Non-equilibrium hydrodynamic pressure tensors from kinetic perspectives [Dragos I. Palade]

1. A kinetic model:

$$\partial_t f + \mathbf{v} \nabla f = \mathcal{K}[\varphi] \otimes_{\mathbf{v}} f; \qquad \qquad \mathcal{K}[\varphi] = \pm \frac{1}{H} \int d\mathbf{s} e^{-\mathbf{i} \mathbf{s} \mathbf{v}/H} \varphi(\mathbf{r} \pm \mathbf{s}/2)$$

2. Supports a hydrodynamic model:

$$\partial_t \mathbf{n} + \nabla \mathbf{j} = 0$$
  $\partial_t \mathbf{j} + \nabla \cdot (\frac{\mathbf{j} \otimes \mathbf{j}}{n} + \hat{\Pi}) + n \nabla \varphi = 0$ 

3. Hydrodynamic linear response function  $(\tilde{\chi}^{hydr})$  should be  $= \tilde{\chi}^{kin}$ 4. Presume functional relation  $\Pi = \delta P[n]/\delta n$ , where

$$P[n] = \int d\mathbf{r} d\mathbf{r}' dt dt' n^{lpha}(\mathbf{r},t) \sigma(\mathbf{r},\mathbf{r}',t,t') n^{lpha}(\mathbf{r}',t')$$

5. Enforcing  $\tilde{\chi}^{hydr} \approx \tilde{\chi}^{kin}$ , we find:

$$\begin{split} \tilde{\sigma}(k,\omega) &= \sigma_0(k) + \frac{[\sigma_\infty(k) - \sigma_0(k)]\omega^2}{[\sigma_\infty(k) - \sigma_0(k)]/\sigma_1(k) + \omega^2} \\ \hat{\Pi}[n] &= \frac{8}{3} n^{4/3}(\mathbf{r},t)(\hat{\mathcal{D}} + \int d\mathbf{r}' \sigma_\infty(\mathbf{r} - \mathbf{r}') n^{4/3}(\mathbf{r}',t) \\ (\partial_{tt} - (\sigma_\infty - \sigma_0)/\sigma_1 \otimes)\hat{\mathcal{D}} &= (\sigma_\infty - \sigma_0)^2 \neq \sigma_1 \otimes n^{4/3} & \text{is a set of } \mathcal{O}(n) \end{split}$$



Figure: 1.  $\tilde{\Pi}/\tilde{n}$  at fixed k = 0.4 versus frequency  $\omega$ . Red (exact, kinetic), blue (present work), Green (TFvW)



Figure: 2. H = 1, t = 20; Pressure tensor  $\hat{\Pi}_{xx}(x)$  profile obtained in a numerical simulation during the dynamics. The present functional (blue) is considerably closer to the exact (kinetic, red) result, than the existing TFvW approach (black, dashed)



Figure: 3. Histogram of overall error (arb. units) from the TFvW (blue) approximation and the present functional (orange). The error from TFvW peaks considerably at a larger value and has a larger width.

イロト 不得 トイヨト イヨト