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Simplify Designs: Reduction Principles Revisited

Simplify Designs: Reduction Principles Revisited

joint work with

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Outline

- **1** Initial Considerations
- 2 Majorization
- **3** Invariance and Equivariance
- **4** Constructions for Multiple Factors
- **5** Final Considerations

1 Initial Considerations

all design problems seem to be solvable by numerical optimization

$$\xi^* = \arg\max_{\xi} \{\ldots\}$$

but some may be substantially reduced

- » multi-factorial models: $\mathbf{x} = (x_1, ..., x_K)$
- » monotonicity and symmetry

Questions

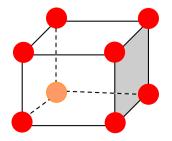
➢ When can the set of optimal design points be reduced to a tractable (finite) set ? $\mathbf{x}^* \in X^* \subset X$

> When can symmetries be utilized ?

$$g(\xi^*) = \xi^*$$

When can multi-factor optimal designs be constructed from marginal models ?

$$\boldsymbol{\xi}^* = h(\boldsymbol{\xi}_1^*, \dots, \boldsymbol{\xi}_K^*)$$



Design

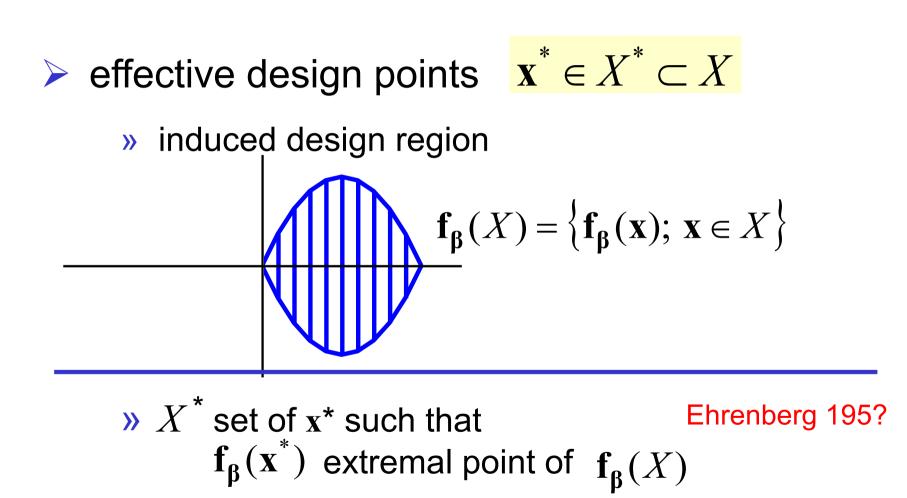
 \succ aim: choose settings x to maximize information

approximate design
$$\xi = \begin{pmatrix} \mathbf{X}_1 & \cdots & \mathbf{X}_m \\ \xi(\mathbf{X}_1) & \cdots & \xi(\mathbf{X}_m) \end{pmatrix} \longleftarrow \text{ settings}$$
proportions

> information matrix $\mathbf{M}(\xi; \mathbf{\beta}) = \sum_{j=1}^{m} \xi(\mathbf{x}_{j}) \mathbf{f}_{\mathbf{\beta}}(\mathbf{x}_{j}) \mathbf{f}_{\mathbf{\beta}}(\mathbf{x}_{j})^{\mathsf{T}}$ > with regression functions $\mathbf{f}_{\mathbf{\beta}}(\mathbf{x}) \left[= \partial \mu(\mathbf{x}) / \partial \mathbf{\beta}\right]$

» for linear models $f_{\beta}(x) = f(x)$

2 Majorization

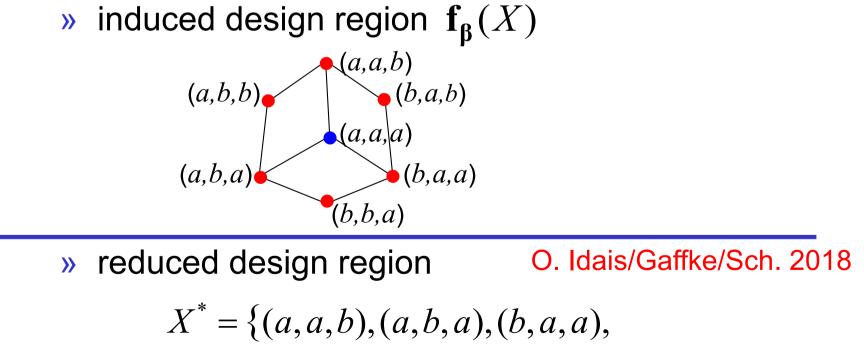


$$\mathbf{f}_{\boldsymbol{\beta}}(\mathbf{x}) = \sum w_j \mathbf{f}_{\boldsymbol{\beta}}(\mathbf{x}_j^*)$$

Gamma model

 $\mathbf{f}_{\boldsymbol{\beta}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) / (\mathbf{f}(\mathbf{x})^{\mathsf{T}} \boldsymbol{\beta})$

» 3 factor on $X=[a,b]^3$ (multilinear), without intercept



 $(a,b,b),(b,a,b),(b,b,a) \}$

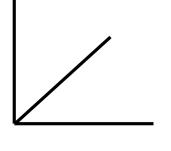
Generalized Linear Models and alike

> weighted regression function
$$\mathbf{f}_{\boldsymbol{\beta}}(\mathbf{x}) = q(\mathbf{f}(\mathbf{x})^{\mathsf{T}}\boldsymbol{\beta})\mathbf{f}(\mathbf{x})$$

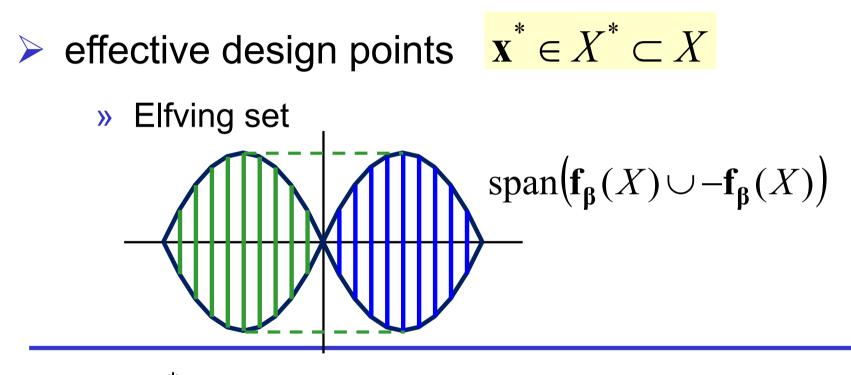
$$\mathbf{f}(\mathbf{x})^{\mathsf{T}}\mathbf{\beta} = c$$

» with weight q as a function of the linear predictor $\mathbf{f}(\mathbf{x})^{\mathsf{T}} \mathbf{\beta} = \beta_0 + \beta_1 x_1 + \ldots + \beta_K x_K$

$$X = [\mathbf{0}.\infty)^K$$



Majorization II



» X^* set of x^* such that Elfving 1952 $\mathbf{f}_{\beta}(\mathbf{x}^*)$ extremal point of the Elfving set

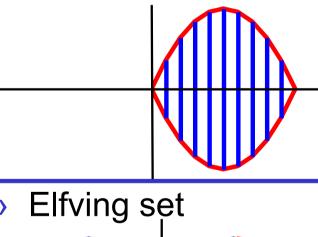
$$\mathbf{M}(\mathbf{x};\boldsymbol{\beta}) = \sum w_j \mathbf{M}(\mathbf{x}_j^*;\boldsymbol{\beta})$$

Graßhoff/Großmann/Holling/Sch. 2001

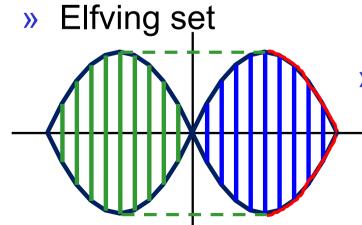
> quadratic paired comparison

$$\mathbf{f}(\mathbf{x}) = (x_1 - x_2, x_1^2 - x_2^2)^{\mathsf{T}}$$

» induced design region: shaded area



reduced design region:
 boundary of the shaded area



 reduced design region:
 boundary to the right of the shaded area

3 Invariance and Equivariance

Ford/Torsney/Wu 1992

> equivariance

- » transformation $g: X \to g(X)$ such that $\mathbf{f}_{\beta}(g(\mathbf{x})) = \mathbf{Q}\mathbf{f}_{\beta}(\mathbf{x})$ \mathbf{f}_{β} and gcompatible
 - » ξ * optimal on $X \Rightarrow g(\xi$ *) optimal on g(X)
- invariance
 Giovagnoli/Pukelsheim/Wynn 1987, Sch. 1996
 - » group of transformations $g: X \to X$

(permutations, sign change, rotations ...)

» invariant optimal designs

$$g(\xi^*) = \xi^*$$

F. Freise/Holling/Sch. 2018

$$\mathbf{f}(\mathbf{x}) = (\mathbf{1}, x_1, x_2, \dots, x_K)^{\mathsf{T}} \qquad X \subset \{\mathbf{0}, \mathbf{1}\}^K$$

» restricted design region

multiple binary predictors

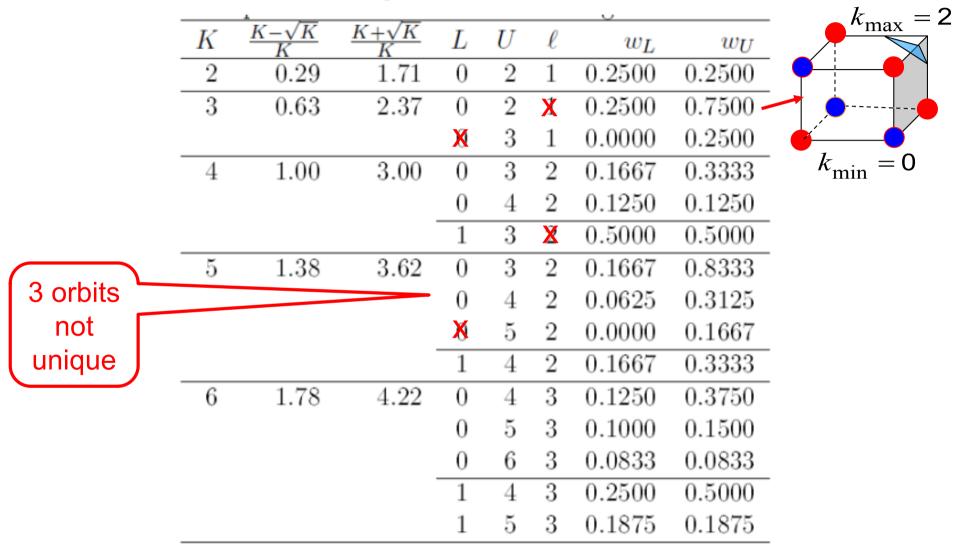
$$k_{\min} \le x_1 + x_2 + \ldots + x_K \le k_{\max}$$

» optimal designs invariant (uniform) on orbits $\{\mathbf{x}; x_1 + x_2 + \ldots + x_K = k\}$ of equal number of active factors

»
$$(K - \sqrt{K})/2 \le k_{\min} < k_{\max} \le (K + \sqrt{K})/2$$

» sensitivity function quadratic in k
optimal design uniform on the orbits
 k_{\min} and k_{\max}

Example (continued)

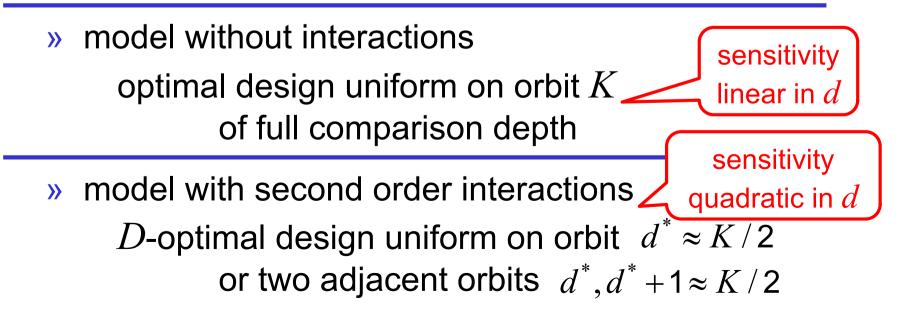


» sensitivity function constant in k information equal to full factorial (without restriction)

paired comparisons (with interactions)

$$\mathbf{f}(\mathbf{x}) = (x_{1k} - x_{2k}, \dots, x_{1k}x_{1\ell} - x_{2k}x_{2\ell}, \dots)^{-1}$$

» optimal designs invariant (uniform) on orbits of equal comparison depth d{**x**;#{ $k; x_{1k} \neq x_{2k}$ } = d}



Example (continued)

E. Nyarko/Sch. 2018

» model with second order interactions

K	d^*	W*
3	1	0.750
4	2	0.857
5	2	0.833
6	3	0.732
7	3	0.697
8	(3)	0.609
9	4	0.577
10	4	0.538

» *D*-optimal design uniform on two orbits K and d^* with weight w^* on d^*

M. Radloff/Sch. 2018

\succ Poisson regression on a ball X $\mathbf{f}_{\mathbf{\beta}}(\mathbf{x}) = \exp(\mathbf{f}(\mathbf{x})^{\mathsf{T}}\mathbf{\beta}/2)\mathbf{f}(\mathbf{x})$ $\arg \max(\mathbf{f}(\mathbf{x})^{\mathsf{T}} \boldsymbol{\beta})$ β

» D-optimal design

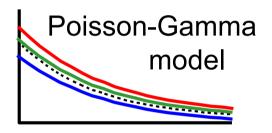
on *K*+1 points on the surface with equal weights



Schmelter 2007, M. Schmidt/Sch. 2018

» estimation

in linear and generalized linear mixed models

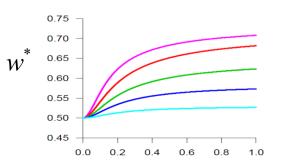


single-group designs are optimal

» prediction

invariance -> balancing

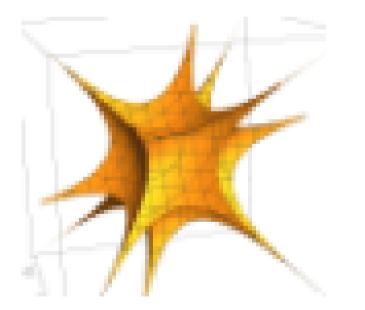
M. Prus/Benda/Sch. 2018



F. Röttger/Kahle/Sch. 2018

Bradley-Terry model

» paired comparisons (4 alternatives)



» optimality regions in the parameter space -> poster

4 Constructions for Multiple Factors

additive linear models

Cook and Thibodeau 1980, Sch./Wierich 1995, Sch. 1996 ξ_k^* D-optimal in the K marginal models $Y_k(x_k) = \mu_k + \mathbf{f}_k(x_k)^{\mathsf{T}} \mathbf{\beta}_k + \varepsilon$ $X_1 \times X_2$ then $\xi^* = \xi_1^* \otimes ... \otimes \xi_k^*$ is D-optimal in the additive model ξı $Y(x_1,\ldots,x_K) = \mu_0 + \mathbf{f}_1(x_1)^{\mathsf{T}} \boldsymbol{\beta}_1 + \ldots + \mathbf{f}_K(x_K)^{\mathsf{T}} \boldsymbol{\beta}_K + \varepsilon$

GLM: Additive Predictors (multiple regression)

$$\mu(x_1, x_2, \dots, x_K) = \mu_0 + x_1 \beta_1 + \dots + x_K \beta_K$$

$$\Rightarrow \text{ design regions } X_k = [0, \infty)$$

D. Schmidt/Sch. 2017

> ξ_k^* with support 0 and x_k^* *D*-optimal in the univariate models, then the design

$$\mathbf{x}_{k}^{*} = x_{k}^{*}\mathbf{e}_{k}, k = 1,...,K, \ \mathbf{x}_{K+1}^{*} = \mathbf{0}$$

with equal weights 1/(K+1)

is *D*-optimal in the additive model

» also valid in GLMMs

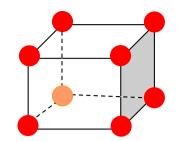
M. Schmidt/Sch. 2018

 $\mathcal{X}_{\mathbf{1}}$

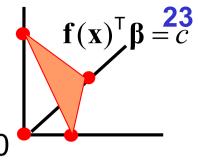
5 Final Considerations

- For high-dimensional models computational burden can be reduced
- invariant and product-type designs have a quite high number of design points
 - » potential reduction by fractional factorials or discretization
- but these designs may serve as a benchmark





Simplify Designs:



Reduction Principles Revisited

