

# Asymptotics of infinite systems of ODEs

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**Frontiers of Operator Dynamics**

Luminy, 28 Sept – 2 Oct 2015

# Overview

- 1 Motivating examples
- 2 General results
- 3 Examples revisited

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1 Motivating examples

2 General results

3 Examples revisited

## Example 1: The 'robot rendezvous problem'

Consider countably many robots at positions  $x_k(t) \in \mathbb{C}$ , where  $t \geq 0$  and  $k \in \mathbb{Z}$ . Aim for mutual 'rendezvous' by setting  $\dot{x}_k(t) = u_k(t)$ , where

$$u_k(t) = x_{k-1}(t) - x_k(t).$$

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Cauchy problem:

$$\begin{cases} \dot{x}(t) = Ax(t), & t \geq 0, \\ x(0) = x_0 \in X, \end{cases} \quad (\text{CP-Rob})$$

where  $x(t) = (x_k(t))_{k \in \mathbb{Z}}$ ,  $A = S - I$  for  $S =$  right-shift on  $X = \ell^p(\mathbb{Z})$ ,  $1 \leq p \leq \infty$ .

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### Theorem (Feintuch, Francis '12)

*For  $p = \infty$  the solution  $x(t)$ ,  $t \geq 0$ , of (CP-Rob) need not converge to a limit as  $t \rightarrow \infty$ , but we always have  $\dot{x}(t) \rightarrow 0$ .*

## Example 2: The platoon system

Consider a more realistic model in which vehicle  $k \in \mathbb{Z}$  at time  $t \geq 0$  has position  $s_k(t)$ , velocity  $v_k(t)$  and acceleration  $a_k(t)$ .

Aim to steer vehicle  $k$  towards *target separation*  $q_k$  from vehicle  $k - 1$  and have all vehicles moving at *target velocity*  $v$ , by controlling its acceleration:  $\dot{a}_k(t) = u_k(t)$ .

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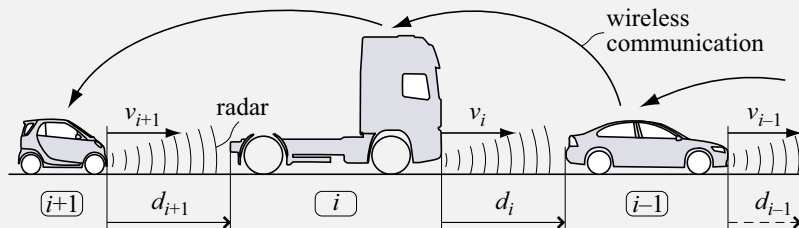
The state vector of vehicle  $k$  is

$$x_k(t) = \begin{pmatrix} y_k(t) \\ w_k(t) \\ a_k(t) \end{pmatrix} = \begin{pmatrix} q_k - d_k(t) \\ v_k(t) - v \\ a_k(t) \end{pmatrix},$$

where  $d_k(t) = s_{k-1}(t) - s_k(t)$ .



# A picture



Taken from Ploeg, van de Wouw, Nijmeijer '14

# Equations of motion

We choose the 'state feedback control'

$$u_k(t) = -\alpha_0 y_k(t) - \alpha_1 w_k(t) - \alpha_2 a_k(t).$$

Then

$$\dot{x}_k(t) = \begin{pmatrix} w_k(t) - w_{k-1}(t) \\ a_k(t) \\ u_k(t) \end{pmatrix} = A_0 x_k(t) + A_1 x_{k-1}(t),$$

where

$$A_0 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{pmatrix} \quad A_1 = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

# The Cauchy problem

Letting  $x(t) = (x_k(t))_{k \in \mathbb{Z}}$  we write this as

$$\begin{cases} \dot{x}(t) = Ax(t), & t \geq 0, \\ x(0) = x_0 \in X, \end{cases} \quad \text{(CP-Plat)}$$

where  $X = \ell^p(\mathbb{Z}; \mathbb{C}^3)$ ,  $1 \leq p \leq \infty$ , and

$$A = \begin{pmatrix} \ddots & & & & & & & & & \\ & \ddots & & & & & & & & \\ & & \ddots & & & & & & & \\ & & & A_0 & & & & & & \\ & & & A_1 & A_0 & & & & & \\ & & & & A_1 & A_0 & & & & \\ & & & & & \ddots & & \ddots & & \\ & & & & & & \ddots & & \ddots & \end{pmatrix}.$$

# Asymptotics of the platoon system

## Theorem (Zwart?)

*For  $p = 2$  and suitable choices of  $\alpha_0, \alpha_1, \alpha_2 \in \mathbb{C}$  we get  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$  for all  $x_0 \in X$ .*

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## Questions

- Do solutions converge for  $p \neq 2$ ?
- If not for all  $x_0$  then for which ones?
- When we have convergence, is there a rate?
- Is it still true that  $\dot{x}(t) \rightarrow 0$  as  $t \rightarrow \infty$ ?
- If so, how fast?

# The general Cauchy problem

We consider the more general problem

$$\begin{cases} \dot{x}(t) = Ax(t), & t \geq 0, \\ x(0) = x_0 \in X, \end{cases} \quad (\text{CP})$$

where  $X = \ell^p(\mathbb{Z}; \mathbb{C}^m)$  with  $1 \leq p \leq \infty$ ,  $m \in \mathbb{N}$  and where

$$A = \begin{pmatrix} \ddots & & & & & & \\ & \ddots & & & & & \\ & & A_0 & & & & \\ & & A_1 & A_0 & & & \\ & & & A_1 & A_0 & & \\ & & & & \ddots & \ddots & \\ & & & & & \ddots & \ddots \end{pmatrix}$$

for suitable matrices  $A_0, A_1 \in \mathbb{C}^{m \times m}$ .

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# The semigroup approach

Observe that the solution of (CP) is given, for  $t \geq 0$ , by

$$x(t) = T(t)x_0,$$

where

$$T(t) = \exp(tA) = \sum_{k=0}^{\infty} \frac{t^k}{k!} A^k.$$

In particular,

$$\dot{x}(t) = AT(t)x_0 = T(t)Ax_0.$$

## Objective

To understand the asymptotic behaviour of solutions to (CP) by studying the semigroup  $T$  and its generator  $A$ .



# An abstract result

**Notation:** For  $\lambda \notin \sigma(A)$ , we let  $R(\lambda, A) = (\lambda - A)^{-1}$ .

Theorem (Batty, Chill, Tomilov '14; Chill, S '15)

Let  $T$  be a bounded semigroup whose generator  $A \in \mathcal{B}(X)$  satisfies  $\sigma(A) \cap i\mathbb{R} = \{0\}$ . Suppose further that

$$\|R(is, A)\| = O(|s|^{-\alpha}), \quad s \rightarrow 0,$$

for some  $\alpha \geq 1$ . Then

$$\|AT(t)\| = O\left(\left(\frac{\log t}{t}\right)^{1/\alpha}\right), \quad t \rightarrow \infty.$$

If  $X$  is a Hilbert space, the logarithmic term can be dropped.

## Two assumptions

### Assumption (A1)

We have  $A_1 \neq 0$ .

### Assumption (A2)

There exists a function  $\phi$  such that

$$A_1 R(\lambda, A_0) A_1 = \phi(\lambda) A_1, \quad \lambda \notin \sigma(A_0).$$

We call  $\phi$  the *characteristic function*.

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We call  $\phi$  the *characteristic function*.

- holds automatically if  $\text{rank } A_1 = 1$
- $\phi$  is rational with poles contained in  $\sigma(A_0)$
- $|\phi(\lambda)| \rightarrow 0$  as  $|\lambda| \rightarrow \infty$

# The spectrum of $A$

Theorem (Paunonen, S '15)

Let  $1 \leq p \leq \infty$  and  $m \in \mathbb{N}$ , and suppose that (A1), (A2) hold. Let

$$\Omega_\phi = \{\lambda \in \mathbb{C} \setminus \sigma(A_0) : |\phi(\lambda)| = 1\}.$$

Then  $\Omega_\phi = \sigma(A) \setminus \sigma(A_0)$  and given  $\lambda \in \Omega_\phi$  we have

- $\lambda \in \sigma_p(A)$  if and only if  $p = \infty$ ,
- $\lambda \in \sigma_r(A)$  if and only if  $p = 1$  or  $p = \infty$ .

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Also know that

- if  $p = \infty$  and  $\lambda \in \Omega_\phi$  then  $\dim \text{Ker}(\lambda - A) = \text{rank } A_1$
- points in  $\sigma(A_0)$  can lie inside or outside  $\sigma(A)$

# Growth of the resolvent

Theorem (Paunonen, S '15)

Let  $1 \leq p \leq \infty$  and  $m \in \mathbb{N}$ , and suppose that (A1), (A2) hold. If  $\mu \in \Omega_\phi$  then

$$\|R(\lambda, A)\| \asymp \frac{1}{|1 - |\phi(\lambda)||}$$

as  $\lambda \rightarrow \mu$  with  $\lambda \notin \sigma(A)$ .

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## Assumption (A3)

We have  $\sigma(A_0) \subset \mathbb{C}_- = \{\lambda \in \mathbb{C} : \operatorname{Re} \lambda < 0\}$ .

## Assumption (A4)

We have  $0 \in \Omega_\phi \subset \mathbb{C}_- \cup \{0\}$  and  $\phi'(0) \neq 0$ .

# A sufficient condition for boundedness

## Theorem (Paunonen, S '15)

Let  $1 \leq p \leq \infty$  and  $m \in \mathbb{N}$ , and suppose that (A1)–(A4) hold. Let  $Q = \{\lambda \in \mathbb{C} : 0 < \operatorname{Re} \lambda \leq 1, |\operatorname{Im} \lambda| \leq \|A\| + 1\}$ . The semigroup  $T$  generated by  $A$  is bounded provided

$$\sup_{\lambda \in Q} \sup_{k \geq 0} \frac{(\operatorname{Re} \lambda)^{k+1}}{k!} \sum_{j=0}^{\infty} |D^k \phi(\lambda)^j| < \infty. \quad (*)$$



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## Assumption (A5)

The function  $\phi$  satisfies (\*).

# Towards an asymptotic result

Would like to characterise the set

$$C = \left\{ x_0 \in X : \lim_{t \rightarrow \infty} x(t) \text{ exists} \right\},$$

where  $x(t)$ ,  $t \geq 0$ , is the solution of (CP) with initial data  $x_0$ .

Also hope to describe the limit when  $x_0 \in C$ , to show that  $\dot{x}(t) \rightarrow 0$  for all  $x_0 \in X$ , and obtain rates where possible.

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**Note:** From (A1)–(A4) we have  $\sigma(A) \cap i\mathbb{R} = \{0\}$  and

$$\|R(is, A)\| \asymp |s|^{-n}, \quad s \rightarrow 0,$$

for some  $n = n_\phi \in 2\mathbb{N}$ .

# Convergence of solutions

Let  $1 \leq p \leq \infty$ ,  $m \in \mathbb{N}$  and suppose that (A1)–(A5) hold.

**Notation:** Let  $M \in \mathcal{B}(X)$  be given by  $M(x_k) = (A_1 A_0^{-1} x_k)$ .

Theorem (Paunonen, S '15)

Given  $x_0 \in X$  we have  $x_0 \in C$  if and only if

$$\left\| \frac{1}{n} \sum_{k=1}^n \phi(0)^k S^k M x_0 - y \right\| \rightarrow 0, \quad n \rightarrow \infty, \quad (\diamond)$$

for some  $y = (\phi(0)^k y_0)$  with  $y_0 \in \text{Ran } A_1$ .

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for some  $y = (\phi(0)^k y_0)$  with  $y_0 \in \text{Ran } A_1$ . Moreover, there exists a matrix  $L$  such that if  $(\diamond)$  holds, then for  $z = (\phi(0)^k L y_0)$  we have

$$\|x(t) - z\| \rightarrow 0, \quad t \rightarrow \infty.$$

In particular,  $C = X$  if and only if  $1 < p < \infty$ .

# Rates of convergence

## Theorem (Paunonen, S '15)

If  $x_0 \in C$  and the convergence in  $(\diamond)$  is like  $O(n^{-1})$  as  $n \rightarrow \infty$ , then

$$\|x(t) - z\| = O\left(\left(\frac{\log t}{t}\right)^{1/n_\phi}\right), \quad t \rightarrow \infty.$$

Moreover, for all  $x_0 \in X$  we have

$$\|\dot{x}(t)\| = O\left(\left(\frac{\log t}{t}\right)^{1/n_\phi}\right), \quad t \rightarrow \infty.$$

In both cases the logarithm can be dropped if  $p = 2$ .

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# The robot rendezvous problem

Here  $m = 1$ ,  $A_0 = -1$  and  $A_1 = 1$ . So (A1)–(A5) hold with

$$\phi(\lambda) = \frac{1}{\lambda + 1} \quad \text{and} \quad n_\phi = 2.$$



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## Corollary (Paunonen, S '15)

Let  $1 \leq p \leq \infty$ . Given  $x_0 \in X$  we have  $x_0 \in C$  if and only if

$$\left\| \frac{1}{n} \sum_{k=1}^n S^k x_0 - y \right\| \rightarrow 0, \quad n \rightarrow \infty, \quad (\#)$$

for some constant sequence  $y \in X$ . If  $(\#)$  holds then  $x(t) \rightarrow y$ .

In particular,  $C = X$  if and only if  $1 < p < \infty$ .

# Rates of convergence

Proposition (Paunonen, S '15)

Let  $1 \leq p \leq \infty$ . If  $x_0 \in C$  and

$$\left\| \frac{1}{n} \sum_{k=1}^n S^k x_0 - y \right\| = O(n^{-1}), \quad n \rightarrow \infty,$$

then

$$\|x(t) - y\| = O(t^{-1/2}), \quad t \rightarrow \infty.$$

Moreover, for all  $x_0 \in X$  we have

$$\|\dot{x}(t)\| = O(t^{-1/2}), \quad t \rightarrow \infty.$$

# The platoon model

Now  $m = 3$  and

$$A_0 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{pmatrix} \quad A_1 = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

So (A1), (A2) hold with

$$\phi(\lambda) = \frac{\alpha_0}{p(\lambda)},$$

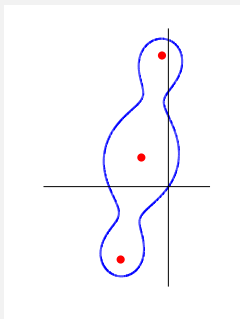
where

$$p(\lambda) = \lambda^3 + \alpha_2\lambda^2 + \alpha_1\lambda + \alpha_0$$

is the characteristic polynomial of  $A_0$ .

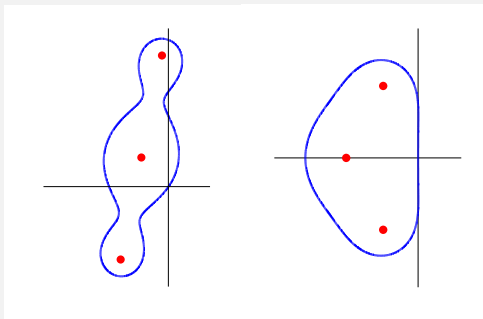
# Placing the poles

Possible choices of  $\sigma(A_0)$  and the resulting  $\Omega_\phi$ :



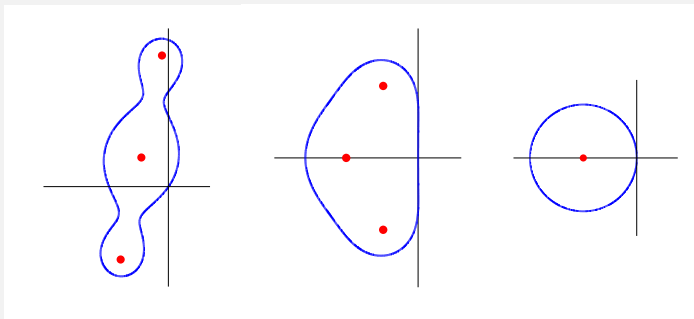
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Choose  $\alpha_0 = 1$ ,  $\alpha_1 = \alpha_2 = 3$ , so that  $p(\lambda) = (\lambda + 1)^3$ .

Then (A1)–(A5) hold and  $n_\phi = 2$ .

# Convergence of solutions

## Corollary (Paunonen, S '15)

Let  $1 \leq p \leq \infty$  and let  $\alpha_0, \alpha_1, \alpha_2$  be as above. Given  $x_0 \in X$  we have  $x_0 \in C$  if and only if there exists  $y \in \ell^p(\mathbb{Z})$  such that

$$\left\| \frac{1}{n} \sum_{k=1}^n S^k y_0 - y \right\|_{\ell^p(\mathbb{Z})} \rightarrow 0, \quad n \rightarrow \infty, \quad (\dagger)$$

where  $y_0$  is the vector of initial deviations.

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where  $y_0$  is the vector of initial deviations. If  $(\dagger)$  holds then  $y = (\dots, c, c, c, \dots)$  for some  $c \in \mathbb{C}$  and  $x(t) \rightarrow z$  where

$$z = \left( \dots, \begin{pmatrix} c \\ -c/3 \\ 0 \end{pmatrix}, \begin{pmatrix} c \\ -c/3 \\ 0 \end{pmatrix}, \begin{pmatrix} c \\ -c/3 \\ 0 \end{pmatrix}, \dots \right).$$

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Let  $1 \leq p \leq \infty$  and let  $\alpha_0, \alpha_1, \alpha_2$  be as before. If  $x_0 \in C$  and if the convergence in  $(\dagger)$  is like  $O(n^{-1})$  as  $n \rightarrow \infty$ , then

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Moreover, for any  $x_0 \in X$  we have

$$\|\dot{x}(t)\| = O\left(\left(\frac{\log t}{t}\right)^{1/2}\right), \quad t \rightarrow \infty.$$

In both cases the logarithm can be dropped if  $p = 2$ .



**Thank you.**