

Qualitative methods in KPZ UNIVERSALITY

CIRM, Luminy, April 24-28, 2017

Mean-field directed polymers on a complete graph.

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Based on collaborations with

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Discrete polymer models in random environment

- ↳ Compact space (= finite, cardinality = N)
- ↳ Mean-field type (to find exactly solvable models)

Approximation of non-compact case $N \rightarrow \infty$

Contents

- 1 Mean-Field Model
- 2 Integrable model on Complete graph
- 3 Large N asymptotics

Mean-Field Model on Complete graph with N sites

- For $1 \leq i, j \leq N$, paths starting at $(0, i)$ ending at (t, j) ,

$$J_N(0, i; t, j) = \{\mathbf{j} = (j_0, \dots, j_t) : 1 \leq j_s \leq N, \forall 0 \leq s \leq t-1, j_0 = i, j_t = j\},$$
- Let $\{\omega_{i,j}(t) : 1 \leq i, j \leq N, t \geq 0\}$ i.i.d. > 0 . **P2P partition function**

$$Z_N(0, i; t, j) = \sum_{\mathbf{j} \in J_N(0, i; t, j)} \prod_{s=1}^t \omega_{j_{s-1}, j_s}(s).$$

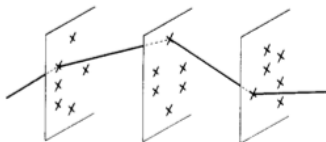


Figure: From Cook-Derrida 1990

- Finite transverse space for polymer: Derrida (+Cook'90; + Brunet'04)
 Free energy (= Lyapunov exp.) Eckman-Wayne 1989
 Last-passage percolation: C-Quastel-Ramirez 2015

Let $\mathfrak{X}(t) = [\omega_{i,j}(t)]_{i,j}$ $N \times N$ positive matrix

$$\Pi(s, t) = \mathfrak{X}(s+1) \dots \mathfrak{X}(t), \quad \Pi(t, t) = \mathbf{I}_N, \quad \Pi(t) = \Pi(0, t).$$

so

$$Z_N(0, i; t, j) = \Pi(0, t)_{i,j}$$

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▮ **P2L** partition function: set $J_N(0, i; t, \star) = \bigcup_{j=1}^N J_N(0, i; t, j)$, etc....

$$Z_N(0, i; t, \star) = \sum_{\mathbf{l} \in J_N(0, i; t, \star)} \prod_{s=1}^t \omega_{j_{s-1}, j_s}(\mathbf{s}) = (\Pi(t)\mathbf{1})_i.$$

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Ⓞ **L2P** partition function

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⊗ We single out the L2P p.f. (column vector) $Z_N(t) = (Z(t, 1), \dots, Z(t, N))^*$

$$Z_N(t, \star) = \sum_{j=1}^N Z_N(t, j) = \|Z_N(t)\|_1,$$

$$Z_N(t)^* = Z_N(t-1)^* \mathfrak{X}(t),$$

Fondamental results on products of random matrices

Products of i.i.d. random matrices. Fustenberg, Kesten'60. Lyapunov exp.
Fix $\alpha > 0$; the α -norm of $v \in \mathbb{R}_+^N$ is $\|v\|_\alpha = (\sum_{j=1}^N v_j^\alpha)^{1/\alpha}$.

$$\bar{B}_\alpha = \{v \in \mathbb{R}_+^N : \|v\|_\alpha = 1\} \quad (\alpha\text{-simplex}),$$

Define projection $\Psi_\alpha : \mathbb{R}_+^N \setminus \{0\} \rightarrow \bar{B}_\alpha$, $\Psi_\alpha(v) = \frac{v}{\|v\|_\alpha}$

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✂ **Normalized product** (action on directions)

$$\mathfrak{x} \cdot v := \frac{\mathfrak{x}v}{\|\mathfrak{x}v\|_\alpha} \in \bar{B}_\alpha.$$

(drop the subscripts from notation when $\alpha = 1$, e.g.

$\bar{B} := \bar{B}_1$, $\mathfrak{x} \cdot v := \mathfrak{x} \cdot v$.) Finally, define

$$X_{N,\alpha}(t) := \Psi_\alpha(Z_N(t)) = \frac{Z_N(t)}{\|Z_N(t)\|_\alpha} \in \bar{B}_\alpha,$$

by the recursion and homogeneity,

$$X_{N,\alpha}(t) = \Psi_\alpha(\mathfrak{x}(t) * Z_{N,\alpha}(t-1)) = \Psi_\alpha(\mathfrak{x}(t) * X_{N,\alpha}(t-1)),$$

thus, $\{X_{N,\alpha}(t) : t \geq 0\}$ is a Markov chain.

$\forall \alpha > 0$, $(X_{N,\alpha}(t))_{t \geq 0}$ is a Markov chain in \bar{B}_α .

Proposition (Hennion 1997, Hennion-Hervé 2008)

1 \exists event Ω_0 with $\mathbb{P}(\Omega_0) = 1$ such that the (random) limit

$$X_{N,\alpha}^\infty = \lim_{t \rightarrow \infty} \Pi(t)^\alpha \cdot v,$$

exists for all $\alpha > 0$, $\omega \in \Omega_0$ and does not depend on $v \in \mathbb{R}_+^N$.

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Moreover, $X_{N,\alpha}^\infty = \Psi_\alpha(X_{N,\beta}^\infty)$ for all $\alpha, \beta > 0$.

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- 2 Let $m_{N,\alpha}$ denote the law of $X_{N,\alpha}^\infty$.

The chain $(X_{N,\alpha}(t))_{t \geq 0}$ with initial law $m_{N,\alpha}$ is stationary and ergodic.

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The chain $(X_{N,\alpha}(t))_{t \geq 0}$ with initial law $m_{N,\alpha}$ is stationary and ergodic.
- 3 Denote by θ_s the shift on Ω by $s \in \mathbb{Z}$, $\theta_s \omega(t) = \omega(s+t)$, and set

$$X_{N,\alpha}^\infty(s) := X_{N,\alpha}^\infty \circ \theta_s = \lim_{t \rightarrow \infty} \Pi(s,t)^\alpha \cdot v,$$

(In particular, $X_{N,\alpha}^\infty(0) = X_{N,\alpha}^\infty(\cdot)$.) Then,

$$\mathfrak{X}(0)^\alpha \cdot X_{N,\alpha}^\infty = X_{N,\alpha}^\infty(-1)$$

Infinite volume polymer measure

↗ P2L polymer measure = probability measure on $J_N(0, i; T, \star)$:

$$P_{0, i; T, \star}^{\omega}(\mathbf{j} = (j_0, \dots, j_t)) = \frac{\mathbf{1}_{j_0=i}}{Z_N(0, i; T, \star)} \prod_{s=1}^t \omega_{j_{s-1}, j_s}(\mathbf{s}).$$

↗ Similarly, there exists an almost-sure limit to the backward product

$$\overleftarrow{X}_{N, \alpha}^{\infty}(\mathbf{s}) = \lim_{t \rightarrow \infty} \Pi(-t, \mathbf{s} - 1)^* \overset{\alpha}{\cdot} \nu$$

which does not depend on $\nu \in \mathbb{R}_+^N$. Since $\mathfrak{X}(0)^* \stackrel{\text{law}}{=} \mathfrak{X}(0)$, we have

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$$\overleftarrow{X}_{N, \alpha}^\infty(\mathbf{s}) \stackrel{\text{law}}{=} X_{N, \alpha}^\infty .$$

↻ Define the random probability measure $\nu_N(t, \cdot)$ on $\{1, \dots, N\}$ by
 $(X_{N, \alpha}^\infty(\mathbf{s}, j) = j\text{-th component of } X_{N, \alpha}^\infty(\mathbf{s}))$

$$\nu_N(t, j) = \frac{\overleftarrow{X}_{N, \alpha}^\infty(t, j) X_{N, \alpha}^\infty(t, j)}{\sum_{k=1}^N \overleftarrow{X}_{N, \alpha}^\infty(t, k) X_{N, \alpha}^\infty(t, k)} .$$

Result: existence of an infinite volume polymer measure and a co-variant law.

Infinite volume polymer measure

Proposition

- 1 For almost every environment ω , the polymer measure $P_{0,,i;T,*}^\omega$ converges as $T \rightarrow \infty$ to the (time-inhomogeneous) Markov chain with $P^\omega(j_0 = i) = 1$ and transition probabilities given by

$$P^\omega(j_{t+1} = \ell | j_t = k) = \frac{\omega_{k,\ell}(t+1) X_N^\infty(t+1, \ell)}{\sum_{\ell'=1}^N \omega_{k,\ell'}(t+1) X_N^\infty(t+1, \ell')} \quad (1)$$

for $t \geq 0, k, \ell \in \{1, \dots, N\}$.

- 2 Let $\omega \in \Omega_0$. For the chain with transition (1) starting at time s with law $\nu(s, \cdot)$, we have for $t \geq s$,

$$P^\omega(j_t = \ell) = \nu_N(t, \ell), \quad \ell = 1, \dots, N.$$

The co-variant law is proportional to the doubly infinite sum of weights over polymers (from times $-\infty$ to $+\infty$) which take the value j at time t .

Infinite volume polymer measure: sketch of proof

□ Finite horizon P2L polymer measure: for $\mathbf{j} \in J_N(0, i; T, \star)$,

$$P_{0,i;T,\star}^\omega(\mathbf{j}) = \frac{\prod_{t=1}^T \omega_{j_{t-1}, j_t}(t)}{Z_N(0, i; T, \star)}$$

is time-inhomogeneous Markov chain on $\{1, \dots, N\}$. Transition for $0 \leq t < T$:

$$P_{0,i;T,\star}^\omega(j_{t+1} = \ell | j_t = k) = \frac{\omega_{k,\ell}(t+1) Z_N(t+1, \ell; T, \star)}{\sum_{1 \leq m \leq N} \omega_{k,m}(t+1) Z_N(t+1, m; T, \star)}$$

But, a.s.,

$$\Pi(t+1, T) \cdot \mathbf{1} \longrightarrow X_N^\infty(t+1)$$

so above LHS converges

$$P_{0,i;T,\star}^\omega(j_{t+1} = \ell | j_t = k) \longrightarrow \frac{\omega_{k,\ell}(t+1) X_N^\infty(t+1, \ell)}{\sum_{\ell'=1}^N \omega_{k,\ell'}(t+1) X_N^\infty(t+1, \ell')}$$



Free energy and Gaussian fluctuation at fixed N

From general results on products of random matrices:

Theorem

Fix N and assume that $\mathbb{E}|\ln \omega_{i,j}|^{2+\delta} < \infty$. Then, there exist v_N and $\sigma_N > 0$ [assuming ω is not constant] such that, for all $j = 1, \dots, N$,

$$\lim_{t \rightarrow \infty} \frac{1}{t} \ln Z_N(t, j) = v_N \quad \text{a.s.,}$$

and

$$\frac{1}{\sqrt{t}} (\ln Z_N(t, j) - v_N t) \xrightarrow{\text{law}} \mathcal{N}(0, \sigma_N^2) \quad \text{as } t \rightarrow \infty.$$

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Furthermore,

$$v_N = \mathbb{E} [\ln \|\mathfrak{X}(0) X_{N,\alpha}^\infty\|_\alpha].$$

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- 1 Mean-Field Model
- 2 Integrable model on Complete graph
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α -Stable Environments

$$\omega \sim \mathcal{S}_\alpha$$

stable law of index $\alpha \in (0, 1)$,

$$\mathbb{E}e^{-\lambda S} = e^{-\lambda^\alpha}, \quad \lambda \geq 0.$$

(For independent \mathcal{S}_α -distributed r.v.s, $\sum_{i=1}^N a_i S_i \stackrel{\text{law}}{=} \mathcal{S}_\alpha$ if $\sum_{i=1}^N a_i^\alpha = 1$.) Let

$$S_N(t, j) := \frac{Z_N(t, j)}{\|Z_N(t-1)\|_\alpha}, \quad \varphi_N(t) := \log \|Z_N(t-1)\|_\alpha,$$

so that

$$\log Z_N(t, j) = \log S_N(t, j) + \varphi_N(t).$$

α -norm describes the mean height of the polymer.

α -Stable Environments

Theorem

Suppose $\{\omega_{i,j}(t)\}$ i.i.d. , S_α -distributed. Then,

- 1 $\{S_N(t,j) : t \geq 1, 1 \leq j \leq N\}$ is i.i.d. S_α -distributed.

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- 2 $\{\varphi_N(t) : t \geq 1\}$ is a random walk with i.i.d jumps $\{\Upsilon_N(t) : t \geq 1\}$

$$\Upsilon_N \stackrel{\text{law}}{=} \ln \|S_N\|_\alpha,$$

where S_N is an i.i.d. family of S_α -distributed random variables.

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- 5 $\{X_{N,\alpha}^\infty(t, j) : t \geq 1, 1 \leq j \leq N\}$ is i.i.d. $m_{N,\alpha}$ -distributed.

α -Stable Environments

Some comments:

- Lyapunov exponents are usually not explicit.
Some exceptions: Cohen-Newman 1984
- polymer height function = moving front

$$\log Z_N(t, j) = \log S_N(t, j) + \varphi_N(t).$$

(height function remains concentrated around a ballistic motion)

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Lyapunov exponent for α -Stable Environments

As the velocity and variance are explicit α -Stable environments, we obtain asymptotics as N grows to ∞ . Observe

$$\Upsilon_N = \frac{1}{\alpha} \ln \sum_{j=1}^N S_N(j)^\alpha \quad \text{where} \quad \sum_{j=1}^N S_N(j)^\alpha \stackrel{\text{law}}{\equiv} c_\alpha N \ln N + N S_1^+ + o(N),$$

since $(S_\alpha)^\alpha \in \text{Dom}(S_1^+)$ **totally asymmetric, Cauchy** distribution.

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Proposition

Assume $\{\omega_{i,j}(t) : t \geq 1, 1 \leq i, j \leq N\}$ is an i.i.d., S_α -distributed family. Then, as $N \rightarrow \infty$,

$$v_N = \alpha^{-1} (\ln N + \ln \ln N + \ln c_\alpha) + o(1), \quad (2)$$

$$\sigma_N^2 = \frac{\pi^2}{3\alpha^2 \ln N} + o\left(\frac{1}{\ln N}\right). \quad (3)$$

Front profile for α -Stable Environments

Front profile $U_N(t, \cdot)$ at time $t :=$ random distribution of the log – P2P polymer partition function :

$$U_N(t, x) = \frac{1}{N} \sum_{j=1}^N \mathbf{1}_{\{\ln Z_N(t,j) > x\}}.$$

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Let

$$u_\alpha(x) = \mathbb{P}(\mathcal{S}_\alpha > e^x), \quad x \in \mathbb{R}$$

Proposition

Fix $t \geq 1$, we have

- 1 Conditionally on \mathcal{F}_t , we have

$$U_N(t, x + \varphi_N(t-1)) \rightarrow u_\alpha(x), \quad \text{a.s.},$$

as $N \rightarrow \infty$, uniformly in x .

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- 2 As $N \rightarrow \infty$,

$$c_\alpha \ln N \times \left[U_N(t, x + (t-1) v_N + \varphi_N(0)) - u_\alpha(x) \right] \xrightarrow{\text{law}} u'_\alpha(x) \mathcal{X}.$$

where \mathcal{X} is distributed as a sum of t independent S_1^+ random variables.

Perturbative results

Environments close to α -stable

Environments that are perturbations of the \mathcal{S}_α laws. Suppose

$$1 - \mathbb{E} \exp(it\omega) \sim t^\alpha, \quad t \sim 0,$$

for some $\alpha \in (0, 1)$.

Claim (in progress)

For $t \geq 2$,

$$\frac{Z_N(t, i)}{\|Z_N(t-1)\|_\alpha} \xrightarrow{\text{law}} \mathcal{S}_\alpha.$$

For any sequence $K_N \subset \{1, \dots, N\}$ with fixed size $|K_N| = k$,

$$\left\{ \frac{Z_N(t, i)}{\|Z_N(t-1)\|_\alpha} : i \in K_N \right\} \xrightarrow{\text{law}} \mathcal{S}_\alpha^{\otimes k}.$$

For $t \geq 2$, we have:

$$U_N(t, x + \varphi_N(t-1)) \rightarrow u_\alpha(x), \quad \text{a.s.},$$

as $N \rightarrow \infty$, uniformly in x .

Perturbative results

Environments close to α -stable

Reason:

$$\sum_{i=1}^N a_i \omega_{i,j}(t) \simeq S_\alpha$$

in law, if

$$\sum_{i=1}^N a_i^\alpha = 1 \quad \text{and} \quad a_i \quad \text{small.}$$

Can be checked with $a_i = \frac{Z(t-1,i)}{\|Z_N(t-1)\|_\alpha}$ after 1 step of the dynamics.

Note: It appears S_α , not S_1^+ .

Other questions

(in progress)

- (α -stable case) Genealogy: Bolthausen-Sznitman (cf Cortines 2016).
- (α -stable case) Asymptotics of the invariant measure
- (α -stable case) Scaling limit

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THANK YOU !