

# CHARACTERIZATION OF A WASSERSTEIN TYPE DISTANCE IN TERMS OF A STOCHASTIC CONTROL PROBLEM

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# INTRODUCTION

Motivated by **ROBUST CALIBRATION PROBLEMS FOR DIFFUSION TYPE MODELS** we introduce a new distance on the set of probability distributions which are solutions to martingale problems. Like the classical Wasserstein distance, **THIS NEW DISTANCE METRIZES THE WEAK TOPOLOGY**.

This new distance is the value function of a stochastic control problem. We prove that **THE CORRESPONDING HAMILTON-JACOBI-BELLMAN EQUATION HAS A SMOOTH SOLUTION**.

This allows one to obtain numerical evaluations.  
We finally exhibit an optimal coupling measure.

# OUTLINE

- 1 THE DISTANCE  $\widetilde{\mathcal{W}}^2$
- 2 INTERPRETATION OF  $\widetilde{\mathcal{W}}^2$  IN TERMS OF STOCHASTIC CONTROL

$\Omega_d = L_2([0, T], \mathbf{R}^d)$  is a Polish space. The Wasserstein distance  $\mathcal{W}^2$  metrizes the weak topology on the set of measures  $\mathbb{P}$  such that  $\mathbb{E}^{\mathbb{P}} \int_0^T |\omega_s|^2 ds < \infty$ .

$$\mathcal{W}^2(\mathbb{P}; \bar{\mathbb{P}}) := \left\{ \inf_{\pi \in \Pi(\mathbb{P}; \bar{\mathbb{P}})} \int_{\Omega_{2d}} \int_0^T |\omega_s - \bar{\omega}_s|^2 ds \pi(d\omega, d\bar{\omega}) \right\}^{\frac{1}{2}}, \quad (1)$$

$\pi$  has marginal distributions  $\mathbb{P}$  and  $\bar{\mathbb{P}}$ .

Unfortunately numerical computation is impossible.

## DEFINITION

$$\mathbf{P} = \{\mathbb{P}_x^{\mu, \sigma}, \mu, \sigma \text{ Lipschitz}, \sigma \text{ strongly elliptic}, x \in \mathbf{R}^d\}$$

where  $\mathbb{P}_x^{\mu, \sigma}$  is the probability distribution of the unique strong solution to the stochastic differential equation with coefficients  $\mu$  and  $\sigma$  and initial condition  $x$ .

## DEFINITION

Given two probability measures  $\mathbb{P}_x^{\mu, \sigma}$  and  $\mathbb{P}_{\bar{x}}^{\bar{\mu}, \bar{\sigma}}$  belonging to  $\mathbf{P}$ , let  $\widetilde{\Pi}(\mathbb{P}_x^{\mu, \sigma}; \mathbb{P}_{\bar{x}}^{\bar{\mu}, \bar{\sigma}})$  be the set of the probability distribution  $\widetilde{\mathbb{P}}$  of  $(X^C, \bar{X})$  solution to the following system of SDEs:

$$\begin{cases} dX_s^C = \mu(X_s^C) ds + \sigma(X_s^C) (\mathcal{C}_s d\bar{W}_s + \mathcal{D}_s dW_s), \\ d\bar{X}_s = \bar{\mu}(\bar{X}_s) ds + \bar{\sigma}(\bar{X}_s) d\bar{W}_s, \end{cases} \quad (2)$$

with initial condition  $(x, \bar{x})$ , with  $(\mathcal{C}_s)$  predictable with values in correlation matrices and  $\mathcal{D}_s = \sqrt{\text{Id}_d - \mathcal{C}_s \mathcal{C}_s^\top}$  for any  $0 \leq s \leq T$ .

# DEFINITION OF $\widetilde{\mathcal{W}}^2$

## DEFINITION

$$\widetilde{\mathcal{W}}^2(\mathbb{P}_x^{\mu, \sigma}; \mathbb{P}_{\bar{x}}^{\bar{\mu}, \bar{\sigma}}) := \left\{ \inf_{\tilde{\mathbb{P}} \in \tilde{\Pi}(\mathbb{P}_x^{\mu, \sigma}; \mathbb{P}_{\bar{x}}^{\bar{\mu}, \bar{\sigma}})} \int_{\Omega} \int_0^T |\omega_s - \bar{\omega}_s|^2 ds \tilde{\mathbb{P}}(d\omega, d\bar{\omega}) \right\}^{\frac{1}{2}}. \quad (3)$$

## PROPOSITION

$\widetilde{\mathcal{W}}^2$  metrizes the weak topology on the set of probability distributions  $\mathbb{P}_x^{\mu, \sigma}$  with coefficients  $\mu$  and  $\sigma$  uniform Lipschitz bounded and  $x$  in a compact set.

# OUTLINE

- 1 THE DISTANCE  $\widetilde{\mathcal{W}}^2$
- 2 INTERPRETATION OF  $\widetilde{\mathcal{W}}^2$  IN TERMS OF STOCHASTIC CONTROL



# INTERPRETATION OF $\widetilde{\mathcal{W}}^2$

The corresponding Hamilton–Jacobi–Bellman equation is the following:

$$\begin{cases} \partial_t V(t, x, \bar{x}) + \mathcal{L}V(t, x, \bar{x}) + H(t, x, \bar{x}, V) = -|x - \bar{x}|^2, & 0 \leq t < T, \\ V(T, x, \bar{x}) = 0, \end{cases} \quad (4)$$

$$\begin{aligned} \mathcal{L}V(t, x, \bar{x}) := & \sum_{i=1}^d \mu_i(x) \partial_{x_i} V(t, x, \bar{x}) + \sum_{i=1}^d \bar{\mu}_i(\bar{x}) \partial_{\bar{x}_i} V(t, x, \bar{x}) \\ & + \frac{1}{2} \sum_{i,j=1}^d (\sigma \sigma^\top(x))^{ij} \partial_{x_i, x_j}^2 V(t, x, \bar{x}) + \frac{1}{2} \sum_{i,j=1}^d (\bar{\sigma}(\bar{x}) \bar{\sigma}(\bar{x})^\top)^{ij} \partial_{\bar{x}_i, \bar{x}_j}^2 V(t, x, \bar{x}) \end{aligned}$$

$$\text{and } H(t, x, \bar{x}, V) := \min_{C \in \mathbb{C}_d} \sum_{i,j=1}^d (\sigma(x) C \bar{\sigma}(\bar{x})^\top)^{ij} \partial_{x_i, \bar{x}_j}^2 V(t, x, \bar{x}).$$

## ONE DIMENSIONAL CASE

Consider the family of stochastic differential equations

$$\begin{aligned}\forall t \leq \theta \leq T, \quad X_\theta^* &= x + \int_t^\theta \mu(X_s^*) ds + \int_t^\theta \sigma(X_s^*) d\bar{W}_s. \\ \bar{X}_\theta &= \bar{x} + \int_t^\theta \bar{\mu}(\bar{X}_s) ds + \int_t^\theta \bar{\sigma}(\bar{X}_s) d\bar{W}_s.\end{aligned}$$

consider the function

$$V^*(t, x, \bar{x}) := \mathbb{E} \int_t^T (X_\theta^*(t, x) - \bar{X}_\theta(t, \bar{x}))^2 d\theta.$$

This function is the unique classical solution to the parabolic PDE

$$\left\{ \begin{array}{l} \frac{\partial V^*}{\partial t} + \mu(x) \frac{\partial V^*}{\partial x} + \bar{\mu}(\bar{x}) \frac{\partial V^*}{\partial \bar{x}} + \frac{1}{2} \sigma^2(x) \frac{\partial^2 V^*}{\partial x^2} + \frac{1}{2} \bar{\sigma}^2(\bar{x}) \frac{\partial^2 V^*}{\partial \bar{x}^2} \\ \quad + \sigma(x) \bar{\sigma}(\bar{x}) \frac{\partial^2 V^*}{\partial x \partial \bar{x}} = -(x - \bar{x})^2, \\ V^*(T, x, \bar{x}) = 0. \end{array} \right.$$

# ONE DIMENSIONAL CASE

$$\frac{\partial^2 V^*}{\partial x \partial \bar{x}}(t, x, \bar{x}) = -2 \int_t^T \mathbb{E} \left[ \frac{d}{dx} X_s^*(t, x) \frac{d}{d\bar{x}} \bar{X}_s(\bar{x}) \right] ds.$$

The derivative of the flow is a stochastic exponential. It follows that

$$\forall t, x, \bar{x}, \quad \frac{\partial^2 V^*}{\partial x \partial \bar{x}}(t, x, \bar{x}) < 0.$$

Therefore we have exhibited a classical solution  $V^*(t, x, \bar{x})$  to the Hamilton-Jacobi-Bellman equation

$$\left\{ \begin{array}{l} \frac{\partial V}{\partial t} + \mu(x) \frac{\partial V}{\partial x} + \bar{\mu}(\bar{x}) \frac{\partial V}{\partial \bar{x}} + \frac{1}{2} \sigma^2(x) \frac{\partial^2 V}{\partial x^2} + \frac{1}{2} \bar{\sigma}^2(\bar{x}) \frac{\partial^2 V}{\partial \bar{x}^2} \\ \quad + \min_{C \in [-1, 1]} \left( C \sigma(x) \bar{\sigma}(\bar{x}) \frac{\partial^2 V}{\partial x \partial \bar{x}} \right) = -(x - \bar{x})^2, \\ V(T, x, \bar{x}) = 0. \end{array} \right.$$

# MULTIDIMENSIONAL CASE: EXISTENCE OF A REGULAR SOLUTION TO THE HJB EQUATION

## THEOREM

Suppose:

- (I) The functions  $\mu, \bar{\mu}, \sigma$  and  $\bar{\sigma}$  are in the Hölder space  $C^{1+\alpha}(\mathbf{R}^d)$  with  $0 < \alpha \leq 1$ .
- (II) The matrix-valued functions  $a(x) := \sigma(x)\sigma(x)^\top$  and  $\bar{a}(x) := \bar{\sigma}(x)\bar{\sigma}(x)^\top$  satisfy the strong ellipticity condition

$$\exists \lambda > 0, \forall \xi, \bar{\xi}, x, \sum_{i,j=1}^d a^{ij}(x) \xi^i \xi^j + \sum_{i,j=1}^d \bar{a}^{ij}(x) \bar{\xi}^i \bar{\xi}^j \geq \lambda(|\xi|^2 + |\bar{\xi}|^2).$$

Then there exists a solution  $V$  to the HJB equation (4),  $V \in C^{1,2}([0, T] \times \mathbf{R}^d)$  such that  $\partial_t V, \partial_{x_i, \bar{x}_j}^2 V, \dots$  are  $(\frac{\alpha}{2}, \alpha)$  Hölder.

# APPROXIMATION AMONG DIFFUSION LAWS

Recall that  $H(t, x, \bar{x}, V) = \min_{C \in \mathbf{C}_d} \sum_{i,j=1}^d (\sigma(x) C \bar{\sigma}(\bar{x})^\top)^{ij} \partial_{x_i, \bar{x}_j}^2 V(t, x, \bar{x})$

## PROPOSITION

For every  $\epsilon > 0$  there is a continuous map  $C_\epsilon(s, x, \bar{x})$  taking values in the set of correlation matrices which is pointwise  $\epsilon$ -optimal:  $\forall s, x, \bar{x}$ ,

$$H(t, x, \bar{x}, V) \leq \sum_{i,j=1}^d (\sigma(x) C_\epsilon(s, x, \bar{x}) \bar{\sigma}(\bar{x})^\top)^{ij} \partial_{x_i, \bar{x}_j}^2 V(t, x, \bar{x}) \leq H(t, x, \bar{x}, V) + \epsilon. \quad (5)$$

There exists a sequence  $(\mathbb{P}^{\mu^m, \sigma^m})$  of solutions to martingale problems with continuous Markovian coefficients  $\mu^m$  and  $\sigma^m$  such that

$$\int_{\Omega} \int_0^T |\omega_s - \bar{\omega}_s|^2 ds \mathbb{P}^{\mu^m, \sigma^m}(d\omega, d\bar{\omega})$$

converges to  $\widetilde{\mathcal{W}}^2(\mathbb{P}^{\mu, \sigma}; \mathbb{P}^{\bar{\mu}, \bar{\sigma}})$ .

# EXISTENCE OF AN OPTIMAL COUPLING MEASURE

## THEOREM

There exist a predictable process  $C^*$  and an adapted and continuous solution on  $[0, T]$  to the system

$$\begin{cases} X_t^* = x + \int_0^t \mu(X_s^*) ds + \int_0^t \sigma(X_s^*) C_s^* d\overline{W}_s + \int_0^t \sigma(X_s^*) D_s^* dW_s, \\ \overline{X}_t = \bar{x} + \int_0^t \overline{\mu}(\overline{X}_s) ds + \int_0^t \overline{\sigma}(\overline{X}_s) d\overline{W}_s, \\ C_s^* \in \arg \min_{C \in \mathbf{C}_d} \sum_{i,j=1}^d \left( \sigma(X_s^*) C \overline{\sigma}(\overline{X}_s)^T \right)_{ij} \partial_{x_i \bar{x}_j}^2 V(s, X_s^*, \overline{X}_s), \\ D_s^* = \sqrt{\text{Id}_d - C_s^* C_s^{*\top}} \end{cases} \quad (6)$$

which satisfies

$$V(0, x, \bar{x}) = \mathbb{E} \int_0^T |X_t^* - \overline{X}_t|^2 dt = \widetilde{\mathcal{W}}^2(\mathbb{P}_x^{\mu, \sigma}; \mathbb{P}_{\bar{x}}^{\overline{\mu}, \overline{\sigma}}).$$