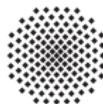


# Non-symmetric kernel-based greedy approximation

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Joint work with Bernard Haasdonk

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## Notation

**Setting:**  $\Omega \subset \mathbb{R}^d$  compact, points  $Y_n := \{y_1, \dots, y_n\} \subset \Omega$ ,  $f(y_1), \dots, f(y_n)$  samples.

- ◆  $K : \Omega \times \Omega \rightarrow \mathbb{R}$  continuous, SPD and sym. kernel (possibly RBF)
- ◆  $s_n(f) := \sum_{j=1}^n \alpha_j K(\cdot, y_j)$  interpolant
- ◆ Interpolation conditions  
 $s_n(f)(y_i) = f(y_i)$
- ◆  $\mathcal{H}(\Omega)$  native space of  $K$  on  $\Omega$  ( $K$  is the reproducing kernel)
- ◆  $V_n := V(Y_n) := \text{span}\{K(\cdot, y), y \in Y_n\}$
- ◆ Interpolation operator  $f \mapsto s_n(f)$ , from  $\mathcal{H}(\Omega)$  to  $V_n$

The vector of coefficients  $c$  exist and it is unique since

$$A = [K(y_i, y_j)]_{i,j=1}^n$$

is SPD.

The interpolation operator is the projection

$$\Pi_{V_n} : \mathcal{H}(\Omega) \rightarrow V_n$$

(best approximation in  $\mathcal{H}(\Omega)$ )

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### Structure

Nested point sets:  $Y_1 \subset Y_2 \subset \dots \subset Y_N$

Nested subspaces:  $V_1 \subset V_2 \subset \dots \subset V_N$

Projections:  $f_1 \quad f_2 \quad \dots \quad f_N$

Use of Newton basis  $v_1, \dots, v_n \leftarrow$  Müller-Sch09

- ◆ nested o.n.b. of  $V_n$
- ◆ easy construction via Gram-Schmidt over kernel basis
- ◆ coefficients from partial Cholesky decomposition of the kernel matrix

Data dependent point-selection rules:

- ◆ [DeM-Sch-Wen05] f-greedy:  $y_i = \arg \max_{y \in Y_N \setminus Y_{i-1}} |f_{i-1}(y)|$
- ◆ [Wirtz-Haas13] f/P-greedy:  $y_i = \arg \max_{y \in Y_N \setminus Y_{i-1}} |f_{i-1}(y)| / |P_{i-1}(y)|$

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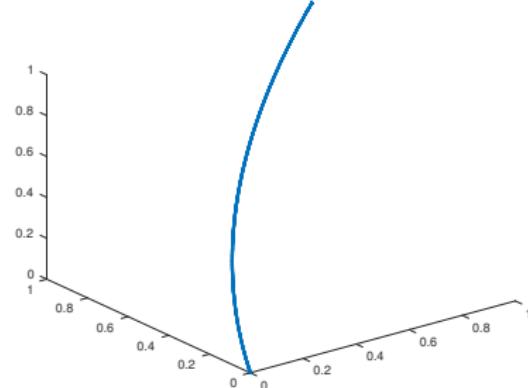
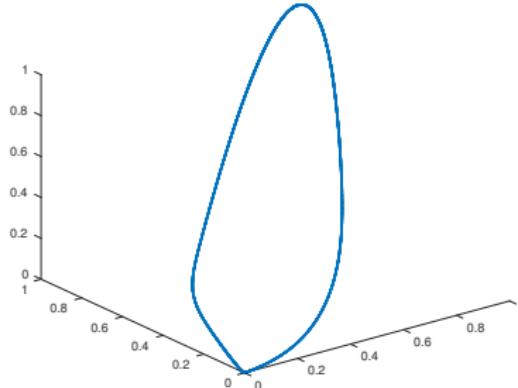
Matrix-valued kernel for  $f : \Omega \rightarrow \mathbb{R}^q$ ,  $q \geq 1$  ([4], [8])

- ◆  $\mathcal{H}_K(\Omega)^q := \{f : \Omega \rightarrow \mathbb{R}^q, f_j \in \mathcal{H}(\Omega)\}$
- ◆  $(f, g)_q := \sum_{j=1}^q (f_j, g_j)$
- ◆ Use the same subspace  $V_n$  over components

### Blood-flow simulation in vascular networks

(with Tobias Köppl, Dep. Hydromechanics and Modelling of Hydrosystems)

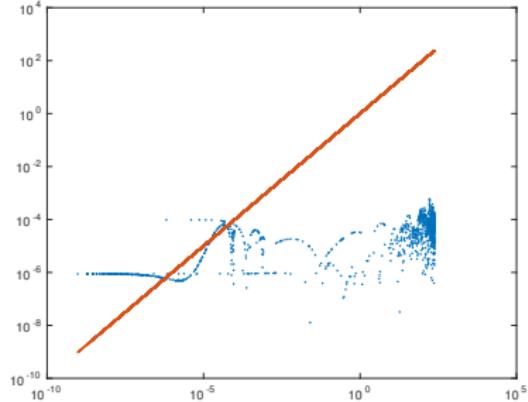
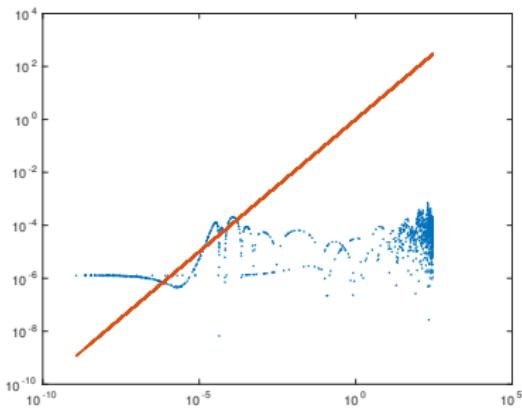
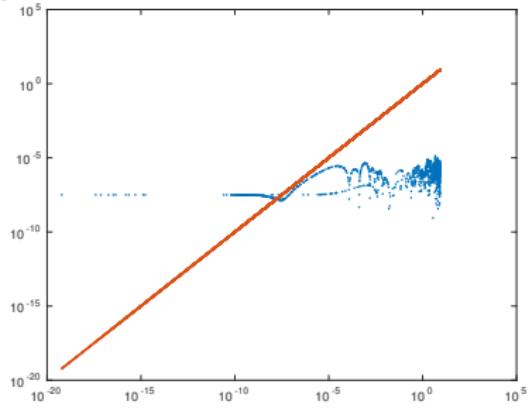
- ◆ 1D - transport eqs.
- ◆ Newton solver for bifurcations
- ◆ Sampling of characteristic curves
- ◆ Surrogate kernel model of the bifurcations
- ◆  $\mathbb{R}^3 \rightarrow \mathbb{R}^3$  model (possibly  $\mathbb{R}^q \rightarrow \mathbb{R}^q$ )



Non-sym kernel

## Notation, motivations and setting

Motivation I



- ◆  $M = 12742$  samples
- ◆  $n = 70$  selected centers
- ◆ issues for small data

## Outline

1. General definition of non-symmetric problem.
2. Some preliminary theoretical result.
3. Construction of approximants.
4. Construction of greedy approximants.
5. Numerical results.

# Characterization

Setting

- ◆ Functionals  $\{\lambda_i\}_{i=1}^M, \{\mu_j\}_{j=1}^N \subset \mathcal{H}(\Omega)^*$  ( $M \leq N$ , each set is lin. indep.)
- ◆ Test and trial spaces

$$V_M := \{\lambda_i^y K(\cdot, y), i = 1, \dots, M\}, \quad U_N := \{\mu_j^x K(x, \cdot), j = 1, \dots, N\},$$

- ◆ Kernel matrix  $(A_{MN})_{ij} := (\lambda_i^y K(\cdot, y), \mu_j^x K(x, \cdot))_{\mathcal{H}(\Omega)^*} = \lambda_i^y \mu_j^x K(x, y)$

**Goals (Given  $f \in \mathcal{H}(\Omega)$  and  $n \leq M$ )**

- ◆ determine subspaces  $V_n \subset V_M, U_n \subset U_N$ , such that

$$s_n(f) := \sum_{j=1}^n \alpha_j u_j, \quad (s_n(f), v_i) = (f, v_i), \quad 1 \leq i \leq n$$

(bases  $\{u_j\}_{j=1}^n$  of  $U_n$  and  $\{v_i\}_{i=1}^n$  of  $V_n$ )

- ◆ Solve

$$A_n \alpha = b$$

$A_n \in \mathbb{R}^{n \times n}$ ,  $(A_n)_{ij} := (v_i, u_j)$   $b \in \mathbb{R}^n$ ,  $b_i := (f, v_i)$  vector of data.

Examples: non-sym interp., non-sym coll. ... (other functs? multiscale interp.?)

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## Principal angles

Let  $\gamma_1, \dots, \gamma_N$  be the cosines of the principal angles between the  $V_M$ ,  $U_N$ . For  $M + 1 \leq n \leq N$ , we set  $\gamma_n := 0$ . Denote by  $\{\psi_i\}_i$ ,  $\{\varphi_j\}_j$  a pair of principal bases.

## Characterization and existence

Given  $n \leq M$ , there exist subspaces  $V_n \subset V_M$ ,  $U_n \subset U_N$  such that the approximation problem with test space  $V_n$  and trial space  $U_n$  has a unique solution, if and only if  $\gamma_n > 0$ .

In this case, given any pair of such subspaces, the operator  $s_n : \mathcal{H}(\Omega) \rightarrow U_n$  is a **projection** with  $\ker(s_n) = V_n^\perp$ , and norm

$$\|s_n\| := \sup_{f \in \mathcal{H}(\Omega)} \frac{\|s_n(f)\|}{\|f\|} = \frac{1}{\gamma_n(V_n, U_n)}.$$

In particular, it is an orthogonal projection if and only if  $V_n = U_n$ . Moreover, there exist such subspaces that are spanned by  $n$  elements of the original bases of  $V_M$  and  $U_N$ .

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$$P_n(\lambda) := \sup_{f \in \mathcal{H}(\Omega), \|f\| \leq 1} \lambda(f - s_n(f)), \quad \lambda \in \mathcal{H}(\Omega)^*$$

**Power Function use:**

$$|\lambda(f - s_n)| \leq P_n(\lambda) \|f\| \text{ for all } \lambda \in \mathcal{H}(\Omega)^* \quad \text{and } P_n(\lambda) = 0 \text{ iff } \lambda \in V_n^*.$$

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# Characterization

Error analysis

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Now fixed  $V_n$ ,  $U_n$ ,  $A_n$ .

$$v_i := \sum_{k=1}^n \textcolor{red}{c}_{ki} \lambda_k^y K(y, \cdot), \quad u_j := \sum_{h=1}^n \textcolor{green}{d}_{hj} \mu_h^x K(\cdot, x).$$

$$(\mathcal{C}_v)_{ij} := c_{ij}, \quad (\mathcal{C}_u)_{ij} := d_{ij}$$

$$(V_v)_{ij} := (\mu_i^x K(x, \cdot), v_j) = \mu_i(v_j), \quad (V_u)_{ij} := (\lambda_i^y K(\cdot, y), u_j) = \lambda_i(u_j).$$

### Bases from matrix factorization

Any basis  $\{u_j\}_{j=1}^n$  of  $U_n$  is uniquely defined by the matrix of coefficients  $\mathcal{C}_u$  or by the matrix of evaluations  $V_u$ , and in particular

$$A_n = V_u \mathcal{C}_u^{-1}. \quad (1)$$

The same holds for any basis  $\{v_j\}_{j=1}^n$  of  $V_n$ , with instead  $A_n^T = V_v \mathcal{C}_v^{-1}$ .

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**Def: biorthonormal bases**

Bases  $\{v_j\}_{j=1}^n$  of  $V_n$  and  $\{u_j\}_{j=1}^n$  of  $U_n$  are biorthonormal (or dual) if

$$(v_i, u_j) = \delta_{ij}, \quad 1 \leq i, j \leq n.$$

**Bi-o.n. bases from matrix factorization**

Bases  $\{v_j\}_{j=1}^n$  and  $\{u_j\}_{j=1}^n$  are biorthonormal if and only if

$$A_n = C_v^{-T} C_u^{-1}. \quad (2)$$

Moreover,

$$C_u = V_u^{-T}, \quad C_v = V_v^{-T}. \quad (3)$$

and in particular for any basis of  $U_n$  there exists a unique dual basis of  $V_n$ .

**Def: biorthonormal bases**

Bases  $\{v_j\}_{j=1}^n$  of  $V_n$  and  $\{u_j\}_{j=1}^n$  of  $U_n$  are biorthonormal (or dual) if

$$(v_i, u_j) = \delta_{ij}, \quad 1 \leq i, j \leq n.$$

**Bi-o.n. bases from matrix factorization**

Bases  $\{v_j\}_{j=1}^n$  and  $\{u_j\}_{j=1}^n$  are biorthonormal if and only if

$$A_n = C_v^{-T} C_u^{-1}. \quad (2)$$

Moreover,

$$C_u = V_u^{-T}, \quad C_v = V_v^{-T}. \quad (3)$$

and in particular for any basis of  $U_n$  there exists a unique dual basis of  $V_n$ .

## Approximation and Power Function

Given a basis  $\{u_j\}_{j=1}^n$  of  $U_n$ , and  $f \in \mathcal{H}(\Omega)$

$$s_n(f) = \sum_{j=1}^n (f, v_j) u_j,$$

where  $\{v_j\}_{j=1}^n$  is the unique basis of  $V_n$  which is dual to  $\{u_j\}_{j=1}^n$ .

For any  $\lambda \in \mathcal{H}(\Omega)^*$ ,

$$P_n(\lambda)^2 = \lambda^x \lambda^y K(x, y) - \sum_{j=1}^n \lambda(u_j) \lambda(2v_j - s_n(v_j)).$$

# Greedy algorithms

Setting

- ◆ Incrementally selected indexes

$$I_n := \{i_1, \dots, i_n\} \subset I_M := \{1, \dots, M\}, \quad J_n := \{j_1, \dots, j_n\} \subset J_N := \{1, \dots, N\}$$

- ◆ Basis elements

$$\lambda_{i_1}^y K(\cdot, y), \dots, \lambda_{i_n}^y K(\cdot, y) \text{ and } \mu_{j_1}^x K(\cdot, x), \dots, \mu_{j_n}^x K(\cdot, x)$$

- ◆ Nested subspaces

$$V_1 \subset V_2 \subset \dots \subset V_n \subset V_M \text{ and } U_1 \subset U_2 \subset \dots \subset U_n \subset U_N,$$

Goals:

- ◆ Nested, bi-o.n.bases

$$U_{k-1} = \text{span } \{u_1, \dots, u_{k-1}\}, \quad U_k = \text{span } \{u_1, \dots, u_k\}$$

and similarly for  $V_n$ .

- ◆ Check solvability in a cheap way ( $\gamma_n > 0$  is not enough)

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### Generalized Newton Bases

A basis  $\{u_j\}_j$  of  $U_n$  is nested if and only if  $C_u$  is upper triangular. A basis  $\{u_j\}_j$  and its dual basis  $\{v_i\}_i$  are both nested bases if and only if

$$C_v = L^{-T}, \quad C_u = U^{-1},$$

or equivalently

$$V_v = U^T, \quad V_u = L,$$

where  $L, U$  are lower- and upper-triangular matrices, without constraints on the diagonals and such that

$$A_n = L \ U$$

is a LU-decomposition of the matrix  $A_n$ , which corresponds to a partial LU-decomposition of the full matrix  $A_{MN}$  after rearrangement of columns and rows.

Use rediduals

$$r_0 := f, \quad r_{n-1} = (r_{n-1}, v_n)u_n + r_n, \quad n \geq 1.$$

### Incremental approximation with gen. Newton bases

We have  $r_n \in V_n^\perp$  and

$$s_n(f) = \sum_{k=1}^n (r_{k-1}, v_n)u_n = \sum_{k=1}^n \lambda_{i_n}(r_{k-1})u_n,$$

and in particular

$$s_n(f) = s_{n-1}(f) + (r_{n-1}, v_n)u_n.$$

For the Power Function:

$$P_n(\lambda)^2 - P_{n-1}(\lambda)^2 = \|v_n\|^2 \lambda(u_n)^2 - 2\lambda(u_n)\lambda(v_n - s_{n-1}(v_n)).$$

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# Greedy algorithms

Remarks on implementation

Matrix free and cheap rank check:

- ◆ Compute  $v_n$ :

$$v_n := \lambda_{i_n}^y K(\cdot, y) - \sum_{k=1}^{n-1} (\lambda_{i_n}^y K(\cdot, y), u_k) v_k = \lambda_{i_n}^y K(\cdot, y) - \sum_{k=1}^{n-1} \lambda_{i_n}(u_k) v_k$$

- ◆ Candidate  $u_n$ :

$$\tilde{u}_n := \mu_{j_n}^x K(\cdot, x) - \sum_{k=1}^{n-1} (\mu_{j_n}^x K(\cdot, x), v_k) u_k = \mu_{j_n}^x K(\cdot, x) - \sum_{k=1}^{n-1} \mu_{j_n}(v_k) u_k$$

- ◆ Check solvability:

$$(v_n, \tilde{u}_n) = \lambda_{i_n}^y \mu_{j_n}^x K(y, x) - \sum_{k=1}^{n-1} \mu_{j_n}(v_k) \lambda_{i_n}(u_k) = \mu_{j_n}(v_n)$$

- ◆ If so, normalize:

$$u_n := \tilde{u}_n / (v_n, \tilde{u}_n)$$

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- ◆  $f$  - greedy with rank maximization  
(minimize residual, maximize spaces extension)

$$i_n := \arg \max_{i \in I_M \setminus I_{n-1}} |\lambda_i(r_{n-1})|$$

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$$\begin{cases} V_u c = b \\ V_v d = -V_v^T c \end{cases}$$

(comes from [3] - regularized solution of under-determined system)

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# Numerical experiments

## Example I

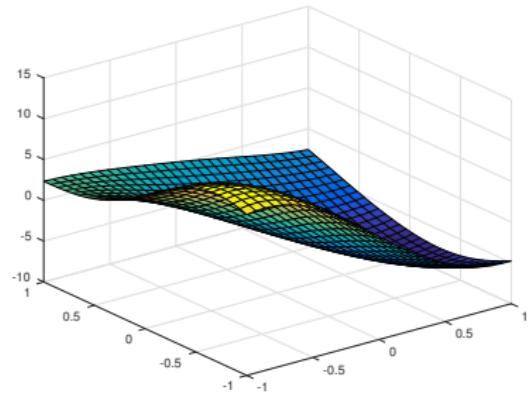
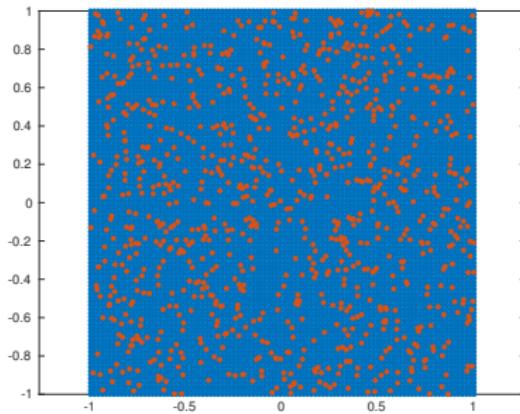


Figure: Gaussian Kernel with  $\epsilon = 1$ ,  $f \in \mathcal{H}(\Omega)$ ,  $\Omega = [-1, 1]^2$ .

# Numerical experiments

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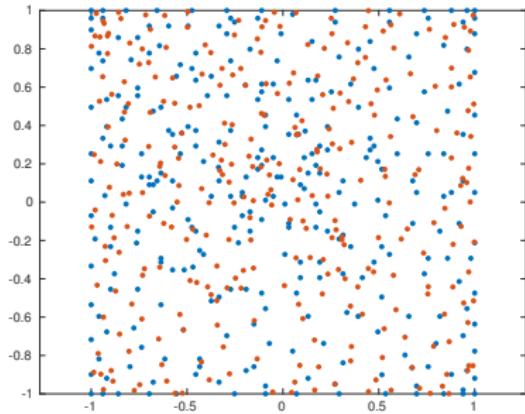
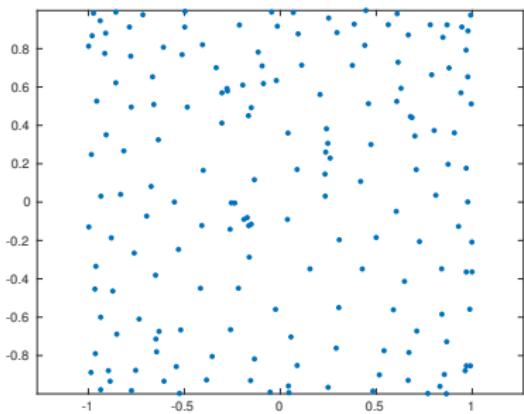


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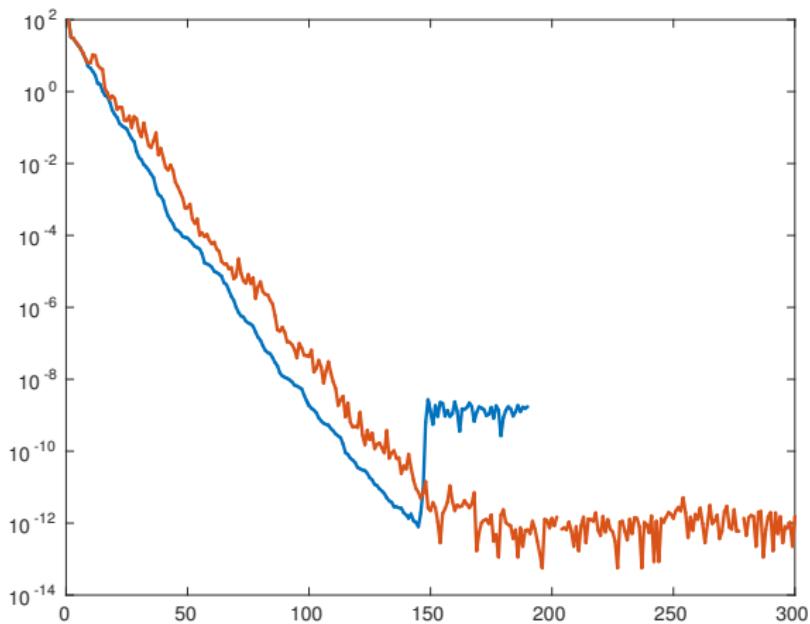


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# Numerical experiments

## Example II

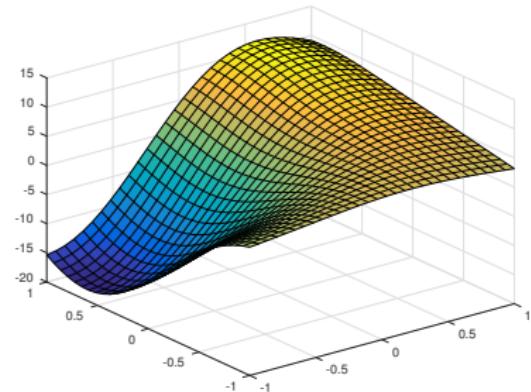
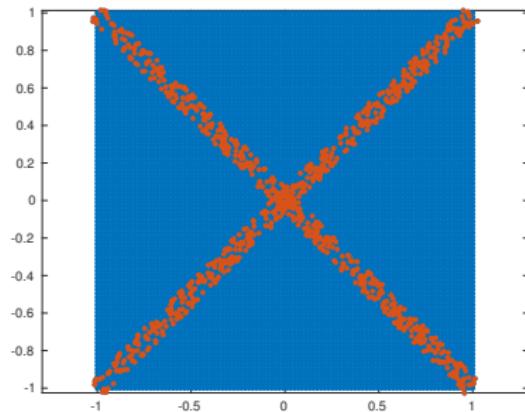


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# Numerical experiments

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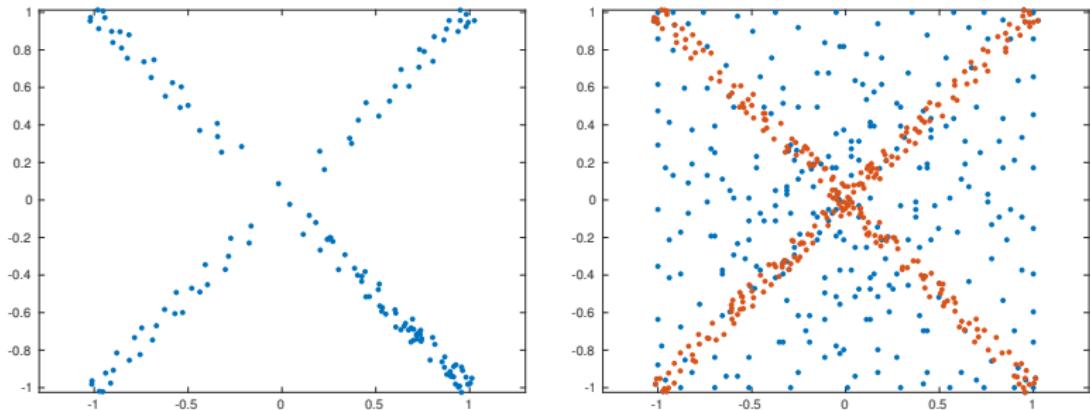


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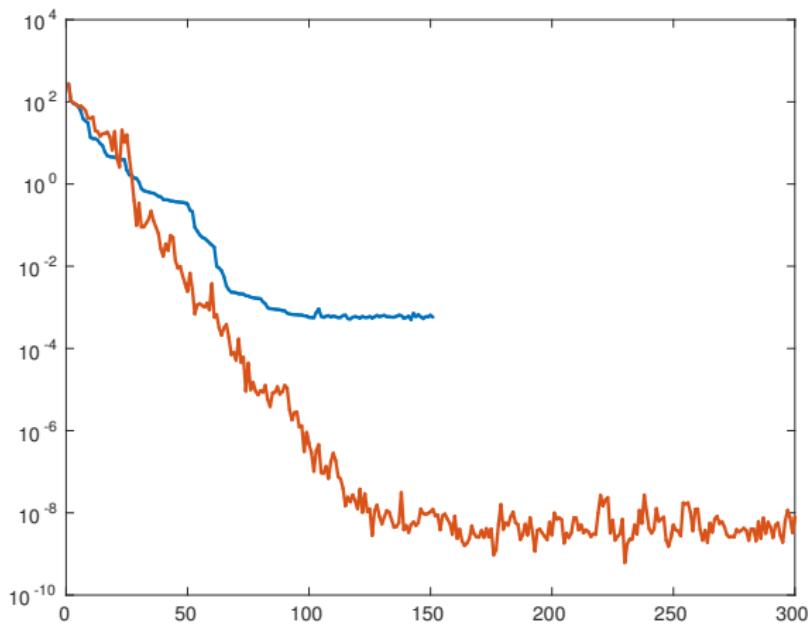
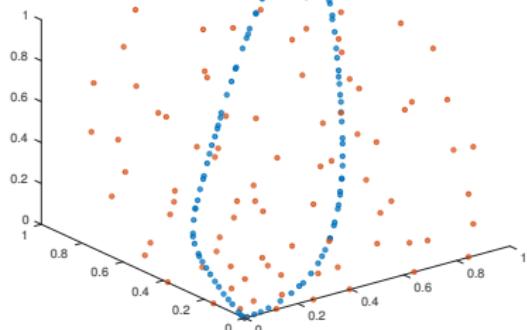
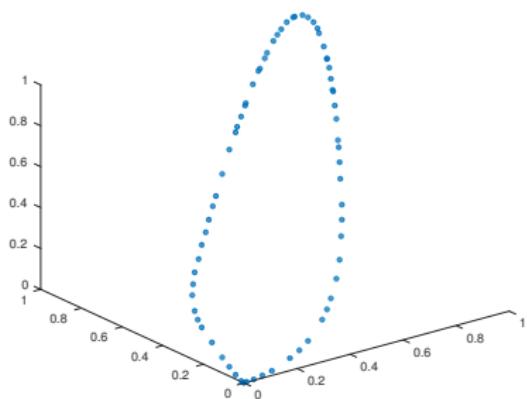


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# Numerical experiments

## Example III

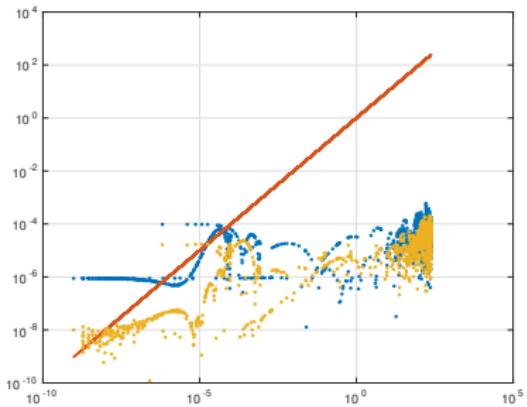
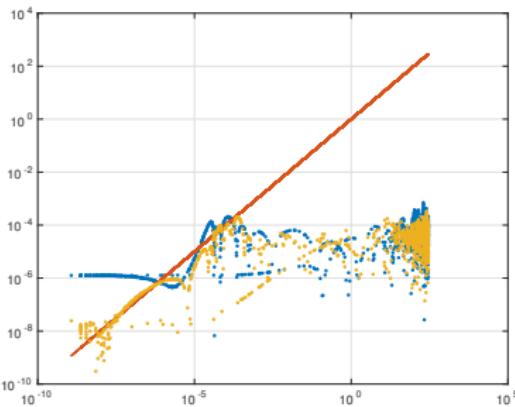
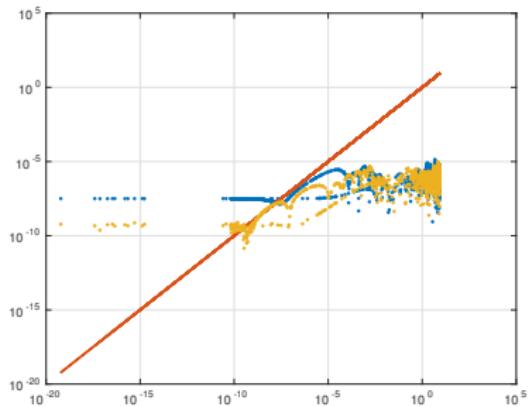


- ◆  $M = 12742$  samples
- ◆  $N = 200000$  points on a uniform grid
- ◆ Random permutation of data:  
80% train, 10% val., 10% test  
(is this restrictive?)

- ◆  $\varepsilon \in [0.1, 4]$ , validate on val. set
- ◆ Sym:  $n = 70$  selected samples/centers
- ◆ Non-Sym:  $n = 102$  selected samples and centers

# Numerical experiments

## Example III



Thank you!

- [1] S. De Marchi, R. Schaback, and H. Wendland. "Near-optimal data-independent point locations for radial basis function interpolation". *Adv. Comput. Math.* 23.3 (2005), pp. 317–330.
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