

# Parameter recovery in two-component contamination mixtures: the $\mathbb{L}^2$ strategy

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# Outline

- 1 Introduction
- 2 Estimation of the mixture components
- 3 Upper bound
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## The mixture model

We have at our disposal a sample  $\mathcal{S} = (X_1, \dots, X_n)$  of i.i.d. random variables ( $X_i \in \mathbb{R}^d$ ), having a common density  $f^*$ .

In an unsupervised classification context,  $f^*$  can be considered of the form

$$f^* = \sum_{j=1}^K \lambda_j^* \phi(\cdot - \mu_j^*),$$

where  $\phi$  is a **known** density,  $\lambda_j^* \in [0, 1]$ ,  $\mu_j^* \in \mathbb{R}^d$  and  $K$  are unknown parameters.

Classical statistical issues

- estimation of the sequences  $(\lambda_j^*)_{j=1, \dots, K}$  and  $(\mu_j^*)_{j=1, \dots, K}$ ,
- estimation of the component number  $K$  (model selection task).

## Mixture as an inverse problem

The estimation of the mixture parameters turns to be an inverse (deconvolution) problem. Indeed,

$$X_i = U_i + \epsilon_i, \quad \forall i \in \{1, \dots, n\},$$

where  $\epsilon_i \sim \phi$  (error term) and  $U_i$  are associated to the discrete measure  $G = \sum_{k=1}^K \lambda_k^* \delta_{\mu_k^*}$ . Then,

$$f^* = G * \phi.$$

In this context, the 'classical' deconvolution tools are not available.

## Two component mixtures

In this talk, we consider the particular contamination case, namely  $K = 2$ ,  $\mu_1 = 0$  and  $\mu_2 = \mu^*$  :

$$f^* = f_{\lambda^*}(x) = (1 - \lambda^*)\phi(x) + \lambda^*\phi(x - \mu^*) \quad \forall x \in \mathbb{R}^d.$$

The  $X_i$  can be written

$$X_i = \mu^* V_i + \epsilon_i, \quad \forall i \in \{1, \dots, n\},$$

where  $V_i \sim \text{Ber}(\lambda^*)$ ,  $\epsilon_i \sim \phi$ .

N.B. : Strong analogies with the sequence model

$$y_k = \theta_k + \eta_k, \quad k \in \{1, \dots, n\},$$

where  $\theta_k \in \{0, \theta\}$  and  $\text{card}\{k : \theta_k \neq 0\} = s$  ( $\sim n\lambda^*$ ).

## References

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- [2] T. Cai, X. Jeng and J. Jin. Optimal detection of heterogeneous and heteroscedastic mixture, *J.R. Stat. Soc. Ser. B*, **73**, (2011) 629-662.
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# Outline

Goal of this contribution :

- provide an estimation of both  $\lambda^*$  and  $\mu^*$  ( $\phi$  is known).
- handle the case where  $\lambda^*, |\mu^*| \rightarrow 0$  as  $n \rightarrow +\infty$ .
- discussion on the 'direct' and 'inverse' point of views.
- establish lower bounds.

All the results are available in a multivariate setting. For the sake of simplicity, we only consider the case  $d = 1$  along this talk.



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## Existing results

- Likelihood methods : No available analytic expression for mixture models : EM algorithms required.
  - Initialisation of the EM ?
  - Robustness issues for related models (see, e.g., Baraud, Birgé and Sart (2017)).
- Arias -Castro and Verzelen (2016) : estimation and clustering in a multivariate setting. The parameter  $\lambda^*$  is fixed and known ( $= 1/2$ ). The density  $\phi$  is available (Gaussian?).
- Butucea and Vandekerkhove (2010) : Estimation of both  $\phi$  (supposed to be symmetric) and the mixture parameters (fixed). Asymptotic normality.

## Existing results

- Collier, Comminges and Tsybakov (2017) : Estimation of linear and quadratic functionals in the sequence model. The sparsity parameter  $s(\sim n\lambda^*)$  is assumed to be known.
- Heinrich and Kahn (2015) : Convergence rates with Wasserstein distance when the component number is unknown. The mixture components are fixed with respect to  $n$ .
- Bunea et als. (2010) : SPADES and mixture models. Algorithm based on the  $\mathbb{L}^2$  distance with a sparsity penalization. The compatibility condition does not allow to handle situations where the mixture parameters are close to each others.

## An estimator based on the $\mathbb{L}^2$ distance

For all  $(\lambda, \mu) \in [0, 1] \times \mathbb{R}$ , define

$$f_{\lambda, \mu} = (1 - \lambda)\phi(\cdot) + \lambda\phi(\cdot - \mu).$$

The term  $\|f_{\lambda, \mu} - f^*\|^2$  can be estimated (with bias) by

$$\|f_{\lambda, \mu}\|^2 - \frac{2}{n} \sum_{i=1}^n f_{\lambda, \mu}(X_i).$$

Given a grid  $\mathcal{M}$  on  $\mu$ , we define

$$(\hat{\lambda}, \hat{\mu}) = \arg \min_{(\lambda, \mu) \in [0, 1] \times \mathcal{M}} \left[ \|f_{\lambda, \mu}\|^2 - \frac{2}{n} \sum_{i=1}^n f_{\lambda, \mu}(X_i) \right],$$

and  $\hat{f} = f_{\hat{\lambda}, \hat{\mu}}$ .

## An estimator based on the $\mathbb{L}^2$ distance

Our estimation strategy is based on the estimation of the convoluted density  $f^*$  (direct problem). We expect to recover informations on the underlying discrete mixture measure  $G^*$  (inverse problem).

Similar approaches (in different setting) in, e.g.,

- Laurent et al. (2011),
- Lepski (2016),
- Blanchard et al. (2016),

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## An estimator based on the $\mathbb{L}^2$ distance

Using classical tools, we can easily establish the following oracle inequality :

### Proposition

$$\mathbb{E}\|\hat{f} - f^*\|^2 \lesssim \inf_{\lambda, \mu \in \mathcal{M}} \|f_{\lambda, \mu} - f^*\|^2 + \frac{\log^2(|\mathcal{M}|)}{n}.$$

**Question** : Can we retrieve convergence results from this inequality ?

## Minoration of the $\mathbb{L}^2$ distance

Using simple algebra

$$\begin{aligned} & \|\hat{f} - f^*\|^2 \\ &= \|(1 - \hat{\lambda})\phi + \hat{\lambda}\phi(\cdot - \hat{\mu}) - (1 - \lambda^*)\phi - \lambda^*\phi(\cdot - \mu^*)\|^2, \end{aligned}$$



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**Question** : How can we handle the scalar product in the last equality?

## Assumptions

**Assumption  $\mathcal{H}_S$**  :  $\phi \in C^3(\mathbb{R}) \cap L^2(\mathbb{R})$

**Assumption  $\mathcal{H}_{Lip}$**  : There exists  $g \in L^2(\mathbb{R})$  s.t.

$$|\phi(x) - \phi(x - \mu)| \leq |\mu|g(x) \quad \forall x \in \mathbb{R}, \forall \mu \in [-\mu_{max}; \mu_{max}],$$

where

$$J := \int_{\mathbb{R}} g^2(x)\phi^{-1}(x)dx < +\infty.$$

Assumptions satisfies by, e.g., Gaussian, Cauchy, Laplace (with slight modification), ...

## Consequence

### Proposition

If the shape  $\phi$  satisfies  $\mathcal{H}_S$  and  $\mathcal{H}_{Lip}$ , then, for all  $a, b \in \mathbb{R}$

$$|\langle \phi - \phi_a, \phi_{a+b} - \phi_a \rangle| \leq \|\phi - \phi_a\| \|\phi_{a+b} - \phi_a\| (1 - c \|\phi - \phi_{a+b}\|).$$

for some positive constant  $c$ .

**Remark :** The classical Cauchy-Schwarz inequality provides  $c = 0$ . It is improved if  $a + b$  is 'far away' from 0 ('correlation' property).

## Consequence

Using the previous inequality with  $a = \hat{\mu}$  and  $b = \mu^* - \hat{\mu}$ , we get

$$\begin{aligned} \|\hat{f} - f^*\|^2 &= (\lambda^* - \hat{\lambda})^2 \|\phi - \phi(\cdot - \hat{\mu})\|^2 + (\lambda^*)^2 \|\phi(\cdot - \hat{\mu}) - \phi(\cdot - \mu^*)\|^2 \\ &\quad + 2(\lambda^* - \hat{\lambda}) \langle \phi - \phi_{\hat{\mu}}, \phi_{\hat{\mu}} - \phi_{\mu} \rangle, \end{aligned}$$

## Consequence

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## Consequence

Using the previous inequality with  $a = \hat{\mu}$  and  $b = \mu^* - \hat{\mu}$ , we get

$$\begin{aligned} & \|\hat{f} - f^*\|^2 \\ &= (\lambda^* - \hat{\lambda})^2 \|\phi - \phi(\cdot - \hat{\mu})\|^2 + (\lambda^*)^2 \|\phi(\cdot - \hat{\mu}) - \phi(\cdot - \mu^*)\|^2 \\ &\quad + 2(\lambda^* - \hat{\lambda}) \langle \phi - \phi_{\hat{\mu}}, \phi_{\hat{\mu}} - \phi_{\mu^*} \rangle, \\ &\geq (\lambda^* - \hat{\lambda})^2 \|\phi - \phi(\cdot - \hat{\mu})\|^2 + (\lambda^*)^2 \|\phi(\cdot - \hat{\mu}) - \phi(\cdot - \mu^*)\|^2 \\ &\quad - 2|\lambda^* - \hat{\lambda}| \lambda^* \|\phi - \phi_{\hat{\mu}}\| \|\phi_{\hat{\mu}} - \phi_{\mu^*}\| (1 - c \|\phi - \phi_{\mu^*}\|), \\ &\gtrsim (\lambda^* - \hat{\lambda})^2 \|\phi - \phi_{\hat{\mu}}\|^2 \|\phi - \phi_{\mu^*}\|^2 + (\lambda^*)^2 \|\phi_{\hat{\mu}} - \phi_{\mu^*}\|^2 \|\phi - \phi_{\mu^*}\|^2. \end{aligned}$$



## Consequence

Gathering the previous result and the oracle inequality obtained few slides ago, we get, with an appropriate choice for the grid  $\mathcal{M}$

$$(\lambda^* - \hat{\lambda})^2 \|\phi - \phi_{\hat{\mu}}\|^2 \|\phi - \phi_{\mu^*}\|^2 + (\lambda^*)^2 \|\phi_{\hat{\mu}} - \phi_{\mu^*}\|^2 \|\phi - \phi_{\mu^*}\|^2 \lesssim \frac{\log^2(n)}{n}.$$

**The Gaussian case :**

$$\|\phi_{\mu_1} - \phi_{\mu_2}\|^2 = \|\phi\|^2 \left(1 - e^{-\frac{(\mu_1 - \mu_2)^2}{4}}\right) \quad \forall \mu_1, \mu_2 \in \mathbb{R}.$$

In particular,

$$\mathbb{E} \left[ (\lambda^* - \hat{\lambda})^2 (\mu^*)^4 + (\lambda^*)^2 (\mu^* - \hat{\mu})^2 (\mu^*)^2 \right] \lesssim \frac{\log^2(n)}{n}.$$

## The Gaussian case

$$\mathbb{E} \left[ (\lambda^* - \hat{\lambda})^2 (\mu^*)^4 + (\lambda^*)^2 (\mu^* - \hat{\mu})^2 (\mu^*)^2 \right] \lesssim \frac{\log^2(n)}{n}.$$

In particular

$$\mathbb{E} \left[ (\lambda^*)^2 (\mu^*)^2 (\mu^* - \hat{\mu})^2 \right] \lesssim \frac{\log^2(n)}{n},$$

or equivalently

$$\mathbb{E} \left[ \left( \frac{\hat{\mu}}{\mu^*} - 1 \right)^2 \right] \lesssim \frac{\log^2(n)}{n(\lambda^*)^2 (\mu^*)^2}.$$

## The Gaussian case

$$\mathbb{E} \left[ \left( \frac{\hat{\mu}}{\mu^*} - 1 \right)^2 \right] \lesssim \frac{\log^2(n)}{n(\lambda^*)^2(\mu^*)^2}.$$

In particular, we have a consistent estimation as soon as

$$n(\lambda^*)^2(\mu^*)^4 \gg 1 \quad \Leftrightarrow \quad \lambda^*|\mu^*|^2 \gg \frac{1}{\sqrt{n}}.$$

In a similar setting, Donoho and Jin (2004) test

$$H_0 : \begin{cases} \lambda^* = 0 \\ \mu^* = 0 \end{cases} \quad \text{against} \quad H_1 : \lambda^*|\mu^*| \gtrsim \frac{1}{\sqrt{n}}$$

In some sense, the detection problem is easier.

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## Additional result

The  $\mathbb{L}^2$  distance between two mixture densities  $f_{\lambda_1, \mu_1}, f_{\lambda_2, \mu_2}$  can be related to the Wasserstein distance between the discrete mixture distribution  $G_{\lambda_1, \mu_1}, G_{\lambda_2, \mu_2}$ .

The Wasserstein  $\mathbb{L}^p$ -transportation distances between two probability measures  $m_1$  and  $m_2$  on  $\Omega$  are defined as

$$W_p^p(m_1, m_2) := \inf_{\pi \in \Pi(m_1, m_2)} \int \|x - y\|_p^p d\pi(x, y),$$

where  $\Pi(m_1, m_2)$  is the set of probability measures on  $\Omega \times \Omega$  having marginals  $m_1$  and  $m_2$ .

## Additional result

### Proposition

For any density that satisfies  $(\mathbf{H}_S)$  and  $(\mathbf{H}_{Lip})$ , there exists a constant  $c_\phi$  such that

$$\|f_{\lambda_1, \mu_1} - f_{\lambda_2, \mu_2}\| \geq c_\phi W_2^2(G_1, G_2),$$

for all  $\lambda_1, \lambda_2 \in (0, 1)$ ,  $\mu_1, \mu_2 \in [-M; M]$ , where

$$G_1 = (1 - \lambda_1)\delta_0 + \lambda_1\delta_{\mu_1} \quad \text{and} \quad G_2 = (1 - \lambda_2)\delta_0 + \lambda_2\delta_{\mu_2}.$$

In some sense, the direct problem allows to recover informations on the inverse problem.

## Conclusion

In order to complete this discussion, it is possible to obtain corresponding lower bounds (not trivial : the loss is not symmetric).

Possible outcomes

- Higher number (unknown) of components ?
- Unknown shape  $\phi$  ?

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# Parameter recovery in two-component contamination mixtures: the $\mathbb{L}^2$ strategy

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