# Subvector Inference in Partially Identified Models with Many Moment Inequalities 

Alexandre Belloni Duke
joint work with Federico Bugni (Duke) and Victor Chernozhukov (MIT)

Meeting in Mathematical Statistics
CIRM, December 20th, 2017

## Happy Birthday



Luminy, December 12, 2013

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## Linear programming approach to high-dimensional errors-in-variables models

Alexandre Tsybakov, joint work with Mathieu Rosenbaum

Laboratoire de Statistique, CREST and
Laboratoire de Probabilités et Modèles Aléatoires, Université Paris 6

Luminy, December 10, 2013
(Mathieu: "Did you get the slides I sent? ... [send] my best to Sacha, I am feeling bad not having been able to make it to Luminy!" )

## Introduction

$\triangleright$ There is a large literature on inference in partially identified (PI) models defined by moment (in)equalities.
$\triangleright$ We consider a model characterized by $\left(\theta^{*}, F\right)$

- $\theta^{*} \in \mathbb{R}^{d_{\theta}}$ is a finite dimensional parameter of interest,
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$\triangleright$ The main prediction of the model is that the true parameter $\theta^{*}$ satisfies

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\begin{align*}
& \mathbb{E}\left[m_{j}(W, \theta)\right] \leqslant 0, \text { for } j=1, \ldots, p_{I} \\
& \mathbb{E}\left[m_{j}(W, \theta)\right]=0, \text { for } j=p_{I}+1, \ldots, p_{I}+p_{E} \tag{1}
\end{align*}
$$

$\triangleright$ key issue: $\theta^{*}$ is not assumed to be point identified, i.e., given $F$, there might be a set of $\theta$ that satisfy (1).

$$
\Theta_{I} \equiv\left\{\theta \in \Theta \text { s.t. } \begin{array}{l}
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\end{array}\right\}
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## Motivating Examples

Interval-Outcome Linear Regression (e.g., Manski and Tamer 2002)
$\triangleright$ let $Y_{i}^{*}$ denote a latent dependent variable

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Y_{i}^{*}=X_{i}^{\prime} \theta^{*}+\varepsilon_{i}, \quad \mathbb{E}\left[\varepsilon_{i} \mid X_{i}\right]=0 \quad \text { a.s. }
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$\triangleright$ We only observe an interval s.t. $Y_{i} \in\left[Y_{i}^{\prime}, Y_{i}^{\mu}\right]$ which leads to

$$
\begin{aligned}
& \mathbb{E}\left[X_{i}^{\prime} \theta^{*}-Y_{i}^{u} \mid X_{i}\right] \leqslant 0 \\
& \mathbb{E}\left[Y_{i}^{\prime}-X_{i}^{\prime} \theta^{*} \mid X_{i}\right] \leqslant 0
\end{aligned}
$$

$\triangleright$ We could use

$$
\begin{gathered}
\mathbb{E}\left[X_{i}^{\prime} \theta^{*}-Y_{i}^{u}\right] \leqslant 0 \\
\mathbb{E}\left[Y_{i}^{\prime}-X_{i}^{\prime} \theta^{*}\right] \leqslant 0 \\
\mathbb{E}\left[\left(X_{i}^{\prime} \theta^{*}-Y_{i}^{u}\right) X_{i j} 1\left\{X_{i j} \geqslant 0\right\}\right] \leqslant 0 \\
\mathbb{E}\left[\left(Y_{i}^{\prime}-X_{i}^{\prime} \theta^{*}\right) X_{i j} 1\left\{X_{i j} \geqslant 0\right\}\right] \leqslant 0 \\
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Discrete Choice Model with Multiple Equilibria (Ciliberto and Tamer, 2009)
$\triangleright m$ firms play an entry game (Nash Equilibrium) on $n$ independent markets
$\triangleright$ On each market, a firm makes an entry decision $d_{j} \in\{0,1\}$

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$\triangleright$ There are set-valued functions $R_{1}, R_{2}$ such that

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& \mathbb{E}\left[1\left\{d=d^{\prime}\right\} \mid X\right] \geqslant \mathbb{E}\left[1\left\{\varepsilon \in R_{1}\left(d, X, \theta_{0}\right)\right\} \mid X\right] \\
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$\triangleright$ If conditional distribution of $\varepsilon$ given $X$ is known (up to a subvector of $\theta_{0}$ ), we can calculate numerically right-hand sides of both inequalities
$\triangleright$ we have $2^{m+1}$ moment inequalities for each value of $X \in \mathcal{X}$ (a discrete set).

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where $p=p_{I}+2 p_{E}$.
$\triangleright$ We formally deal with unconditional moments but conditional moments can be approximated via

$$
\mathbb{E}\left[m_{j}\left(W, \theta^{*}\right) \mid z_{i}\right] \leqslant 0 \Rightarrow \mathbb{E}\left[m_{j}\left(W, \theta^{*}\right) 1\left\{z_{i} \in[a, b]\right\}\right] \leqslant 0 \text { for all }[a, b]
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$\triangleright$ We are not interested on $\theta^{*}$ but on $h\left(\theta^{*}\right)$ for a known fn. $h: \Theta \rightarrow \Lambda$. This is the problem addressed in this paper:

Hypothesis test (HT): For fixed $h_{0}$, we want to test:

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Confidence set (CS) for $h\left(\theta^{*}\right)$ : based on HT inversion of a test for (3).
$\triangleright$ Main application: Subvector inference: For $\theta^{*} \in \Theta \subset \mathbb{R}^{d_{\theta}}, d_{\theta}>1$,

$$
H_{0}: \theta_{1}^{*}=h_{0} \quad \text { vs. } \quad H_{1}: \theta_{1}^{*} \neq h_{0} .
$$

$\Rightarrow$ Special case of Eq. (3) with $h(\theta)=\theta_{1}$ and $h_{0} \in \Lambda \subseteq \mathbb{R}$.

## Literature review

Most of literature on inference in PI moment (in)eq. is on "vector inference"

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$\triangleright$ Testing unconditional moment inequalities: Chernozhukov, Hong, and Tamer (2007), Romano and Shaikh (2008), Andrews and Guggenberger (2009), Andrews and Soares (2010), Canay (2010), Bugni (2011), Andrews and Jia Barwick (2012), Romano, Shaikh, and Wolf (2012)
$\triangleright$ Testing conditional moment inequalities: Andrews and Shi (2013), Chernozhukov, Lee, and Rosen (2013), Armstrong (2011), Chetverikov (2011), Armstrong and Chan (2012)

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$\triangleright$ Testing conditional moment inequalities: Andrews and Shi (2013), Chernozhukov, Lee, and Rosen (2013), Armstrong (2011), Chetverikov (2011), Armstrong and Chan (2012)

In both cases, the number of moments $p$ is fixed (explicitly or due to the structure)
Testing unconditional moment inequalities with $p \rightarrow \infty$
$\triangleright$ Menzel (2014), where $p \ll n$
$\triangleright$ Chernozhukov, Chetverikov and Kato (WP 2013), where $p \gg n$

## Literature review: subvector

Asymptotically uniformly valid inference for

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$\triangleright$ Projections of CS: Project usual CS for $\theta$ onto space of $H_{0}$. Considered by Andrews et. al. (2009, 10).

- Related work improving projections: Kaido, Molinari \& Stoye (WP, 2015), Gafarov (affine models, WP 2017)
$\triangleright$ Subsampling: Profile the criterion function and approximate critical value with subsampling. Proposed by Romano \& Shaikh (2008, 10).
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In all cases, the number of moments inequalities $p$ is fixed and asymptotic analysis (i.e., based on the limiting distribution of the process)


## Positioning in the literature

|  | Donsker (e.g. $p$ fixed) | non-Donsker <br> (e.g. p growing) |
| :---: | :---: | :---: |
| Vector Inference | Chernozhukov et al (2007) <br> Romano and Shaikh (2008) <br> Andrews and Guggenberger (2009) <br> Andrews and Soares (2010) | Menzel (2014, $p \ll n$ ) <br> Chernozhukov et al <br> (WP 2013, $p \gg n$ ) |
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Starting point:
$\triangleright$ the minimum resampling critical value in Bugni, Canay and Shi (2017); and
$\triangleright$ CLTs for the max of high-dim vectors used in Chernozhukov et al (WP 2013)

## Setting and Contributions

Profiled test statistics for $H_{0}: h\left(\theta^{*}\right)=h_{0}$ vs. $H_{1}: h\left(\theta^{*}\right) \neq h_{0}$

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T_{n}\left(h_{0}\right)=\inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}
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where $\Theta\left(h_{0}\right)=h^{-1}\left(h_{0}\right)=\left\{\theta \in \Theta: h(\theta)=h_{0}\right\}$ and

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\bar{m}_{\theta, j}=\frac{1}{n} \sum_{i=1}^{n} m_{j}\left(W_{i}, \theta\right) \quad \text { and } \quad \widehat{\sigma}_{\theta, j}^{2}=\frac{1}{n} \sum_{i=1}^{n}\left\{m_{j}\left(W_{i}, \theta\right)-\bar{m}_{\theta, j}\right\}^{2}
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The test: reject if $T_{n}\left(h_{0}\right)>c_{n}\left(h_{0}, 1-\alpha\right)$ where $c_{n}\left(h_{0}, 1-\alpha\right)$ is a critical value.

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Under $H_{0}$ :

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P\left(T_{n}\left(h_{0}\right)>c_{n}\left(h_{0}, 1-\alpha\right)\right) \leqslant \alpha+o(1)
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Our contribution is to construct critical values $c_{n}\left(h_{0}, 1-\alpha\right)$ that
$\triangleright$ uniformly controls asymptotic size over a large class of dgps $\left(F \in \mathcal{P}_{n}\right)$
$\triangleright$ in the presence of many moment inequalities $(p \rightarrow \infty$ as $n \rightarrow \infty)$

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\bar{m}_{\theta, j}=\frac{1}{n} \sum_{i=1}^{n} m_{j}\left(W_{i}, \theta\right) \quad \text { and } \quad \widehat{\sigma}_{\theta, j}^{2}=\frac{1}{n} \sum_{i=1}^{n}\left\{m_{j}\left(W_{i}, \theta\right)-\bar{m}_{\theta, j}\right\}^{2}
$$

The test: reject if $T_{n}\left(h_{0}\right)>c_{n}\left(h_{0}, 1-\alpha\right)$ where $c_{n}\left(h_{0}, 1-\alpha\right)$ is a critical value.

$$
\text { Under } H_{0}: \quad P\left(T_{n}\left(h_{0}\right)>c_{n}\left(h_{0}, 1-\alpha\right)\right) \leqslant \alpha+o(1)
$$

Our contribution is to construct critical values $c_{n}\left(h_{0}, 1-\alpha\right)$ that
$\triangleright$ uniformly controls asymptotic size over a large class of dgps $\left(F \in \mathcal{P}_{n}\right)$
$\triangleright$ in the presence of many moment inequalities ( $p \rightarrow \infty$ as $n \rightarrow \infty$ )
$\triangleright$ allow for $p \gg n$ (also $d_{\theta} \rightarrow \infty$ but not clear if empirically relevant)
$\triangleright$ finite sample analysis, and rate for size error (e.g. polynomially in $n$ )
$\triangleright$ towards data-driven choice of parameters

## Overview of Proposals

Profiled test statistics for $H_{0}: h\left(\theta^{*}\right)=h_{0}$ vs. $H_{1}: h\left(\theta^{*}\right) \neq h_{0}$

$$
T_{n}\left(h_{0}\right)=\inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}
$$

We consider different methods to calculate the critical value $c_{n}\left(h_{0}, 1-\alpha\right)$ :
$\triangleright$ Self-Normalized method (not covering today)

- fast
- works under very weak conditions
- potentially conservative
$\triangleright$ Bootstrap-based methods
- slower (requires simulations)
- requires stronger conditions
- but less conservative
$\triangleright$ Hybrids are possible (not covering today)
- potentially useful to speed up bootstrap-based methods


## Proposal via Bootstrap-based methods

Profiled test statistics for $H_{0}: h\left(\theta^{*}\right)=h_{0}$ vs. $H_{1}: h\left(\theta^{*}\right) \neq h_{0}$

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Letting $\widehat{v}_{\theta, j}=\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{m_{j}\left(W_{i}, \theta\right)-\mathbb{E}\left[m_{j}\left(W_{i}, \theta\right)\right]\right\} / \widehat{\sigma}_{\theta, j}$

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T_{n}\left(h_{0}\right)=\inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}+\sqrt{n} \mathbb{E}\left[m_{j}(W, \theta)\right] / \widehat{\sigma}_{\theta, j}
$$

bootstrap: $\quad \widehat{v}_{\theta, j}^{*}=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \xi_{i} \frac{m_{j}\left(W_{i}, \theta\right)-\bar{m}_{\theta, j}}{\widehat{\sigma}_{\theta, j}} \quad$ where $\xi_{i}$ 's are i.i.d. $N(0,1)$.

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$$

Remark: It has been shown that although we can suitably approximate

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\widehat{v}_{\theta, j} \text { by } \widehat{v}_{\theta, j}^{*}
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Remark: It has been shown that although we can suitably approximate

$$
\widehat{v}_{\theta, j} \text { by } \widehat{v}_{\theta, j}^{*}
$$

Andrews and Soares (2010) show it is more delicate to approximate

$$
\sqrt{n} \mathbb{E}\left[m_{j}(W, \theta)\right] / \widehat{\sigma}_{\theta, j} \quad \text { by } \quad \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}
$$

as there is a non-vanishing noise due to the scaling by $\sqrt{n}$.

## Standard Bootstrap-based methods via GMS

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$$

A standard way to proceed is to use Generalized Moment Selection (GMS)

$$
\varphi_{\theta, j}=\left\{\begin{array}{l}
0, \text { if } \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j} \geqslant-\kappa_{n}, \\
-\infty, \text { otherwise } \text { (i.e., inequality will not be used) }
\end{array}\right.
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for a tuning parameter $\kappa_{n} \rightarrow \infty$

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$$

for a tuning parameter $\kappa_{n} \rightarrow \infty \quad$ (recommendation $\sim\{\log n\}^{1 / 2}$ when $p$ is fixed)
Then set

$$
T_{n}^{G M S *}\left(h_{0}\right):=\inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}^{*}+\varphi_{\theta, j}
$$

and compute the critical values based on the quantile of $T_{n}^{G M S_{*}}\left(h_{0}\right)$.

## Standard Bootstrap-based methods via GMS

Example: $d_{\theta}=2$, and $\Theta=[-1,1]^{2}$. Let $p=2$, and consider

$$
\begin{aligned}
\mathbb{E}\left[m_{1}\left(W_{i}, \theta\right)\right] & =\mathbb{E}\left[\theta_{1}+\theta_{2}-W_{i, 1}\right] \leqslant 0 \\
\mathbb{E}\left[m_{2}\left(W_{i}, \theta\right)\right] & =\mathbb{E}\left[W_{i, 2}-\theta_{1}-\theta_{2}\right] \leqslant 0
\end{aligned}
$$

where $W_{i} \in \mathbb{R}^{p}, W_{i} \sim N(0, I)$ and we are interest on testing

$$
H_{0}: \theta_{1}=0 \text { vs. } H_{1}: \theta_{1} \neq 0
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It follows that for $\left(Z_{1}, Z_{2}\right) \sim N(0, I)$ we have

$$
T_{n}(0)=\inf _{-1 \leqslant \theta_{2} \leqslant 1} \max \left\{\frac{\sqrt{n} \theta_{2}-\bar{W}_{1}}{\widehat{\sigma}_{1}}, \frac{\bar{W}_{2}-\sqrt{n} \theta_{2}}{\widehat{\sigma}_{2}}\right\}
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$$

In turn, for GMS, using $\kappa_{n}=\sqrt{\log n}$ we select both inequalities whp and

$$
T_{n}^{G M S_{*}}(0) \mid\left(W_{i}\right)_{i=1}^{n} \approx \inf _{-1 \leqslant \theta_{2} \leqslant 1} \max \left\{-Z_{1}+\varphi_{\theta_{2}, 1}, Z_{2}+\varphi_{\theta_{2}, 2}\right\}
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Critical values based on $T_{n}^{G M S *}(0)$ fail to control size.

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Critical values based on $T_{n}^{G M S *}(0)$ fail to control size. Indeed, for $\alpha=0.1$

- $c_{n}^{G M S}(0,1-\alpha) \approx 0.5$ and $P\left(T_{n}(0)>c_{n}^{G M S}(0,1-\alpha)\right) \approx 0.24$.
- $c_{n}(0,1-\alpha) \approx 0.86$
- GMS quantiles are "too" small


## Bootstrap-based methods for subvector inference

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1) "Discard Resampling" (DR):

$$
T_{n}^{D R *}\left(h_{0}\right) \equiv \inf _{\theta \in \widehat{\Theta}_{1}\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}^{*}+\varphi_{\theta, j}
$$

where $\widehat{\Theta}_{l}\left(h_{0}\right) \subseteq " \arg \min "{ }_{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}$

$$
\varphi_{\theta, j}=\left\{\begin{array}{l}
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-\infty, \text { otherwise } \text { (i.e., inequality will not be used) }
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$$

2) "Penalized Resampling" (PR):

$$
T_{n}^{P R *}\left(h_{0}\right) \equiv \inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}^{*}+\kappa_{n}^{-1} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}
$$

where $\kappa_{n} \geqslant 1$ is a penalty parameter

## Bootstrap-based methods for subvector inference

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-\infty, \text { otherwise } \quad \text { (i.e., inequality will not be used) }
\end{array}\right.
$$

2) "Penalized Resampling" (PR):

$$
T_{n}^{P R *}\left(h_{0}\right) \equiv \inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}^{*}+\kappa_{n}^{-1} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}
$$

where $\kappa_{n} \geqslant 1$ is a penalty parameter
3) "Minimum Resampling" (MR):

$$
T_{n}^{M R *}\left(h_{0}\right) \equiv \min \left\{T_{n}^{D R *}\left(h_{0}\right), T_{n}^{P R *}\left(h_{0}\right)\right\}
$$

## The impact of many moment inequalities, $p \gg n$

$\triangleright$ lack of a Donsker property for the whole process $\left\{v_{\theta, j}: \theta \in \Theta\left(h_{0}\right), j \in[p]\right\}$

- no limiting distributions guaranteed to exist
- cannot invoke Donsker's functional CLT to establish the convergence in distribution of $T_{n}\left(h_{0}\right)$
$\triangleright$ restriction on the criterion functions
- we use $Q(\theta)=\max _{j \in[p]} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}$
- do not use (MMM): $Q(\theta)=\sum_{j=1}^{p}\left\{\sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}\right\}_{+}^{2}$
- do not use (AQLR): $Q(\theta)=\min _{t \in \mathbb{R}^{p}}\left(\sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}-t\right)^{\prime} \widetilde{\Sigma}_{\theta}^{-1}\left(\sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}-t\right)$
$\triangleright$ tuning parameters need to account for growing entropy


## Assumptions for Hypothesis Testing

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(iii) Polynomial Minorant condition away from the identified set

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(i) set $\Theta\left(h_{0}\right)$ is convex and $\sup _{\theta \in \Theta\left(h_{0}\right)}\|\theta\|_{\infty} \leqslant C \sqrt{n}$

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(ii) $\left\{\widetilde{m}_{j}(\cdot, \theta): \theta \in \Theta\left(h_{0}\right), j \in[p]\right\}$ is VC type class of functions

- with constants $\bar{A}$ and $v \geqslant 1$ and envelope $F$ (i.e. $\left.F(W) \geqslant\left|\widetilde{m}_{j}(W, \theta)\right|\right)$
- for some $b>0, q \geqslant 4$, we have

$$
E p\left[F^{q}\right]^{1 / q} \leqslant b \text { and } \mathbb{E}\left[\left|\widetilde{m}_{j}(W, \theta)\right|^{k}\right] \leqslant b^{k-2}, \quad k=3,4
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- $\mathbb{E}\left[\left\{\widetilde{m}_{j}(W, \theta)-\widetilde{m}_{j}(W, \tilde{\theta})\right\}^{2}\right] \leqslant L_{C}\|\theta-\tilde{\theta}\|^{\chi}$ for some $\chi \geqslant 1$.
- $\max _{j \in[p]}\left\|\nabla_{\theta} \mathbb{E}\left[\tilde{m}_{j}(W, \theta)\right]\right\| \leqslant L_{G}$ for every $\theta \in \Theta\left(h_{0}\right)$


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$$
\max _{j \in[p]} \mathbb{E}\left[\widetilde{m}_{j}(W, \theta)\right] \geqslant \vartheta_{n} \min \left\{\delta, \inf _{\tilde{\theta} \in \Theta\left(h_{0}\right) \cap \Theta_{1}}\|\theta-\tilde{\theta}\|\right\}
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$$

Define $\gamma=o(1)$, in particular $\gamma \ll \alpha$
$\triangleright \bar{w}_{n}=(1-\gamma)$-quantile of $\sup _{\theta \in \Theta\left(h_{0}\right), j \in[p]}\left|\widehat{v}_{\theta, j}^{*}\right|$
$\triangleright K_{n}=v \log (n \bar{A} b)+d_{\theta} \log (n b)+\log p$

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$$

Define $\gamma=o(1)$, in particular $\gamma \ll \alpha$

$$
\text { (e.g., } \gamma=n^{-c} \text { for some } c>0 \text { ) }
$$

$\triangleright \bar{w}_{n}=(1-\gamma)$-quantile of $\sup _{\theta \in \Theta\left(h_{0}\right), j \in[p]}\left|\widehat{\widehat{v}}_{\theta, j}^{*}\right| \lesssim \sqrt{d_{\theta} \log (p n)}$
$\triangleright K_{n}=v \log (n \bar{A} b)+d_{\theta} \log (n b)+\log p \quad \lesssim d_{\theta} \log (p n)$

Rates for Size Control

## Rates for Size Control for Discard Resampling

$$
T_{n}^{D R *}\left(h_{0}\right) \equiv \inf _{\theta \in \widehat{\Theta}_{l}\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}^{*}+\varphi_{\theta, j}
$$

where $\widehat{\Theta}_{l}\left(h_{0}\right) \subseteq " \arg \min "_{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}$

$$
\varphi_{\theta, j}=\left\{\begin{array}{l}
0, \text { if } \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j} \geqslant \max _{\ell \in[p]} \sqrt{n} \bar{m}_{\theta, \ell} / \widehat{\sigma}_{\theta, \ell}-\kappa_{n}, \\
-\infty, \text { otherwise } \text { (i.e., inequality will not be used) }
\end{array}\right.
$$

## Rates for Size Control for Discard Resampling

$$
T_{n}^{D R *}\left(h_{0}\right) \equiv \inf _{\theta \in \widehat{\Theta}_{1}\left(h_{0}\right)} \max _{j \in[p]}{\widehat{\widehat{v}_{\theta, j}}}_{*}^{*}+\varphi_{\theta, j}
$$

where $\widehat{\Theta}_{l}\left(h_{0}\right) \subseteq " \arg \min "_{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}$

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-\infty, \text { otherwise } \text { (i.e., inequality will not be used) }
\end{array}\right.
$$

Issues to address:

- no functional min max CLT since $p \rightarrow \infty$ (and potentially $d_{\theta} \rightarrow \infty$ )
- handle random set $\widehat{\Theta}_{l}\left(h_{0}\right)$
- handle random selection of inequalities
- penalty parameter $\kappa_{n}$


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-\infty, \text { otherwise (i.e., inequality will not be used) }
\end{array}\right.
$$

Theorem (Simplified)
Suppose Condition $M$ is satisfied with $d_{\theta}+L_{G} / \vartheta_{n} \leqslant C$ and that $H_{0}$ holds. Then

$$
P\left(T_{n}\left(h_{0}\right) \geqslant t\right) \leqslant P\left(T_{n}^{D S_{*}}\left(h_{0}\right) \geqslant t-C \delta_{n, \gamma}^{\prime}\right)+C\left\{\gamma+n^{-1}\right\}
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$$

where we have

$$
\delta_{n, \gamma}^{\prime} \lesssim \frac{\log ^{2 / 3}(n p)}{\gamma^{1 / 3} n^{1 / 6}}
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provided that $\kappa_{n} / \bar{w}_{n} \rightarrow \infty$.

## Rates for Size Control for Discard Resampling

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$$

for some $0<c<1 / 6$

$$
\delta_{n, \gamma}^{\prime} \lesssim \frac{\log ^{2 / 3}(n p)}{n^{1 / 6-c}}
$$

provided that $\kappa_{n} / \sqrt{\log p} \rightarrow \infty$.

## Rates for Size Control for Discard Resampling

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Theorem
Assume that Condition $M$ is satisfied and that $H_{0}$ holds. Then

$$
P\left(T_{n}\left(h_{0}\right) \geqslant t\right) \leqslant P\left(T_{n}^{D S *}\left(h_{0}\right) \geqslant t-C \delta_{n, \gamma}^{\prime}\right)+C\left\{\gamma+n^{-1}\right\}
$$

where we have

$$
\delta_{n, \gamma}^{\prime} \quad:=\frac{C b K_{n}}{\gamma^{3 / q} n^{1 / 2}}+\frac{C\left(b K_{n}^{2}\right)^{1 / 3}}{\gamma^{1 / 3} n^{1 / 6}}+C L_{C}^{1 / 2}\left(\frac{C K_{n}^{1 / 2}}{\gamma^{1 / q} n^{1 / 2} \vartheta_{n}}\right)^{\chi / 2} \frac{K_{n}^{1 / 2}}{\gamma^{1 / q}}+\frac{C b K_{n}}{\gamma^{1 / q} n^{1 / 2-1 / q}}
$$

provided that $\kappa_{n} \geqslant \bar{w}_{n}\left\{6+2 L_{G} / \vartheta_{n}\right\}$

## Rates for Size Control for Penalized Resampling

$$
T_{n}^{P R *}\left(h_{0}\right)=\inf _{\theta \in \Theta\left(h_{0}\right)} \max _{j \in[p]} \widehat{v}_{\theta, j}^{*}+\kappa_{n}^{-1} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}
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Issues to address:

- no functional CLT for min max since $p \rightarrow \infty$ (and potentially $d_{\theta} \rightarrow \infty$ )
- need to handle random centering $\kappa_{n}^{-1} \sqrt{n} \bar{m}_{\theta, j} / \widehat{\sigma}_{\theta, j}$
- penalty parameter $\kappa_{n}$


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Theorem (Simplified)
Suppose Condition $M$ is satisfied with $d_{\theta}+L_{G} / \vartheta_{n} \leqslant C, \chi=2$, and that $H_{0}$ holds. Then

$$
P\left(T_{n}\left(h_{0}\right) \geqslant t\right) \leqslant P\left(T_{n}^{P R *}\left(h_{0}\right) \geqslant t-C \delta_{n, \gamma}^{\prime \prime}\right)+C\left\{\gamma+n^{-1}\right\}
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where we have

$$
\delta_{n, \gamma}^{\prime \prime}:=\frac{\log ^{2 / 3}(n p)}{\gamma^{1 / 3} n^{1 / 6}}+\kappa_{n} \frac{\log ^{3 / 2}(n p)}{n^{1 / 2}}+\frac{\bar{w}_{n}}{\kappa_{n}}
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$$
\begin{gathered}
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+\frac{\bar{w}_{n}}{\kappa_{n}}+L_{C}^{1 / 2}\left(\frac{\kappa_{n} K_{n}^{1 / 2}}{n^{1 / 2} \vartheta_{n} \gamma^{1 / q}}\right)^{\chi / 2} \frac{K_{n}^{1 / 2}}{\gamma^{1 / q}}
\end{gathered}
$$

## Rates for Size Control for Minimum Resampling

$$
T_{n}^{M R *}\left(h_{0}\right)=\min \left\{T_{n}^{D R *}\left(h_{0}\right), T_{n}^{M R *}\left(h_{0}\right)\right\}
$$

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## Issues:

$\triangleright$ note that $T_{n}^{M R *}$ is also a MinMax statistics

- as it is the minimum of two MinMax statistics
- need to handle random set in the minimization
- need to handle random centering
$\triangleright$ clearly need to couple the statistics (use the same $\xi_{i} \sim N(0,1)$ for both)
$\triangleright$ no functional CLT for MinMax as $p \rightarrow \infty$ (and potentially $d_{\theta} \rightarrow \infty$ )


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## Theorem

Assume that Condition $M$ is satisfied and that $H_{0}$ holds. Then

$$
P\left(T_{n}\left(h_{0}\right) \geqslant t\right) \leqslant P\left(T_{n}^{M R *}\left(h_{0}\right) \geqslant t-C \delta_{n, \gamma}\right)+C\left\{\gamma+n^{-1}\right\}
$$

where we have

$$
\delta_{n, \gamma}:=\delta_{n, \gamma}^{\prime}+\delta_{n, \gamma}^{\prime \prime}
$$

## Key New Coupling Result

Theorem. Let $X_{1}, \ldots, X_{n}$ be independent random matrices in $\mathbb{R}^{N \times p}(N p \geqslant 2)$, $Y_{1}, \ldots, Y_{n}$ be independent random matrices in $\mathbb{R}^{N \times p}$ with $Y_{i} \sim N\left(\mathbb{E}\left[X_{i}\right], \operatorname{Var} X_{i}\right)$.

$$
\text { Define } T=\min _{k \in[N]} \max _{j \in[p]} \sum_{i=1}^{n} \frac{X_{i k j}}{\sqrt{n}} \text {, and } \widetilde{T}=\min _{k \in[N]} \max _{j \in[p]} \sum_{i=1}^{n} \frac{Y_{i k j}}{\sqrt{n}}
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$$

Then for every $\delta>0$ and every Borel subset $A$ of $\mathbb{R}$ we have

$$
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\begin{aligned}
& L_{n}=\max _{k \in N, j \in[p]} \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[\left|\widetilde{X}_{i k j}\right|^{3}\right], \\
& M_{n, W}(\delta)=\frac{1}{n} \sum_{i=1}^{n} \mathbb{E}\left[\max _{k \in N, j \in[p]}\left|\widetilde{W}_{i k j}\right|^{3} \cdot 1\left\{\max _{k \in N, j \in[p]}\left|\widetilde{W}_{i k j}\right|>\delta \sqrt{n} / \log (N p)\right\}\right],
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\delta=\frac{C \log ^{2 / 3}(N p)}{\gamma^{1 / 3} n^{1 / 6}} \quad \text { in our case } N \leqslant n^{C d_{\theta}} \quad(N=1 \text { recovers the case of max })
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that satisfies:

$$
\begin{gathered}
-\beta^{-1} \log N \leqslant G_{\beta}(X)-\min _{k \in[N]} \max _{j \in[p]} X_{k j} \leqslant \beta^{-1} \log p \\
\left\|\nabla G_{\beta}(X)\right\|_{1} \leqslant 1 \\
\left\|\nabla^{2} G_{\beta}(X)\right\|_{1} \leqslant 4 \beta \\
\left\|\nabla^{3} G_{\beta}(X)\right\|_{1} \leqslant 24 \beta^{2}
\end{gathered}
$$

## Key New Coupling Result

Lemma 11. Consider $m(X)=g \circ G_{\beta}(X)$. Then we have (1) for $(k, j) \in[N] \times[p]$

$$
m_{k j}^{\prime}(X)=g^{\prime}\left(G_{\beta}(X)\right) \pi_{k}\left(-F_{\beta}(X)\right) \pi_{j}^{\mu_{k}}\left(X_{k}\right)
$$

(2) for $(k, j) \in([N] \times[p])^{2}$, we have

$$
\begin{aligned}
m_{(k, j)}^{\prime \prime}(X) & =g^{\prime \prime}\left(G_{\beta}(X)\right) \pi_{k_{2}}\left(-F_{\beta}(X)\right) \pi_{j 2}^{\mu_{k_{2}}}\left(X_{k_{2} \cdot}\right) \pi_{k_{1}}\left(-F_{\beta}(X)\right) \pi_{j_{1}}^{\beta_{k_{1}}}\left(X_{k_{1}}\right) \\
& -g^{\prime}\left(G_{\beta}(X)\right) \beta w_{k_{1} k_{2}}\left(-F_{\beta}(X)\right) \pi_{j_{2}}^{\mu_{k_{2}}}\left(X_{k_{2}}\right) \pi_{j_{1}}^{\mu_{k_{1}}}\left(X_{k_{1}} .\right) \\
& +g^{\prime}\left(G_{\beta}(X)\right) \pi_{k_{1}}\left(-F_{\beta}(X)\right) \delta_{k_{1} k_{2}} \beta w_{j_{1} j_{2}}\left(X_{k_{1} \cdot}\right)
\end{aligned}
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(3) for $(k, j) \in([N] \times[p])^{3}$, we have

$$
\begin{aligned}
& m_{(k, j)}^{\prime \prime \prime}(X)=g^{\prime \prime \prime}\left(G_{\beta}(X)\right) \prod_{\ell=1}^{3} \pi_{k_{\ell}}\left(-F_{\beta}(X)\right) \pi_{j_{\ell}}^{\mu_{k_{\ell}}}\left(X_{k_{\ell}}\right) \\
& -g^{\prime \prime}\left(G_{\beta}(X)\right) \beta w_{k_{2} k_{3}}\left(-F_{\beta}(X)\right) \pi_{k_{1}}\left(-F_{\beta}(X)\right) \prod_{\ell=1}^{3} \pi_{j \ell}^{\bar{\mu}_{\ell}}\left(X_{k_{\ell}}\right) \\
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We obtained

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i.e., that $T_{n}^{M R *}\left(h_{0}\right)$ does not concentrate too fast around $c_{n, 1-\alpha}$ as $p \rightarrow \infty$.

## Anti-Concentration

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Let $X \in \mathbb{R}^{p}$ be a vector of Gaussian random variables such that $\operatorname{Var}\left(X_{j}\right) \geqslant 1$. Let $Z=\max _{j \in[p]} X_{j}$. Then for any $\epsilon>0$ and $x \in \mathbb{R}$

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\mathbb{P}(|Z-x| \leqslant \epsilon) \leqslant C \epsilon \sqrt{\log p}
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In particular the probability density function of $Z$ satisfies $\max _{t \in \mathbb{R}} f_{Z}(t) \leqslant C \sqrt{\log p}$

- allows for non-central and arbitrary correlation structure


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- allows for non-central and arbitrary correlation structure

For coupling between Max statistics $(N=1)$, say $T$ and $Z$,

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## Anti-Concentration: Max

Anti-concentration essentially bounds the probability density function

## Theorem (CCK (2011))

Let $X \in \mathbb{R}^{p}$ be a vector of Gaussian random variables such that $\operatorname{Var}\left(X_{j}\right) \geqslant 1$. Let $Z=\max _{j \in[p]} X_{j}$. Then for any $\epsilon>0$ and $x \in \mathbb{R}$

$$
\mathbb{P}(|Z-x| \leqslant \epsilon) \leqslant C \epsilon \sqrt{\log p}
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In particular the probability density function of $Z$ satisfies $\max _{t \in \mathbb{R}} f_{Z}(t) \leqslant C \sqrt{\log p}$

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For coupling between Max statistics ( $N=1$ ), say $T$ and $Z$,
we need $\delta_{n, \gamma} \sqrt{\log p}+\gamma \rightarrow 0$ implied by $\delta_{n, \gamma}=\frac{\log ^{2 / 3}(p)}{\gamma^{1 / 3} n^{1 / 6}}=o\left(\frac{1}{\sqrt{\log p}}\right)$
That is, $\log ^{7 / 6}(p)=o\left(n^{1 / 6}\right)$.

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For $X_{k j} \sim N(0,1)$, i.i.d., $k \in[N], j \in[p]$, let

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\left\{\sqrt{2} \log ^{1 / 2}\left(\frac{p / \sqrt{2 \pi}}{\log N}\right)-2\right\} \frac{\log (N)}{e} \leqslant \max _{t \in \mathbb{R}} f_{Z}(t) \leqslant 4 \sqrt{2} \log ^{3 / 2}(N p)
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That is, if $p=N$, for some universal constants $0<c<C$ we have

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$\triangleright$ suggests anti-concentration of MinMax is quite different from the Max
$\triangleright$ currently only partial results for arbitrary correlation structures

## Anti-Concentration

However note that our bounds are

$$
P\left(T_{n}\left(h_{0}\right) \geqslant t\right) \leqslant P\left(T_{n}^{M R *}\left(h_{0}\right) \geqslant t-C \delta_{n, \gamma}\right)+C\left\{\gamma+n^{-1}\right\}
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It suffices to control the concentration of the bootstrapped statistics

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We can estimate

$$
P\left(\left|T_{n}^{M R *}\left(h_{0}\right)-t\right| \leqslant 2 C \delta_{n, \gamma}\right)
$$

via bootstrap for $t=c_{n}\left(h_{0}, 1-\alpha\right)$ and bound the anti-concentration factor
$\triangleright$ adaptive to the setting (in contrast to analytical bounds)
$\triangleright$ can be estimated using the same bootstrap that computed $c_{n}\left(h_{0}, 1-\alpha\right)$
Let $\mathcal{A}_{1-\alpha}^{*}:=\frac{P\left(\left|T_{n}^{M R *}\left(h_{0}\right)-t\right| \leqslant 2 C \delta_{n, \gamma}\right)}{2 C \delta_{n, \gamma}}$ denote the anti-concentration rate.

## Examples of Simple Conditions for "Penalized Resampling"

Suppose Condition $\mathrm{M}, m_{j}$ and its derivatives are uniformly bounded, $\sigma_{\theta, j} \geqslant c$, $L_{G} / \vartheta_{n}+L_{C} \leqslant C$. Then, letting $\mathcal{A}_{1-\alpha}^{*}$ denote the anti-concentration rate, provided

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\begin{equation*}
\frac{K_{n}^{2 / 3}}{n^{1 / 6}}+\kappa_{n} \frac{d_{\theta}^{1 / 2} K_{n}}{n^{1 / 2}}+\frac{\bar{w}}{\kappa_{n}}=o\left(\frac{1}{\mathcal{A}_{1-\alpha}^{*}}\right) \tag{4}
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where $K_{n}=\log p+d_{\theta} \log n$, we have $P\left(T_{n}\left(h_{0}\right) \geqslant c_{n}\left(h_{0}, 1-\alpha\right)\right) \leqslant \alpha+o(1)$

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Remark: we can simulate $\bar{w}$ and bound $\mathcal{A}_{1-\alpha}^{*}$
$\triangleright$ yields a data-driven choice of $\kappa_{n}$
For the traditional setting, e.g., fixed $p$ and $d_{\theta}$
$\triangleright \mathcal{A}_{1-\alpha}^{*} \leqslant C$
$\triangleright K_{n} \leqslant C$
$\triangleright \kappa_{n} \rightarrow \infty$ and $\kappa_{n} / n^{1 / 2} \rightarrow 0$

## Examples of Simple Conditions for "Penalized Resampling"

For non-Donsker cases:
Example (Many inequalities and fixed $d_{\theta}$ )
Let $p=n^{C}$ for some fixed $C>1, d_{\theta} \leqslant C$, and the anti-concentration $\mathcal{A}_{1-\alpha}^{*} \leqslant C \log ^{3 / 2} n$. It suffices $\kappa_{n} \in\left[\log ^{5 / 2} n, n^{\frac{1}{2}} \log ^{-3} n\right]$.

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Let $p=n^{C}$ for some fixed $C>1, d_{\theta}=n^{a}$ for some $a<1 / 4$, and the anti-concentration $\mathcal{A}_{1-\alpha}^{*} \leqslant C \log ^{3 / 2} n$. It suffices $\kappa_{n} \in\left[n^{a / 2} \log ^{5 / 2} n, \quad n^{\frac{1}{2}-\frac{3}{2} a} \log ^{-3} n\right]$.

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Example (Exponentially many inequalities)
Suppose that $d_{\theta} \leqslant C \log n, p \geqslant n^{\log n}$ and the anti-concentration $\mathcal{A}_{1-\alpha}^{*} \leqslant C \log ^{3 / 2} p$. It suffices $\kappa_{n} \in\left[\log ^{2} p \log n, \quad n^{1 / 2} \log ^{-5 / 2} p \log ^{-1} n\right]$, provided that $n^{-1 / 6} \log ^{13 / 6} p \log n=o(1)$.

## Conclusion

$\triangleright$ subvector inference in PI models with many moment restrictions

- allow for non-Donsker classes
- finite sample analysis
- need more than $\kappa_{n} \rightarrow \infty$ and $\kappa_{n} / \sqrt{n} \rightarrow 0$ when $p \rightarrow \infty$
- valid data-driven choice of penalty parameters (via additional bootstrap)
$\triangleright$ new CLTs for $\min _{k \in[N]} \max _{j \in[p]} W_{k j}$
- results parallel results for $\max _{j \in[p]} W_{j}$
- approximation based on composition of smooth maximum (LSE)
$\triangleright$ new anti-concentration pattern
- does not parallel results for $\max _{j \in[p]} W_{j}$ (counter example)
- estimate anti-concentration via bootstrap
$\triangleright$ Future (ongoing) work
- sharper constants
- hybrid methods
- power comparisons
- analytical bounds for anti-concentration
- orthogonal moment conditions

