Rectilinear Polygon Exchange Transformations via Cut-and-Project Methods

Ren Yi (joint work with Ian Alevy and Richard Kenyon)

Zero Entropy System, CIRM



Outline

- 1. Polygon Exchange Transformations (PETs)
- 2. Cut-and-Project Sets
- 3. (1) + (2) \Rightarrow Rectilinear PETs (RETs)

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- 3. (1) + (2) \Rightarrow Rectilinear PETs (RETs) (Renormalization)
- 4. Multi-Stage RETs
- 5. Parameter Space of Multi-Stage RETs

(Polygon Exchange Transformation)

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Let A = {A_k}^N_{k=0} and B = {B_k}^N_{k=0} be two partitions of X into polygons such that

$$B_k = A_k + v_k, \quad \forall k = 0, \cdots, N.$$

For each k, the polygons A_k and B_k are translation equivalent.

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For each k, the polygons A_k and B_k are translation equivalent.

► A polygon exchange transformation (PET) is a dynamical system on X. The map T : X → X is defined by

$$\mathbf{x} \mapsto \mathbf{x} + v_k, \quad \forall \mathbf{x} \in \mathsf{Int}(A_k).$$



Figure: 1-dim example (interval exchange transformation)



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Figure: An example of PETs



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Multigraph PETs (R. Schwartz and R. Yi)

Rectilinear PETs (RETs)

We consider the case when all $A_k \in \mathcal{A}$ and $B_k \in \mathcal{B}$ in the partitions are rectilinear polygons.



Figure: An example of rectilinear PETs

Renormalization: An approach to study PETs

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Renormalization

Renormalization is a tool to zoom the space and accelerate the orbits of points along time.

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▶ Let $T: X \to X$ be a PET and Y be a subset of X. The first return map $\hat{T}|_Y: Y \to Y$ is given by

 $\hat{T}|_{Y}(p) = T^{n}(p), \text{ where } n = \min\{T^{k}(p) \in Y | k > 0\}.$

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Definition (Renormalization)

A PET $T: X \to X$ is **renormalizable** if there exists a subset $Y \subset X$ such that $\hat{T}|_Y$ is conjugate to T by a affine map.

Renormalization

An example of piecewise isometric maps and its renormalization (A. Goetz).



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Characteristic polynomial:

$$q(x) = x^3 - (n+1)x^2 + nx - 1$$

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• Eigenvectors (corresponding to λ_i):

$$\xi_i = (1, \lambda_i, \lambda_i^2).$$

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▶ ℍ_e := the expanding line
 ▶ ℍ_c := the contracting hyperplane
 ▶ π_e := the projection of ℝ³ onto ℍ_e along ℍ_c

$$\pi_e: \mathbf{x} \mapsto \mathbf{x} \cdot \xi_3$$



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$$\pi_e: \mathbf{x} \mapsto \mathbf{x} \cdot \xi_3$$

▶ $\pi_c :=$ the projection of \mathbb{R}^3 onto \mathbb{H}_c along \mathbb{H}_e

$$\pi_c: \mathbf{x} \mapsto (\mathbf{x} \cdot \xi_1, \mathbf{x} \cdot \xi_2)$$

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For $p \in \Lambda_X$, define $w_p \in \Lambda_X$ to be the point such that

$$\pi_e(w_p) - \pi_e(p) = \min_{w \in \Lambda_X} \{\pi_e(w) - \pi_e(p) > 0\}$$

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 $|\mathcal{E}| = N < \infty$

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Rectilinear PET

via

Cut-and-Project Methods

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Translation vectors on X:

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Translation vectors on X:

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We define an order on the elements in *E* by

$$\eta_i < \eta_j$$
 if $\pi_e(\eta_i) < \pi_e(\eta_j)$.

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▶ An example of the rectilinear PET $T_n: X \to X$ constructed from cut-and-project method via matrix

$$M_n = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -n & n+1 \end{bmatrix} \text{ for } n = 6.$$



An example of the rectilinear PET $T_n : X \to X$ constructed from cut-and-project method via matrix $M_n = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -n & n+1 \end{bmatrix}$ for n = 6.

Each orbit of point $x \in X$ corresponds to a lattice walk.



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Theorem

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$$\hat{T}_n|_Y = \psi^{-1} \circ T_n \circ \psi$$

where $\psi: X \to X$ is defined by

$$\psi: (x,y) \mapsto (\frac{x+\lambda_1-1}{\lambda_1}, \frac{y+\lambda_2-1}{\lambda_2}).$$

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Figure: An illustration of renormalization.

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Figure: An illustration of renormalization.

Proof Sketch:

► Define
$$\Lambda_Y = \{(a, b, c) \in \mathbb{Z}^3 | \pi_c(a, b, c) \in Y\}.$$

Note the fact that $\Lambda_Y \subset \Lambda_X$.

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 \blacktriangleright Define $\Psi:\Lambda_X\to\Lambda_X$ to be the acceleration map defined by

$$\Psi: \begin{bmatrix} a \\ b \\ c \end{bmatrix} \mapsto \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & -n \\ 0 & 1 & n+1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

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We show that $\Psi : \Lambda_Y \to \Lambda_Y$ corresponds to $\hat{T}|_Y : Y \to Y$.



Proof Sketch:

► Return

$$\pi_c \left(\begin{bmatrix} a \\ b \\ c \end{bmatrix} \right) = (x, y) \quad \Rightarrow \quad \pi_c \circ \Psi \left(\begin{bmatrix} a \\ b \\ c \end{bmatrix} \right) = (\lambda_1 x, \lambda_2 y)$$

where $0 < \lambda_1 < \lambda_2 < 1$ are eigenvalues of M_n .

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▶ First return

The map Ψ preserves the order of the lattice walk $\{\omega_1,\omega_2,\cdots\},$ i.e.

$$\pi_e(\omega_i) < \pi_e(\omega_j) \quad \Rightarrow \quad \pi_e \circ \Psi(\omega_i) < \pi_e \circ \Psi(\omega_j).$$

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substitution of Pisot type



Underlying substitution symbolic dynamics:



- $\blacktriangleright \text{ Set } a = v_0, \ b = v_1 \text{ and } c = v_3.$
- substitution of Pisot type
 - $a\mapsto abc$, $b\mapsto abcb$, and
 - $c \mapsto (abc)^{n-3}bc$ for $n \ge 6$

Underlying substitution symbolic dynamics:



Set a = v₀, b = v₁ and c = v₃.
substitution of Pisot type a → abc, b → abcb, and c → (abc)ⁿ⁻³bc for n ≥ 6

Incidence matrix:

$$W_n = \begin{bmatrix} 1 & 1 & n-3 \\ 1 & 2 & n-2 \\ 1 & 1 & n-2 \end{bmatrix}$$

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 \triangleright $W_n \sim M_n$

Multi-Stage Rectilinear PETs

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Multi-Stage Rectilinear PETs

Let P_n be the matrix of translation. Consider matrix products

$$P_0 = P_{n_1} \cdots P_{n_k}$$
 and $P_i = P_{n_1} \cdots P_{n_i}$ for $i \ge 1$.

For each stage $i \ge 0$, we want to construct a RET S_i by via P_i such that
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 \blacktriangleright each S_i is renormalizable, i.e.

$$\sim \iota_1 I_1 \qquad \varphi_1 \qquad \sim \iota_1 I_1 \qquad \varphi_1$$

 $\hat{S}_{i}|_{\mathcal{X}} = i h_{i}^{-1} \circ S_{i+1} \circ i h_{i}$



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The matrix of translation

$$P_n = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 2 & 1 & 1 & 2 & 2 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 & 2 \\ 0 & 1 & 1 & 1 & 2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 1 & 2 \\ 0 & 0 & 0 & n-4 & n-3 & n-4 & n-4 \end{bmatrix}$$

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The matrix P_n can be reduced to the incidence matrix W_n .

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Figure: An illustration of renormalization.

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There is a RET $S: X \to X$ with the set of translation vectors $V = \{v_j\}_{j=0}^6$ if $v_j \in (-1, 1) \times (-1, 1)$.

$$\triangleright$$
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► Translation vector for *i*th stage:

$$v_0^i = (x_0^i, y_0^i), \dots, v_6^i = (x_6^i, y_6^i).$$

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There is a **multi-stage RET** $S: X \to X$ if at each stage i, all translation vectors $v_j^i \in (-1, 1) \times (-1, 1)$. A product P is called **admissible** if there is a multi-stage RET.



Figure: The multi-stage rectilinear PETs for $P = P_7 P_8 P_6 P_7$.

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Multi-Stage RETs (Renormalization)

Theorem (Renormalization Scheme)

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for the affine map $\psi_i: Y_i \mapsto X$



Figure: The parameter space of admissible rectilinear PETs in \mathbb{R}^4

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Theorem (in process)

The parameter space \mathcal{M} of admissible rectilinear PETs is a Cantor set in \mathbb{R}^4 .



Figure: $P_n \mathcal{M}$ and $P_n^{-1} \mathcal{M}$

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We expect the dynamics on the parameter space to be a 'discrete horseshoe map'



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Domain Exchange Transformation

We can construct domain exchange transformation on more general domains by the cut-and-project method.



Figure: An example of circle exchange transformation by the cut-and-project method

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(Conjecture) The domain exchange transformations on convex domains via cut-and-project methods are renormalizable.

Future Directions

- PETs on general domains and their renormalizations
- Piecewise isometries arisen from cut-and-project methods associated to quartic polynomials

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- Generalizations of the Three Gap Theorem
- Self-similar tilings from RETs?
- Generalizations of Rauzy inductions in PETs
- Complexity of the PETs

Thank you

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