

Dispersive partial differential equations on the half-line

Nikos Tzirakis (UIUC)

French-American Conference on Nonlinear Dispersive PDEs
June 12–16, 2017

Joint work with B. Erdogan and B. Gurel

For manuscripts see <http://www.math.uiuc.edu/~tzirakis/>

Consider the nonlinear Schrödinger equation (NLS) on \mathbb{R} or \mathbb{T} :

$$iu_t + u_{xx} \pm |u|^2 u = 0, \quad x \in \mathbb{R} \text{ or } \mathbb{T}, t \in \mathbb{R},$$
$$u(\cdot, 0) = g(\cdot) \in H^s.$$

Consider the nonlinear Schrödinger equation (NLS) on \mathbb{R} or \mathbb{T} :

$$\begin{aligned}iu_t + u_{xx} \pm |u|^2 u &= 0, \quad x \in \mathbb{R} \text{ or } \mathbb{T}, t \in \mathbb{R}, \\u(\cdot, 0) &= g(\cdot) \in H^s.\end{aligned}$$

- Duhamel's formula

$$u(t) = e^{it\partial_{xx}} g \mp i \int_0^t e^{i(t-s)\partial_{xx}} \left(|u(x, s)|^2 u(x, s) \right) ds.$$

Consider the nonlinear Schrödinger equation (NLS) on \mathbb{R} or \mathbb{T} :

$$\begin{aligned}iu_t + u_{xx} \pm |u|^2 u &= 0, \quad x \in \mathbb{R} \text{ or } \mathbb{T}, t \in \mathbb{R}, \\u(\cdot, 0) &= g(\cdot) \in H^s.\end{aligned}$$

- Duhamel's formula

$$u(t) = e^{it\partial_{xx}} g \mp i \int_0^t e^{i(t-s)\partial_{xx}} \left(|u(x, s)|^2 u(x, s) \right) ds.$$

- Bourgain '93: Wellposedness in $H^s(\mathbb{T})$, $s \geq 0$; using periodic $L^4_{x,t}$ Strichartz and $X^{s,b}$ spaces:

$$\|u\|_{X^{s,b}} = \|e^{-it\partial_{xx}} u\|_{H_x^s H_t^b} = \|\langle k \rangle^s \langle \tau + k^2 \rangle^b \widehat{u}(k, \tau)\|_{\ell_k^2 L_\tau^2}.$$

Smoothing theorem for NLS, Erdogan–Tz. (MRL '13)

- Fix $s > 0$. Assume that $g \in H^s(\mathbb{T})$. Then for any $a < \min(2s, 1/2)$,

$$u(x, t) - e^{i(\partial_{xx} + P)t}g \in C_{t \in \mathbb{R}}^0 H_{x \in \mathbb{T}}^{s+a},$$

where $P = \|g\|_2^2/\pi$.

Smoothing theorem for NLS, Erdogan–Tz. (MRL '13)

- Fix $s > 0$. Assume that $g \in H^s(\mathbb{T})$. Then for any $a < \min(2s, 1/2)$,

$$u(x, t) - e^{i(\partial_{xx} + P)t}g \in C_{t \in \mathbb{R}}^0 H_{x \in \mathbb{T}}^{s+a},$$

where $P = \|g\|_2^2/\pi$.

- For fixed $s > 0$, $a < \min(2s, \frac{1}{2})$, $0 < b - \frac{1}{2}$ sufficiently small :

$$\| |u|^2 u \|_{X^{s+a, b-1}} \lesssim \|u\|_{X^{s, b}}^3.$$

Smoothing theorem for NLS, Erdogan–Tz. (MRL '13)

- Fix $s > 0$. Assume that $g \in H^s(\mathbb{T})$. Then for any $a < \min(2s, 1/2)$,

$$u(x, t) - e^{i(\partial_{xx} + P)t}g \in C_{t \in \mathbb{R}}^0 H_{x \in \mathbb{T}}^{s+a},$$

where $P = \|g\|_2^2/\pi$.

- For fixed $s > 0$, $a < \min(2s, \frac{1}{2})$, $0 < b - \frac{1}{2}$ sufficiently small :

$$\| |u|^2 u \|_{X^{s+a, b-1}} \lesssim \|u\|_{X^{s, b}}^3.$$

- Compaan '14: the analogous statement on \mathbb{R} .

Smoothing theorem for NLS, Erdogan–Tz. (MRL '13)

- Fix $s > 0$. Assume that $g \in H^s(\mathbb{T})$. Then for any $a < \min(2s, 1/2)$,

$$u(x, t) - e^{i(\partial_{xx} + P)t}g \in C_{t \in \mathbb{R}}^0 H_{x \in \mathbb{T}}^{s+a},$$

where $P = \|g\|_2^2/\pi$.

- For fixed $s > 0$, $a < \min(2s, \frac{1}{2})$, $0 < b - \frac{1}{2}$ sufficiently small :

$$\| |u|^2 u \|_{X^{s+a, b-1}} \lesssim \|u\|_{X^{s, b}}^3.$$

- Compaan '14: the analogous statement on \mathbb{R} .
- Kappaler–Schaad–Topalov '15: defocusing NLS on \mathbb{T} . For $g \in H^k$, $k \geq 1$ integer,

$$\|u - e^{iLt}g\|_{H^{k+1}} \leq C(\|g\|_{H^k}), \quad t \in \mathbb{R}$$

where L is a linear operator depending on g nonlinearly.

Improved smoothing theorem for NLS, Erdogan–Gurel–Tz. (to appear in Indiana Math. J.)

Consider the cubic NLS on \mathbb{T} . For any $s > \frac{1}{4}$, and $a \leq \min(1, 2s)$ (the inequality has to be strict if the minimum is $2s$), we have

$$\|u(t) - e^{it(\partial_{xx} + P)}g\|_{C_t^0 H_x^{s+a}} \lesssim \|g\|_{H^s}^3 + \|g\|_{H^s}^5.$$

Improved smoothing theorem for NLS, Erdogan–Gurel–Tz. (to appear in Indiana Math. J.)

Consider the cubic NLS on \mathbb{T} . For any $s > \frac{1}{4}$, and $a \leq \min(1, 2s)$ (the inequality has to be strict if the minimum is $2s$), we have

$$\|u(t) - e^{it(\partial_{xx} + P)}g\|_{C_t^0 H_x^{s+a}} \lesssim \|g\|_{H^s}^3 + \|g\|_{H^s}^5.$$

On \mathbb{R} , for any $s > \frac{1}{2}$, and $a < 1$, we have $u(t) - e^{it\partial_{xx}}g \in C_t^0 H_x^{s+a}$ and

$$\begin{aligned} \|u(t) - e^{it\partial_{xx}}g\|_{H^{s+a}} &\lesssim \|g\|_{H^s} (1 + \|g\|_{H^{\frac{1}{2}+}}^2) + \|u(t)\|_{H^s} \|u(t)\|_{H^{\frac{1}{2}+}}^2 \\ &\quad + \int_0^t \|u(t')\|_{H^s} (\|u(t')\|_{H^{\frac{1}{2}+}}^2 + \|u(t')\|_{H^{\frac{1}{2}+}}^4) dt'. \end{aligned}$$

NLS on \mathbb{R}^+ :

We study the following initial-boundary value problem (IBVP)

$$\begin{aligned}iu_t + u_{xx} \pm |u|^2 u &= 0, \quad x \in \mathbb{R}^+, t \in \mathbb{R}^+, \\u(x, 0) &= g(x), \quad u(0, t) = h(t).\end{aligned}\tag{1}$$

Here $g \in H^s(\mathbb{R}^+)$ and $h \in H^{\frac{2s+1}{4}}(\mathbb{R}^+)$, $s \in [0, \frac{5}{2}) \setminus \{\frac{1}{2}, \frac{3}{2}\}$, with the additional compatibility condition $g(0) = h(0)$ for $s > \frac{1}{2}$.

NLS on \mathbb{R}^+ :

We study the following initial-boundary value problem (IBVP)

$$\begin{aligned}iu_t + u_{xx} \pm |u|^2 u &= 0, \quad x \in \mathbb{R}^+, t \in \mathbb{R}^+, \\ u(x, 0) &= g(x), \quad u(0, t) = h(t).\end{aligned}\tag{1}$$

Here $g \in H^s(\mathbb{R}^+)$ and $h \in H^{\frac{2s+1}{4}}(\mathbb{R}^+)$, $s \in [0, \frac{5}{2}) \setminus \{\frac{1}{2}, \frac{3}{2}\}$, with the additional compatibility condition $g(0) = h(0)$ for $s > \frac{1}{2}$.

- Kato smoothing:

$$\left\| \eta(t) e^{it\partial_{xx}} g \right\|_{L_x^\infty H_t^{\frac{2s+1}{4}}} \lesssim \|g\|_{H^s(\mathbb{R})}.$$

To construct the solutions of (1), first consider the linear problem:

$$\begin{aligned}iv_t + v_{xx} &= 0, \quad x \in \mathbb{R}^+, t \in \mathbb{R}^+, \\v(x, 0) &= g(x) \in H^s(\mathbb{R}^+), \quad v(0, t) = h(t) \in H^{\frac{2s+1}{4}}(\mathbb{R}^+).\end{aligned}\tag{2}$$

To construct the solutions of (1), first consider the linear problem:

$$\begin{aligned}iv_t + v_{xx} &= 0, \quad x \in \mathbb{R}^+, t \in \mathbb{R}^+, \\v(x, 0) &= g(x) \in H^s(\mathbb{R}^+), \quad v(0, t) = h(t) \in H^{\frac{2s+1}{4}}(\mathbb{R}^+).\end{aligned}\tag{2}$$

The solution v can be written as

$$W_0^t(g, h) = W_0^t(0, h - p) + e^{it\partial_{xx}} g_e,$$

where g_e is an H^s extension of g to \mathbb{R} , and $p(t) = e^{it\partial_{xx}} g_e|_{x=0}$, which is locally in $H^{\frac{2s+1}{4}}(\mathbb{R}^+)$ by Kato smoothing.

Here $W_0^t(0, h)$ denotes the solution of (2) when $g = 0$.

Using Laplace transform (Bona–Sun–Zhang), we have

$W_0^t(0, h) = W_1 h + W_2 h$, where

$$W_1 h(x, t) = \frac{1}{\pi} \int_0^\infty e^{-i\beta^2 t + i\beta x} \beta \widehat{h}(-\beta^2) d\beta,$$

$$W_2 h(x, t) = \frac{1}{\pi} \int_0^\infty e^{i\beta^2 t - \beta x} \rho(\beta x) \beta \widehat{h}(\beta^2) d\beta,$$

$\rho(x)$: a smooth function supported on $(-2, \infty)$, $\rho(x) = 1$ for $x > 0$.

$$\widehat{h}(\xi) = \mathcal{F}(\chi_{(0, \infty)} h)(\xi) = \int_0^\infty e^{-i\xi t} h(t) dt.$$

$W_0^t(0, h)$ is well-defined for $x \in \mathbb{R}$, but satisfies linear Schrödinger for $x > 0$.

Duhamel's formula for (1).

$$u(t) = W_0^t(g, h - q)(t) + \int_0^t e^{i(t-t')\partial_{xx}} |u|^2 u dt', \quad (3)$$

$$q(t) = \int_0^t e^{i(t-t')\partial_{xx}} |u|^2 u dt' \Big|_{x=0}.$$

We solve (3) on \mathbb{R} . The restriction of the solution to \mathbb{R}^+ satisfies NLS.

Fixed point argument on $X^{s,b}$ on \mathbb{R} for $b < \frac{1}{2}$, $s > 0$.

In addition, the solution is in

$$C_t^0 H_x^s \cap C_x^0 H_t^{\frac{2s+1}{4}}.$$

$X^{s,b}$ estimates ($0 \leq b < \frac{1}{2}$)

$$\left\| \eta(t) \int_0^t e^{i(t-t')\partial_{xx}} F(t') dt' \right\|_{X^{s,b}} \lesssim \|F\|_{X^{s,-b}}, \quad s \in \mathbb{R},$$

$X^{s,b}$ estimates ($0 \leq b < \frac{1}{2}$)

$$\left\| \eta(t) \int_0^t e^{i(t-t')\partial_{xx}} F(t') dt' \right\|_{X^{s,b}} \lesssim \|F\|_{X^{s,-b}}, \quad s \in \mathbb{R},$$

$$\|\eta(t) W_0^t(g, h)\|_{X^{s,b}} \lesssim \|g\|_{H^s(\mathbb{R}^+)} + \|h\|_{H_t^{\frac{2s+1}{4}}(\mathbb{R}^+)}, \quad s \geq 0,$$

$X^{s,b}$ estimates ($0 \leq b < \frac{1}{2}$)

$$\left\| \eta(t) \int_0^t e^{i(t-t')\partial_{xx}} F(t') dt' \right\|_{X^{s,b}} \lesssim \|F\|_{X^{s,-b}}, \quad s \in \mathbb{R},$$

$$\|\eta(t) W_0^t(g, h)\|_{X^{s,b}} \lesssim \|g\|_{H^s(\mathbb{R}^+)} + \|h\|_{H_t^{\frac{2s+1}{4}}(\mathbb{R}^+)}, \quad s \geq 0,$$

$$\left\| \eta(t) \int_0^t e^{i(t-t')\partial_{xx}} F dt' \right\|_{C_x^0 H_t^{\frac{2s+1}{4}}} \lesssim \begin{cases} \|F\|_{X^{s,-b}} & 0 \leq s \leq 1/2, \\ \|F\|_{X^{\frac{1}{2}, \frac{2s-1-4b}{4}}} + \|F\|_{X^{s,-b}} & 1/2 \leq s \leq 5/2. \end{cases}$$

Proposition (Erdogan–Tz. (JFA '16))

For fixed $0 < s < \frac{5}{2}$, and $0 \leq a < \min(2s, \frac{1}{2}, \frac{5}{2} - s)$, there exists $\epsilon > 0$ such that for $\frac{1}{2} - \epsilon < b < \frac{1}{2}$, we have

$$\| |u|^2 u \|_{X^{s+a, -b}} \lesssim \|u\|_{X^{s, b}}^3,$$

$$\| |u|^2 u \|_{X^{\frac{1}{2}, \frac{2s+2a-1-4b}{4}}} \lesssim \|u\|_{X^{s, b}}^3, \quad \text{for } 1/2 < s + a < 5/2.$$

- Yields the local theory for $0 < s < \frac{5}{2}$.

- Also yields the following smoothing statement:

Theorem (Erdogan–Tz. (JFA '16))

Fix $s \in (0, \frac{5}{2})$, $g \in H^s(\mathbb{R}^+)$, and $h \in H^{\frac{2s+1}{4}}(\mathbb{R}^+)$, with the additional compatibility condition $g(0) = h(0)$ for $s > \frac{1}{2}$. Then, for t in the local existence interval $[0, T]$ and $a < \min(2s, \frac{1}{2}, \frac{5}{2} - s)$ we have

$$u(x, t) - W_0^t(g, h) \in C_t^0 H_x^{s+a}([0, T] \times \mathbb{R}^+).$$

Energy identities

Recall that on \mathbb{R} : $\|u\|_{L^2} = \|g\|_{L^2}$, and

$$E(t) := \frac{1}{2} \|\partial_x u\|_{L^2}^2 \mp \frac{1}{4} \|u\|_{L^4}^4 = E(0).$$

Energy identities

Recall that on \mathbb{R} : $\|u\|_{L^2} = \|g\|_{L^2}$, and

$$E(t) := \frac{1}{2} \|\partial_x u\|_{L^2}^2 \mp \frac{1}{4} \|u\|_{L^4}^4 = E(0).$$

The following provide a priori bounds for the H^1 norm of the solution, bounded in the defocusing, and exponential in the focusing case.

$$\partial_t |u|^2 = -2\Im(u_x \bar{u})_x,$$

$$\partial_t (|u_x|^2 \mp \frac{1}{2} |u|^4) = 2\Re(u_x \bar{u}_t)_x,$$

$$\partial_x (|u_x|^2 \pm \frac{1}{2} |u|^4) = -i[(u \bar{u}_x)_t - (u \bar{u}_t)_x].$$

Energy identities

Recall that on \mathbb{R} : $\|u\|_{L^2} = \|g\|_{L^2}$, and

$$E(t) := \frac{1}{2} \|\partial_x u\|_{L^2}^2 \mp \frac{1}{4} \|u\|_{L^4}^4 = E(0).$$

The following provide a priori bounds for the H^1 norm of the solution, bounded in the defocusing, and exponential in the focusing case.

$$\partial_t |u|^2 = -2\Im(u_x \bar{u})_x,$$

$$\partial_t (|u_x|^2 \mp \frac{1}{2} |u|^4) = 2\Re(u_x \bar{u}_t)_x,$$

$$\partial_x (|u_x|^2 \pm \frac{1}{2} |u|^4) = -i[(u \bar{u}_x)_t - (u \bar{u}_t)_x].$$

- Bona–Sun–Zhang '15. Solution is global in H^1 if $g, h \in H^1$.

Theorem (Erdogan–Tz. (JFA '16))

In the case $s \in [1, \frac{5}{2})$, $g \in H^s(\mathbb{R}^+)$, and $h \in H^{\frac{2s+1}{4}}(\mathbb{R}^+) \cap H^1(\mathbb{R}^+)$, the solution u is global and the smoothing statement holds for all times. Moreover, in the defocusing case $\|u\|_{H^s(\mathbb{R}^+)}$ grows at most polynomially, whereas in the focusing case it grows at most exponentially.

- Zakharov system on \mathbb{R}^+ :

$$\left\{ \begin{array}{l} iu_t + u_{xx} = nu, \quad x \in \mathbb{R}^+, \quad t \in \mathbb{R}^+, \\ n_{tt} - n_{xx} = (|u|^2)_{xx}, \\ u(x, 0) = g(x) \in H^{s_0}(\mathbb{R}^+), \\ n(x, 0) = n_0(x) \in H^{s_1}(\mathbb{R}^+), \quad n_t(x, 0) = n_1(x) \in \hat{H}^{s_1-1}(\mathbb{R}^+), \\ u(0, t) = h(t) \in H^{\frac{2s_0+1}{4}}(\mathbb{R}^+), \quad n(0, t) = f(t) \in H^{s_1}(\mathbb{R}^+), \end{array} \right.$$

(with some additional compatibility conditions).

- Zakharov system on \mathbb{R}^+ :

$$\left\{ \begin{array}{l} iu_t + u_{xx} = nu, \quad x \in \mathbb{R}^+, \quad t \in \mathbb{R}^+, \\ n_{tt} - n_{xx} = (|u|^2)_{xx}, \\ u(x, 0) = g(x) \in H^{s_0}(\mathbb{R}^+), \\ n(x, 0) = n_0(x) \in H^{s_1}(\mathbb{R}^+), \quad n_t(x, 0) = n_1(x) \in \hat{H}^{s_1-1}(\mathbb{R}^+), \\ u(0, t) = h(t) \in H^{\frac{2s_0+1}{4}}(\mathbb{R}^+), \quad n(0, t) = f(t) \in H^{s_1}(\mathbb{R}^+), \end{array} \right.$$

(with some additional compatibility conditions).

- Erdogan–Tz: Local theory and smoothing for admissible (s_0, s_1) :
 $\frac{3}{2} > s_1 > -\frac{1}{2}$ and $\max(s_1, \frac{s_1}{2} + \frac{1}{4}) < s_0 \leq s_1 + 1$.

- Zakharov system on \mathbb{R}^+ :

$$\begin{cases} iu_t + u_{xx} = nu, & x \in \mathbb{R}^+, \quad t \in \mathbb{R}^+, \\ n_{tt} - n_{xx} = (|u|^2)_{xx}, \\ u(x, 0) = g(x) \in H^{s_0}(\mathbb{R}^+), \\ n(x, 0) = n_0(x) \in H^{s_1}(\mathbb{R}^+), \quad n_t(x, 0) = n_1(x) \in \hat{H}^{s_1-1}(\mathbb{R}^+), \\ u(0, t) = h(t) \in H^{\frac{2s_0+1}{4}}(\mathbb{R}^+), \quad n(0, t) = f(t) \in H^{s_1}(\mathbb{R}^+), \end{cases}$$

(with some additional compatibility conditions).

- Erdogan–Tz: Local theory and smoothing for admissible (s_0, s_1) :
 $\frac{3}{2} > s_1 > -\frac{1}{2}$ and $\max(s_1, \frac{s_1}{2} + \frac{1}{4}) < s_0 \leq s_1 + 1$.
- On \mathbb{R} the local theory is studied in $X^{s,b}$ spaces (Bourgain, Colliander, Ginibre, Tsutsumi, Velo).

Theorem (Erdogan–Tz. Comm. PDE '17)

For any admissible pair (s_0, s_1) the Zakharov system is locally wellposed in $H^{s_0}(\mathbb{R}^+) \times H^{s_1}(\mathbb{R}^+)$. Moreover, in the noncritical case when $s_0 < s_1 + 1$, we have the following smoothing bounds

$$\begin{aligned}u - W_0^t(g, h) &\in C_t^0 H^{s_0+a_0}([0, T] \times \mathbb{R}^+) \\n - V_0^t(n_0, n_1, f) &\in C_t^0 H^{s_1+a_1}([0, T] \times \mathbb{R}^+),\end{aligned}$$

for any $a_0 < \min(\frac{1}{2}, s_1 + \frac{1}{2}, s_1 - s_0 + 1, \frac{5}{2} - s_0)$ and $a_1 < \min(s_0 - s_1, 2s_0 - s_1 - \frac{1}{2}, \frac{3}{2} - s_1)$. In the case $s_0 = s_1 + 1$, we have the one sided smoothing

$$n - V_0^t(n_0, n_1, f) \in C_t^0 H^{s_1+a_1}([0, T] \times \mathbb{R}),$$

for any $a_1 < \min(1, \frac{3}{2} - s_1)$.

- Derivative Schrödinger equation on \mathbb{R}^+ :

$$\begin{cases} iu_t + u_{xx} - i(|u|^2u)_x = 0, & x \in \mathbb{R}^+, t \in \mathbb{R}^+, \\ u(x, 0) = G(x), \quad u(0, t) = H(t). \end{cases}$$

$$\mathcal{G}_\alpha f(x) = f(x) \exp\left(-i\alpha \int_x^\infty |f(y)|^2 dy\right), \quad \alpha \in \mathbb{R}$$

- Derivative Schrödinger equation on \mathbb{R}^+ :

$$\begin{cases} iu_t + u_{xx} - i(|u|^2u)_x = 0, & x \in \mathbb{R}^+, t \in \mathbb{R}^+, \\ u(x, 0) = G(x), \quad u(0, t) = H(t). \end{cases}$$

$$\mathcal{G}_\alpha f(x) = f(x) \exp\left(-i\alpha \int_x^\infty |f(y)|^2 dy\right), \quad \alpha \in \mathbb{R}$$

If u solves the above equation, then $v = \mathcal{G}_\alpha u$ satisfies

$$\begin{cases} iv_t + v_{xx} - i(2\alpha + 1)v^2\bar{v}_x - i(2\alpha + 2)|v|^2v_x + \frac{\alpha}{2}(2\alpha + 1)|v|^4v = 0 \\ v(x, 0) = g(x), \quad v(0, t) = h(t), \end{cases}$$

where $g(x) = \mathcal{G}_\alpha G(x)$, and

$$h(t) = H(t) \exp\left(-i\alpha \int_0^\infty |u(y, t)|^2 dy\right) = H(t) \exp\left(-i\alpha \int_0^\infty |v(y, t)|^2 dy\right).$$

For $\alpha = -1$

$$\begin{cases} iv_t + v_{xx} + iv^2 \bar{v}_x + \frac{1}{2}|v|^4 v = 0, & x, t \in \mathbb{R}^+, \\ v(x, 0) = g(x), \quad v(0, t) = h(t). \end{cases}$$

Theorem

Fix $s \in (\frac{1}{2}, \frac{5}{2})$, $s \neq \frac{3}{2}$, and $a < \min(\frac{5}{2} - s, \frac{1}{4}, 2s - 1)$. Then the solution v satisfies

$$v(x, t) - W_0^t(g, h)(x) \in C_t^0 H_x^{s+a}([0, T] \times \mathbb{R}^+),$$

where T is the local existence time, and $W_0^t(g, h)$ is the solution of the corresponding linear equation.

THREE PROBLEMS

1. Local well-posedness from v to u
2. Uniqueness of strong solutions
3. Global well-posedness theory in the energy space

1. The first requires to prove a different boundary value problem since the boundary function depends on the value of the function in the interior of the domain. Need to find h of the form $e^{i\gamma(t)} H(t)$, so that the solution v with data g, h , satisfies

$$\int_0^\infty |v(y, t)|^2 dy = \gamma(t), \quad t \in [0, T].$$

Lemma

Given $G \in H^s(\mathbb{R}^+)$ and $H \in H^{\frac{2s+1}{4}}(\mathbb{R}^+)$, there is a unique real valued function $\gamma \in H^{\frac{2s+1}{4}}([0, T])$ such that the solution v with data $g(x) = e^{i \int_x^\infty |G(y)|^2 dy} G(x)$, and $h(t) = e^{i\gamma(t)} H(t)$, satisfies

$$\gamma(t) = \int_0^\infty |v(y, t)|^2 dy, \quad t \in [0, T].$$

Here $T = T(\|G\|_{H^s}, \|H\|_{H^{\frac{2s+1}{4}}})$. Moreover, γ depends on G and H continuously.

2. The second requires an iteration of the smoothing estimates

First step: Uniqueness for smooth solutions/Energy arguments

Second step: Smoother approximation and smoothing

3. The third requires small initial and boundary data

Theorem

For any $\alpha \in \mathbb{R}$, there exists an absolute constant $c > 0$ such that DNLS on half line is globally well-posed in $H^1(\mathbb{R}^+)$ provided that

$$\|g\|_{H^1(\mathbb{R}^+)} + \|h\|_{H^1(\mathbb{R}^+)} \leq c.$$