Efficient nonparametric statistical inference for a non-linear inverse problem with the Schrödinger equation

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• We consider a regression-type measurement model

$$Y_i = u_f(x_i) + g_i, \quad i = 1, ..., n; \quad g_i \sim^{i.i.d.} N(0, 1)$$

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• The appropriate translation of this model to the continuous limit is

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 The regression function u_f = K(f) represents the forward data of some inverse problem. The goal is to infer f from the observation Y ~ P_{u_f}.

Partial Differential Equation (PDE) Models

- In many important applications (Stuart (2010)), the forward map $u_f = u(f)$ arises as the solution of a PDE with unknown coefficients f.
- For example $u = u_f$ is the solution of an elliptic partial differential equation

$$f_1 \Delta u + f_2 \cdot \nabla u - f_3 u = 0$$
 on \mathcal{O} , $f = (f_1, f_2, f_3)$,

on some domain \mathcal{O} in \mathbb{R}^d , subject to suitable boundary conditions. Here

$$\Delta = \sum_{i=1}^{d} \frac{\partial^2}{\partial x_i^2}$$

is the standard Laplacian and ∇ is the gradient operator.

- Some non-standard features:
- a) $f \mapsto u_f$ is **non-linear**, and
- b) unless d = 1 the solutions u_f do not have closed-form expressions.

 \bullet Suppose $\mathcal O$ is a bounded open domain in $\mathbb R^d$ with a smooth boundary. Let

$$f:\mathcal{O}\to [0,\infty)$$

be an unknown potential and consider solutions to the Schrödinger equation

$$rac{\Delta}{2}u - fu = 0 ext{ on } \mathcal{O}, \quad s.t. \ u = g ext{ on } \partial \mathcal{O},$$

where $g : \partial \mathcal{O} \to (0, \infty)$ is a given function describing Dirichlet boundary conditions.

• The unknown function f models an attenuation of the solution of the standard Laplace equation.

Inverse medium and scattering problems

• Recovering f from observed solutions u_f is important in many physical applications, including photo-acoustics (Bal and Uhlmann, 2010) or electromagnetic waves (Bao and Li, 2005).

• Physically f models a 'cooling' or 'absorption' effect in the medium O, where the local amount of absorption or cooling is described by the values f(x).



• From the famous Feynman-Kac representation we know

$$u_f(x) = E^x \left[g(X_{\tau_{\mathcal{O}}}) e^{-\int_0^{\tau_{\mathcal{O}}} f(W_s) ds} \right], \ x \in \mathcal{O},$$

where $(W_s : s \ge 0)$ is a *d*-dimensional Brownian motion started at $x \in \mathcal{O}$, with almost surely finite exit time $\tau_{\mathcal{O}}$ from \mathcal{O} .

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• From the above representation, and since g > 0, one shows $u_f \ge c > 0$, so

$$f = \frac{\Delta u_f}{2u_f}$$
 on \mathcal{O} .

One also shows, using standard regularity theory for elliptic PDEs, that u_f is two degrees smoother than f.

- Things **not** to do are:
 - a) Estimate f by $\frac{\Delta Y}{2Y}$, as it makes no pointwise sense.

b) Estimate f by a plug-in regression smoother $\frac{\Delta \hat{u}_f}{2\hat{u}_f}$ since nonparametric regression estimators \hat{u}_f are **not** solutions of the Schrödinger equation.

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- This would be closely related to the Tikhonov-regulariser:

$$\min_{f} \left[-2\langle Y, u_f \rangle_{L^2} + \|u_f\|_{L^2}^2 + \lambda \|f\|_{H^s}^2 \right],$$

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• As is well known, such a 'penalised least squares' approach is closely related to Bayesian inference with Gaussian priors (Kimeldorf and Wahba (1970)).

Bayes solutions of noisy inverse problems

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- Formally we model the function *f* by some prior distribution Π on function space and use Bayes' rule to compute the conditional posterior distribution

$$f \sim \Pi, \ Y | f \sim P_{u_f} \Rightarrow f | Y \sim \frac{dP_{u_f}(Y)d\Pi(f)}{\int dP_{u_f}(Y)d\Pi(f)}$$

where $dP_f \equiv dP_{u_f}$ is the law of a Gaussian white noise shifted by u_f .

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• Numerically efficient MCMC algorithms for computing posterior distributions have been put forward in the past decade; they allow to compute point estimates (MAP) and 'credible sets' for the unknown parameter f from the posterior distribution $\Pi(\cdot|Y)$.

Implementation for smooth images



Minimax rates for the inverse Schrödinger problem

• Recall that we are observing $Y = u_f + \varepsilon \mathbb{W}$ where u_f is the solution of

$$\frac{\Delta}{2}u - fu = 0 \text{ on } \mathcal{O}, \quad s.t. \ u = g \text{ on } \partial \mathcal{O}$$

in a smooth domain \mathcal{O} and we consider the inverse problem of finding the positive potential f from the data as the noise level $\varepsilon \to 0$.

• Let $C^{s}(\mathcal{O})$ denote the usual Hölder space over the domain \mathcal{O} , and for later use also define the subspace $C_{c}^{s}(\mathcal{O})$ of functions compactly supported within \mathcal{O} .

Theorem 1

Suppose
$$g \in C^{s+2}(\partial \mathcal{O})$$
 satisfies $g \ge g_{min} > 0$. We have as $\varepsilon \to 0$ that

$$\inf_{\tilde{f}=\tilde{f}(Y,g)} \sup_{f:\|f\|_{\mathcal{C}^{s}(\mathcal{O})\leq B, f\geq f_{min}>0}} \varepsilon^{-2s/(2s+4+d)} E_{f}^{Y} \|\tilde{f}-f\|_{L^{2}(\mathcal{O})}\simeq c(s,B,g)>0.$$

• This corresponds to a 2-ill posed problem but also incorporates the 2-smoothing property of the 'elliptic forward map' $f \mapsto u_f$.

A wavelet series prior and contraction theorem

• We model f by a prior Π induced by the random function

$$\log f = \sum_{l \leq J,r} b_{l,r} \Phi_{l,r}^{\mathcal{O}}, \quad b_{l,r} \sim^{i.i.d.} U(-B2^{-l(s+d/2)}, 2^{-l(s+d/2)}B),$$

where the $(\Phi_{l,r}^{\mathcal{O}})$ form a (boundary corrected) wavelet basis of $L^2(\mathcal{O})$.

• We do not consider hyper-priors for B, s, J here, but regard s, B as given and choose J such that $2^J \approx \varepsilon^{-2s/(2s+4+d)}$ ('non-adaptive' case).

Theorem 2

Suppose $f_0 > 0$ satisfies $\|\log f_0\|_{C^s_c(\mathcal{O})} \le B$ for some s > 2 + d/2. If $\Pi(\cdot|Y)$ is the posterior distribution arising from the above prior Π , then, as $\varepsilon \to 0$ we have

$$\exists \left(f: \|f-f_0\|_{L^2} \geq M \varepsilon^{-2s/(2s+4+d)} \log^{\gamma}(1/\varepsilon) |Y\right) \to 0 \text{ in } P_{f_0}^Y \text{-probability}.$$

• The posterior mean $\overline{f}(Y)$ attains the same convergence rate in $L^2(\mathcal{O})$.

Towards Bernstein -von Mises theorems: LAN expansion

- We want more precise 'efficiency' results, and to justify Bayesian 'uncertainty quantification'.
- To do this we first need to understand the 'information geometry' of the LAN expansion. Using perturbation arguments for PDEs one can prove

Theorem 3

Under mild conditions on $h \in C(\mathcal{O}), f_0 > 0, g > 0$, if $Y = u_{f_0} + \varepsilon \mathbb{W}$ then as $\varepsilon \to 0$

$$\log \frac{dP_{u_{f_0}+\varepsilon h}}{dP_{u_{f_0}}}(Y) = \langle Du_{f_0}[h], \mathbb{W} \rangle_{L^2} - \frac{1}{2} \| Du_{f_0}[h] \|_{L^2}^2 + o_{P_{f_0}^Y}(1),$$

where the score operator $Du_{f_0}[\cdot]$ maps h into the solution $v = v_h$ of the inhomogeneous Schrödinger equation

$$rac{\Delta v}{2} - fv = hu_{f_0} ext{ on } \mathcal{O} ext{ s.t. } v = 0 ext{ on } \partial \mathcal{O}.$$

• The forward operator has the strong quadratic approximation

$$\|u_{f_0+h}-u_{f_0}-Du_{f_0}[h]\|_{L^2}=O(\|h\|_{L^2}\|h\|_{H^{-2}}), h\in C(\mathcal{O}).$$

Semi-parametric Cramer-Rao bound

• To find the Cramér-Rao information bound for inference on linear forms $\langle f, \psi \rangle_{L^2}$ we need to find $\tilde{\psi}$ s.t. for all $h \in C(\mathcal{O})$,

$$\langle h,\psi\rangle_{L^2(\mathcal{O})} = \langle Du_{f_0}(h), D_{u_{f_0}}(\tilde{\psi})\rangle_{L^2(\mathcal{O})} = \langle V_{f_0}(hu_{f_0}), V_{f_0}(\tilde{\psi}u_{f_0})\rangle_{L^2(\mathcal{O})}$$

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• Using properties of the Feynman-Kac semigroup one shows that V_f has a symmetric integral kernel and inverse given by the Schrödinger operator,

$$S_f(u) = \frac{\Delta}{2}u - fu, \quad u \in C^2(\mathcal{O}).$$

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Theorem 4

For sufficiently regular, compactly supported functions ψ , the information lower bound for estimating $\langle f, \psi \rangle_{L^2(\mathcal{O})}$ at $f = f_0$ from observations $Y = u_{f_0} + \varepsilon \mathbb{W}$ is

$$I_{f_0}(\psi) = \|Du_{f_0}[\tilde{\psi}]\|_{L^2(\mathcal{O})}^2 = \|S_{f_0}(\psi/u_{f_0})\|_{L^2(\mathcal{O})}^2.$$

• PDE techniques are key to derive an explicit Cramer-Rao lower bound.

Formulation of the Bernstein-von Mises theorem

• For a fixed function ψ we can now ask whether the 'semi-parametric' Bernstein von Mises theorem holds true:

Let $f \sim \Pi(\cdot|Y)$ and \overline{f} the posterior mean. As $\varepsilon \to 0$ do we have

$$\varepsilon^{-1} \int_{\mathcal{O}} (f - \bar{f}) \psi | Y \to^{d} N(0, I_{f_0}(\psi))$$

in $P_{f_0}^Y$ -probability?

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• In fact we want more: following a multi-scale approach, we wish to prove simultaneous convergence of the stochastic processes

$$\left(\varepsilon^{-1}\int_{\mathcal{O}}(f-\bar{f})\psi:\psi\in\Psi_{a}|Y
ight)
ightarrow^{d}(X(\psi):\psi\in\Psi_{a}),$$

where Ψ_a is a maximal class of test functions and $X(\psi) \sim N(0, I_{f_0}(\psi))$.

• The Gaussian process

 $\mathbb{X} = (X(\psi)), \quad \mathbb{E}X(\psi)X(\psi') = \langle S_{f_0}(\psi/u_{f_0}), S_{f_0}(\psi'/u_{f_0}) \rangle_{L^2(\mathcal{O})}, \quad \psi, \psi' \in C^{\alpha}_c(\mathcal{O}),$

is the image of a standard Gaussian white noise \mathbb{W} under the Schrödinger-type operator $\psi \mapsto S_{f_0}(\psi/u_{f_0})$.

• If a sequence of stochastic processes $(X_n(\psi))$ is to converge uniformly in $\psi \in \Psi$ towards \mathbb{X} , then the law \mathcal{N}_{f_0} of \mathbb{X} needs to be **tight** for the supremum norm on Ψ .

• If $\Psi = \Psi_a$ consists of the unit ball of an α -Hölder space $C_c^{\alpha}(\mathcal{O})$, then the maximal spaces where this is possible are characterised in the following

Theorem 5

The Gaussian measure \mathcal{N}_{f_0} induces a tight Gaussian probability measure on the topological dual space $(C_c^{\alpha}(\mathcal{O}))^*$ when $\alpha > 2 + d/2$ but **not** when $\alpha \leq 2 + d/2$.

• The last theorem identifies the 'minimal' spaces $(C_c^{\alpha}(\mathcal{O}))^*, \alpha > 2 + d/2$, in which we can converge weakly towards \mathcal{N}_{f_0} .

Theorem 6

Let $s > \max(2 + d/2, d)$ and $\alpha > 2 + d/2$. Assume $\|\log f_0\|_{C^s_c(\mathcal{O})} < B$. Let $f \sim \Pi(\cdot|Y)$ with posterior mean \overline{f} , and denote by β any metric for weak convergence of probability distributions on $(C^{\alpha}_c(\mathcal{O}))^*$. Then

$$\beta\left(\mathcal{L}(\varepsilon^{-1}(f-\bar{f})|Y),\mathcal{N}_{f_0}
ight)
ightarrow 0$$

as $\varepsilon \to 0$ in $P_{f_0}^Y$ -probability. Moreover \overline{f} is an efficient estimator of f.

• The proof is quite involved, based on uniform perturbation expansions of the Laplace transform of the posterior distribution.

Optimal credible sets I

• As a first application, posterior inference for linear functionals $\langle f, \psi \rangle_{L^2}, \psi \in C_c^{\alpha}$ is asymptotically valid and optimal, without requiring estimation of the inverse Fisher information.

• For a fixed 'credibility level' $1 - \beta, \beta > 0$ and test function ψ , let

$$C_{\varepsilon} = \{ x \in \mathbb{R} : |x - \langle \overline{f}, \psi \rangle_{L^2} | \le R_{\varepsilon} \}$$

with posterior quantile constants R_{ε} chosen such that $\Pi(C_{\varepsilon}|Y) = 1 - \beta$.

Theorem 7

Let $\psi \in C^{\alpha}_{c}(\mathcal{O})$ with $\alpha > 2 + d/2$. Then as $\varepsilon \to 0$ we have

 $P_{f_0}^{\boldsymbol{Y}}(\langle f_0,\psi\rangle_{L^2}\in \mathcal{C}_{\varepsilon}) o 1-eta,$

as arepsilon
ightarrow 0 and the diameter $R_arepsilon$ of $\mathcal{C}_arepsilon$ satisfies

$$\varepsilon^{-1}R_{\varepsilon} \rightarrow^{P_{f_0}^Y} \Phi^{-1}(1-\beta)$$

where Φ^{-1} is the inverse of the map $t \mapsto N(0, \|S_{f_0}(\psi/u_{f_0})\|_{L^2(\mathcal{O})}^2)([-t, t])$.

• Let $C_{\varepsilon} \subset supp(\Pi(\cdot|Y))$ be the smallest $(C_{c}^{\alpha}(\mathcal{O}))^{*}$ -ball centred at the posterior mean \overline{f} for which $\Pi(C_{\varepsilon}|Y) = 1 - \beta$, with fixed credibility $1 - \beta, \beta > 0$.

Theorem 8

Under the conditions of Theorem 6 the above credible set satisfies

 $P_{f_0}^Y(f_0 \in C_{\varepsilon}) \rightarrow 1-\beta,$

as $\varepsilon \to 0$. Its diameter in $L^1(K)$ -norm, for K any compact subset of \mathcal{O} , is of (near) minimax-optimal order: for any $\kappa > 0$,

$$|C_{\varepsilon}|_{L^{1}(K)} = O_{P_{f_{0}}^{Y}} \Big(\varepsilon^{2s/(2s+4+d)} \varepsilon^{-\kappa} \Big).$$

• See Ray (2017, AoS) for more discussion of 'geometric aspects' of such 'multiscale' credible sets in infinite dimensions.

Bayesian Algorithms for Inverse problems

A. Stuart, Inverse problems: A Bayesian perspective, *Acta Numerica*, 2010.M. Dashti, A. Stuart, The Bayesian approach to inverse problems, arxiv 2016.

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R. Nickl, Bernstein-von Mises theorems for non-linear inverse problems I: Schrödinger equation, arxiv 1707.01764

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