Controllability properties and irreducibility of SPDEs driven by Lévy Processes

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2 Controllability and Irreducibility



Decomposibility of the measure

Discretization of the noise by Daubechies wavelets ()

E.H. and Paul Razafimandimby (Leoben)

The solution operator

- *H* denotes a separable Hilbert space
- $\mathcal{L}: D(\mathcal{L}) \subset H \rightarrow H$ be a possible unbounded linear operator;
- $B: H \rightarrow H$ is a densely defined nonlinear operator taking values in H
- Let \mathcal{U} be the space of controls, e.g. $\mathcal{U} = L^2(0, T; U)$.

Let u^c be a solution to the following equation

$$(*) \begin{cases} \dot{u}^{c}(t,x,v) = \mathcal{L}u^{c}(t,x,v) + B(u^{c}(t,x,v)) + C \underbrace{v(t)}_{=\text{control}}, \quad t \ge 0, \\ u^{c}(0,x,v) = x. \end{cases}$$

Fix T > 0. Let us denote by

$$\mathcal{R}_{\mathcal{T}}: H \times L^2(0, T; U) \to H \tag{1}$$

the operator that takes each function $v \in L^2(0, T; U)$ and initial condition $x \in H$ to the solution $u^c(T, x, v)$ of the system (*).

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• We say that the system (*) is *exact controllable in time* T, iff for any $x \in H$

 $\mathcal{R}_T(x, L^2(0, T; U)) \supset H.$

 We say that the system (*) is approximate controllable in time T > 0 iff for any x ∈ H

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Examples without nonlineartity

B = 0 :

- The heat equation with Neumann boundary control is approximate controllable in time T > 0 (Laroche, Martin and Rouchon 2000, Coron (2007) Theorem 2.76);
- The wave equation with Neumann boundary control is exactly controllable in time T > 2π (Zuazua 1991, Tucsnak and Weiss 2009);

Controllability Concepts and Stochastic Equations

Let M be a semimartingale and let u be a solution of

$$(**) \begin{cases} \dot{u}(t,x) = \mathcal{L}u(t,x,v) + B(u(t,x)) + C\dot{\mathbf{M}}(t), & t \geq 0, \\ u(0,x) = x. \end{cases}$$

Definition:

Let $(\mathcal{P}_t)_{t\geq 0}$ be the Markov semigroup defined by

 $[\mathcal{P}_t\Phi](x) = \mathbb{E}[\Phi(u(t,x))], \ \Phi \in B_b(H), x \in H, \ t \ge 0,$

where $u(\cdot, x)$ is the unique solution to (**) with initial condition $x \in H$.

Definition

Given a Markovian semigroup $(\mathcal{P}_t)_{t\geq 0}$

- $(\mathcal{P}_t)_{t\geq 0}$ has the Feller property, iff $\mathcal{P}_t f \in C_{\infty}(H)$ for $f \in C_{\infty}(H)$ and t > 0.
- $(\mathcal{P}_t)_{t\geq 0}$ has the strong Feller property, iff $\mathcal{P}_t\mathcal{B}_b(H) \subset \mathcal{C}_b(H)$ for any t > 0.

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Controllability Concepts and properties of $(\mathcal{P}_t)_{t\geq 0}$

In many situations, replacing the noise by a control term gives information on the solution.

- strong Feller property
- support Theorem and irreducibility
- blow up of solutions (Debussche and de Bouard 2005)

Idea:

- By the Girsanov transform one generates a drift term mimicking the control;
- Small ball probabilities give the result.

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related Results

- Da Prato: controllability and strong Feller property;
- Röckner and Wang: controllability implies strong Feller but with nondegenerate Gaussian part.
- Zabczyk and Priola (2011): spectral noise (noise is a sum of independent Lévy processes multiplied by the eigenfunctions) support theorems.
- Maslowski;
- Hausenblas and Razafimanbimby (2015): approximate controllability and exact controllability implies reducibility
- Mattingly (talk yesterday), Glatt-Holtz, Geordie.

Controllability versus Irreducibility

The heat equation with Neuman boundary noise

We are interested in a model of a one dimensional rod, on side is perfectly isolated the other side is exposed to a fire.





Theorem

(H. and Razafimandimy (2015)) For any $x, y \in H$ and $\delta > 0$ there exists a $\kappa > 0$ such that

 $\mathbb{P}(u(T,x) \in \mathcal{D}_H(y,\delta)) \geq \kappa.$

(3)

Controllability Concepts

Definition

A system is controllable in time T > 0 for a finite dimensional subspace $F \subset H$, iff for any $x \in H$

 $\pi_F \mathcal{R}_T(x, L^1(0, T; \mathcal{K})) \supset F.$

Definition

A system is *solidly controllable* in time T > 0 for a finite dimensional subspace $F \subset H$, iff for any R > 0 and any $x \in H$, there exists an $\epsilon > 0$ and a compact set $K_{\epsilon} \subset L^{1}(0, T; \mathcal{K})$ such that for any function $\Phi : K_{\epsilon} \to F$ satisfying

$$\sup_{x\in K_{\epsilon}} |\Phi(x) - \pi_F \mathcal{R}_T(x,x)|_F \leq \epsilon,$$

we have

$$\Phi(K_{\epsilon}) \supset B_F(R).$$

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Controllability Concepts

Remark

(Agrachev and Sarychev (2005)) The 2D-Navier Stokes with set of controls

$$\mathcal{K} := \left\{ \begin{pmatrix} 0\\1 \end{pmatrix} \sin(x_1), \begin{pmatrix} 0\\-1 \end{pmatrix} \cos(x_1), \\ \begin{pmatrix} -1\\1 \end{pmatrix} \sin(x_1 + x_2), \begin{pmatrix} 1\\-1 \end{pmatrix} \cos(x_1 + x_2) \right\}$$

described above is solid controllable on finite dimensional spaces.

- Let (U, d) be a metric space, X and F be finite-dimensional vector spaces;
 - $f: U \times X \to F$ a continuous operator;
 - for any probability measure $\mu \in P(X)$ and any $u \in U$ let us define $\mu_f(u, \cdot) : \mathcal{B}(X) \ni B \mapsto \mu(f^{-1}(u, B)) \in [0, 1].$

Theorem

(Agrachev et. all) Suppose that,

- for any $u \in U$, the function $f(u, \cdot)$ is analytic and the interior of the set f(u, X) is nonempty.
- $\mu \in \mathcal{P}(X)$ is absolutely continuous w.r.t. the Lebesgue measure on X.

Then,

- For any x ∈ U, the measure µ_f(x, ·) is absolutely continuous with respect to Leb_F;
- The function µ_f : U ∋ u ↦ µ_f(u, ·) ∈ P(F) endowed with the total variation norm^a is continuous.

^aThe total variation distance between two probability measures P and Q on a probability space (Ω, \mathcal{F}) is defined by $\delta_{var}(P, Q) = \sup_{A \in \mathcal{F}} |P(A) - Q(A)|$.

The proof is a straightforward application of the Sard Theorem.

Sard's Theorem The image under an analytic function of the set of singular points has measure zero.

How to extend this result to infinite dimensional measures?

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Decomposability of a Measure

Definition

Let *H* be a Hilbert space. We call a measure μ decomposable, iff there exists an ONB $\{e_n : n \in \mathbb{N}\}$ in *H* such that

$$\mu = \otimes_{n=1}^{\infty} \mu_n,$$

and μ_n is defined by

$$\mathcal{B}(\mathbb{R}) \ni B \mapsto \mu_n(B) := \mu\left(\{h \in H : \langle h, e_n \rangle \in B\}\right), \ n \in \mathbb{N}$$

Example

Let us consider the process $\{W(t) : t \in [0,1]\}$, where W is a Wiener process. Then, the Wiener measure is decomposable. In fact, one can find an ONB $\{e_n : n \in \mathbb{N}\}$ such that the random variables

$$\xi_n := \int_0^1 e_n(s) dW(s), \quad n \in \mathbb{N},$$

are independent.

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are independent.

- Let (U, d) be a metric space, X be an infinite vector spaces;
 - $f: U \times X \to F$ a continuous operator (remember F is finite);
 - for any probability measure $\mu \in P(X)$ and any $u \in U$ let us define

$$\mu_f(u, \cdot) : \mathcal{B}(X) \ni B \mapsto \mu(f^{-1}(u, B)) \in [0, 1].$$

Theorem

(Agrachev et. all) Let us assume that

- ∀u ∈ H f(u, ·) is analytic and f has continuous Frechet derivative with resp. to (u, x)
- $\forall u \in U$, \exists finite dimensional subspace $\tilde{X}_u \subset X$ and a ball $B_u \subset \tilde{X}_u$ such that the interior of the set $f(u, B_u)$ is non-empty.

Let $\mu \in \mathcal{P}(X)$ being decomposable and with finite second moments. Then

- For any x ∈ U, the measure µ_f(x, ·) is absolutely continuous w.r.t. Leb_F;
- The function µ_f : U ∋ u ↦ µ_f(u, ·) ∈ P(F) endowed with the total variation norm is continuous.

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Application of the Abstract result

Given the SPDE

$$(\star) \left\{ \begin{array}{rll} \dot{u}(t,x) &=& \mathcal{L}u(t,x,v) + B(u(t,x)) + W(t), \quad t \geq 0, \\ u(0,x) &=& x. \end{array} \right.$$

Theorem

(Agrachev, Kuksin, Sarychev, and Shirikyan, 2007) Given the control system corresponding to (\star) is solid controllable. Then, for any finite dimensional subspace F of H, the measure

$$\mathcal{B}(F) \ni U \mapsto \mathbb{E}1_U(\pi_F u(T, x)),$$

where π_F denotes the orthogonal projection onto F, has a absolutely continuous density with respect to the Lebesgue measure. In addition, the measure

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depends continuously on the initial condition $x \in H$ in the total variation norm.

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Ingredients of the proof

- solid controllability (see Agrachev and Sarychev (2005));
- analyticity of the solution operators $\mathcal{R}_{\mathcal{T}}$ (see Kuksin (1998));
- decomposability of the Wiener measure.

The stochastic Navier Stokes with Lévy noise

Then the initial-boundary value problem associated with the 2D– Navier–Stokes equations is given by

$$\begin{cases} \frac{\partial u}{\partial t} & - \nu \bigtriangleup u + (u \cdot \nabla)u + \nabla p = \dot{L}_t & \text{in } \mathbb{T}^2, \\ \operatorname{div} u & = 0 \text{ in } \mathbb{T}^2, \\ u(\cdot, 0) & = x \text{ in } \mathbb{T}^2, \end{cases}$$
(4)

with

$$\begin{split} L_t &= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(x_1) l_t^1 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \cos(x_1) l_t^2 \\ &+ \begin{pmatrix} -1 \\ 1 \end{pmatrix} \sin(x_1 + x_2) l_t^3 + \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos(x_1 + x_2) l_t^4. \end{split}$$

Here, $l = \{l_t^j : t \ge 0\}$, j = 1, ..., 4, are independent, one dimensional, α -stable processes. Uniqueness and Existence of a solution is given by Brzezniak, H. and Jia Hui (2014).

Irreducibility Results

Theorem

(H. and Razafimandimby 2017) Let u be the solution of the stochastic Navier Stokes driven by a Lévy processes described above. Then, for any finite dimensional subspace F of H, the measure

$$\mathcal{B}(F) \ni U \mapsto \mathbb{E}1_U(\pi_F u(T, x)),$$

where π_F denotes the orthogonal projection onto F, has a absolutely continuous density with respect to the Lebesgue measure. In addition, the measure

$$\mathcal{B}(F) \ni U \mapsto \mathbb{E}1_U(\pi_F u(T, x)) \in [0, 1]$$

depends continuously on the initial condition $x \in H$ in the total variation norm.

Why is the decomposability of the measure is important?

Notation

- E be a separable Banach space, B(E) be the σ-algebra generated by the open sets and μ be a probability measure on (E, B(E));
- Let $E = F_n \oplus G^n$ be the algebraic direct sum, where
 - F_n is finite dimensional given;
 - G^n is infinite and the complement;
- let $\mu_{(F_n,G^n)}$ the probability measure defined by

$$\mu_{(F_n,G^n)}: \mathcal{B}(F_n) \ni A \mapsto \mu(A + G^n) \in [0,1];$$

• For $A \subset E$ and $y \in G^n$ let $A_{(F_n,G^n)}(y) = \{x \in F_n : x + y \in A\};$

What we need:

For all $n \in \mathbb{N}$ there exists a kernel

$$m_n: G^n \times \mathcal{B}(F_n) \to \mathbb{R}^+_0$$

such that $\mu(A) = \int_{\mathcal{G}^n} \int_{\mathcal{A}_{(F_n,\mathcal{G}^n)(y)}} m_n(y,d\mathsf{x}) \mu_{\mathcal{G}^n}(dy).$

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Why is the decomposability of the measure is important?

Corollary

Let *E* be a separable Banach space and $\{e_n : n \in \mathbb{N}\}$ be a Schauder basis. Put $E_n := \{\lambda e_n : \lambda \in \mathbb{R}\}$ and $F_n := E_1 \oplus \cdots \oplus E_n$, $\mu_n = \prod_{E_n} \mu$.

- for all $n \in \mathbb{N}$ μ_n is absolutely continuous with respect to the Leb_{F_n}
- for any $y \in F_{n-1}$ the probability measure

$$\mathcal{B}(\mathbb{R}) \ni A \mapsto \mathbb{P}\left(\{x \in E : \langle x, e_n \rangle \in A\} \mid \pi_{F_{n-1}} = y\right)$$

is absolutely continuous.

Then for any $n \in \mathbb{N}$ there exists a function $h_n : G^n \times E_1 \oplus \cdots \oplus E_n \to \mathbb{R}_0^+$ such that μ_n -a.s.

$$m_n(y,A) = \int_A h_n(y,x)\mu_n(dx).$$

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Let ψ be the mother wavelet and ϕ the to ψ associated scaling function given The wavelet system is given by

$$\psi_{j,k}:=2^{-rac{j}{2}}\psi(2^jt+k) ext{ and } \phi_{j,k}:=2^{-rac{j}{2}}\phi(2^jt+k), \quad k\in\mathbb{N}, \, j=0,\dots,2^k-1.$$

The corresponding multiresolution analysis is defined by

$$V_n := \operatorname{span}\{\phi_{j,k} : j = 1, \dots, n, \ j = 1, \dots, 2^j\},\$$

and

$$W_n := \operatorname{span}\{\psi_{n,k} : j = 1, \dots, 2^n\}.$$

Note, that

$$V_{n+1}=V_n\otimes W_n.$$

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Theorem

Let $0 , <math>0 < q < \infty$, $s \in \mathbb{R}$ and the mother wavelet and scaling function be *u* times continuously differentiable with $u > \max(s; 1 - \frac{1}{p} - s)$. Then the wavelet system is an unconditional basis in $B^s_{p,q}(\mathbb{R})$. (See Triebel or Kahane and Lemarié-Rieusset)

A compound Poisson process with intensity ν can be written $\int_0^1 \int_{\mathbb{R}} z\eta(dz, ds) = \sum_{i=1}^N \delta_{\mathcal{T}_i} Y_i,$

where

- *N* is Poisson distributed with parameter $\nu(\mathbb{R})$;
- $\{T_i : i \in \mathbb{N}\}$ independent and uniform distributed in [0, 1];
- $\{Y_i : i \in \mathbb{N}\}$ are independent and distributed as $\nu/\nu(\mathbb{R})$.

Note, that $\delta \in B^s_{p,p}(\mathbb{R})$ for $s < \frac{1}{p} - 1$.

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Theorem

Let $0 , <math>0 < q < \infty$, $s \in \mathbb{R}$ and the mother wavelet and scaling function be *u* times continuously differentiable with $u > \max(s; 1 - \frac{1}{p} - s)$. Then the wavelet system is an unconditional basis in $B^s_{p,q}(\mathbb{R})$. (See Triebel or Kahane and Lemarié-Rieusset)

A compound Poisson process with intensity ν can be written $\int_0^1 \int_{\mathbb{R}} z\eta(dz, ds) = \sum_{i=1}^N \delta_{T_i} Y_i,$ where

where

- *N* is Poisson distributed with parameter $\nu(\mathbb{R})$;
- $\{T_i : i \in \mathbb{N}\}$ independent and uniform distributed in [0, 1];
- $\{Y_i : i \in \mathbb{N}\}$ are independent and distributed as $\nu/\nu(\mathbb{R})$.

Note, that $\delta \in B^{s}_{p,p}(\mathbb{R})$ for $s < \frac{1}{p} - 1$.

Let η be a Poisson random measure on \mathbb{R} with intensity ν . Let us define for a continuous function $f : [0, 1] \to \mathbb{R}$

$$\xi(f) := \int_0^1 \int_{\mathbb{R}} f(s) \eta(dz, ds),$$

and $\psi_{j,k}(f) = \int_0^1 \psi_{j,k}(s) f(s) \, ds$ and $\phi(f) = \int_0^1 f(s)\phi(s) \, ds$. Note, that

$$\xi(f) := \sum_{j=1}^{\infty} \sum_{k=1}^{2^{\prime}} \zeta_{j,k} \psi_{j,k}(f) + a_0 \phi(f), \quad t \in [0,1]$$

where $\{\zeta_{j,i} : j \in \mathbb{N}, i = 1, \dots, 2^j\}$ is a family of random variables, such that

$$\zeta_{j,k} \stackrel{d}{=} \int_0^1 \int_{\mathbb{R}} \psi_{j,k}(s) \, z\eta(dz,ds),$$

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Proposition

Let us assume for $p \in [1,2)$ and $\int |z|^p \nu(dz) < \infty$. Then, for $s < \frac{1}{p} - 1$, we have

$$\mathbb{E}|\xi|_{B^s_{p,p}}^p < \infty.$$

Proposition

The probability

 $\mathcal{B}(\mathbb{R}) \ni U \mapsto \mathbb{P}\left(\zeta_{n,k} \in U\right)$

is absolutely continuous with respect to the Lebesgue measure.

Proposition

The conditional probability

$$\mathcal{B}(\mathbb{R}) \ni U \mapsto m_k^n(U, x) := \mathbb{P}\left(\zeta_{n,k} \in U \mid \mathcal{F}(V_n)\right)$$

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For a function $f:[0,1]
ightarrow \mathbb{R}$ we write

$$\xi(f) := \int_0^1 \int_{\mathbb{R}} f(s) z \, \eta(dz, ds).$$

Lemma

Let $f : [0,1] \to \mathbb{R}$ such that there exists a $\delta > 0$ and $t_1, t_2 \in [0,1]$, $t_1 < t_2$ such that $|f(s)| \ge \delta$ for all $s \in [t_1, t_2]$. Then

•
$$supp(\xi(f)) = \mathbb{R};$$

2 the law of ξ(f) is absolutely continuous with respect to the Lebesgue measure.

The proof follows by the fact that a Levy process with infinite intensity has absolutely continuous distribution and support \mathbb{R} (Sato, Chapter 27).

Small deviation property

Proposition

For $s < \frac{1}{p} - 1$, for any $\epsilon > 0$ there exists a $\delta > 0$ such that $\mathbb{P}\left(|\xi|_{B^s_{p,p}} \le \epsilon\right) \ge \delta.$

This follows from a result of Derreich and Arzuda.

Small deviation property

Proposition

For
$$s < \frac{1}{\rho} - 1$$
, for any $\epsilon > 0$ there exists a $\delta > 0$ such that
 $\mathbb{P}\left(|\xi|_{B^s_{\rho,\rho}} \le \epsilon\right) \ge \delta.$

This follows from a result of Derreich and Arzuda.

Extension

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The same result can be shown by the stochastic Navier Stokes driven by fractional Brownian motion with Hurst parameter $H > \frac{1}{2}$.

Extension

Same result should be possible for shell models.

Possible Extension to infinite dimension

Lie–Trotter splitting of the Markovian semigroup in low modes and high modes \Rightarrow determining modes.

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Thank you for your attention