

Robust Hedging of Options on a Leveraged Exchange Traded Fund

(Discretisation and Duality of Optimal Skorokhod Embedding Problems)

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Advances in Stochastic Analysis for Risk Modeling
CIRM, Luminy, 17th November, 2017



Model-independent/Robust bounds for option prices

- Aim: make statements about the price of options given very mild modelling assumptions
- Incorporate market information by supposing the prices of vanilla call options are known
- Typically want to know the largest/smallest price of an exotic option (Lookback option, Barrier option, Variance option, Asian option, . . .) given observed call prices, but with (essentially) no other assumptions on behaviour of underlying
- This talk: options on *Leveraged Exchange Traded Funds (LETF)*
- Why? Heavily traded, and interesting features to the solution!

Leveraged Exchange Traded Fund (LETF)

- ETF attempts to match returns on a benchmark asset/index 1:1
- LETF attempts to match returns on a benchmark asset/index up to factor, e.g. 2:1 — 10% increase in index \rightarrow 20% increase in LETF
- Over time, e.g. daily rebalancing leads to tracking errors
- Dynamics of the LETF with leverage ratio $\beta > 1$ are given by

$$L_t = S_t^\beta \exp\left(-\frac{\beta(\beta-1)}{2} V_t\right),$$

V_t is the accumulated quadratic variation of $\log S_t$

- Eliminate V_t by time change, $\tau_t := \inf\{s \geq 0 : V_s = t\}$ and $X_t := S_{\tau_t}$. So,

$$d\langle X \rangle_t = d\langle S \rangle_{\tau_t} = S_{\tau_t}^2 dV_{\tau_t} = X_t^2 dt$$

and X_t is a geometric Brownian motion (GBM)

LETF model-independent pricing problem

Want to consider (maximum) price of call option on LETF under assumption that law of S_T (under \mathbb{Q}) is known, but no other modelling assumption. Corresponds to:

Main Problem

Find

$$\sup_{\tau} \mathbb{E} \left[\left(X_{\tau}^{\beta} \exp \left(-\frac{\beta(\beta-1)}{2} \tau \right) - k \right)_{+} \right], \quad (\text{LOptSEP})$$

over stopping times τ such that $X_{\tau} \sim \mu$, where X is a GBM

- This is a form of Optimal Skorokhod Embedding Problem (**OptSEP**): Given γ an optional process and μ probability on \mathbb{R} , find stopping time τ to maximise

$$\mathbb{E}[\gamma_{\tau}] \quad (\text{OptSEP})$$

subject to $B_{\tau} \sim \mu$, $(B_{t \wedge \tau})_{t \geq 0}$ is UI, B is Brownian motion.



Monotonicity principle

- In Beiglböck, C., Huesmann [BCH] (2017), systematic study of **all known** optimal solutions

- Key observation of [BCH]:

*Solutions to (OptSEP) are often characterised by simple **geometric** criteria*

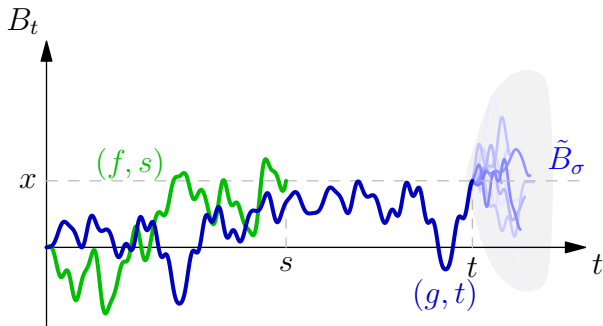
- Geometric criteria typically determined by the **monotonicity principle** ([BCH]):

if I am better off 'stopping' a currently running path, and 'transplanting' the tail onto another stopped path (stopping at the same level), my solution is not optimal

- Monotonicity principle can be used to show that optimisers of (OptSEP) have a certain geometric form

Monotonicity Principle

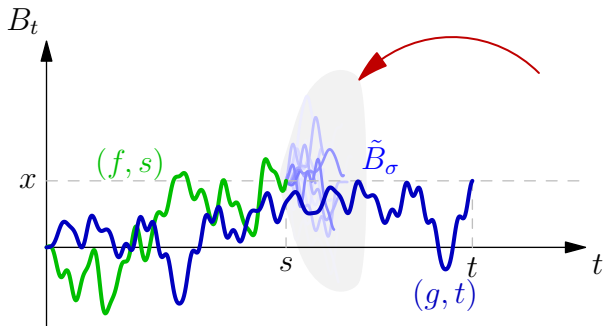
Stopped paths: $S := \{(f, s) | s \in \mathbb{R}_+, f \in C[0, s]\}$. Objective, $\gamma : S \rightarrow \mathbb{R}$.



“Reward”: $\gamma((f, s)) + \mathbb{E} \left[\gamma((g, t) \oplus \tilde{B}_\sigma) \right]$

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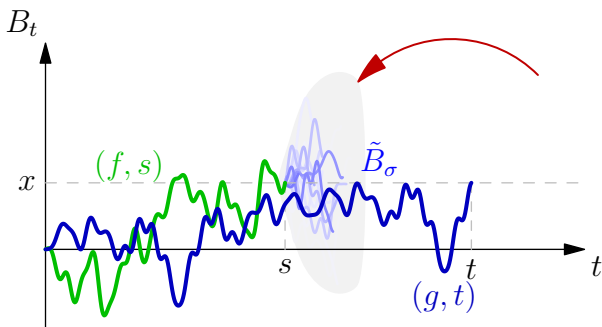
Stop-Go Pair: $((f, s), (g, t)) \in SG^\gamma \iff f(s) = g(t) \ \& \ \forall \text{ st. t. } \sigma > 0:$

$$\gamma((f, s)) + \mathbb{E} \left[\gamma((g, t) \oplus \tilde{B}_\sigma) \right] > \mathbb{E} \left[\gamma((f, s) \oplus \tilde{B}_\sigma) \right] + \gamma((g, t))$$



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Monotonicity Principle

Theorem ([BCH] (2017))

Let τ^* be an optimiser to (OptSEP). Then there exists $\Gamma \subset S$ such that

$$\mathbb{P}(\{(B_t)_{t \leq \tau}, \tau\} \in \Gamma) = 1$$

and

$$(\Gamma^< \times \Gamma) \cap \text{SG}^\gamma = \emptyset,$$

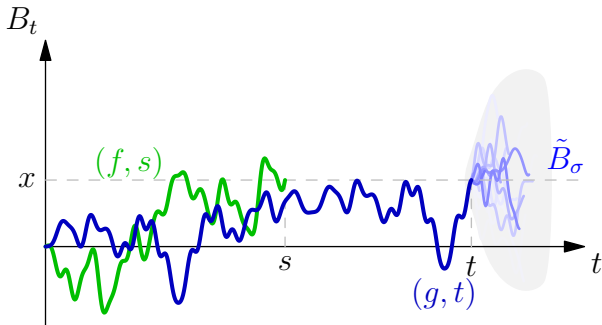
where

$$\Gamma^< := \{(g, t) : \exists (f, s) \in \Gamma, s > t, f|_{[0,t]} = g\}.$$

- Sufficient to recover **every** known optimal solution (at the time of writing)

Example: Rost's embedding

Consider $\gamma_t = F(t)$, F a convex function:



Score either: $F(s) + \mathbb{E}[F(t + \sigma)]$ or $\mathbb{E}[F(s + \sigma)] + F(t)$.

If $s < t$, we see that $F(s) + \mathbb{E}[F(t + \sigma)] > \mathbb{E}[F(s + \sigma)] + F(t)$ and so

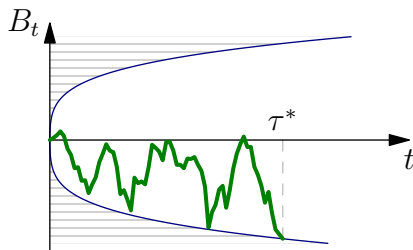
$((f, s), (g, t)) \in SG^\gamma$.

Example: Rost's embedding

- Monotonicity Principle implies stopping region is a reversed barrier:

$$\tau^* = \inf\{t \geq 0 : (t, B_t) \in \mathcal{R}\}$$

where $\mathcal{R} \subset \mathbb{R}_+ \times \mathbb{R}$, $(s, x) \in \mathcal{R} \implies (t, x) \in \mathcal{R}$ for all $t < s$



- Loynes' argument says that there is (essentially) one such barrier (take union of two barriers, also embeds same law)

Example: LETF model-independent pricing problem

- Problem is to maximise $\mathbb{E}[(M_\tau - k)_+]$, where $M_t = X_t^\beta e^{-\beta(\beta-1)t/2}$ is a martingale. Intuitively, aim to maximise local time of M at k
- Can compute $M_t = k$ when $K(X_t) = t$, $K(x) = \frac{2}{\beta(\beta-1)} \ln(\frac{x^\beta}{k})$
- A **K -cave barrier** is a subset \mathcal{R} of $\mathbb{R}_+ \times \mathbb{R}_+$ of the form $\mathcal{R} = \{(t, x) : t \leq \ell(x) \text{ or } t \geq r(x)\}$, where $\ell(x) \leq K(x) \leq r(x)$

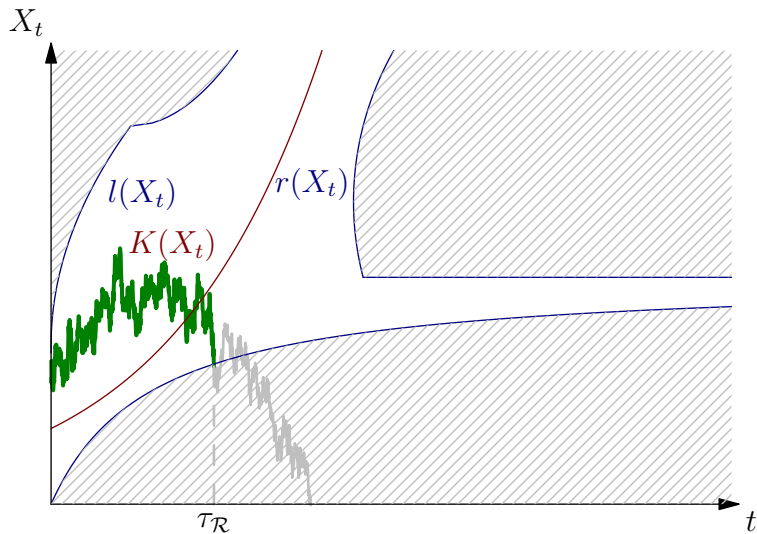
Theorem

There exists an optimiser to **(LOptSEP)** which is of the form

$$\tau_{\mathcal{R}} := \inf\{t > 0 : (t, X_t) \in \mathcal{R}\}$$

where \mathcal{R} is a K -cave barrier.

K-cave barriers



(Non-)uniqueness of cave-type Barriers

- *Normally*, at this point, Loynes' argument would imply that there is a unique (K -)cave barrier with the right stopping distribution, which would then be the optimiser.
- However, for the (K -)cave barriers, there are generally multiple (K -)cave barriers which embed the same distribution; consider 3-atom measures. Crucial question:

How to identify the optimal K -cave barrier?

PDE Heuristics for the Dual Solution (LETF case)

- We expect the Dual solution (superhedging portfolio) to take the form: $\exists G, \lambda$ such that

$$G(t, x) + \lambda(x) \geq F(t, x),$$

where λ represents a portfolio of calls, F is the payoff of the option, and γ is the proceeds of a dynamic trading strategy in the underlying.

- We argue heuristically, inspired by arguments of Henry-Labordère: write $F^\lambda(t, x) = F(t, x) - \lambda(x)$. Then we require:

$$\mathcal{L}G := \frac{x^2}{2} \partial_x^2 G + \partial_t G \leq 0 \text{ and } G \geq F^\lambda \quad \forall (t, x)$$

and expect equality in PDE in \mathcal{R}^c , and $G = F^\lambda$ in \mathcal{R} .

- Also conjecture smooth fit: $\partial_t G = \partial_t F^\lambda = \partial_t F$ on boundaries

$$\implies M := \partial_t G \text{ solves } \mathcal{L}M = 0 \text{ in } \mathcal{R}^c \text{ and } M = \partial_t F \text{ on } \partial\mathcal{R}$$



PDE Heuristics for the Dual Solution

- In particular, we get: $M(t, x) = \mathbb{E}^{(t,x)}[\partial_t F(X_{\tau_{\mathcal{R}}}, \tau_{\mathcal{R}})]$, and integrating, we see that

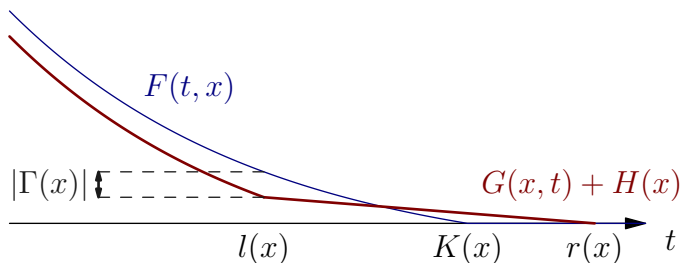
$$G(t, x) = \int_t^{r(x)} M(s, x) ds - Z(x)$$

for some function Z .

- In fact, Z can be chosen (uniquely up to affine functions) in such a way to make G a martingale in \mathcal{R}^G .
- Now $G(t, x) \geq F^\lambda(t, x)$ at $t = \ell(x)$, $t = r(x)$ implies that:

$$\lambda(x) \geq Z(x) + \underbrace{\max\{0\}}_{t=r(x)}, \quad \underbrace{F(\ell(x), x) - \int_{\ell(x)}^{r(x)} M(s, x) ds}_{\substack{:=\Gamma(x) \\ t=\ell(x)}}$$

Γ -condition: $\Gamma > 0$



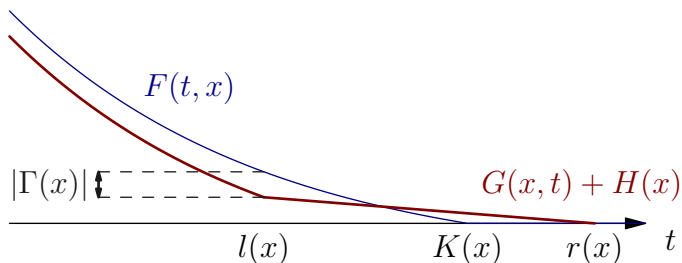
Lemma (Easy)

Suppose \mathcal{R} is a K -cave barrier which embeds μ , and such that $\Gamma(x) = 0$ for all x . Then $\tau_{\mathcal{R}}$ is an optimiser of (LOptSEP).

Theorem (Hard)

There exists a (unique) K -cave barrier \mathcal{R} which embeds μ , and such that $\Gamma(x) = 0$ for all x .

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Dual Feasibility

First step to proving the results:

Theorem

The dual solution described above is indeed a dual solution (i.e. G is a martingale for some suitable Z).

- Shown using essentially probabilistic techniques
- NB: No 'explicit' form for Z
- Clearly $\Gamma = 0$ is then a sufficient condition \implies primal = dual
- In fact, enough to show

$$\Gamma(x) \leq 0 \quad \mu_r\text{-a.s.}, \quad \Gamma(x) \geq 0 \quad \mu_l\text{-a.s.}$$

where μ_l, μ_r are left and right exit distributions of optimiser.

- But: Not enough for theorem... Know (e.g. Dolinsky & Soner) that no duality gap, but don't know optimal dual solution of this form



Discretisation of Problem

- Idea: Take the original problem, and discretise time and space suitably (Random walk converging to the original Brownian motion)
- Can formulate the original problem in the discrete setting and formulate (LOptSEP) as a (countably infinite) linear programming problem
- Strong duality holds (in an appropriate sense) for the discretised problem, and can show existence of dual solutions, and natural condition corresponding to $\Gamma = 0$
- In the limit, exists optimal barrier, and embedding, and can make sense of $\Gamma = 0$ condition

\implies *Theorem holds*

Discretisation

- Fix a (centred, integrable) measure μ , supported on $[x_*, x^*]$. Fix N .
- Define $\mathcal{J} := \{\lfloor x_* \sqrt{N} \rfloor, \lfloor x_* \sqrt{N} \rfloor + 1, \dots, \lfloor x^* \sqrt{N} \rfloor\}$, and $x_j^N = \frac{j}{\sqrt{N}}$.
- Can construct a discrete time random walk Y_j^N from hitting times of Brownian motion B to $\{x_0^N, \dots, x_L^N\}$, $L = |\mathcal{J}| - 1$.
- By considering a stopping rule τ for B , can construct stopping rule $\tilde{\tau}^N$ for Y . Then consider probabilities:

$$p_{j,n}^N := \mathbb{P} \left(Y_n^N = x_j^N, \tilde{\tau}^N \geq n + 1 \right)$$

$$q_{j,n}^N := \mathbb{P} \left(Y_n^N = x_j^N, \tilde{\tau}^N = n \right).$$

- Recall, wanted to optimise $F(t, B_t)$. Write $t(n) = n/N$ for 'time' corresponding to step n of Y . Then $\bar{F}_{j,n} := F(t(n), x_j)$.

First LP problem

Then the optimisation problem for the discrete process can formally be rewritten as:

$$\mathcal{P}^{N'} : \text{maximise } \sum_{\substack{j \in \mathcal{J} \\ n \geq 1}} \bar{F}_{j,n}^N q_{j,n} \quad \text{over } (p_{j,n})_{\substack{j \in \mathcal{J}' \\ n \geq 1}}, (q_{j,n})_{\substack{j \in \mathcal{J} \\ n \geq 1}}$$

subject to:

- $p_{j,n}, q_{j,n} \geq 0, \quad \forall j, n$
- $\sum_{n=1}^{\infty} q_{j,n} = \mu^N(\{x_j^N\}), \quad \forall j \in \mathcal{J}$
- $p_{j,n} + q_{j,n} = \frac{1}{2}(p_{j-1,n-1} + p_{j+1,n-1}), \quad \forall n \geq 2, j \in \mathcal{J}''$
- $p_{j_1^N,n} + q_{j_1^N,n} = \frac{1}{2}p_{j_2^N,n-1}, \quad p_{j_{L-1}^N,n} + q_{j_{L-1}^N,n} = \frac{1}{2}p_{j_{L-2}^N,n-1}, \quad \forall n \geq 2$
- $p_{j^*+1,1} + q_{j^*+1,1} = \frac{1}{2}, \quad \bullet p_{j^*-1,1} + q_{j^*-1,1} = \frac{1}{2}$
- $p_{j,1} + q_{j,1} = 0, \quad \forall j \neq j^*, j_0^N, j_L^N, \quad \bullet q_{j_0^N,1} = 0 = q_{j_L^N,1}$
- $q_{j_L^N,n} = \frac{1}{2}p_{j_{L-1}^N,n-1}, q_{j_0^N,n} = \frac{1}{2}p_{j_1^N,n-1}, \quad \forall n \geq 2$

Discretisation

In principle, we could consider this problem, but direct approach doesn't seem to help. . . Introduce new formulation $\mathcal{P}^N(\lambda)$ where:

- Remove q variable: embedding condition derived from potential:

$$\sum_{n=1}^{\infty} p_{j,n} \leq U_j \sim \int |x_j^N - y| \mu(dy) - |x_j^N|$$

- Restrict to $p_{j,n}$ satisfying a decay requirement. Lemma: If $\pi_{j,n}$ is probability when only stopping at x_*, x^* , then $\pi_{j,n} \approx \rho^n m_j$, some $\rho \in (0, 1)$.
- Fix $\lambda > \rho^{-1} > 1$. Then restrict to set

$$\ell^1(\lambda) := \left\{ (p_{j,n})_{j,n} : \sum_{j,n} |p_{j,n}| \lambda^n < \infty \right\}$$

Dual problem

$$\mathcal{D}^N(\lambda) = \inf \left\{ \sum_{j \in \mathcal{J}'} \nu_j U_j + \frac{1}{2} (\eta_{j^*+1,1} + \eta_{j^*-1,1}) + \frac{1}{2} (\bar{F}_{j^*+1,1}^N + \bar{F}_{j^*-1,1}^N) \right\}$$

over $(\nu_j)_{j \in \mathcal{J}'}, (\eta_{j,t})_{\substack{j \in \mathcal{J} \\ t \geq 1}}$, where $(\nu, \eta) \in \ell^\infty(\lambda^{-1})$ and:

- $\eta_{j,t}, \nu_j \geq 0, \forall j, t$
- $\frac{1}{2} (\eta_{j+1,t+1} + \eta_{j-1,t+1}) - \eta_{j,t} - \nu_j$
 $\leq \bar{F}_{j,t}^N - \frac{1}{2} (\bar{F}_{j+1,t+1}^N + \bar{F}_{j-1,t+1}^N), \quad \forall j, t.$

- Note: Close correspondence to previous (continuous) dual solution

Theorem

For $\mathcal{P}^N(\lambda), \mathcal{D}^N(\lambda)$, there is no duality gap, and the optimiser is attained in the dual problem.

- Key point: can show 'core' of feasible solutions using properties of the probabilities $\pi_{j,n}$. Essentially, can 'run' stopped mass to the boundaries for 'interior' solutions to the primal problem.

Lemma

Suppose $\mathcal{P}^N < \infty$. Then \mathcal{P}^N is attained by some $p^* \in \ell^1$, and $\mathcal{P}^N = \mathcal{P}^N(\lambda)$.

- Essentially, feasible region of \mathcal{P}^N is compact in ℓ^1 .
- In general, do not expect $\mathcal{P}^N(\lambda)$ to be attained, but can ‘cut-off’ solutions in ℓ^1 to make them feasible for $\ell^1(\lambda)$.
- Discrete version of Monotonicity Principle \implies geometric form of optimiser.

Dual optimisers

- Our motivation for looking at the dual solution is to understand the Γ condition
- In e.g. the LETF case, can also verify that the dual solution can be assumed to be in ℓ^∞ by a truncation argument
- This is sufficient to ensure that complementary slackness holds!
- In particular, we can show:

Lemma

Condition (Γ) holds in the limiting K -cave barrier \mathcal{B}^∞ .

And hence:

Theorem

For a K -cave stopping time τ given by curves l, r , the condition (Γ) is necessary for optimality.

- "Robust Hedging of Options on a Leveraged Exchange Traded Fund", (With S. M. Kinsley). arXiv:1702.07169
- "Discretisation and Duality of Optimal Skorokhod Embedding Problems", (With S. M. Kinsley). arXiv:1702.07173

Conclusions

- Considered solutions to SEP which could not be completely recovered from the Monotonicity Principle: geometric characterisation does not guarantee uniqueness
- Need an additional condition, based on dual solution to determine optimal stopping region
- Proof of sufficiency of condition based on discretisation and classical duality results
- Need subtle duality results to get dual existence

Theorem (Borwein & Zhu, Theorem 4.4.3)

Let X and Y be Banach spaces, let $f : X \rightarrow \mathbb{R} \cup \{\infty\}$ and $g : Y \rightarrow \mathbb{R} \cup \{\infty\}$ be convex functions and let $A : X \rightarrow Y$ be a bounded linear map. Define the primal and dual values $p, d \in [-\infty, \infty]$ by the Fenchel problems

$$p = \inf_{x \in X} \{f(x) + g(Ax)\}$$

$$d = \sup_{y^* \in Y^*} \{-f^*(A^*y^*) - g^*(-y^*)\}.$$

Then $p = d$, and *the supremum in the dual problem is achieved if either of the following hold*

- 1 $0 \in \text{core}(\text{dom}(g) - A\text{dom}(f))$ and f, g are lower semi-continuous
- 2 $A\text{dom}(f) \cap \text{cont}(g) \neq \emptyset$.

Hard part: show dual attainment.