Undecidability of the Domino Problem

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Theorem (Berger 1964 (PhD), 1966 (Memoirs of the AMS))

There is no algorithm that decides, given a tileset τ , if τ tiles the plane.

To prove such a statement, we need a formal definition of an algorithm/program/computable function.

Many formal definitions of computable functions:

- with programs (λ-calculus) (Church 1936)
- with axioms (Herbrand-Gödel-Kleene 1936)
- with a mechanical device (Turing 1937)

All definitions are equivalent: there is a single notion of a computable function.

Church-Turing thesis: all reasonable notions of computable functions agree.

Note: these are notions of computable functions, not of algorithms.

Computable functions and computable sets are either defined on nonnegative integers or finite words.

To speak about an algorithm that takes tilesets as input, we need to agree on an encoding of tilesets as integers, or finite words. The exact encoding doesn't matter, as long as it is natural.



2) The Fixed Domino Problem



The Turing machine is a mathematical abstraction of computations by a human being, introduced by Turing (1937).

Out of all models of computations, the TM is arguably the one most suitable for undecidability proofs, due to its mechanical nature.

- The TM works in discrete time steps.
- At each step, the entire work space of the Turing is represented by a one-dimensional *tape*
 - The tape can be simply infinite or biinfinite. Both models are equivalent.
 - Formally, a tape is an element of A^N or A^Z, for A some given finite alphabet.

a	b	b	a	b	a	b	a	a	b

- A scanning device is installed on the tape. It is called a *head*.
- The scanning device has an internal state, formally an element of a finite set Q

			$\overbrace{1}$						
a	b	Ъ	a	Ъ	a	b	a	a	Ъ

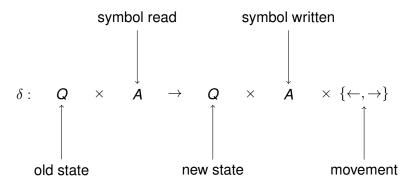
At each step, the Turing machine operates only depending on what the scanning device can see:

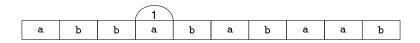
- Its internal state
- The symbol it sees

and may:

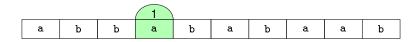
- Change its internal state
- Change the symbol on the head
- Move the head

Formally, this is given by a (finite) map:

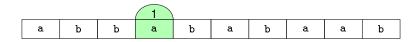




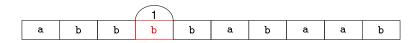
	a	b
0	a,1, $ ightarrow$	b,1,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



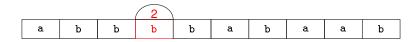
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



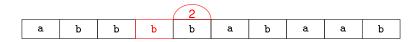
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b, 0 ,←	a,2, $ ightarrow$



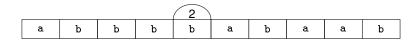
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



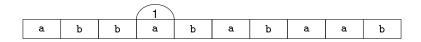
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b, 0 ,←	a,2, $ ightarrow$



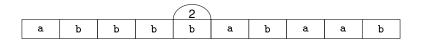
	a	b
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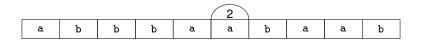
	a	b
0	a,1, $ ightarrow$	b,1,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



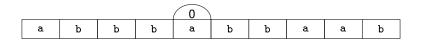
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



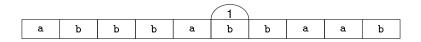
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



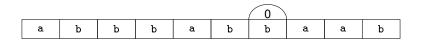
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$	b,0, $ ightarrow$
2	b,0,←	a,2, $ ightarrow$



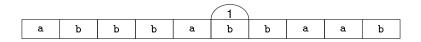
	a	b	
0	a,1, $ ightarrow$	b, 1 ,←	
1	b,2, $ ightarrow$	b,0, $ ightarrow$	
2	b,0,←	a,2, $ ightarrow$	



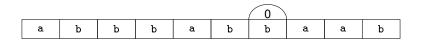
	a	b	
0	a,1, $ ightarrow$	b, 1 ,←	
1	b,2, $ ightarrow$ $ $ b,0,-		
2	b,0,←	a,2, $ ightarrow$	



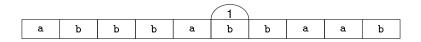
	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$ b,0, $ ightarrow$	
2	b,0,←	a,2, $ ightarrow$



	a	b	
0	a,1, $ ightarrow$	b, 1 ,←	
1	b,2, $ ightarrow$ $ $ b,0,-		
2	b,0,←	a,2, $ ightarrow$	



	a	b
0	a,1, $ ightarrow$	b, 1 ,←
1	b,2, $ ightarrow$ b,0, $ ightarrow$	
2	b,0,←	a,2, $ ightarrow$

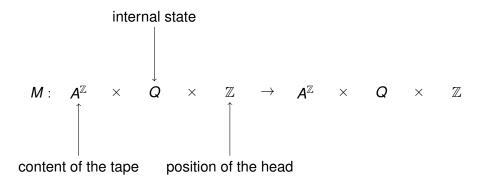


	a	b	
0	a,1, $ ightarrow$	b, 1 ,←	
1	b,2, $ ightarrow$ $ $ b,0,-		
2	b,0,←	a,2, $ ightarrow$	

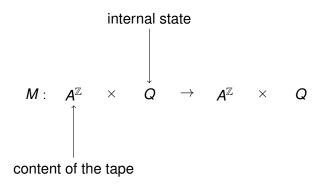
In the previous example, the head was moving

Dually, we can keep the head in the same place and move the tape

(if the tape is biinfinite) The approach we will take depends on the context.



We can switch \mathbb{Z} with \mathbb{N} for simply infinite tapes.



Head always at position 0.

How to compute with a Turing machine ?

- We write the input on the tape
- We reset the head (at the beginning of the tape, with an initial internal state)
- We run the Turing machine until we go to a special state, called the Halting state
- We read the output from the tape

A Turing machine defines a function from Σ^* to Σ^* where Σ is the input/output alphabet.

 $(\Sigma^{\star} \text{ is the set of finite words over alphabet } \Sigma)$

The function may not be defined everywhere: If the Turing machine does not reach the Halting state, it will not halt, and the function is not defined.

Any algorithm may be simulated by a Turing

Definition

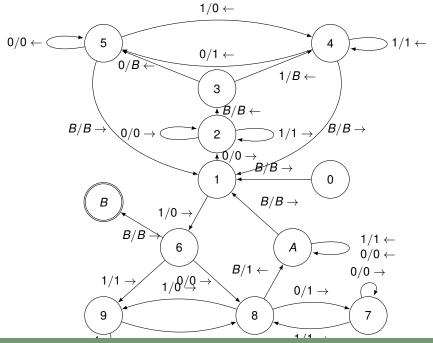
A function is *computable* if it can be computed by a Turing machine.

Example

	0	1	В
0			$^{\mathrm{B},1, ightarrow}$
1	0,2,→	0,6,→	
2	0,2,→	1,2,→	Β,3,←
3		в,4,←	
4	1,5,←	1,4,←	
5	0,5,←	0,4,←	$^{\tt B,1,\rightarrow}$
6	0 ,8 ,→	1,9,→	$^{\tt B,B,\rightarrow}$
7	0,7,→	1,8,→	
8	1,7, $ ightarrow$	0 ,9 ,→	1, A ,←
9	0,8,→	1,9,→	0 ,8 ,→
Α	0, A ,←	1, A ,←	$^{\tt B,1,\rightarrow}$

Initial state: 0 Halting state: B What is the output starting from 011?

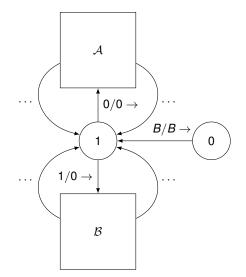
E. Jeandel and P. Vanier



To understand this particular Turing machine, the input has to be seen as an number represented in binary from least to most significant bit.

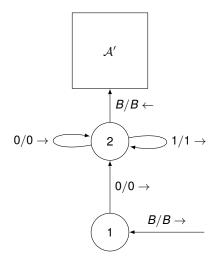
So 011 represents the number 6.

Form of the Turing Machine



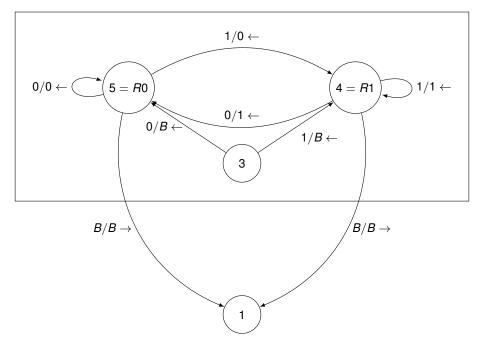
- 1. If the input begins with 0
 - $\bullet \, \text{ do } \mathcal{A}$
- else
 - do B

Our input is 011, so it begins with 0, let's see ${\cal A}$



- 1. If the input begins with 0
 - go to the end of the input
 - $\bullet \ \text{do} \ \mathcal{A}'$

 $\bullet \ \text{do} \ \mathcal{B}$

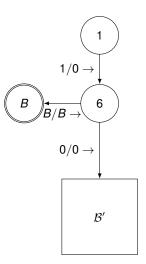


- 1. If the input begins with 0
 - go to the end of the input
 - shift the input to the left
 - go back to 1.

o do B

- 1. If *n* is even
 - divide *n* by 2
 - go back to 1.

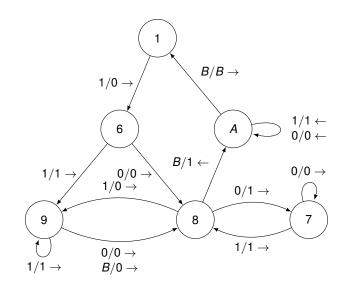
 $\bullet \ \text{do} \ \mathcal{B}$

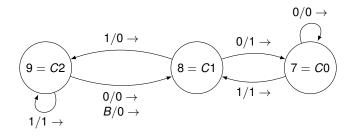


- 1. If n is even
 - divide n by 2
 - go back to 1.

- If *n* = 1
 - Output 0 and halt
- else
 - $\bullet \ \, \text{Do} \ \, \mathcal{B}'$

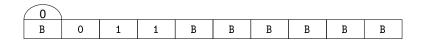
1. If *n* is even • $n \leftarrow n/2$ • go back to 1. else • If n = 1• Output 0 and halt • else • $n \leftarrow 3n + 1$ • go back to 1.





The Turing machine, starting from n (seen as a number coded in binary)

- halts and output 0 if the Collatz sequence starting from n eventually reaches the integer 1
- o does not halt otherwise.







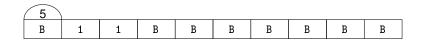
			2						
В	0	1	1	В	В	В	В	В	В

				2					
В	0	1	1	В	В	В	В	В	В

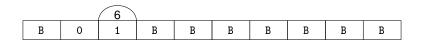
			3						
В	0	1	1	В	В	В	В	В	В







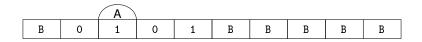




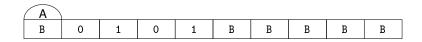
			9						
В	0	1	В	В	В	В	В	В	В

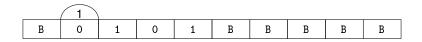
				8					
В	0	1	0	В	В	В	В	В	В

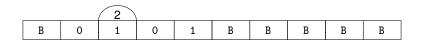
			A						
В	0	1	0	1	В	В	В	В	В











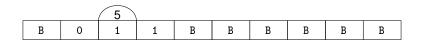
			2						
В	0	1	0	1	В	В	В	В	В

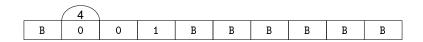
				2					
В	0	1	0	1	В	В	В	В	В

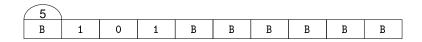
					2				
В	0	1	0	1	В	В	В	В	В

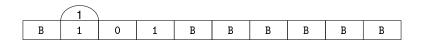
3										
	В	0	1	0	1	В	В	В	В	В

4										
	В	0	1	0	В	В	В	В	В	В









With Turing machines, we can code:

- Arithmetic
- Subroutines
- Flow control (if, while)

""""Therefore""""

We can code any algorithm with a Turing machine

The Turing Machine





Theorem (Berger 1964 (PhD), 1966 (Memoirs of the AMS))

There is no algorithm that decides, given a tileset τ , if τ tiles the plane.

How to use the concept of a Turing machine to prove this ?

We first need a hard problem on Turing machines

Theorem

There is no algorithm that can decide, given a Turing machine M and an input n, if M halts on input n.

The set of Turing machines is countable, write M_n for the function computed by the *n*-th Turing machine

By Cantor's diagonal argument, there exists a function which is not computed by a Turing machine:

$$f(n) = \begin{cases} 0 & \text{if } M_n(n) \text{ does not halt} \\ undef & \text{if } M_n(n) \text{ halts} \end{cases}$$

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$$f(n) = \begin{cases} 0 & \text{if } M_n(n) \text{ does not halt} \\ undef & \text{if } M_n(n) \text{ halts} \end{cases}$$

The only thing we need to turn f into an algorithm is to decide in which case we are

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By Cantor's diagonal argument, there exists a function which is not computed by a Turing machine:

$$f(n) = \begin{cases} 0 & \text{if } M_n(n) \text{ does not halt} \\ undef & \text{if } M_n(n) \text{ halts} \end{cases}$$

Therefore no algorithm can decide in which case we are

Theorem

There is no algorithm that can decide, given a Turing machine M, if M halts on the empty input.

(Given a machine M and an input n, we can build a machine M^n s.t. M^n on the empty input simulates M on input n.)

- We will build an algorithm that, starting from a Turing machine M, will build a tileset τ s.t.
 - Deciding if τ tiles the plane is the same as deciding if *M* halts on the empty input.
- Therefore no algorithm can decide if a tileset tiles the plane, as it would be able to decide if a Turing machine halts.

- It is easy to see that a tileset τ does not tile the plane: just find an N s.t. it does not tile a N × N square
- It is easy to see that a Turing machine halts : just find an N s.t. it halts in N steps.

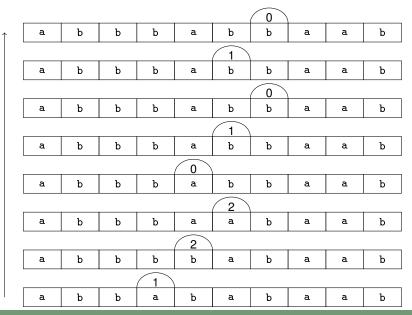
Therefore our transformation should satisfy:

 τ tiles the plane iff *M* does not halt on empty input.

How to transform a Turing machine into a tileset ?

It is actually very easy! (sadly with a *caveat*).

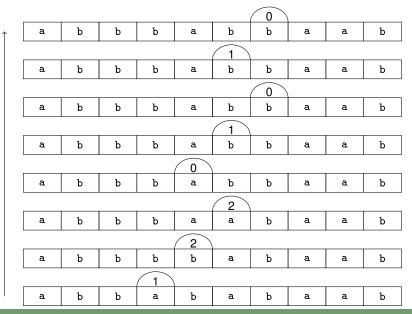
Space-time diagram



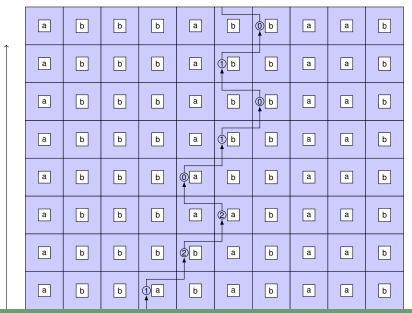
The space-time diagram of a Turing machine is almost a tiling.

• Every constraint can be expressed locally

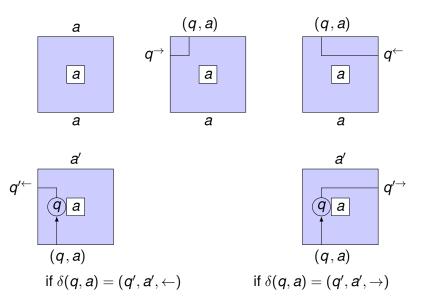
Space-time diagram



Space-time diagram



Tiles



Every infinite computation of a Turing machine gives rise to a tiling of the upper half plane

It can be completed into a tiling of the entire plane by adding "blank tiles" in the bottom half plane.

Not every tiling of the plane is an infinite computation of a Turing machine.

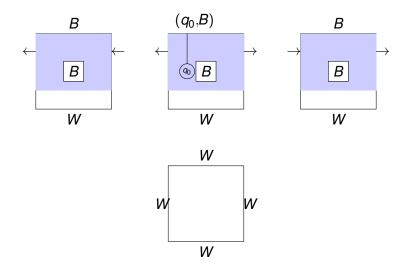
Erratic configurations:

- tilings with no head per row
- tilings with more than one head per row
- tilings may no start from the initial state
- tilings using only the blank tile

If one row of a tiling represents a configuration of the TM, then the upper lane above it is correct.

If we can force one row, we can force everything above.

Semi-solution



Let t be the tile at the middle of the previous slide. Then there exists a tiling that contains t iff the TM does not halt on the empty input.

Theorem (Wang, Kahr-Moore-Wang)

There is no algorithm that decides, given a tileset τ and a tile t whethere there exist a tiling by τ that contains t.

Theorem

There is no algorithm that decides, given a tileset τ and a tile t whethere there exist a tiling of a quarter of the plane by τ with t at the bottom left.

Use a Turing machine with a simply infinite tape, and "border tiles".

Theorem

There is no algorithm that decides, given a tileset τ and two tiles t_1 , t_2 if there is a tiling of a square by τ with t_1 at the bottom left and t_2 at the top right.

Use border tiles to form a square, and take t_2 to contain the halting state of *M*.

What is missing to prove the undecidability of the Domino Problem ?

Two methods:

- Find a way to force the tile t to appear
- Change the coding to be certain that a head will appear in every row
 - Does not solve everything.
- We will explain this next time.

The Turing Machine

2 The Fixed Domino Problem



We are missing some ingredients for the Domino Problem, but we are almost ready to prove the undecidability of the Periodic Domino Problem.

Theorem (Gurevich-Koryakov)

There is no algorithm that decides, given a tileset τ whethere there exist a periodic tiling by τ .

Assume there is an aperiodic tileset.

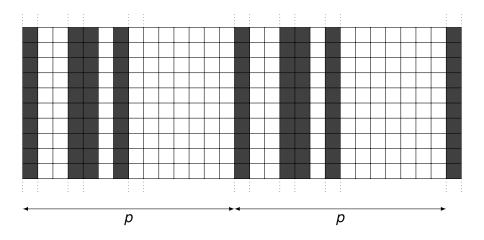
None

Second Ingredient

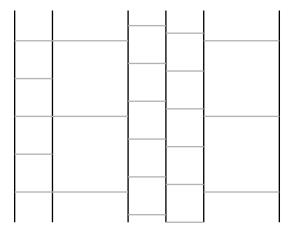


for each color that appear in the aperiodic tileset.

Periodic tilings ?

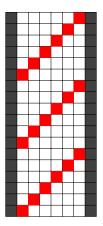


Third Ingredient. Goal



Third Ingredient. Concept

A red particle that teleports once it reads a vertical wall

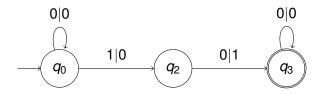


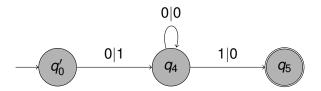
The particle is a 1, the void is 0

Each line is therefore a word in $0^{+}10^{+}$.

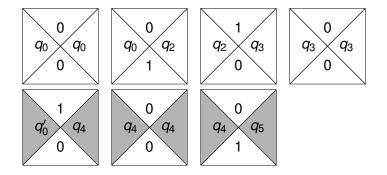
Third Ingredient. A transducer

The transducer takes one line to the next one.

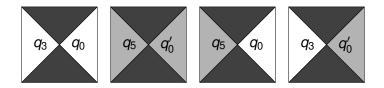




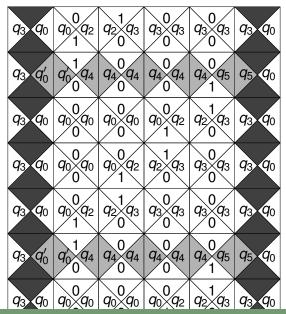
Third Ingredient. White tiles



Third Ingredient. Black tiles

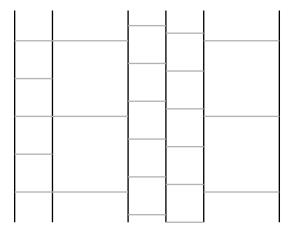


Third Ingredient. Proof of concept



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Third Ingredient. Goal: ACHIEVED



The previous result:

Theorem

There is no algorithm that decides, given a tileset τ and two tiles t_1 , t_2 if there is a tiling of a square by τ with t_1 at the bottom left and t_2 at the top right.

Given a tileset τ with colors in *C*, and tiles t_1 , t_2 , superimpose the tileset τ with the tileset we built:

- Every tile inside a square can hold an element of au
- Tiles on the border of squares can hold anything with colors in C (even if not in τ)
- The tile on the bottom-left on the square should be *t*₁.
- The tile on the top-right on the square should be *t*₂.

Last condition are easy to ensure, as the corners can be spotted easily.

There exists a tiling of period n \downarrow This tiling contains a square of size p \downarrow This square contains a tiling of τ with t_1 at the bottom left and t_2 at the top right There exist a tiling of a square by τ with t_1 at the bottom left and t_2 at the top right. \downarrow There exist a tiling of period p + 1

The proof of the undecidability of the Domino Problem (finally!)