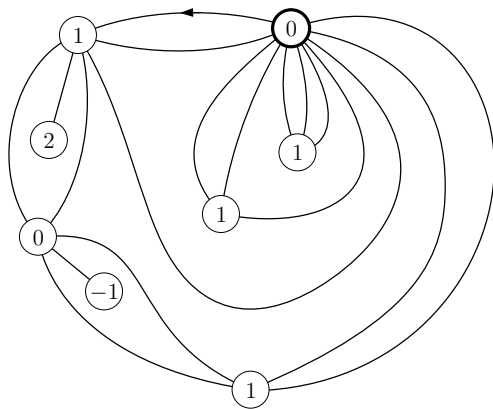
DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex.



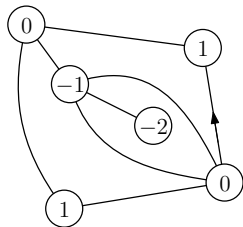
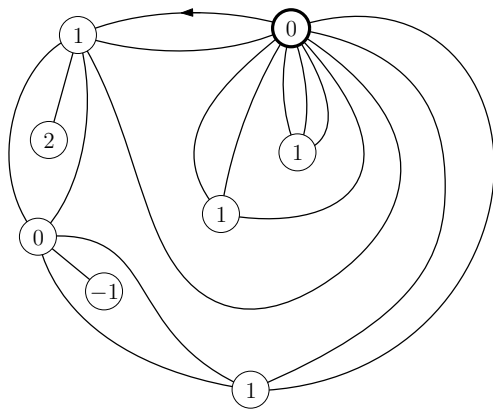
DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex.



DECOMPOSITION OF D-PATCHES

Merge the new vertex with the root vertex. This new map is a D-patch!



EQUATIONS FOR LABELLED QUADRANGULATIONS

$$q_n = [yt^n]P(t, y)$$

$$P(t, y) = \frac{1}{y}[x^1]C(t, x, y)$$

$$D(t, x, y) = \frac{1}{1 - C\left(t, \frac{1}{1-x}, y\right)}$$

$$D(t, x, y) = 1 + yD(t, x, y)[y^1]D(t, x, y) + y[x^{\geq 0}] \frac{1}{x} P\left(t, \frac{1}{x}\right) D(t, x, y)$$

$$[y^1]D(t, x, y) = \frac{1}{1-x} (1 + 2t[y^2]D(t, x, y) - t([y^1]D(t, x, y))^2).$$

SOLVING THE EQUATIONS

- At this point we just needed to guess the values of the series P , C and D and verify that the guesses satisfy the equations.

SOLVING THE EQUATIONS

- At this point we just needed to guess the values of the series P , C and D and verify that the guesses satisfy the equations.
- Bref, we did.

SOLUTION FOR LABELLED QUADRANGULATIONS

$$t\mathbf{P}(t, ty) = \sum_{n \geq 0} \sum_{j=0}^n \frac{1}{n+1} \binom{2n-j}{n} \binom{3n-j}{n} y^j \mathbf{R}^{n+1},$$

$$\mathbf{C}(t, x, ty) = 1 - \exp \left(- \sum_{n \geq 0} \sum_{j=0}^n \sum_{i=0}^{2n-j} \frac{1}{n+1} \binom{2n-j}{n} \binom{3n-i-j}{n} x^{i+1} y^{j+1} \mathbf{R}^{n+1} \right),$$

$$\mathbf{D}(t, x, ty) = \exp \left(\sum_{n \geq 0} \sum_{j=0}^n \sum_{i \geq 0} \frac{1}{n+1} \binom{2n-j}{n} \binom{3n+i-j+1}{2n-j} x^i y^{j+1} \mathbf{R}^{n+1} \right),$$

where $\mathbf{R}(t)$ satisfies

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n} \binom{3n}{n} \mathbf{R}(t)^{n+1} :$$

SOLUTION FOR LABELLED QUADRANGULATIONS

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n} \binom{3n}{n} \mathbf{R}(t)^{n+1}.$$

SOLUTION FOR LABELLED QUADRANGULATIONS

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n} \binom{3n}{n} \mathbf{R}(t)^{n+1}.$$

The number of labelled quadrangulations with n faces is then

$$q_n = -\frac{1}{3} [t^{n+2}] \mathbf{R}(t).$$

SOLUTION FOR LABELLED QUADRANGULATIONS

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n} \binom{3n}{n} \mathbf{R}(t)^{n+1}.$$

The number of labelled quadrangulations with n faces is then

$$q_n = -\frac{1}{3} [t^{n+2}] \mathbf{R}(t).$$

Asymptotically this behaves as

$$q_n \sim \kappa \frac{\mu^{n+2}}{n^2 (\log n)^2},$$

where $\kappa = 1/18$ and $\mu = 4\sqrt{3}\pi$.

SOLUTION FOR LABELLED QUADRANGULATIONS

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n} \binom{3n}{n} \mathbf{R}(t)^{n+1}.$$

The number of labelled quadrangulations with n faces is then

$$q_n = -\frac{1}{3} [t^{n+2}] \mathbf{R}(t).$$

Asymptotically this behaves as

$$q_n \sim \kappa \frac{\mu^{n+2}}{n^2 (\log n)^2},$$

where $\kappa = 1/18$ and $\mu = 4\sqrt{3}\pi$.

This asymptotic form verifies predictions of Kostov, Zinn-Justin and Guttman.

SOLUTION FOR LABELLED QUADRANGULATIONS

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n} \binom{3n}{n} \mathbf{R}(t)^{n+1}.$$

The number of labelled quadrangulations with n faces is then

$$q_n = -\frac{1}{3} [t^{n+2}] \mathbf{R}(t).$$

Asymptotically this behaves as

$$q_n \sim \kappa \frac{\mu^{n+2}}{n^2 (\log n)^2},$$

where $\kappa = 1/18$ and $\mu = 4\sqrt{3}\pi$.

This asymptotic form verifies predictions of Kostov, Zinn-Justin and Guttmann. This appears to be the first exactly solved map problem with this universality class.

ENUMERATING GENERAL ROOTED PLANAR EULERIAN ORIENTATIONS

- Rooted planar Eulerian are in bijection with labelled maps (both counted by edges).

ENUMERATING GENERAL ROOTED PLANAR EULERIAN ORIENTATIONS

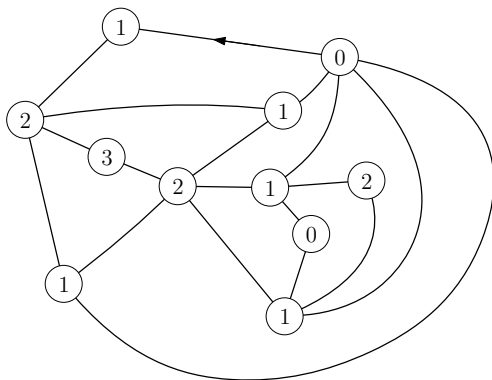
- Rooted planar Eulerian are in bijection with labelled maps (both counted by edges).
- I will now describe a bijection to labelled quadrangulations (counted by faces) in which each face has three distinct labels.

ENUMERATING GENERAL ROOTED PLANAR EULERIAN ORIENTATIONS

- Rooted planar Eulerian are in bijection with labelled maps (both counted by edges).
- I will now describe a bijection to labelled quadrangulations (counted by faces) in which each face has three distinct labels.
- This bijection is based on the mobile construction of Bouttier, Di Francesco and Guitter.

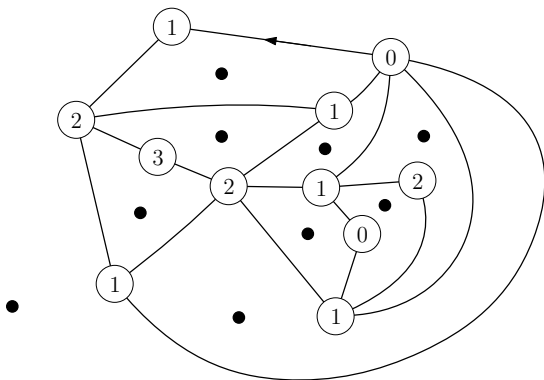
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Start with a quadrangulation in which each face has three labels.



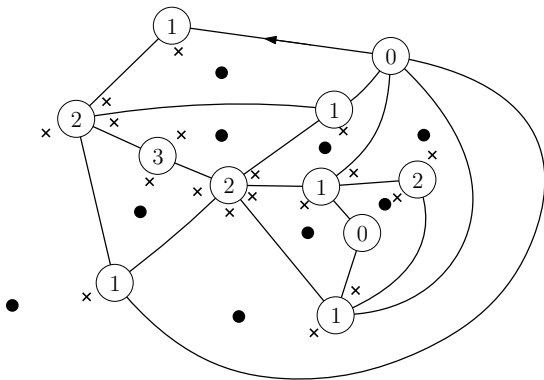
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Add a black vertex in each face.



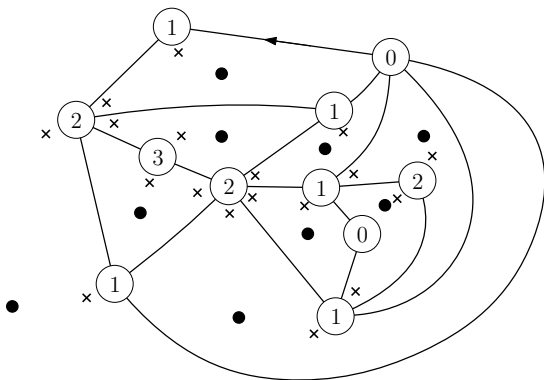
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Around each face, put a cross at each corner whose label is greater than the next label clockwise.



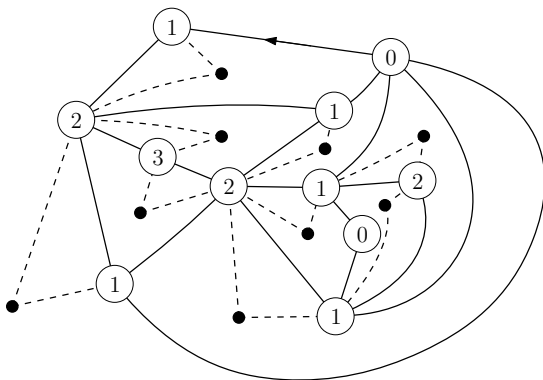
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Draw an edge from each black vertex to each surrounding corner with a cross.



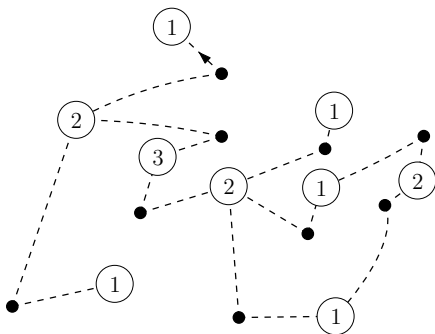
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Draw an edge from each black vertex to each surrounding corner with a cross.



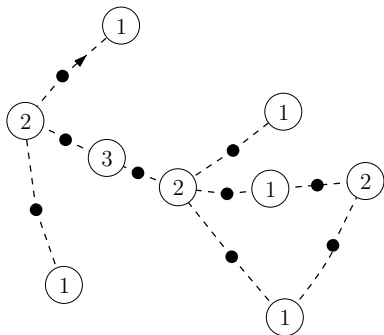
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Remove any isolated vertices.



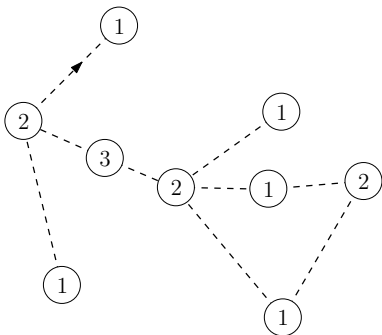
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

So far this is identical to the mobile bijection of Bouttier et al. (apart from the initial labelled map)



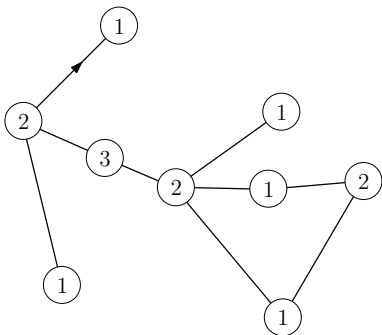
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

Remove the black vertices.



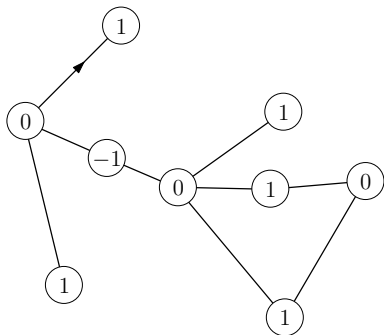
BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

This map will either be a labelled map, or will become one when each label ℓ is changed to $2 - \ell$.



BIJECTION FROM RESTRICTED QUADRANGULATIONS TO LABELLED MAPS.

This map will either be a labelled map, or will become one when each label ℓ is changed to $2 - \ell$.



ENUMERATING GENERAL ROOTED PLANAR EULERIAN ORIENTATIONS

- So, $2g_n$ is the number of labelled quadrangulations with n faces in which each face has three distinct labels.

ENUMERATING GENERAL ROOTED PLANAR EULERIAN ORIENTATIONS

- So, $2g_n$ is the number of labelled quadrangulations with n faces in which each face has three distinct labels.
- We solve this problem in a similar way to how we enumerated labelled quadrangulations.

ENUMERATING ROOTED PLANAR EULERIAN ORIENTATIONS

The number of rooted planar Eulerian orientations with n edges is then

$$g_n = -\frac{1}{4}[t^{n+2}]\mathbf{S}(t),$$

where $\mathbf{S}(t)$ is the unique series with constant term 0 satisfying

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n}^2 \mathbf{S}(t)^{n+1}.$$

ENUMERATING ROOTED PLANAR EULERIAN ORIENTATIONS

The number of rooted planar Eulerian orientations with n edges is then

$$g_n = -\frac{1}{4}[t^{n+2}]\mathbf{S}(t),$$

where $\mathbf{S}(t)$ is the unique series with constant term 0 satisfying

$$t = \sum_{n=0}^{\infty} \frac{1}{n+1} \binom{2n}{n}^2 \mathbf{S}(t)^{n+1}.$$

Asymptotically this behaves as

$$g_n \sim \kappa \frac{\mu^{n+2}}{n^2(\log n)^2},$$

where $\kappa = 1/16$ and $\mu = 4\pi$.

FURTHER QUESTIONS

FURTHER QUESTIONS

- Is there a more direct, less algebraic proof of our formulas for q_n and g_n ?

FURTHER QUESTIONS

- Is there a more direct, less algebraic proof of our formulas for q_n and g_n ?
- Can we generalise these results by counting labelled quadrangulations with a weight ω per face with only two distinct labels?

FURTHER QUESTIONS

- Is there a more direct, less algebraic proof of our formulas for q_n and g_n ?
- Can we generalise these results by counting labelled quadrangulations with a weight ω per face with only two distinct labels? In physics, this corresponds to the six vertex model on a random lattice.

FURTHER QUESTIONS

- Is there a more direct, less algebraic proof of our formulas for q_n and g_n ?
- Can we generalise these results by counting labelled quadrangulations with a weight ω per face with only two distinct labels? In physics, this corresponds to the six vertex model on a random lattice.
- What about other weights?

THANK YOU

Thank you!

BONUS SLIDE: GUESSING THE SOLUTIONS

- Using an earlier system of equations, Tony Guttmann and I computed the first 100 values of q_n .

BONUS SLIDE: GUESSING THE SOLUTIONS

- Using an earlier system of equations, Tony Guttmann and I computed the first 100 values of q_n .
- By analysing the series, Tony guessed the exact asymptotic form of the series, including the growth rate $4\sqrt{3}\pi$.

BONUS SLIDE: GUESSING THE SOLUTIONS

- Using an earlier system of equations, Tony Guttmann and I computed the first 100 values of q_n .
- By analysing the series, Tony guessed the exact asymptotic form of the series, including the growth rate $4\sqrt{3}\pi$.
- Mireille noticed that this growth rate had appeared before, in enumerating quadrangulations decorated by a spanning forest.

BONUS SLIDE: GUESSING THE SOLUTIONS

- Using an earlier system of equations, Tony Guttmann and I computed the first 100 values of q_n .
- By analysing the series, Tony guessed the exact asymptotic form of the series, including the growth rate $4\sqrt{3}\pi$.
- Mireille noticed that this growth rate had appeared before, in enumerating quadrangulations decorated by a spanning forest.
- So, we searched for an algebraic relationship between the problems, and we found one!

BONUS SLIDE: GUESSING THE SOLUTIONS

- We then transformed the series by writing $\mathcal{P}(t, y) = t\mathbf{P}(t, ty)$, $\mathcal{C}(t, x, y) = \mathbf{C}(t, x, ty)$ and $\mathcal{D}(t, x, y) = \mathbf{D}(t, x, ty)$ to remove t from the equations.

BONUS SLIDE: GUESSING THE SOLUTIONS

- We then transformed the series by writing $\mathcal{P}(t, y) = t\mathbf{P}(t, ty)$, $\mathcal{C}(t, x, y) = \mathbf{C}(t, x, ty)$ and $\mathcal{D}(t, x, y) = \mathbf{D}(t, x, ty)$ to remove t from the equations.
- Next, we wrote $\mathcal{P}(t, y)$, $\mathcal{C}(t, x, y)$ and $\mathcal{D}(t, x, y)$ as series in \mathbf{R} , x and y .

BONUS SLIDE: GUESSING THE SOLUTIONS

- We then transformed the series by writing $\mathcal{P}(t, y) = t\mathbf{P}(t, ty)$, $\mathcal{C}(t, x, y) = \mathbf{C}(t, x, ty)$ and $\mathcal{D}(t, x, y) = \mathbf{D}(t, x, ty)$ to remove t from the equations.
- Next, we wrote $\mathcal{P}(t, y)$, $\mathcal{C}(t, x, y)$ and $\mathcal{D}(t, x, y)$ as series in \mathbf{R} , x and y .
- We noticed that $\mathcal{P}(t, y)$ is a simple hypergeometric function of \mathbf{R} and y .

BONUS SLIDE: GUESSING THE SOLUTIONS

- We then transformed the series by writing $\mathcal{P}(t, y) = t\mathbf{P}(t, ty)$, $\mathcal{C}(t, x, y) = \mathbf{C}(t, x, ty)$ and $\mathcal{D}(t, x, y) = \mathbf{D}(t, x, ty)$ to remove t from the equations.
- Next, we wrote $\mathcal{P}(t, y)$, $\mathcal{C}(t, x, y)$ and $\mathcal{D}(t, x, y)$ as series in \mathbf{R} , x and y .
- We noticed that $\mathcal{P}(t, y)$ is a simple hypergeometric function of \mathbf{R} and y .
- After looking up some specialisations of $\mathcal{D}(t, x, y)$ in oeis, we guessed that it was an exponential of something simpler.

BONUS SLIDE: GUESSING THE SOLUTIONS

- We then transformed the series by writing $\mathcal{P}(t, y) = t\mathbf{P}(t, ty)$, $\mathcal{C}(t, x, y) = \mathbf{C}(t, x, ty)$ and $\mathcal{D}(t, x, y) = \mathbf{D}(t, x, ty)$ to remove t from the equations.
- Next, we wrote $\mathcal{P}(t, y)$, $\mathcal{C}(t, x, y)$ and $\mathcal{D}(t, x, y)$ as series in \mathbf{R} , x and y .
- We noticed that $\mathcal{P}(t, y)$ is a simple hypergeometric function of \mathbf{R} and y .
- After looking up some specialisations of $\mathcal{D}(t, x, y)$ in oeis, we guessed that it was an exponential of something simpler.
- Indeed, $\log(\mathcal{D}(t, x, y))$ is a simple hypergeometric function of \mathbf{R} , x and y !