## Computer experiments with big *n*: Has Gaussian process computation been tamed?

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## Outline



- Computer experiments and Gaussian processes
- Computational complexity

#### 2 Design for Big n (to Make Analysis Fast)

Sparse grid designs

#### 3 Analysis for Big n

- Local approximate Gaussian processes (IaGP)
- Treed GPs (tgp)

#### Results

#### 5 Conclusions







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#### Standard Gaussian Process (GP) Model

- *d*-dimensional vector of inputs **x**
- Output y(x)
- Treat  $y(\mathbf{x})$  as a realization of

$$Y(\mathbf{x}) =$$
regression model +  $Z(\mathbf{x})$ 

- $Z(\mathbf{x})$  hence  $Y(\mathbf{x})$  is a correlated process
- The correlation function  $R(\mathbf{x}, \mathbf{x}') \equiv R(Y(\mathbf{x}), Y(\mathbf{x}'))$  is the workhorse of the GP model



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- Sacks et al. (1989)







#### Computational complexity

- Training data of *n* runs at  $\mathbf{x}^{(1)}, \ldots, \mathbf{x}^{(n)}$ 
  - Key is the  $n \times n$  correlation matrix

$$\mathbf{R} = R(\mathbf{x}^{(i)}, \mathbf{x}^{(j)}) \quad ext{for } 1 \leq i, j \leq n$$

- Maximum likelihood or Bayes MCMC needs  $\mathbf{R}^{-1}$  and  $\mathsf{det}(\mathbf{R}),$  or the Cholesky decomposition
- Computational time for one likelihood calculation is  $O(n^3)$
- Need 1000's or 10 000's likelihood calculations
- Prediction at N test points
  - Point prediction: O(n) computation per prediction; O(nN) for all test points
  - Predictive variance:  $O(n^2)$  per prediction;  $O(n^2N)$  for all test points \_\_\_\_\_



Dennis pointed out big *n* to statisticians is not so big. For GPs big is 1000's or 10000's.





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Dennis pointed out big *n* to statisticians is not so big. For GPs big is 1000's or 10000's.

- To illustrate methods, *n* will be really small: *n*
- Then some results for larger n





#### Student Audience Participation

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Has Gaussian process computation been tamed?

- A No
- B Yes
- C I don't know
- D Nobody knows



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- E Who cares? Isn't it dinner time yet?



Same designs as Henry's talk



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## Grid Designs: Intuition

Design for d = 2 inputs on a  $21 \times 21$  grid (n = 441)



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 $\bullet\,$  For the above  $21\times21$  grid design

$$\begin{array}{rcl} {\bf R}_{441\times 441} & = & {\bf R}_{21\times 21}^{(1)} & \otimes & {\bf R}_{21\times 21}^{(2)} \\ x_1 \mbox{ and } x_2 & & x_1 & & x_2 \end{array}$$

- $O(441^3)$  computation becomes  $O(21^3) + O(21^3)$  computation
- In general, for d = 2 inputs  $O(n^3)$  becomes  $O(n^{3/2})$
- i.e.,  $O(n^{3/2})$  speed up
- For d inputs,  $O(n^3)$  becomes  $O(n^{3/d})$ : even more relative speed-up
- But (dense) grid designs need too many computer-model runs, so ...





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SGD (eta = 5, n = 25)



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SGD (eta = 6, n = 41)





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#### Franke's Function





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#### Franke's Function and Sparse Grid Design (n = 41)





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# Franke's Function and Maximin Design (n = 41) for Comparison





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#### Measures of Prediction Accuracy

- Prediction accuracy measured using "gold standard" hold-out test set
- N = 1000 or 10000 random points **x** in the input space with y known
- Average error: Normalized root mean squared prediction error

$$\sqrt{\frac{1}{N}\sum_{\text{test points}} (y - \hat{y})^2}$$

test set standard deviation of y

• Worst error: Normalized max absolute prediction error

$$\frac{\max\limits_{\text{test points}} |y - \hat{y}|}{\max\limits_{\text{test points}} |y - \bar{y}|}$$

• Normalization: 0 = perfect, 1 = no better than predicting using  $\bar{y}$ 



(1000 test points from a random Latin hypercube)

	Normalized		
Design	RMSPE	Max Error	
Sparse grid	0.068	0.099	
Maximin	0.047	0.110	



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## Local Approximate Gaussian Processes (IaGP, Gramacy and Apley, 2015; Gramacy, 2016)

#### for each test point do

Find  $n_0 < n$  training neighbours of the test point Fit GP using only the  $n_0$  neighbours of the test point Predict the test point using the GP end for

- $O(n^3)$  training computation becomes  $O(n_0^3)$ , i.e.,  $(n/n_0)^3$  speed up
- Has to be repeated for each prediction



#### Franke's Function: Training Data and a Test Point





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#### Franke's Function: 10 Local Training Points





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(1000 test points from a random Latin hypercube)

	Normalized		
Design	RMSPE	Max Error	
Sparse grid	0.068	0.099	
Maximin	0.047	0.110	
laGP	0.061	0.127	



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- Partition the input space with a binary tree
- For each leaf (terminal node) fit a GP using the leaf's data
- Actually builds many trees and averages them for prediction



#### Franke's Function: Treed GP

Tree with 2 leaves:  $x_2 \leq 0.44$  and  $x_2 > 0.44$ 



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(1000 test points from a random Latin hypercube)

	Normalized		
Design	RMSPE	Max Error	
Sparse grid	0.068	0.099	
Maximin	0.047	0.110	
laGP	0.061	0.127	
Treed GP	0.259	0.425	



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Two functions  $y(\mathbf{x})$  with 8-dimensional  $\mathbf{x}$ 

- Borehole function: easy to predict
- Corner peak function: difficult to predict (increases rapidly at the origin)



#### Borehole: Normalized RMS Prediction Error Versus n



#### Corner Peak: Normalized Max Absolute Error Versus n



#### Corner Peak: Computing Time Versus n



• Bayesian local kriging (Pronzato and Rendas, 2017): dynamically weighted combination of local GPs



 Compactly supported correlated functions (Kaufman, Bingham, Habib, Heitmann, and Frieman, 2011): induce sparse correlation matrix





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- A No
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- D Nobody knows
- E 3 hours to dinner



- Implementation of "standard" analysis is difficult for some local methods
- Any one of these methods is not one method:
  - How to choose a sparse grid?
  - How many points in a local region?
- Domain of practical problems?
  - Do these methods allow large enough *n* for a useful statistical model of a complex function?
  - Remember, we have to run the computer model *n* times





## THANK YOU! 📛



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