

Local approximation methods using hierarchical splines

A framework based on the THB-spline basis

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Joint work with Carla Manni

Multivariate Approximation and Interpolation with Applications
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Motivation

- ▶ Splines and B-splines are of interest in a wide range of areas:
 - ▶ established tool: **geometric modelling, approximation theory**
 - ▶ recently: **isogeometric analysis (paradigm for solving PDEs)**
- ▶ In higher dimensions usually based on **tensor-product topology**
 - ▶ ☺ computationally efficient, geometrically intuitive
 - ▶ ☹ restriction to rectangular meshes
 - not well suited for **adaptive local refinement**
- ▶ Alternative spline spaces
 - ▶ **(Truncated) Hierarchical B-splines**
 - ▶ T-splines
 - ▶ LR-splines
 - ▶ B-splines on triangulations

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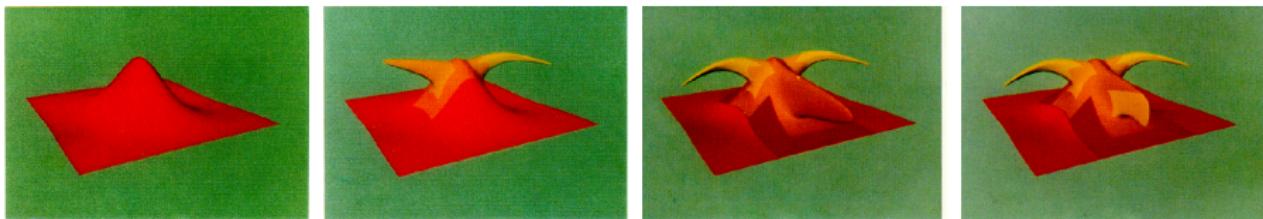
Hierarchical model

Hierarchical B-splines

[Forsey-Bartels, CG 1988]

[Kraft, 1997]

- ▶ framework for surface fitting and modelling
efficient construction of local features



Hierarchical model

Hierarchical splines

- ✓ local refinement
- ✓ any degree, any smoothness, any dimension

Hierarchical basis

- ✓ linearly independent
- ✓ nonnegative
- ✓ weakly stable
[Kraft, 1997]

Normalization: truncated basis

- ✓ linearly independent
- ✓ nonnegative
- ✓ partition of unity
- ✓ smaller support
- ✓ improved stability
[Giannelli-Jüttler-Speleers, CAGD 2012]

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- ▶ sequence of n nested (tensor-product) spline spaces on Ω^0

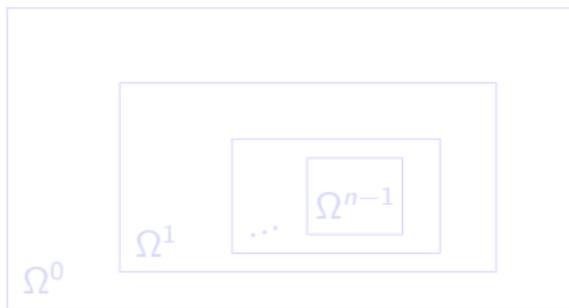
$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{n-1}$$

each spline space \mathbb{V}^ℓ spanned by normalized B-spline basis

$$\mathcal{B}^\ell = \{B_{i,\ell}, i = 1, \dots, N_\ell\}$$

- ▶ sequence of n sets

$$\Omega^0 \supseteq \Omega^1 \supseteq \dots \supseteq \Omega^{n-1}$$



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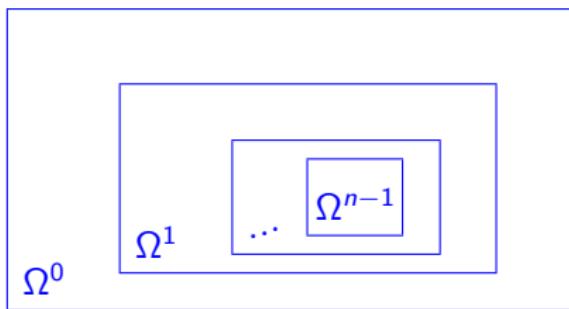
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hierarchical set (domain)

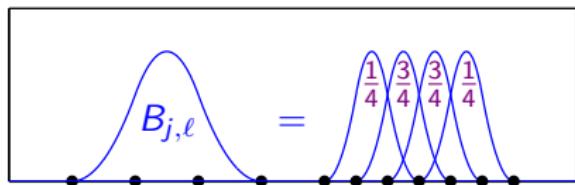


Hierarchical model

From hierarchical basis to truncated basis

- ▶ by subdivision, we can write every $B_{j,\ell} \in \mathbb{V}^\ell \subset \mathbb{V}^{\ell+1}$

$$B_{j,\ell} = \sum_{i=1}^{N_{\ell+1}} c_{i,\ell+1} B_{i,\ell+1}$$



- ▶ truncation mechanism:

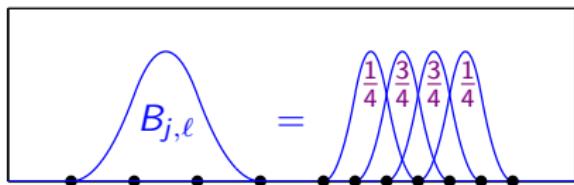
$$\text{trunc}^{\ell+1}(B_{j,\ell}) = \sum_{i: \text{supp}^0(B_{i,\ell+1}) \not\subseteq \Omega^{\ell+1}} c_{i,\ell+1} B_{i,\ell+1}$$

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Hierarchical model

THB-splines: construction [Giannelli-Jüttler-Speleers, CAGD 2012]

recursive definition of \mathcal{T} :

- (I) initialization: $\mathcal{T}^0 = \{B_{i,0} \in \mathcal{B}^0 : \text{supp}^0(B_{i,0}) \neq \emptyset\}$
- (II) recursive case: construct $\mathcal{T}^{\ell+1}$ from \mathcal{T}^ℓ

$$\mathcal{T}^{\ell+1} = \mathcal{T}_A^{\ell+1} \cup \mathcal{T}_B^{\ell+1}, \quad \ell = 0, \dots, n-2,$$

where

$$\mathcal{T}_A^{\ell+1} = \{\text{trunc}^{\ell+1}(B_{i,j}^{\ell}) : B_{i,j}^{\ell} \in \mathcal{T}^\ell \wedge \text{supp}^0(B_{i,j}^{\ell}) \not\subseteq \Omega^{\ell+1}\}$$

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- (III) $\mathcal{T} = \mathcal{T}^{n-1}$

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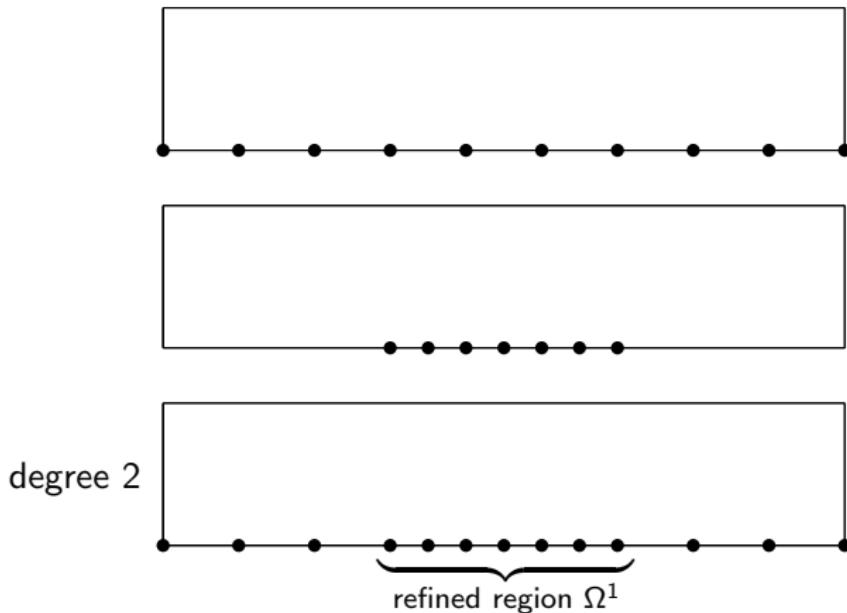
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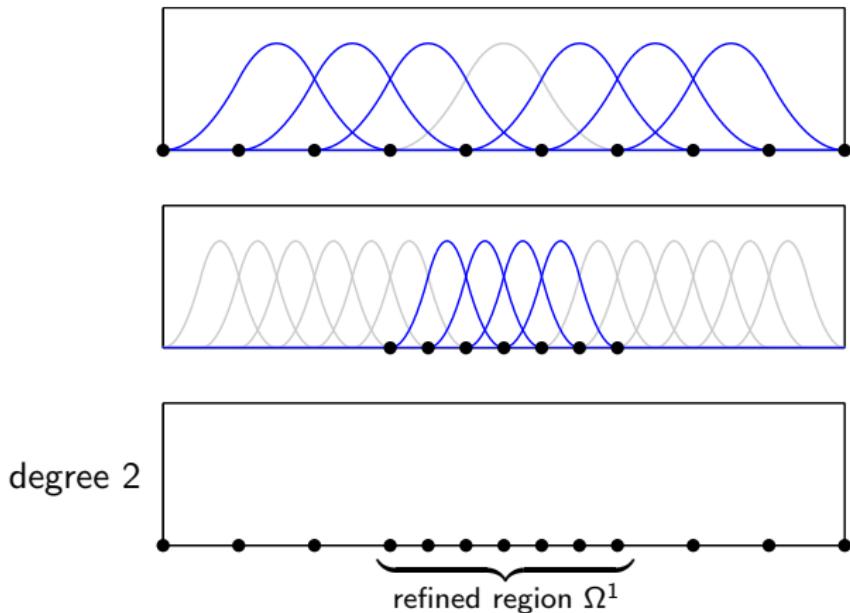
Hierarchical model

THB-splines: 1D example



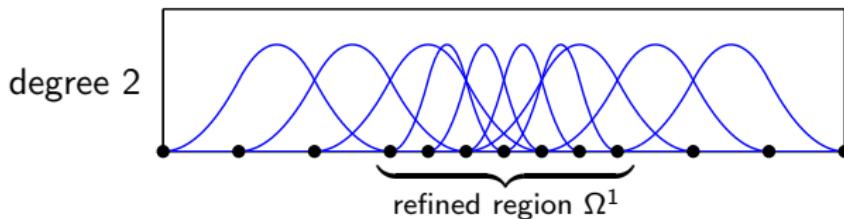
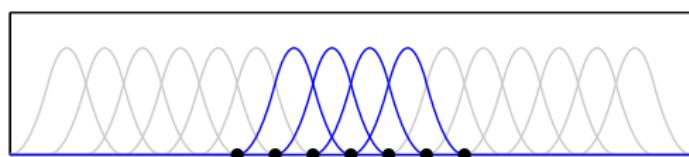
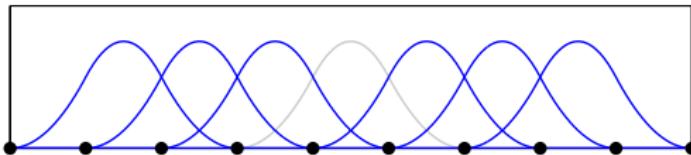
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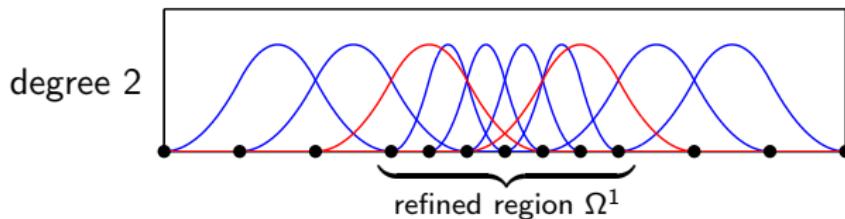
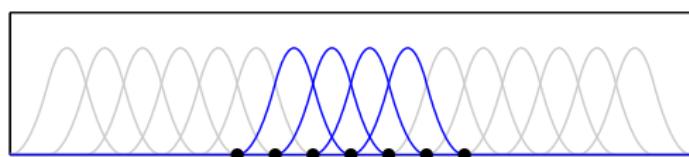
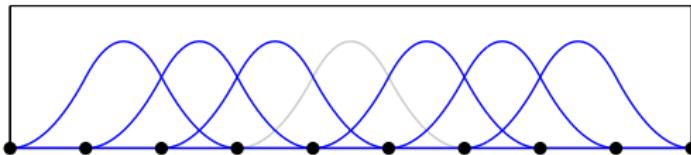
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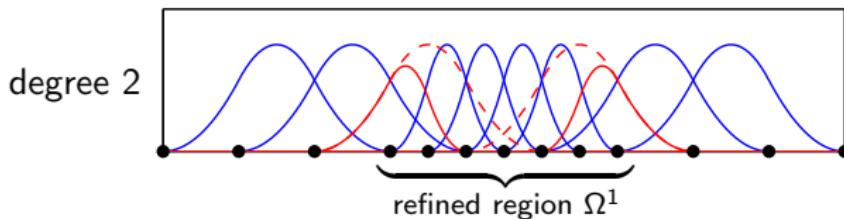
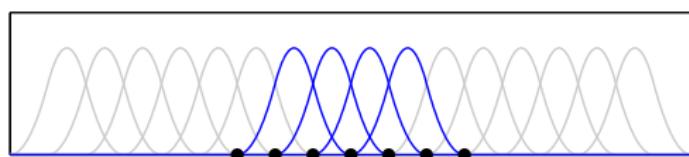
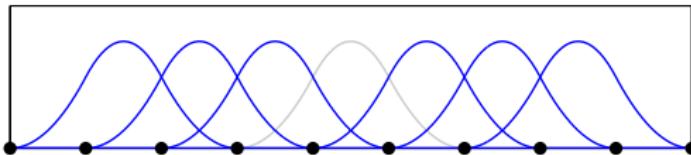
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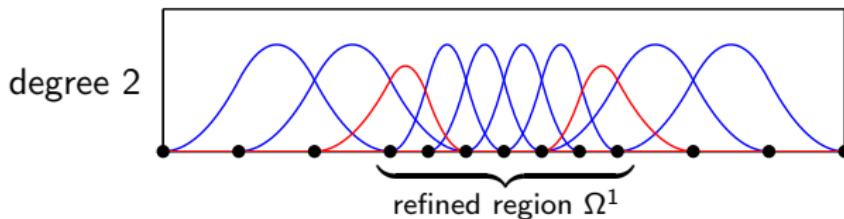
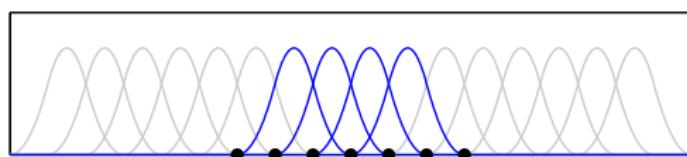
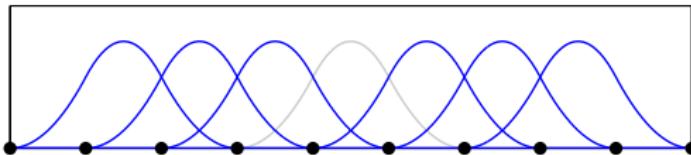
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Truncated basis: properties

Truncated basis: another basis for hierarchical spline space

With respect to classical hierarchical basis:

- (1) THB-splines are **nonnegative** and **linearly independent**
- (2) THB-basis is **strongly L_∞ -stable**:
stability constants independent of # levels
- (3) **reduced support** of coarse basis functions;
reduced overlap of basis supports → sparser systems

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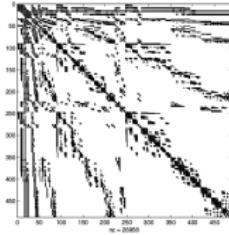
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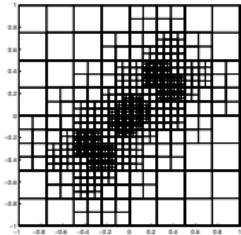
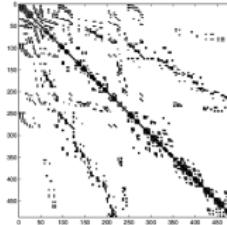
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HB:



THB:



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(4) preservation of coefficients:

let $\mathcal{I}_\ell := \{i : B_{i,\ell} \in \mathcal{B}^\ell \cap \mathcal{H}\}$, let $D^\ell := \Omega^\ell \setminus \Omega^{\ell+1}$, and let

$$f|_{D^\ell} = \sum_{k=0}^{n-1} \sum_{i \in \mathcal{I}_k} c_{i,k}^T B_{i,k}^T|_{D^\ell} = \sum_{j=1}^{N_\ell} c_{j,\ell} B_{j,\ell}|_{D^\ell}, \quad \forall \ell$$

then $c_{i,\ell}^T = c_{i,\ell}$, $i \in \mathcal{I}_\ell$ [Giannelli-Jüttler-Speleers, AiCM 2014]

(5) the truncated basis forms a partition of unity on Ω^0

\Rightarrow convex partition of unity

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Quasi-interpolation

Hierarchical quasi-interpolants [Speleers-Manni, NM 2016]

- ▶ QI based on truncated hierarchical basis
 - ▶ convex partition of unity
 - ▶ small support
 - ▶ preservation of coefficients
- ▶ Consider a sequence of QIs in \mathbb{V}^ℓ , $\ell = 0, \dots, n-1$

$$Q^\ell(f) := \sum_{i=1}^{N_\ell} \lambda_{i,\ell}(f) B_{i,\ell}$$

with

Quasi-interpolation

Hierarchical quasi-interpolants [Speleers-Manni, NM 2016]

- ▶ QI based on truncated hierarchical basis
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 - ▶ small support → local control
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note:

$\lambda_{i,k}$ can have various expressions;
e.g, involve function values,
derivative values, integrals

Quasi-interpolation

Hierarchical quasi-interpolants

► Let $Q^\ell(f) := \sum_{i=1}^{N_\ell} \lambda_{i,\ell}(f) B_{i,\ell}$, $\ell = 0, \dots, n-1$

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► Polynomial reproduction ($\mathbb{P}_d \subset \mathbb{V}^0$):

if $Q^\ell(g) = g$, $\forall g \in \mathbb{P}_d$, $\forall \ell$ then $Q(g) = g$, $\forall g \in \mathbb{P}_d$

► Spline reproduction (projector):

if $\begin{cases} Q^\ell(s) = s, & \forall s \in \mathbb{V}^\ell, \forall \ell \\ \lambda_{i,\ell} \text{ is supported in } \Omega^\ell \setminus \Omega^{\ell+1} \end{cases}$ then $Q(s) = s$, $\forall s \in \mathbb{S}$

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Quasi-interpolation

Hierarchical quasi-interpolants

- Let Υ be a cell, and

$$\Lambda_\Upsilon = \text{conv} \left(\bigcup_{(i,\ell) : \text{supp}^0(B_{i,\ell}^\Upsilon) \cap \Upsilon \neq \emptyset} \Lambda_{i,\ell} \cup \Upsilon \right), \quad \Lambda_{i,\ell} : \text{support of } \lambda_{i,\ell}$$

- Local approximation order** [Speleers, AiCM 2016]:

if $f \in W_q^{p+1}(\Lambda_\Upsilon)$ and $Q(g) = g$, $\forall g \in \mathbb{P}_p$ then

$$\|f - Q(f)\|_{L_q(\Upsilon)} \leq C (\text{diam}(\Lambda_\Upsilon))^{p+1} (1 + C_Q) |f|_{W_q^{p+1}(\Lambda_\Upsilon)}$$

(similar estimates for higher order derivatives of $f - Q(f)$)

Quasi-interpolation

Hierarchical quasi-interpolants

- ▶ Local approximation order: some remarks
 - ▶ Q should be bounded: sufficient in infinity norm (bound C_Q)
 - ✓ each Q^ℓ is bounded separately
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 - ✓ bounded number of THB-splines supported on any cell Υ
⇒ control mesh refinement

not



but



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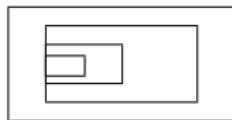


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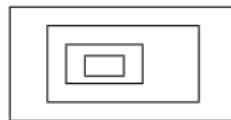
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Quasi-interpolation

Numerical example: setup

- ▶ C^1 quadratic bivariate tensor-product B-splines
- ▶ Building block $\tilde{Q}^\ell(f) := \sum_{i=1}^{N_\ell} \tilde{\lambda}_{i,\ell}(f) B_{i,\ell}$ at level ℓ :
 - ▶ choose a cell $\Upsilon_{i,\ell}$ in support of each $B_{i,\ell}$
 - ▶ choose 3×3 points $x_{j,i,\ell} \in \Upsilon_{i,\ell}$, $j = 1, \dots, 9$
 - ▶ solve the system $\sum_{k: \text{supp}(B_{k,\ell}) \cap \Upsilon_{i,\ell} \neq \emptyset} c_{k,\ell} B_{k,\ell}(x_{j,i,\ell}) = f(x_{j,i,\ell})$
 - ▶ set $\tilde{\lambda}_{i,\ell} = c_{i,\ell}$
- ▶ Set $\tilde{Q}(f) := \sum_{k=0}^{n-1} \sum_{i \in \mathcal{I}_k} \tilde{\lambda}_{i,k}(f) B_{i,k}^T$

Quasi-interpolation

Numerical example: setup

- ▶ C^1 quadratic bivariate tensor-product B-splines
- ▶ Building block $\tilde{Q}^\ell(f) := \sum_{i=1}^{N_\ell} \tilde{\lambda}_{i,\ell}(f) B_{i,\ell}$ at level ℓ :
 - ▶ choose a cell $\Upsilon_{i,\ell}$ in support of each $B_{i,\ell}$
 - ▶ choose 3×3 points $x_{j,i,\ell} \in \Upsilon_{i,\ell}$, $j = 1, \dots, 9$
 - ▶ solve the system $\sum_{k: \text{supp}(B_{k,\ell}) \cap \Upsilon_{i,\ell} \neq \emptyset} c_{k,\ell} B_{k,\ell}(x_{j,i,\ell}) = f(x_{j,i,\ell})$
 - ▶ set $\tilde{\lambda}_{i,\ell} = c_{i,\ell}$
- ▶ Set $\tilde{Q}(f) := \sum_{k=0}^{n-1} \sum_{i \in \mathcal{I}_k} \tilde{\lambda}_{i,k}(f) B_{i,k}^T$

Quasi-interpolation

Numerical example: setup

- ▶ C^1 quadratic bivariate tensor-product B-splines

- ▶ Building block $\tilde{Q}^\ell(f) := \sum_{i=1}^{N_\ell} \tilde{\lambda}_{i,\ell}(f) B_{i,\ell}$ at level ℓ :

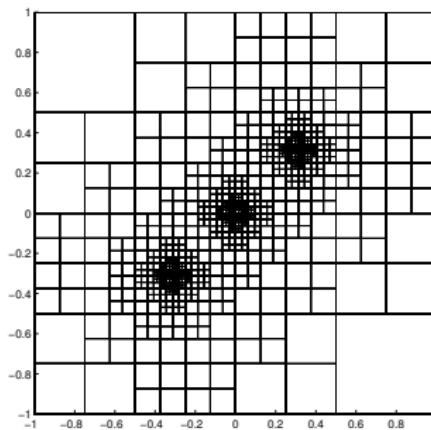
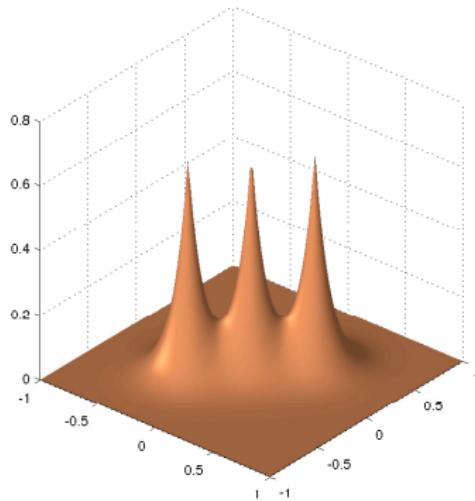
- ▶ choose a cell $\Upsilon_{i,\ell}$ in support of each $B_{i,\ell}$
- ▶ choose 3×3 points $x_{j,i,\ell} \in \Upsilon_{i,\ell}$, $j = 1, \dots, 9$
- ▶ solve the system $\sum_{k: \text{supp}(B_{k,\ell}) \cap \Upsilon_{i,\ell} \neq \emptyset} c_{k,\ell} B_{k,\ell}(x_{j,i,\ell}) = f(x_{j,i,\ell})$
- ▶ set $\tilde{\lambda}_{i,\ell} = c_{i,\ell}$

- ▶ Set $\tilde{Q}(f) := \sum_{k=0}^{n-1} \sum_{i \in \mathcal{I}_k} \tilde{\lambda}_{i,k}(f) B_{i,k}^T$

Quasi-interpolation

Numerical example

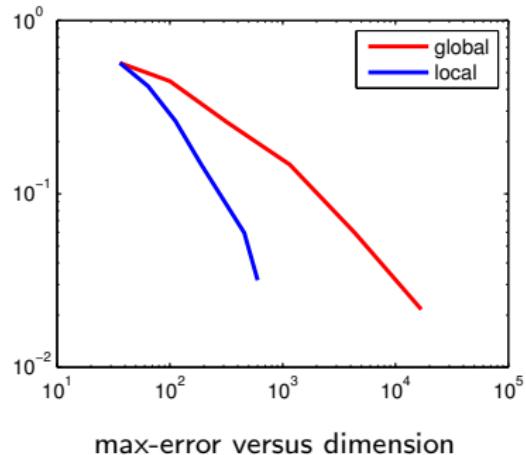
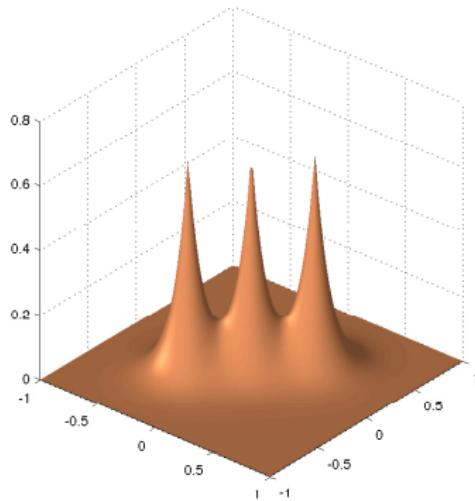
$$f(x, y) = \frac{2}{3 \exp(\sqrt{(10x-3)^2 + (10y-3)^2})} + \frac{2}{3 \exp(\sqrt{(10x+3)^2 + (10y+3)^2})} + \frac{2}{3 \exp(\sqrt{(10x)^2 + (10y)^2})}$$



Quasi-interpolation

Numerical example

$$f(x, y) = \frac{2}{3 \exp(\sqrt{(10x-3)^2 + (10y-3)^2})} + \frac{2}{3 \exp(\sqrt{(10x+3)^2 + (10y+3)^2})} + \frac{2}{3 \exp(\sqrt{(10x)^2 + (10y)^2})}$$



Concluding message

Truncated B-splines

- ▶ the hierarchical model: **local refinement**
- ▶ the **truncation mechanism**:
construction of a basis for a hierarchical space with properties
 - ✓ linear independence
 - ✓ nonnegativity
 - ✓ small support
 - ✓ partition of unity
 - ✓ preservation of coefficients
 - ✓ strong L_∞ -stability
 - ✓ quasi-interpolants
- ▶ **not confined** to tensor-product splines, e.g., also box splines

References

-  C. Giannelli, B. Jüttler and H. Speleers. *THB-splines: The truncated basis for hierarchical splines*. Comput. Aided Geom. Design 29, 485–498. 2012
-  C. Giannelli, B. Jüttler and H. Speleers. *Strongly stable bases for adaptively refined multilevel spline spaces*. Adv. in Comput. Math. 40, 459–490. 2014
-  H. Speleers and C. Manni. *Effortless quasi-interpolation in hierarchical spaces*. Numer. Math. 132, 155–184. 2016
-  H. Speleers. *Hierarchical spline spaces: quasi-interpolants and local approximation estimates*. Adv. in Comput. Math. 2016

Thank you for your attention

Announcement

CIME Summer School

“Splines and PDEs: Recent Advances from Approximation Theory to Structured Numerical Linear Algebra”

Organizers:

Tom Lyche, Carla Manni, Hendrik Speleers

Date:

July 2–8, 2017

Place:

Hotel S. Michele, Cetraro, Italy

