

An Introduction to the BV-BFV Formalism

Alberto Cattaneo

Institut für Mathematik, Universität Zürich

Based on joint work with P. Mnëv, N. Moshayedi, N. Reshetikhin, M. Schiavina, K. Wernli

Outline

- 1 **Differential Graded Symplectic Manifolds**
- 2 **BFⁿV structures**
 - BFV
 - BV
- 3 **Relaxed BFⁿV Structures**
- 4 **Quantization**
 - BFV-BF²V
 - BV-BFV

Graded manifolds

- A **graded manifold** is “like a manifold,” but we also allow **odd local coordinates**.
- The odd coordinates anticommute with themselves and commute with the even coordinates.
- We also assign a \mathbb{Z} -degree to coordinates (in physics **ghost number**). In this talk, I will assume *parity = \mathbb{Z} -degree modulo 2*
- If M is a graded manifold, then $C^\infty(M)$ is a **graded commutative algebra**.
- Example: $M = T[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates v^j degree +1.
 - $C^\infty(M) = \Omega^*(N)$.

Graded manifolds

- A **graded manifold** is “like a manifold,” but we also allow **odd local coordinates**.
- The odd coordinates anticommute with themselves and commute with the even coordinates.
- We also assign a \mathbb{Z} -degree to coordinates (in physics **ghost number**). In this talk, I will assume *parity = \mathbb{Z} -degree modulo 2*
- If M is a graded manifold, then $C^\infty(M)$ is a **graded commutative algebra**.
- Example: $M = T[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates v^j degree +1.
 - $C^\infty(M) = \Omega^*(N)$.

Graded manifolds

- A **graded manifold** is “like a manifold,” but we also allow **odd local coordinates**.
- The odd coordinates anticommute with themselves and commute with the even coordinates.
- We also assign a \mathbb{Z} -degree to coordinates (in physics **ghost number**). In this talk, I will assume *parity = \mathbb{Z} -degree modulo 2*
- If M is a graded manifold, then $C^\infty(M)$ is a **graded commutative algebra**.
- Example: $M = T[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates v^j degree +1.
 - $C^\infty(M) = \Omega^*(N)$.

Graded manifolds

- A **graded manifold** is “like a manifold,” but we also allow **odd local coordinates**.
- The odd coordinates anticommute with themselves and commute with the even coordinates.
- We also assign a \mathbb{Z} -degree to coordinates (in physics **ghost number**). In this talk, I will assume *parity = \mathbb{Z} -degree modulo 2*
- If M is a graded manifold, then $C^\infty(M)$ is a **graded commutative algebra**.
- Example: $M = T[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates v^j degree +1.
 - $C^\infty(M) = \Omega^\bullet(N)$.

Cohomological vector fields

- If M is a graded manifold, a differential on $C^\infty(M)$ has been called by Vaintrob a cohomological vector field (cvf).
- Explanation:
 - Derivation on $C^\infty(M)$ = vector field Q on M .
 - Differential = $\text{deg } Q = 1$ and $[Q, Q] = 0$.
- Example: $M = T[1]N$, N an ordinary manifolds.
The de Rham differential on N is a cvf on $C^\infty(M)$: $Q = \sum_i v^i \frac{\partial}{\partial q^i}$
- Example: $M = \mathfrak{g}[1]$, \mathfrak{g} a Lie algebra:
 - All coordinates c_i have degree 1.
 - $C^\infty(M) = \Lambda^* \mathfrak{g}^*$.
 - The Chevalley–Eilenberg differential on \mathfrak{g} is a cvf:

$$Q = \frac{1}{2} \sum_{ijk} f_k^{ij} c_i c_j \frac{\partial}{\partial c_k}$$

with f_k^{ij} the structure constants. (In physics the BRST operator.)

Cohomological vector fields

- If M is a graded manifold, a differential on $C^\infty(M)$ has been called by Vaintrob a cohomological vector field (cvf).
- Explanation:
 - Derivation on $C^\infty(M)$ = vector field Q on M .
 - Differential = $\text{deg } Q = 1$ and $[Q, Q] = 0$.
- Example: $M = T[1]N$, N an ordinary manifolds.
The de Rham differential on N is a cvf on $C^\infty(M)$: $Q = \sum_i v^i \frac{\partial}{\partial q^i}$
- Example: $M = \mathfrak{g}[1]$, \mathfrak{g} a Lie algebra:
 - All coordinates c_i have degree 1.
 - $C^\infty(M) = \Lambda^* \mathfrak{g}^*$.
 - The Chevalley–Eilenberg differential on \mathfrak{g} is a cvf:

$$Q = \frac{1}{2} \sum_{ijk} f_k^{ij} c_i c_j \frac{\partial}{\partial c_k}$$

with f_k^{ij} the structure constants. (In physics the BRST operator.)

Cohomological vector fields

- If M is a graded manifold, a differential on $C^\infty(M)$ has been called by Vaintrob a cohomological vector field (cvf).
- Explanation:
 - Derivation on $C^\infty(M)$ = vector field Q on M .
 - Differential = $\text{deg } Q = 1$ and $[Q, Q] = 0$.
- Example: $M = T[1]N$, N an ordinary manifolds.

The de Rham differential on N is a cvf on $C^\infty(M)$: $Q = \sum_i v^i \frac{\partial}{\partial q^i}$

- Example: $M = \mathfrak{g}[1]$, \mathfrak{g} a Lie algebra:
 - All coordinates c_i have degree 1.
 - $C^\infty(M) = \Lambda^* \mathfrak{g}^*$.
 - The Chevalley–Eilenberg differential on \mathfrak{g} is a cvf:

$$Q = \frac{1}{2} \sum_{ijk} f_k^{ij} c_i c_j \frac{\partial}{\partial c_k}$$

with f_k^{ij} the structure constants. (In physics the BRST operator.)

Cohomological vector fields

- If M is a graded manifold, a differential on $C^\infty(M)$ has been called by Vaintrob a cohomological vector field (cvf).
- Explanation:
 - Derivation on $C^\infty(M)$ = vector field Q on M .
 - Differential = $\text{deg } Q = 1$ and $[Q, Q] = 0$.
- Example: $M = T[1]N$, N an ordinary manifolds.
The de Rham differential on N is a cvf on $C^\infty(M)$: $Q = \sum_i v^i \frac{\partial}{\partial q^i}$
- Example: $M = \mathfrak{g}[1]$, \mathfrak{g} a Lie algebra:
 - All coordinates c_i have degree 1.
 - $C^\infty(M) = \Lambda^\bullet \mathfrak{g}^*$.
 - The Chevalley–Eilenberg differential on \mathfrak{g} is a cvf:

$$Q = \frac{1}{2} \sum_{ijk} f_k^{ij} c_i c_j \frac{\partial}{\partial c_k}$$

with f_k^{ij} the structure constants. (In physics the BRST operator.)

Graded symplectic forms

- A **graded symplectic form** ω of degree n is a **closed, nondegenerate 2-form** with internal degree equal to n .
- Example: $M = T^*[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates p_i degree 1.
 - $C^\infty(M) = \mathfrak{X}^*(N)$ (multivector fields).
 - $\omega = \sum_i dp_i dq^i$ is a **graded symplectic form of degree 1**.
 - The Schouten–Nijenhuis bracket on multivector fields is the associated Poisson bracket.
- This may be generalized to $M = T^*[n]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates p_i degree n .
 - $\omega = \sum_i dp_i dq^i$ is a **graded symplectic form of degree n** .

Graded symplectic forms

- A **graded symplectic form** ω of degree n is a **closed, nondegenerate 2-form** with internal degree equal to n .
- Example: $M = T^*[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates p_i degree 1.
 - $C^\infty(M) = \mathfrak{X}^\bullet(N)$ (multivector fields).
 - $\omega = \sum_i dp_i dq^i$ is a **graded symplectic form of degree 1**.
 - The Schouten–Nijenhuis bracket on multivector fields is the associated Poisson bracket.
- This may be generalized to $M = T^*[n]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates p_i degree n .
 - $\omega = \sum_i dp_i dq^i$ is a **graded symplectic form of degree n** .

Graded symplectic forms

- A **graded symplectic form** ω of degree n is a **closed, nondegenerate 2-form** with internal degree equal to n .
- Example: $M = T^*[1]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates p_i degree 1.
 - $C^\infty(M) = \mathfrak{X}^\bullet(N)$ (multivector fields).
 - $\omega = \sum_i dp_i dq^i$ is a **graded symplectic form of degree 1**.
 - The Schouten–Nijenhuis bracket on multivector fields is the associated Poisson bracket.
- This may be generalized to $M = T^*[n]N$, N an ordinary manifold:
 - Coordinates q^i on N degree 0; fiber coordinates p_i degree n .
 - $\omega = \sum_i dp_i dq^i$ is a **graded symplectic form of degree n** .

Differential graded symplectic structure

- A differential graded symplectic structure of degree n on a graded manifold M is a pair (ω, Q) where:
 - ω is a graded symplectic form of degree n , and
 - Q is a symplectic cvf, i.e.,

$$L_Q \omega = 0 \quad \text{and} \quad [Q, Q] = 0$$

- A stronger version is when Q is Hamiltonian, i.e., there is a function S (necessarily of degree $n+1$) such that

$$L_Q \omega = dS \quad \text{and} \quad \{S, S\} = 0 \quad (\text{classical master equation})$$

- As observed by Roytenberg, if $n \neq -1$, a symplectic cvf is always Hamiltonian (with a unique Hamiltonian function):

$$S = \frac{1}{n+1} \iota_E \iota_Q \omega$$

with E the “graded Euler vector field”: $E(f) = \deg f f$.

Differential graded symplectic structure

- A differential graded symplectic structure of degree n on a graded manifold M is a pair (ω, Q) where:
 - ω is a graded symplectic form of degree n , and
 - Q is a symplectic cvf, i.e.,

$$L_Q \omega = 0 \quad \text{and} \quad [Q, Q] = 0$$

- A stronger version is when Q is Hamiltonian, i.e., there is a function S (necessarily of degree $n+1$) such that

$$\iota_{Q^*} \omega = dS \quad \text{and} \quad \{S, S\} = 0 \quad (\text{classical master equation})$$

- As observed by Roytenberg, if $n \neq -1$, a symplectic cvf is always Hamiltonian (with a unique Hamiltonian function):

$$S = \frac{1}{n+1} \iota_{E} \iota_{Q^*} \omega$$

with E the “graded Euler vector field”: $E(f) = \deg f f$.

Differential graded symplectic structure

- A differential graded symplectic structure of degree n on a graded manifold M is a pair (ω, Q) where:
 - ω is a graded symplectic form of degree n , and
 - Q is a symplectic cvf, i.e.,

$$L_Q \omega = 0 \quad \text{and} \quad [Q, Q] = 0$$

- A stronger version is when Q is Hamiltonian, i.e., there is a function S (necessarily of degree $n+1$) such that

$$\iota_Q \omega = dS \quad \text{and} \quad \{S, S\} = 0 \quad (\text{classical master equation})$$

- As observed by Roytenberg, if $n \neq -1$, a symplectic cvf is always Hamiltonian (with a unique Hamiltonian function):

$$S = \frac{1}{n+1} \iota_{E} \iota_Q \omega$$

with E the “graded Euler vector field”: $E(f) = \deg f f$.

Examples of differential graded symplectic structures

- Example: $M = T^*[1]N$, N an ordinary manifold:
 - A function S of degree 2 on M is then the same as a bivector field π on N .
 - The master equation $\{S, S\} = 0$ translates to $[\pi, \pi] = 0$; i.e., π is a Poisson bivector field.
 - Q is then the Poisson–Lichnerowicz differential.
- Example: $M = \mathfrak{g}[1]$, \mathfrak{g} a Lie algebra:
 - A nondegenerate symmetric bilinear form on \mathfrak{g} can be viewed as a constant symplectic form of degree 2 on $\mathfrak{g}[1]$.
 - If Q corresponds to the Chevalley–Eilenberg differential, it is symplectic iff the pairing is invariant.
 - The corresponding Hamiltonian function turns out to be

$$S = \frac{1}{6} \sum f^{ijk} c_i c_j c_k$$

with f^{ijk} the structure constants with one index raised by using the pairing.

Examples of differential graded symplectic structures

- Example: $M = T^*[1]N$, N an ordinary manifold:
 - A function S of degree 2 on M is then the same as a bivector field π on N .
 - The master equation $\{S, S\} = 0$ translates to $[\pi, \pi] = 0$; i.e., π is a **Poisson bivector field**.
 - Q is then the Poisson–Lichnerowicz differential.
- Example: $M = \mathfrak{g}[1]$, \mathfrak{g} a Lie algebra:
 - A **nondegenerate symmetric bilinear form** on \mathfrak{g} can be viewed as a constant symplectic form of degree 2 on $\mathfrak{g}[1]$.
 - If Q corresponds to the Chevalley–Eilenberg differential, it is symplectic iff the pairing is invariant.
 - The corresponding Hamiltonian function turns out to be

$$S = \frac{1}{6} \sum f^{ijk} c_i c_j c_k$$

with f^{ijk} the structure constants with one index raised by using the pairing.

BFⁿV structures

There are three important particular cases:

- $n = -1$ This is the **Batalin–Vilkovisky (BV)** formalism used in QFT. The Hamiltonian function is required to exist as an extra assumption.
- $n = 0$ This is the **Batalin–Fradkin–Vilkovisky (BFV)** formalism used to give a cohomological resolution of symplectic reduction (see next).
- $n = 1$ If there are only coordinates of nonnegative degree, this is just the example of $M = T^*[1]N$ with a **Poisson** structure on N .
More generally, it describes Poisson structures up to homotopy (i.e., the Poisson bracket is an L_∞ -structure).

We may call the general case of degree n a **BFⁿ⁺¹V** structure.

$$\text{Poisson}_\infty = \text{BF}^2\text{V}$$

BFⁿV structures

There are three important particular cases:

- $n = -1$ This is the **Batalin–Vilkovisky (BV)** formalism used in QFT. The Hamiltonian function is required to exist as an extra assumption.
- $n = 0$ This is the **Batalin–Fradkin–Vilkovisky (BFV)** formalism used to give a cohomological resolution of symplectic reduction (see next).
- $n = 1$ If there are only coordinates of nonnegative degree, this is just the example of $M = T^*[1]N$ with a **Poisson** structure on N .
More generally, it describes Poisson structures up to homotopy (i.e., the Poisson bracket is an L_∞ -structure).

We may call the general case of degree n a **BFⁿ⁺¹V** structure.

$$\text{Poisson}_\infty = \text{BF}^2\text{V}$$

BFⁿV structures

There are three important particular cases:

- $n = -1$ This is the **Batalin–Vilkovisky (BV)** formalism used in QFT. The Hamiltonian function is required to exist as an extra assumption.
- $n = 0$ This is the **Batalin–Fradkin–Vilkovisky (BFV)** formalism used to give a cohomological resolution of symplectic reduction (see next).
- $n = 1$ If there are only coordinates of nonnegative degree, this is just the example of $M = T^*[1]N$ with a **Poisson** structure on N .
More generally, it describes Poisson structures up to homotopy (i.e., the Poisson bracket is an L_∞ -structure).

We may call the general case of degree n a **BFⁿ⁺¹V** structure.

$$\text{Poisson}_\infty = \text{BF}^2\text{V}$$

BFⁿV structures

There are three important particular cases:

- $n = -1$ This is the **Batalin–Vilkovisky (BV)** formalism used in QFT. The Hamiltonian function is required to exist as an extra assumption.
- $n = 0$ This is the **Batalin–Fradkin–Vilkovisky (BFV)** formalism used to give a cohomological resolution of symplectic reduction (see next).
- $n = 1$ If there are only coordinates of nonnegative degree, this is just the example of $M = T^*[1]N$ with a **Poisson** structure on N .
More generally, it describes Poisson structures up to homotopy (i.e., the Poisson bracket is an L_∞ -structure).

We may call the general case of degree n a **BFⁿ⁺¹V** structure.

$$\text{Poisson}_\infty = \text{BF}^2\text{V}$$

BFⁿV structures

There are three important particular cases:

- $n = -1$ This is the **Batalin–Vilkovisky (BV)** formalism used in QFT. The Hamiltonian function is required to exist as an extra assumption.
- $n = 0$ This is the **Batalin–Fradkin–Vilkovisky (BFV)** formalism used to give a cohomological resolution of symplectic reduction (see next).
- $n = 1$ If there are only coordinates of nonnegative degree, this is just the example of $M = T^*[1]N$ with a **Poisson** structure on N .
More generally, it describes Poisson structures up to homotopy (i.e., the Poisson bracket is an L_∞ -structure).

We may call the general case of degree n a **BFⁿ⁺¹V** structure.

$$\text{Poisson}_\infty = \text{BF}^2\text{V}$$

BFⁿV structures

There are three important particular cases:

- $n = -1$ This is the **Batalin–Vilkovisky (BV)** formalism used in QFT. The Hamiltonian function is required to exist as an extra assumption.
- $n = 0$ This is the **Batalin–Fradkin–Vilkovisky (BFV)** formalism used to give a cohomological resolution of symplectic reduction (see next).
- $n = 1$ If there are only coordinates of nonnegative degree, this is just the example of $M = T^*[1]N$ with a **Poisson** structure on N .
More generally, it describes Poisson structures up to homotopy (i.e., the Poisson bracket is an L_∞ -structure).

We may call the general case of degree n a **BFⁿ⁺¹V** structure.

$$\text{Poisson}_\infty = \text{BF}^2\text{V}$$

Symplectic reduction in codimension one (BFV)

- Let (N, ω_N) be a symplectic manifold, ϕ a function and $C := \phi^{-1}(0)$ a submanifold.
- The restriction of ω_N to C is degenerate. Its kernel is generated by the Hamiltonian vector field X_ϕ of ϕ :

$$\iota_{X_\phi} \omega_N = d\phi \approx 0$$

- We define $\underline{C} = C/X_\phi$. Algebraically,

$$C^\infty(\underline{C}) = (C^\infty(N) / \langle \phi \rangle)^{X_\phi} = N(\langle \phi \rangle) / \langle \phi \rangle,$$

with $N(\langle \phi \rangle) = \{f \in C^\infty(N) : \{\phi, f\} = g\phi, g \in C^\infty(N)\}$.

- Define $M = N \times T^*\mathbb{R}[1]$, $\omega = \omega_N + dbdc$, $S = c\phi$ a dgs manifold of degree 0. Then

$$Qb = \phi, \quad Qf = \{\phi, f\}c, \quad Qc = 0.$$

In particular, in degree 0 and -1 :

$$Q(f + gcb) = \{\phi, f\}c - g\phi c, \quad Q(hb) = h\phi + \{\phi, h\}cb.$$

Hence $H_0^0(M) = C^\infty(\underline{C})$.



Symplectic reduction in codimension one (BFV)

- Let (N, ω_N) be a symplectic manifold, ϕ a function and $C := \phi^{-1}(0)$ a submanifold.
- The restriction of ω_N to C is degenerate. Its kernel is generated by the Hamiltonian vector field X_ϕ of ϕ :

$$\iota_{X_\phi} \omega_N = d\phi \approx 0$$

- We define $\underline{C} = C/X_\phi$. Algebraically,

$$C^\infty(\underline{C}) = (C^\infty(N) / \langle \phi \rangle)^{X_\phi} = N(\langle \phi \rangle) / \langle \phi \rangle,$$

with $N(\langle \phi \rangle) = \{f \in C^\infty(N) : \{\phi, f\} = g\phi, g \in C^\infty(N)\}$.

- Define $M = N \times T^*\mathbb{R}[1]$, $\omega = \omega_N + dbdc$, $S = c\phi$ a dgs manifold of degree 0. Then

$$Qb = \phi, \quad Qf = \{\phi, f\}c, \quad Qc = 0.$$

In particular, in degree 0 and -1 :

$$Q(f + gcb) = \{\phi, f\}c - g\phi c, \quad Q(hb) = h\phi + \{\phi, h\}cb.$$

Hence $H_0^0(M) = C^\infty(\underline{C})$.

Symplectic reduction in codimension one (BFV)

- Let (N, ω_N) be a symplectic manifold, ϕ a function and $C := \phi^{-1}(0)$ a submanifold.
- The restriction of ω_N to C is degenerate. Its kernel is generated by the Hamiltonian vector field X_ϕ of ϕ :

$$\iota_{X_\phi} \omega_N = d\phi \approx 0$$

- We define $\underline{C} = C/X_\phi$. Algebraically,

$$C^\infty(\underline{C}) = (C^\infty(N) / \langle \phi \rangle)^{X_\phi} = N(\langle \phi \rangle) / \langle \phi \rangle,$$

with $N(\langle \phi \rangle) = \{f \in C^\infty(N) : \{\phi, f\} = g\phi, g \in C^\infty(N)\}$.

- Define $M = N \times T^*\mathbb{R}[1]$, $\omega = \omega_N + dbdc$, $S = c\phi$ a dgs manifold of degree 0. Then

$$Qb = \phi, \quad Qf = \{\phi, f\}c, \quad Qc = 0.$$

In particular, in degree 0 and -1 :

$$Q(f + gcb) = \{\phi, f\}c - g\phi c, \quad Q(hb) = h\phi + \{\phi, h\}cb.$$

Hence $H_Q^0(M) = C^\infty(\underline{C})$.

Symplectic reduction of coisotropic submanifolds

- The previous slide may be generalized to the case when we have a set of r functions ϕ^i and a submanifold

$$C := \{x \in N : \phi^i(x) = 0 \ i = 1, \dots, r\}$$

- Assume that C is **coisotropic**, i.e., $\{\phi^i, \phi^j\}|_C = 0 \ \forall i, j$.
- The kernel of the restriction of ω_N to C is generated by the Hamiltonian vector fields of the ϕ^i 's. We denote by \underline{C} the quotient of C by this kernel. (The **reduced phase space**.)
- The main result by BFV and Stasheff is that

$$C^\infty(\underline{C}) = H_0^0(M) \quad \text{as Poisson algebras}$$

with: $M = N \times T^*\mathbb{R}^r[1]$, $\omega = \omega_N + \sum_{i=1}^r db^i dc_i$,

$$S = \sum_{i=1}^r c_i \phi^i + \dots$$

where the dots contain higher powers of the b^i 's and are obtained by cohomological perturbation theory.

Symplectic reduction of coisotropic submanifolds

- The previous slide may be generalized to the case when we have a set of r functions ϕ^i and a submanifold

$$C := \{x \in N : \phi^i(x) = 0 \ i = 1, \dots, r\}$$

- Assume that C is **coisotropic**, i.e., $\{\phi^i, \phi^j\}|_C = 0 \ \forall i, j$.
- The kernel of the restriction of ω_N to C is generated by the Hamiltonian vector fields of the ϕ^i 's. We denote by \underline{C} the quotient of C by this kernel. (The **reduced phase space**.)
- The main result by BFV and Stasheff is that

$$C^\infty(\underline{C}) = H_Q^0(M) \quad \text{as Poisson algebras}$$

with: $M = N \times T^*\mathbb{R}^r[1]$, $\omega = \omega_N + \sum_{i=1}^r db^i dc_i$,

$$S = \sum_{i=1}^r c_i \phi^i + \dots$$

where the dots contain higher powers of the b^i 's and are obtained by cohomological perturbation theory.

Equivariant momentum map

- A special case is when the ϕ^i are the components of an equivariant momentum map $\phi: N \rightarrow \mathfrak{g}^*$.
- In this case we have

$$S = \sum_{i=1}^r c_i \phi^i + \frac{1}{2} \sum f_k^{ij} b^k c_i c_j$$

- Q in this case is also called the BRS operator.

The BV formalism

- Let \mathcal{F} be an odd finite dimensional symplectic manifold. By results of Batalin–Vilkovisky, Witten, Schwarz, Khudaverdian, Ševera. . . :
 - ① Half densities on \mathcal{F} naturally define densities on Lagrangian submanifolds of \mathcal{F} , so they can be integrated.
 - ② There is a canonically defined operator Δ on half densities satisfying $\Delta^2 = 0$.
 - ③ $\int_{\mathcal{L}} \Delta \rho = 0$, for \mathcal{L} Lagrangian, ρ half density.
 - ④ $\frac{d}{dt} \int_{\mathcal{L}_t} \sigma = 0$ if $\Delta \sigma = 0$ and \mathcal{L}_t a family of Lagrangian submanifolds.
- Main example: $\mathcal{F} = \Pi T^*M$, M manifold.
Then half densities on \mathcal{F} = differential forms on M ,
 $\int_{\Pi N^*C} \rho = \int_C \rho$, $\Delta \equiv d$.
- Application: Use \mathcal{L} as a gauge fixing.
Idea: $\int_{\mathcal{L}_0}$ ill defined, so deform to $\int_{\mathcal{L}_t}$, $t \neq 0$.

The BV formalism

- Let \mathcal{F} be an odd finite dimensional symplectic manifold. By results of Batalin–Vilkovisky, Witten, Schwarz, Khudaverdian, Ševera. . . :
 - ① Half densities on \mathcal{F} naturally define densities on Lagrangian submanifolds of \mathcal{F} , so they can be integrated.
 - ② There is a canonically defined operator Δ on half densities satisfying $\Delta^2 = 0$.
 - ③ $\int_{\mathcal{L}} \Delta \rho = 0$, for \mathcal{L} Lagrangian, ρ half density.
 - ④ $\frac{d}{dt} \int_{\mathcal{L}_t} \sigma = 0$ if $\Delta \sigma = 0$ and \mathcal{L}_t a family of Lagrangian submanifolds.
- Main example: $\mathcal{F} = \Pi T^*M$, M manifold.
Then half densities on \mathcal{F} = differential forms on M ,

$$\int_{\Pi N^*C} \rho = \int_C \rho, \quad \Delta \equiv d.$$
- Application: Use \mathcal{L} as a gauge fixing.
Idea: $\int_{\mathcal{L}_0}$ ill defined, so deform to $\int_{\mathcal{L}_t}$, $t \neq 0$.

The BV formalism

- Let \mathcal{F} be an odd finite dimensional symplectic manifold. By results of Batalin–Vilkovisky, Witten, Schwarz, Khudaverdian, Ševera. . . :
 - ① Half densities on \mathcal{F} naturally define densities on Lagrangian submanifolds of \mathcal{F} , so they can be integrated.
 - ② There is a canonically defined operator Δ on half densities satisfying $\Delta^2 = 0$.
 - ③ $\int_{\mathcal{L}} \Delta \rho = 0$, for \mathcal{L} Lagrangian, ρ half density.
 - ④ $\frac{d}{dt} \int_{\mathcal{L}_t} \sigma = 0$ if $\Delta \sigma = 0$ and \mathcal{L}_t a family of Lagrangian submanifolds.
- Main example: $\mathcal{F} = \Pi T^*M$, M manifold.
Then half densities on \mathcal{F} = differential forms on M ,
 $\int_{\Pi N^*C} \rho = \int_C \rho, \quad \Delta \equiv d$.
- **Application: Use \mathcal{L} as a gauge fixing.**
Idea: $\int_{\mathcal{L}_0}$ ill defined, so deform to $\int_{\mathcal{L}_t}, t \neq 0$.

The master equation

- Fix a half density ρ with $\Delta\rho = 0$. On functions define Δ by

$$\Delta f := \frac{\Delta(f\rho)}{\rho}.$$

- In view of applications to path integrals, consider $f = e^{\frac{i}{\hbar}S}$. Then $\Delta f = 0$ corresponds to the **Quantum Master Equation (QME)**

$$\frac{1}{2}(S, S) - i\hbar\Delta S = 0$$

Either working with $\hbar \rightarrow 0$ or assuming $\Delta S = 0$, we get the **Classical Master Equation (CME)**

$$(S, S) = 0$$

- The main point here is that the CME may be defined on infinite dimensional manifolds (needed in field theory). Integration together with the actual definition of Δ are deferred to a second step (e.g., perturbative path integral quantization).

The master equation

- Fix a half density ρ with $\Delta\rho = 0$. On functions define Δ by

$$\Delta f := \frac{\Delta(f\rho)}{\rho}.$$

- In view of applications to path integrals, consider $f = e^{\frac{i}{\hbar}S}$. Then $\Delta f = 0$ corresponds to the **Quantum Master Equation (QME)**

$$\frac{1}{2}(S, S) - i\hbar\Delta S = 0$$

Either working with $\hbar \rightarrow 0$ or assuming $\Delta S = 0$, we get the **Classical Master Equation (CME)**

$$(S, S) = 0$$

- The main point here is that the CME may be defined on infinite dimensional manifolds (needed in field theory). Integration together with the actual definition of Δ are deferred to a second step (e.g., perturbative path integral quantization).

The master equation

- Fix a half density ρ with $\Delta\rho = 0$. On functions define Δ by

$$\Delta f := \frac{\Delta(f\rho)}{\rho}.$$

- In view of applications to path integrals, consider $f = e^{\frac{i}{\hbar}S}$. Then $\Delta f = 0$ corresponds to the **Quantum Master Equation (QME)**

$$\frac{1}{2}(S, S) - i\hbar\Delta S = 0$$

Either working with $\hbar \rightarrow 0$ or assuming $\Delta S = 0$, we get the **Classical Master Equation (CME)**

$$(S, S) = 0$$

- The main point here is that the CME may be defined on infinite dimensional manifolds (needed in field theory). Integration together with the actual definition of Δ are deferred to a second step (e.g., perturbative path integral quantization).

The master equation

- Fix a half density ρ with $\Delta\rho = 0$. On functions define Δ by

$$\Delta f := \frac{\Delta(f\rho)}{\rho}.$$

- In view of applications to path integrals, consider $f = e^{\frac{i}{\hbar}S}$. Then $\Delta f = 0$ corresponds to the **Quantum Master Equation (QME)**

$$\frac{1}{2}(S, S) - i\hbar\Delta S = 0$$

Either working with $\hbar \rightarrow 0$ or assuming $\Delta S = 0$, we get the **Classical Master Equation (CME)**

$$(S, S) = 0$$

- The main point here is that the CME may be defined on infinite dimensional manifolds (needed in field theory). Integration together with the actual definition of Δ are deferred to a second step (e.g., perturbative path integral quantization).

Further remarks

- It is convenient to introduce a \mathbb{Z} -grading (For simplicity in this talk: parity = \mathbb{Z} -grading modulo 2.).
- One then assigns degrees so that S has degree zero and its Hamiltonian vector field Q

$$\iota_Q \omega = \delta S$$

has degree 1. This forces ω to have degree -1 .

- This way we have returned to differential graded symplectic manifolds of degree -1 : i.e., BV.
- Note that in physics, degree 0 corresponds to physical fields. We want the the action to be an extension of the physical action: this is why we require degree 0.

Further remarks

- It is convenient to introduce a \mathbb{Z} -grading (For simplicity in this talk: parity = \mathbb{Z} -grading modulo 2.).
- One then assigns degrees so that S has degree zero and its Hamiltonian vector field Q

$$\iota_Q \omega = \delta S$$

has degree 1. This forces ω to have degree -1 .

- This way we have returned to differential graded symplectic manifolds of degree -1 : i.e., BV.
- Note that in physics, degree 0 corresponds to physical fields. We want the the action to be an extension of the physical action: this is why we require degree 0.

Example: gauge theories

- Suppose we have a gauge theory with space of fields F_M , a local action functional S_M^0 and a gauge group acting on it.
- We denote by ϕ the fields, by c the ghosts and by δ_{BRST} the BRST operator. We assign degrees by $|\phi| = 0$ and $|c| = 1$.
- We introduce antifields ϕ^+ , c^+ with opposite nature than the field, opposite parity and degrees given by $|\phi^+| = -1$ and $|c^+| = -2$.
- We denote by \mathcal{F}_M the space of all the (ϕ, c, ϕ^+, c^+) 's and we set

$$S_M = S_M^0(\phi) + \int_M (\phi^+ \delta_{\text{BRST}}\phi + c^+ \delta_{\text{BRST}}c),$$

$$\omega_M = \int_M (\delta\phi^+ \delta\phi + \delta c^+ \delta c)$$

- Then, if $\partial M = \emptyset$, the BV action S satisfies the CME.
- We usually consider these “BRST-like” theories, but there are more general examples.

Example: gauge theories

- Suppose we have a gauge theory with space of fields F_M , a local action functional S_M^0 and a gauge group acting on it.
- We denote by ϕ the fields, by c the ghosts and by δ_{BRST} the BRST operator. We assign degrees by $|\phi| = 0$ and $|c| = 1$.
- We introduce antifields ϕ^+ , c^+ with opposite nature than the field, opposite parity and degrees given by $|\phi^+| = -1$ and $|c^+| = -2$.
- We denote by \mathcal{F}_M the space of all the (ϕ, c, ϕ^+, c^+) 's and we set

$$S_M = S_M^0(\phi) + \int_M (\phi^+ \delta_{\text{BRST}}\phi + c^+ \delta_{\text{BRST}}c),$$

$$\omega_M = \int_M (\delta\phi^+ \delta\phi + \delta c^+ \delta c)$$

- Then, if $\partial M = \emptyset$, the BV action S satisfies the CME.
- We usually consider these “BRST-like” theories, but there are more general examples.

Example: gauge theories

- Suppose we have a gauge theory with space of fields F_M , a local action functional S_M^0 and a gauge group acting on it.
- We denote by ϕ the fields, by c the ghosts and by δ_{BRST} the BRST operator. We assign degrees by $|\phi| = 0$ and $|c| = 1$.
- We introduce antifields ϕ^+ , c^+ with opposite nature than the field, opposite parity and degrees given by $|\phi^+| = -1$ and $|c^+| = -2$.
- We denote by \mathcal{F}_M the space of all the (ϕ, c, ϕ^+, c^+) 's and we set

$$S_M = S_M^0(\phi) + \int_M (\phi^+ \delta_{\text{BRST}}\phi + c^+ \delta_{\text{BRST}}c),$$

$$\omega_M = \int_M (\delta\phi^+ \delta\phi + \delta c^+ \delta c)$$

- Then, if $\partial M = \emptyset$, the BV action S satisfies the CME.
- We usually consider these “BRST-like” theories, but there are more general examples.

Relaxed structures

- Suppose we have a graded manifold M with a cohomological vector field Q and a closed 2-form ω of degree n . We set

$$\check{\alpha} := \iota_Q \omega - dS$$

and

$$\check{\omega} := d\check{\alpha} = -L_Q \omega$$

- It turns out that $\check{\omega}$ is a closed, Q -invariant 2-form ω of degree $n + 1$.
- We denote by \underline{M} the quotient of M by the kernel of $\check{\omega}$ (assume it is smooth). We denote by $\underline{\omega}$ its symplectic form of degree $n + 1$.
- It turns out that Q is projectable to a cohomological vector field \underline{Q} . So \underline{M} becomes a dgs manifold of degree $n + 1$.

Relaxed structures

- Suppose we have a graded manifold M with a cohomological vector field Q and a closed 2-form ω of degree n . We set

$$\check{\alpha} := \iota_Q \omega - dS$$

and

$$\check{\omega} := d\check{\alpha} = -L_Q \omega$$

- It turns out that $\check{\omega}$ is a closed, Q -invariant 2-form ω of degree $n + 1$.
- We denote by \underline{M} the quotient of M by the kernel of $\check{\omega}$ (assume it is smooth). We denote by $\underline{\omega}$ its symplectic form of degree $n + 1$.
- It turns out that Q is projectable to a cohomological vector field \underline{Q} . So \underline{M} becomes a dgs manifold of degree $n + 1$.

Relaxed structures

- Suppose we have a graded manifold M with a cohomological vector field Q and a closed 2-form ω of degree n . We set

$$\check{\alpha} := \iota_Q \omega - dS$$

and

$$\check{\omega} := d\check{\alpha} = -L_Q \omega$$

- It turns out that $\check{\omega}$ is a closed, Q -invariant 2-form ω of degree $n + 1$.
- We denote by \underline{M} the quotient of M by the kernel of $\check{\omega}$ (assume it is smooth). We denote by $\underline{\omega}$ its symplectic form of degree $n + 1$.
- It turns out that Q is projectable to a cohomological vector field \underline{Q} . So \underline{M} becomes a dgs manifold of degree $n + 1$.

Field theory

- Suppose that M is a space of fields on some compact manifold Σ .
- Suppose we have a BFⁿ⁻¹V structure on M with ω , Q , and S local.
- This allows us to write ω , Q , and S also on some Σ with boundary.
- If S contains derivatives of the fields, there will be boundary terms that spoil the structure.
- This relaxed structure will however induce a BFⁿV structure on the fields on $\partial\Sigma$ (the kernel of $\check{\omega}$ contains in particular fields in the bulk).

Field theory

- Suppose that M is a space of fields on some compact manifold Σ .
- Suppose we have a BFⁿ⁻¹V structure on M with ω , Q , and S local.
- This allows us to write ω , Q , and S also on some Σ with boundary.
- If S contains derivatives of the fields, there will be boundary terms that spoil the structure.
- This relaxed structure will however induce a BFⁿV structure on the fields on $\partial\Sigma$ (the kernel of $\tilde{\omega}$ contains in particular fields in the bulk).

Field theory

- Suppose that M is a space of fields on some compact manifold Σ .
- Suppose we have a BFⁿ⁻¹V structure on M with ω , Q , and S local.
- This allows us to write ω , Q , and S also on some Σ with boundary.
- If S contains derivatives of the fields, there will be boundary terms that spoil the structure.
- This relaxed structure will however induce a BFⁿV structure on the fields on $\partial\Sigma$ (the kernel of $\check{\omega}$ contains in particular fields in the bulk).

An application

- Suppose (M, ω, Q, S) is a local BFⁿV structure on a space of fields on Σ .
- Then on the space of fields \underline{M} on $\partial\Sigma$ we get a BFⁿ⁺¹V structure.
- If $\partial\Sigma = \emptyset$, we expect to quantize M to some graded vector space \mathcal{H} (with S some operator).
- **Example $n = 0$.** On Σ we have a (relaxed) BFV structure describing the reduced phase space of some field theory. On $\partial\Sigma$ we have a BF²V structure describing a Poisson structure (possibly up to homotopy).
- **Example $n = -1$.** On Σ we have a (relaxed) BV structure describing the symmetry content of some field theory. On $\partial\Sigma$ we have a BFV structure describing its reduced phase space (possibly up to homotopy).

An application

- Suppose (M, ω, Q, S) is a local **BFⁿV structure on a space of fields on Σ** .
- Then on the space of fields \underline{M} on $\partial\Sigma$ we get a **BFⁿ⁺¹V structure**.
- If $\partial\Sigma = \emptyset$, we expect to quantize M to some graded vector space \mathcal{H} (with S some operator).
- **Example $n = 0$** . On Σ we have a (relaxed) BFV structure describing the **reduced phase space** of some field theory. On $\partial\Sigma$ we have a BF²V structure describing a **Poisson structure** (possibly up to homotopy).
- **Example $n = -1$** . On Σ we have a (relaxed) BV structure describing the **symmetry content** of some field theory. On $\partial\Sigma$ we have a BFV structure describing its **reduced phase space** (possibly up to homotopy).

An application

- Suppose (M, ω, Q, S) is a local **BFⁿV structure on a space of fields on Σ** .
- Then on the space of fields \underline{M} on $\partial\Sigma$ we get a **BFⁿ⁺¹V structure**.
- If $\partial\Sigma = \emptyset$, we expect to quantize M to some graded vector space \mathcal{H} (with S some operator).
- **Example $n = 0$** . On Σ we have a (relaxed) BFV structure describing the **reduced phase space** of some field theory. On $\partial\Sigma$ we have a BF²V structure describing a **Poisson structure** (possibly up to homotopy).
- **Example $n = -1$** . On Σ we have a (relaxed) BV structure describing the **symmetry content** of some field theory. On $\partial\Sigma$ we have a BFV structure describing its **reduced phase space** (possibly up to homotopy).

Quantization of the example $n = 0$

- If $\partial\Sigma = \emptyset$, we expect to get a vector space \mathcal{H} by geometric quantization of M together with a coboundary operator Ω quantizing \mathcal{S} . Its cohomology in degree zero describes a quantization of the reduced phase space.
- If $\partial\Sigma \neq \emptyset$, we expect \mathcal{H} to be a representation of a quantization of \underline{M} .
- For example, we may consider the deformation quantization of the Poisson structure described by \underline{M} .
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect \mathcal{H} for Σ to be recovered as the tensor product of the \mathcal{H} s for Σ_1 and Σ_2 over the algebra associated to D .

Quantization of the example $n = 0$

- If $\partial\Sigma = \emptyset$, we expect to get a vector space \mathcal{H} by geometric quantization of M together with a coboundary operator Ω quantizing S . Its cohomology in degree zero describes a quantization of the reduced phase space.
- If $\partial\Sigma \neq \emptyset$, we expect \mathcal{H} to be a representation of a quantization of \underline{M} .
- For example, we may consider the deformation quantization of the Poisson structure described by \underline{M} .
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect \mathcal{H} for Σ to be recovered as the tensor product of the \mathcal{H} s for Σ_1 and Σ_2 over the algebra associated to D .

Quantization of the example $n = 0$

- If $\partial\Sigma = \emptyset$, we expect to get a vector space \mathcal{H} by geometric quantization of M together with a coboundary operator Ω quantizing \mathcal{S} . Its cohomology in degree zero describes a quantization of the reduced phase space.
- If $\partial\Sigma \neq \emptyset$, we expect \mathcal{H} to be a representation of a quantization of \underline{M} .
- For example, we may consider the deformation quantization of the Poisson structure described by \underline{M} .
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect \mathcal{H} for Σ to be recovered as the tensor product of the \mathcal{H} s for Σ_1 and Σ_2 over the algebra associated to D .

Quantization of the example $n = 0$

- If $\partial\Sigma = \emptyset$, we expect to get a vector space \mathcal{H} by geometric quantization of M together with a coboundary operator Ω quantizing S . Its cohomology in degree zero describes a quantization of the reduced phase space.
- If $\partial\Sigma \neq \emptyset$, we expect \mathcal{H} to be a representation of a quantization of \underline{M} .
- For example, we may consider the deformation quantization of the Poisson structure described by \underline{M} .
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect \mathcal{H} for Σ to be recovered as the tensor product of the \mathcal{H} s for Σ_1 and Σ_2 over the algebra associated to D .

Example: Chern–Simons

- Let Σ be a 2-manifold and \mathfrak{g} a quadratic Lie algebra.
- Let N be the space of \mathfrak{g} -valued 1-forms A (connections) on Σ with the Atiyah–Bott symplectic structure $\omega = \frac{1}{2} \int_{\Sigma} \delta A \delta A$.
- We let C denote the space of flat connections. Then \underline{C} turns out to be the quotient by gauge transformations.
- BFV: $M = N \times T^*\Omega^0(\Sigma, \mathfrak{g})[1]$ and

$$S = \int_{\Sigma} (c, F_A) + \frac{1}{2} (b, [c, c])$$

- On $\partial\Sigma$ we get $\underline{\omega} = \int_{\partial\Sigma} \delta A \delta c$,

$$\underline{S} = \frac{1}{2} \int_{\partial\Sigma} c d_A c$$

- We can interpret this as an affine Poisson structure on $\Omega^1(\Sigma, \mathfrak{g})$, which we may regard as the dual of the affine Lie algebra $\hat{\mathfrak{g}} = \Omega^0(\Sigma, \mathfrak{g}) \oplus \mathbb{R}$.

Example: Chern–Simons

- Let Σ be a 2-manifold and \mathfrak{g} a quadratic Lie algebra.
- Let N be the space of \mathfrak{g} -valued 1-forms A (connections) on Σ with the Atiyah–Bott symplectic structure $\omega = \frac{1}{2} \int_{\Sigma} \delta A \delta A$.
- We let C denote the space of **flat connections**. Then \underline{C} turns out to be the quotient by **gauge transformations**.
- BFV: $M = N \times T^*\Omega^0(\Sigma, \mathfrak{g})[1]$ and

$$S = \int_{\Sigma} (c, F_A) + \frac{1}{2} (b, [c, c])$$

- On $\partial\Sigma$ we get $\underline{\omega} = \int_{\partial\Sigma} \delta A \delta c$,

$$\underline{S} = \frac{1}{2} \int_{\partial\Sigma} c d_A c$$

- We can interpret this as an affine Poisson structure on $\Omega^1(\Sigma, \mathfrak{g})$, which we may regard as the dual of the **affine Lie algebra** $\hat{\mathfrak{g}} = \Omega^0(\Sigma, \mathfrak{g}) \oplus \mathbb{R}$.

Example: Chern–Simons

- Let Σ be a 2-manifold and \mathfrak{g} a quadratic Lie algebra.
- Let N be the space of \mathfrak{g} -valued 1-forms A (connections) on Σ with the Atiyah–Bott symplectic structure $\omega = \frac{1}{2} \int_{\Sigma} \delta A \delta A$.
- We let C denote the space of **flat connections**. Then \underline{C} turns out to be the quotient by **gauge transformations**.
- BFV: $M = N \times T^* \Omega^0(\Sigma, \mathfrak{g})[1]$ and

$$S = \int_{\Sigma} (c, F_A) + \frac{1}{2} (b, [c, c])$$

- On $\partial \Sigma$ we get $\underline{\omega} = \int_{\partial \Sigma} \delta A \delta c$,

$$\underline{S} = \frac{1}{2} \int_{\partial \Sigma} c d_A c$$

- We can interpret this as an affine Poisson structure on $\Omega^1(\Sigma, \mathfrak{g})$, which we may regard as the dual of the **affine Lie algebra** $\hat{\mathfrak{g}} = \Omega^0(\Sigma, \mathfrak{g}) \oplus \mathbb{R}$.

Example: Chern–Simons

- Let Σ be a 2-manifold and \mathfrak{g} a quadratic Lie algebra.
- Let N be the space of \mathfrak{g} -valued 1-forms A (connections) on Σ with the Atiyah–Bott symplectic structure $\omega = \frac{1}{2} \int_{\Sigma} \delta A \delta A$.
- We let C denote the space of **flat connections**. Then \underline{C} turns out to be the quotient by **gauge transformations**.
- BFV: $M = N \times T^* \Omega^0(\Sigma, \mathfrak{g})[1]$ and

$$S = \int_{\Sigma} (c, F_A) + \frac{1}{2} (b, [c, c])$$

- On $\partial\Sigma$ we get $\underline{\omega} = \int_{\partial\Sigma} \delta A \delta c$,

$$\underline{S} = \frac{1}{2} \int_{\partial\Sigma} c d_A c$$

- We can interpret this as an affine Poisson structure on $\Omega^1(\Sigma, \mathfrak{g})$, which we may regard as the dual of the **affine Lie algebra** $\hat{\mathfrak{g}} = \Omega^0(\Sigma, \mathfrak{g}) \oplus \mathbb{R}$.

Quantization of the example $n = -1$

- In this case, we expect to get a vector space \mathcal{H} by **geometric quantization** of \underline{M} together with a **coboundary operator** Ω **quantizing** \underline{S} . We expect the gauge fixed integral of $e^{\frac{i}{\hbar}S}$ to yield an **Ω -closed state** (defined up to Ω -exact terms).
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect the state for Σ to be recovered as the **pairing** of the states for Σ_1 and Σ_2 in the Hilbert **space associated to D** .
- We produced a **rather general construction, which relies on the existence of a “nice” polarization of \underline{M}** . The construction also keeps track of “residual fields” (e.g., zero modes).
- We have successfully applied this construction to abelian **BF theories**:

$$S_M^0 = \int_M B \, dA$$

with

$$(A, B) \in F_M = \Omega^1(M) \oplus \Omega^{d-2}(M)$$

Quantization of the example $n = -1$

- In this case, we expect to get a vector space \mathcal{H} by **geometric quantization** of \underline{M} together with a **coboundary operator** Ω **quantizing** \underline{S} . We expect the gauge fixed integral of $e^{\frac{i}{\hbar}S}$ to yield an **Ω -closed state** (defined up to Ω -exact terms).
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect the state for Σ to be recovered as the **pairing** of the states for Σ_1 and Σ_2 in the Hilbert **space associated to D** .
- We produced a **rather general construction, which relies on the existence of a “nice” polarization of \underline{M}** . The construction also keeps track of “residual fields” (e.g., zero modes).
- We have successfully applied this construction to abelian **BF theories**:

$$S_M^0 = \int_M B \, dA$$

with

$$(A, B) \in F_M = \Omega^1(M) \oplus \Omega^{d-2}(M)$$

Quantization of the example $n = -1$

- In this case, we expect to get a vector space \mathcal{H} by **geometric quantization** of \underline{M} together with a **coboundary operator** Ω **quantizing** \underline{S} . We expect the gauge fixed integral of $e^{\frac{i}{\hbar}S}$ to yield an **Ω -closed state** (defined up to Ω -exact terms).
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect the state for Σ to be recovered as the **pairing** of the states for Σ_1 and Σ_2 in the Hilbert **space associated to D** .
- We produced a **rather general construction, which relies on the existence of a “nice” polarization of \underline{M}** . The construction also keeps track of “residual fields” (e.g., zero modes).
- We have successfully applied this construction to abelian **BF theories**:

$$S_M^0 = \int_M B \, dA$$

with

$$(A, B) \in F_M = \Omega^1(M) \oplus \Omega^{d-2}(M)$$

Quantization of the example $n = -1$

- In this case, we expect to get a vector space \mathcal{H} by **geometric quantization** of \underline{M} together with a **coboundary operator** Ω **quantizing** \underline{S} . We expect the gauge fixed integral of $e^{\frac{i}{\hbar}S}$ to yield an **Ω -closed state** (defined up to Ω -exact terms).
- If $\Sigma = \Sigma_1 \cup_D \Sigma_2$ with D a common boundary component for Σ_1 and Σ_2 , we expect the state for Σ to be recovered as the **pairing** of the states for Σ_1 and Σ_2 in the Hilbert **space associated to D** .
- We produced a **rather general construction, which relies on the existence of a “nice” polarization** of \underline{M} . The construction also keeps track of “residual fields” (e.g., zero modes).
- We have successfully applied this construction to abelian **BF theories**:

$$S_M^0 = \int_M B \, dA$$

with

$$(A, B) \in F_M = \Omega^1(M) \oplus \Omega^{d-2}(M)$$

Deformations of abelian BF theory

- By perturbing abelian BF theory, we have extended the construction to other theories like
 - 1 Quantum mechanics and topological quantum mechanics
 - 2 Split Chern–Simons theory
 - 3 2D Yang–Mills theory
 - 4 Poisson sigma model
- In the last example, one can e.g. recover the associativity of Kontsevich's star product from the composition of states.
- 2D Yang–Mills theory has been recently studied in full detail by Mnëv and Iraso also for manifolds with corners. This way, one may recover the full nonperturbative results out of the perturbative expansions.

Deformations of abelian BF theory

- By perturbing abelian BF theory, we have extended the construction to other theories like
 - 1 Quantum mechanics and topological quantum mechanics
 - 2 Split Chern–Simons theory
 - 3 2D Yang–Mills theory
 - 4 Poisson sigma model
- In the last example, one can e.g. recover the associativity of Kontsevich's star product from the composition of states.
- 2D Yang–Mills theory has been recently studied in full detail by Mnëv and Iraso also for manifolds with corners. This way, one may recover the full nonperturbative results out of the perturbative expansions.

Deformations of abelian BF theory

- By perturbing abelian BF theory, we have extended the construction to other theories like
 - 1 Quantum mechanics and topological quantum mechanics
 - 2 Split Chern–Simons theory
 - 3 2D Yang–Mills theory
 - 4 Poisson sigma model
- In the last example, one can e.g. **recover the associativity of Kontsevich's star product from the composition of states.**
- **2D Yang–Mills theory** has been recently studied in full detail by Mnëv and Iraso **also for manifolds with corners**. This way, one may **recover the full nonperturbative results out of the perturbative expansions.**

Final remarks

- Other theories like scalar field, spinor field, Yang–Mills can be treated alike (but one has to take renormalization into account).
- Classical BV-BFV gravity theories (in the Einstein–Hilbert as well as in the Palatini–Cartan version) have also been studied.
- A discretized version of nonabelian *BF* theory has also been studied: in this setting, all spaces are finite dimensional and all the quantum BV-BFV results are rigorous from the start.

Final remarks

- Other theories like scalar field, spinor field, Yang–Mills can be treated alike (but one has to take renormalization into account).
- Classical BV-BFV gravity theories (in the Einstein–Hilbert as well as in the Palatini–Cartan version) have also been studied.
- A discretized version of nonabelian *BF* theory has also been studied: in this setting, all spaces are finite dimensional and all the quantum BV-BFV results are rigorous from the start.

Final remarks

- Other theories like scalar field, spinor field, Yang–Mills can be treated alike (but one has to take renormalization into account).
- Classical BV-BFV gravity theories (in the Einstein–Hilbert as well as in the Palatini–Cartan version) have also been studied.
- A **discretized version of nonabelian BF theory** has also been studied: in this setting, all spaces are finite dimensional and **all the quantum BV-BFV results are rigorous from the start**.

Final remarks

- Other theories like scalar field, spinor field, Yang–Mills can be treated alike (but one has to take renormalization into account).
- Classical BV-BFV gravity theories (in the Einstein–Hilbert as well as in the Palatini–Cartan version) have also been studied.
- A **discretized version of nonabelian BF theory** has also been studied: in this setting, all spaces are finite dimensional and **all the quantum BV-BFV results are rigorous from the start**.

Happy Birthday
Kolya