## On the stability and the <u>applications</u> of interacting particle systems

P. Del Moral

INRIA Bordeaux Sud Ouest

PDE/probability interactions - CIRM, April 2017

**Synthesis**  $\subset$  **joint works** with A.N. Bishop, J. Garnier, A. Guionnet, A. Kurtzmann, J. Jacod M. Ledoux, L. Miclo, J. Tugaut, L. Wu

Nonlinear Markov chains

Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models (⊃ filtering, rare events,...) A brief review on genetic type models Non commutative models Lyapunov weighted dynamics model

Particle Gibbs-Glauber dynamics Many body Feynman-Kac (particle) models Duality formulae + Taylor expansions Branching proc. and Interacting MCMC

Continuous time models

Feynman-Kac models - Diffusion Monte Carlo Gradient type diffusions Ensemble Kalman-Bucy filter Stability + Unif. prop. chaos

◆□▶ ◆□▶ ◆□▶ ◆□▶ ●□

Nonlinear Markov chains

Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models ( $\supset$  filtering, rare events,...)

Particle Gibbs-Glauber dynamics

Continuous time models

## Nonlinear distribution flows

Probability measures  $\eta_n$  on some state spaces  $S_n$ 

$$\eta_n = \Phi_n(\eta_{n-1})$$

## Nonlinear distribution flows

#### Probability measures $\eta_n$ on some state spaces $S_n$

$$\eta_n = \Phi_n\left(\eta_{n-1}\right)$$

#### Ex.

Feynman-Kac measures, conditional distributions, nonlinear MCMC, discrete time McKean-Vlasov, discrete time approximations of any nonlinear integro-diff eq. of proba (jumps, collisions, diffusions),...

#### Nonlinear distribution flows

#### Probability measures $\eta_n$ on some state spaces $S_n$

$$\eta_n = \Phi_n\left(\eta_{n-1}\right)$$

#### Ex.

Feynman-Kac measures, conditional distributions, nonlinear MCMC, discrete time McKean-Vlasov, discrete time approximations of any nonlinear integro-diff eq. of proba (jumps, collisions, diffusions),...

#### Continuous time ~> Discrete time on time mesh

- Drift + Diffusion : Euler type scheme
- Jumps + Exponential rates : Geometric/Bernoulli type schemes

 $\eta_n = \Phi_n(\eta_{n-1}) \qquad \approx_{dt\downarrow 0} \qquad \text{nonlinear integro-diff equation}$ 

(日) (日) (日) (日) (日) (日) (日) (日) (日)

## Nonlinear Markov models

$$\eta_n = \Phi_n\left(\eta_{n-1}\right)$$

↕

Always  $\exists K_{n,\eta}$  Markov transitions s.t.

$$\Phi_n(\eta_{n-1}) = \eta_{n-1} K_{n,\eta_{n-1}} = \operatorname{Law}\left(\overline{X}_n\right) = \eta_n$$

i.e. :

$$\mathbb{P}(\overline{X}_n \in dx_n \mid \overline{X}_{n-1}) = K_{n,\eta_{n-1}}(\overline{X}_{n-1}, dx_n)$$

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

#### Nonlinear Markov models

$$\eta_n = \Phi_n(\eta_{n-1})$$

↕

Always  $\exists K_{n,\eta}$  Markov transitions s.t.

$$\Phi_n(\eta_{n-1}) = \eta_{n-1} \mathcal{K}_{n,\eta_{n-1}} = \operatorname{Law}\left(\overline{X}_n\right) = \eta_n$$

i.e. :

$$\mathbb{P}(\overline{X}_n \in dx_n \mid \overline{X}_{n-1}) = K_{n,\eta_{n-1}}(\overline{X}_{n-1}, dx_n)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

Non unique Markov interpretations,...

$$\mathbb{P}((\overline{X}_0,\ldots,\overline{X}_n) \in d(x_0,\ldots,x_n))$$
  
=  $\eta_0(dx_0) \ K_{1,\eta_0}(x_0,dx_1) \ \ldots \ K_{n,\eta_{n-1}}(x_{n-1},dx_n)$ 

$$\mathbb{P}((\overline{X}_0,\ldots,\overline{X}_n) \in d(x_0,\ldots,x_n))$$
  
=  $\eta_0(dx_0) \ K_{1,\eta_0}(x_0,dx_1) \ \ldots \ K_{n,\eta_{n-1}}(x_{n-1},dx_n)$ 

defined sequentially with

$$\eta_n = \Phi_n(\eta_{n-1}) = n$$
-th marginal  $= Law(\overline{X}_n)$ 

$$\mathbb{P}((\overline{X}_0,\ldots,\overline{X}_n) \in d(x_0,\ldots,x_n))$$
  
=  $\eta_0(dx_0) \ K_{1,\eta_0}(x_0,dx_1) \ \ldots \ K_{n,\eta_{n-1}}(x_{n-1},dx_n)$ 

defined sequentially with

$$\eta_n = \Phi_n(\eta_{n-1}) = n$$
-th marginal  $= \operatorname{Law}(\overline{X}_n)$ 

Nb: the historical process is also a nonlinear Markov chain

$$\overline{\boldsymbol{X}}_{\boldsymbol{n}} := \left(\overline{X}_0, \dots, \overline{X}_n\right)$$

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のへで

$$\mathbb{P}((\overline{X}_0,\ldots,\overline{X}_n) \in d(x_0,\ldots,x_n))$$
  
=  $\eta_0(dx_0) \ K_{1,\eta_0}(x_0,dx_1) \ \ldots \ K_{n,\eta_{n-1}}(x_{n-1},dx_n)$ 

defined sequentially with

$$\eta_n = \Phi_n(\eta_{n-1}) = n$$
-th marginal  $= Law(\overline{X}_n)$ 

◆□ → ◆□ → ◆三 → ◆□ → ◆○ ◆

Nb: the historical process is also a nonlinear Markov chain

$$\overline{\mathbf{X}}_{\mathbf{n}} := (\overline{X}_0, \dots, \overline{X}_n)$$
 $\Downarrow$ 

$$\operatorname{Law}(\overline{\boldsymbol{X}}_n) = \eta_n = \Phi_n \left( \eta_{n-1} \right)$$

$$\mathbb{P}((\overline{X}_0,\ldots,\overline{X}_n) \in d(x_0,\ldots,x_n))$$
  
=  $\eta_0(dx_0) \ K_{1,\eta_0}(x_0,dx_1) \ \ldots \ K_{n,\eta_{n-1}}(x_{n-1},dx_n)$ 

defined sequentially with

$$\eta_n = \Phi_n(\eta_{n-1}) = n$$
-th marginal  $= Law(\overline{X}_n)$ 

Nb: the historical process is also a nonlinear Markov chain

$$\overline{\boldsymbol{X}}_{\boldsymbol{n}} := \left(\overline{X}_0, \dots, \overline{X}_n\right)$$

$$\Downarrow$$

$$\operatorname{Law}(\overline{\boldsymbol{X}}_n) = \eta_n = \Phi_n\left(\eta_{n-1}\right) = \eta_{n-1}K_{n,\eta_{n-1}}, \dots$$

Nonlinear Markov chains

#### Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models ( $\supset$  filtering, rare events,...)

Particle Gibbs-Glauber dynamics

Continuous time models

## Mean field particle interpretation

Markov chain  $\xi_n = (\xi_n^1, \xi_n^2, \dots, \xi_n^N) \in S_n^N$ 

$$\xi_{n-1}^{i} \rightsquigarrow \xi_{n}^{i} \sim \mathcal{K}_{n,\eta_{n-1}^{N}}(\xi_{n-1}^{i}, dx_{n}) \quad \text{with} \quad \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{\xi_{n}^{i}} := \eta_{n}^{N} \simeq_{N\uparrow\infty} \eta_{n}$$

Same models for the McKean measures

 $\boldsymbol{\xi_n^i} = \left( \xi_0^i, \dots, \xi_n^i \right) \quad \text{mean field particle of} \quad \overline{\boldsymbol{X}}_n := \left( \overline{X}_0, \dots, \overline{X}_n \right)$ 

・ロト < 団ト < 三ト < 三ト < 三 ・ のへで</li>

## Mean field particle interpretation

Markov chain  $\xi_n = (\xi_n^1, \xi_n^2, \dots, \xi_n^N) \in S_n^N$ 

$$\xi_{n-1}^{i} \rightsquigarrow \xi_{n}^{i} \sim \mathcal{K}_{n,\eta_{n-1}^{N}}(\xi_{n-1}^{i}, dx_{n}) \quad \text{with} \quad \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{\xi_{n}^{i}} := \eta_{n}^{N} \simeq_{N\uparrow\infty} \eta_{n}$$

Same models for the McKean measures

 $\boldsymbol{\xi_n^i} = \left( \xi_0^i, \dots, \xi_n^i \right) \quad \text{mean field particle of} \quad \overline{\boldsymbol{X}}_n := \left( \overline{X}_0, \dots, \overline{X}_n \right)$ 

#### $\neq$ Interpretations:

Stochastic adaptive grid, stochastic linearization, microscopic particle model, Sequential Monte Carlo method,...

(日) (同) (三) (三) (三) (○) (○)

Nonlinear Markov chains

Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models ( $\supset$  filtering, rare events,...)

Particle Gibbs-Glauber dynamics

Continuous time models



### General fluctuation theorem

local fluctuation random fields

$$\eta_n^N - \Phi_n \left( \eta_{n-1}^N \right) = \frac{1}{\sqrt{N}} V_n^N$$

#### General fluctuation theorem

local fluctuation random fields

$$\eta_n^N - \Phi_n \left( \eta_{n-1}^N \right) = \frac{1}{\sqrt{N}} V_n^N$$

\delta f / Multivariate / Functional / Donsker theorems
(dp+Guionnet [99], Miclo [00], Ledoux [00], Jacod [02], ..., Wu [11,13])

$$(V_n^N)_{n\geq 0} \longrightarrow_{N\to\infty} (V_n)_{n\geq 0}$$

with independent centered Gaussian fields  $V_n$  s.t.

$$\mathbb{E}\left(\left[V_n(f)\right]^2\right) = \eta_{n-1}\left[K_{n,\eta_{n-1}}\left[f - K_{n,\eta_{n-1}}(f)\right]^2\right]$$

(日) (日) (日) (日) (日) (日) (日) (日) (日)

"Intuitive picture"  $\rightsquigarrow$  nonlinear sg :

$$\eta_n = \Phi_n(\eta_{n-1}) = \Phi_{p,n}(\eta_p) = \eta_n$$

Local fluctuations transport formulation :

"Intuitive picture"  $\rightsquigarrow$  nonlinear sg :

$$\eta_n = \Phi_n(\eta_{n-1}) = \Phi_{p,n}(\eta_p) = \eta_n$$

Local fluctuations transport formulation :

Local fluctuation errors

$$\eta_n^N = \Phi_n(\eta_{n-1}^N) + \frac{1}{\sqrt{N}} V_n^N$$

### Key decomposition formulae

For any "time-window"

$$\eta_n^N - \eta_n = \underbrace{\eta_n^N - \Phi_{n-p,n}(\eta_{n-p}^N)}_{\simeq e^{c_1 \cdot p} / \sqrt{N}} + \underbrace{\Phi_{n-p,n}(\eta_{n-p}^N) - \Phi_{n-p,n}(\eta_{n-p})}_{\simeq e^{-c_2 \cdot p}}$$

then  $c = c_1 + c_2$ 

$$p = (2c)^{-1} \log N \Longrightarrow e^{c_1 p} / \sqrt{N} = e^{-c_2 p} = \left(\frac{1}{\sqrt{N}}\right)^{c_2/(c_1+c_2)}$$

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ ▲□ ● ● ●

More refined analysis

$$\eta_n^N - \eta_n = \sum_{q=0}^n [\Phi_{q,n}(\eta_q^N) - \Phi_{q,n}(\Phi_q(\eta_{q-1}^N))]$$

## Key decomposition formulae

For any "time-window"

$$\eta_n^N - \eta_n = \underbrace{\eta_n^N - \Phi_{n-p,n}(\eta_{n-p}^N)}_{\simeq e^{c_1 \cdot p} / \sqrt{N}} + \underbrace{\Phi_{n-p,n}(\eta_{n-p}^N) - \Phi_{n-p,n}(\eta_{n-p})}_{\simeq e^{-c_2 \cdot p}}$$

then  $c = c_1 + c_2$ 

$$p = (2c)^{-1} \log N \Longrightarrow e^{c_1 p} / \sqrt{N} = e^{-c_2 p} = \left(\frac{1}{\sqrt{N}}\right)^{c_2/(c_1+c_2)}$$

More refined analysis

$$\begin{split} \eta_n^N - \eta_n &= \sum_{q=0}^n \left[ \Phi_{q,n}(\eta_q^N) - \Phi_{q,n}(\Phi_q(\eta_{q-1}^N)) \right] \\ &= \sum_{q=0}^n \left[ \Phi_{q,n} \left( \Phi_q(\eta_{q-1}^N) + \frac{1}{\sqrt{N}} V_n^N \right) - \Phi_{q,n} \left( \Phi_q(\eta_{q-1}^N) \right) \right] \end{split}$$

Semigroup/Stability/Uniform propagation of chaos/... dp+Guionnet CRAS [99], and IHP [00], Miclo [00], [02], [03], Rousset [05],...

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ ののの

Another tool  $I_q^N :=$  q-multi-indexes with  $\neq$  values

$$\eta_n^{(N,q)}(f) := m(\xi_n)^{\odot q} := \frac{1}{(N)_q} \sum_{c \in I_q^N} \delta(\xi_n^{c(1)}, ..., \xi_n^{c(q)})$$

Another tool  $I_q^N :=$  q-multi-indexes with  $\neq$  values  $\eta_n^{(N,q)}(f) := m(\xi_n)^{\odot q} := \frac{1}{(N)_q} \sum_{c \in I_q^N} \delta(\xi_n^{c(1)}, \dots, \xi_n^{c(q)})$ 

 $\exists$  combinatorial/transport/coalescent tree formulae between  $m(\xi_n)^{\odot q}$ and  $m(\xi_n)^{\otimes q}$  and

$$\|m(\xi_n)^{\otimes q} - m(\xi_n)^{\odot q}\|_{tv} \leq (q-1)^2/N$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● ● ● ● ● ●

Another tool  $I_q^N :=$  q-multi-indexes with  $\neq$  values  $\eta_n^{(N,q)}(f) := m(\xi_n)^{\odot q} := \frac{1}{(N)_q} \sum_{c \in I_q^N} \delta_{\left(\xi_n^{c(1)}, \dots, \xi_n^{c(q)}\right)}$ 

 $\exists$  combinatorial/transport/coalescent tree formulae between  $m(\xi_n)^{\odot q}$ and  $m(\xi_n)^{\otimes q}$  and

$$\|m(\xi_n)^{\otimes q} - m(\xi_n)^{\odot q}\|_{tv} \leq (q-1)^2/N$$

#### Why these objects?

Another tool  $I_q^N :=$  q-multi-indexes with  $\neq$  values  $\eta_n^{(N,q)}(f) := m(\xi_n)^{\odot q} := \frac{1}{(N)_q} \sum_{c \in I_q^N} \delta_{\left(\xi_n^{c(1)}, \dots, \xi_n^{c(q)}\right)}$ 

 $\exists$  combinatorial/transport/coalescent tree formulae between  $m(\xi_n)^{\odot q}$ and  $m(\xi_n)^{\otimes q}$  and

$$\|m(\xi_n)^{\otimes q} - m(\xi_n)^{\odot q}\|_{tv} \leq (q-1)^2/N$$

#### Why these objects? ⇒ Propagation of chaos = Bias

$$\mathbb{E}\left(f(\xi_n^1,\ldots,\xi_n^q)\mid\xi_{n-1}\right) = \mathbb{E}\left(\eta_n^{(N,q)}(f)\mid\xi_{n-1}\right) = \eta_{n-1}^{(N,q)}\mathcal{K}_{m(\xi_{n-1})}^{\otimes q}(f)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ ● ● ●

Another tool  $I_q^N :=$  q-multi-indexes with  $\neq$  values  $\eta_n^{(N,q)}(f) := m(\xi_n)^{\odot q} := \frac{1}{(N)_q} \sum_{c \in I_q^N} \delta_{\left(\xi_n^{c(1)}, \dots, \xi_n^{c(q)}\right)}$ 

 $\exists$  combinatorial/transport/coalescent tree formulae between  $m(\xi_n)^{\odot q}$ and  $m(\xi_n)^{\otimes q}$  and

$$\|m(\xi_n)^{\otimes q} - m(\xi_n)^{\odot q}\|_{tv} \leq (q-1)^2/N$$

Why these objects? ⇒ Propagation of chaos = Bias

$$\mathbb{E}\left(f(\xi_n^1,\ldots,\xi_n^q)\mid\xi_{n-1}\right) = \mathbb{E}\left(\eta_n^{(N,q)}(f)\mid\xi_{n-1}\right) = \eta_{n-1}^{(N,q)}\mathcal{K}_{m(\xi_{n-1})}^{\otimes q}(f)$$

#### Non asymp. Taylor exp.+ Uniform propagation of chaos *q*-particles

 $\subset$  dp Springer [04], dp+Peters SIAM [06], dp+Patras+Rubenthaler AoAP [06], dp+Miclo SAA[07] Chan+dp+Jasra Arxiv [14] Nonlinear Markov chains

Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models (⊃ filtering, rare events,...) A brief review on genetic type models Non commutative models Lyapunov weighted dynamics model

Particle Gibbs-Glauber dynamics

Continuous time models

## Feynman-Kac measures

$$\mathbb{Q}_n(F_n)=\Gamma_n(F_n)/\Gamma_n(1) \quad ext{and} \quad \eta_n(f_n)=\gamma_n(f_n)/\gamma_n(1)$$
 with

 $\Gamma_n(F_n) = \mathbb{E}\left(F_n(\boldsymbol{X_n}) \ Z_n(X)\right) \quad \text{and} \quad \gamma_n(f_n) = \mathbb{E}\left(f_n(X_n) \ Z_n(X)\right)$ 

with the historical process

$$\boldsymbol{X}_{\boldsymbol{n}} = (X_0, \ldots, X_n) \quad ext{and} \quad Z_n(X) = \prod_{0 \leq k < n} G_k(X_k)$$

### Feynman-Kac measures

$$\mathbb{Q}_n(F_n) = \Gamma_n(F_n)/\Gamma_n(1) \text{ and } \eta_n(f_n) = \gamma_n(f_n)/\gamma_n(1)$$
with
$$\Gamma_n(F_n) = \mathbb{E} \left( F_n(\boldsymbol{X}_n) \ Z_n(X) \right) \text{ and } \gamma_n(f_n) = \mathbb{E} \left( f_n(X_n) \ Z_n(X) \right)$$
with the historical process
$$\boldsymbol{X}_n = (X_0, \dots, X_n) \text{ and } \boldsymbol{Z}_n(X) = \prod_{0 \le k < n} G_k(X_k)$$

Mean field particle  $\rightsquigarrow$  Genetic/Branching process  $\xi_n = (\xi_n^i)_i$ 

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

$$\eta_n \simeq \eta_n^N = \underbrace{\frac{1}{N} \sum_{1 \le i \le N} \delta_{\xi_n^i}}_{:=m(\xi_n)}$$

### Feynman-Kac measures

$$\mathbb{Q}_n(F_n) = \Gamma_n(F_n)/\Gamma_n(1)$$
 and  $\eta_n(f_n) = \gamma_n(f_n)/\gamma_n(1)$  with

 $\Gamma_n(F_n) = \mathbb{E}(F_n(\boldsymbol{X_n}) \ Z_n(X)) \quad \text{and} \quad \gamma_n(f_n) = \mathbb{E}(f_n(X_n) \ Z_n(X))$ 

with the historical process

$$\boldsymbol{X}_{\boldsymbol{n}} = (X_0, \dots, X_n) \quad ext{and} \quad Z_n(X) = \prod_{0 \leq k < n} G_k(X_k)$$

Mean field particle  $\rightsquigarrow$  Genetic/Branching process  $\xi_n = (\xi_n^i)_i$ 

$$\eta_n \simeq \eta_n^N = \underbrace{\frac{1}{N} \sum_{1 \le i \le N} \delta_{\xi_n^i}}_{:=m(\xi_n)} \stackrel{\text{path-space}}{=} \underbrace{\frac{1}{N} \sum_{1 \le i \le N} \delta_{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i)}}_{=\text{Law ancestral line }:= \mathbb{X}_n} \simeq \mathbb{Q}_n$$












































### **Equivalent particle algorithms**

Sequential Monte Carlo	Sampling	Resampling
Particle Filters	Prediction	Updating
Genetic Algorithms	Mutation	Selection
<b>Evolutionary Population</b>	Exploration	Branching-selection
Diffusion Monte Carlo	Free evolutions	Absorption
Quantum Monte Carlo	Walkers motions	Reconfiguration
Sampling Algorithms	Transition proposals	Accept-reject-recycle

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ / 圖 / のへで

### Equivalent particle algorithms

Sequential Monte Carlo	Sampling	Resampling
Particle Filters	Prediction	Updating
Genetic Algorithms	Mutation	Selection
<b>Evolutionary Population</b>	Exploration	Branching-selection
Diffusion Monte Carlo	Free evolutions	Absorption
Quantum Monte Carlo	Walkers motions	Reconfiguration
Sampling Algorithms	Transition proposals	Accept-reject-recycle

#### Many other lively buzzwords :

bootstrapping, spawning, cloning, pruning, replenish, splitting, enrichment, go with the winner, look-ahead, weighted dynamics, quantum teleportation...

1947  $\leq$  Heuristic style algo.  $\leq$  1996  $\leq$  Particle Feynman-Kac models

Convergence analysis : Uniform propagation of chaos, concentration, stability, CLT, LDP, MDP, Empirical processes, ...

### Feynman-Kac measures

**Unnormalized measures** 

$$\gamma_n(f_n) = \eta_n(f_n) \times \prod_{0 \le p < n} \eta_p(G_p)$$

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

### Feynman-Kac measures



▲ロト ▲□ト ▲ヨト ▲ヨト ヨー のへの

### Feynman-Kac measures



**Application domains :** Any conditional distributions, Bayesian prior/posterior, nonlinear filtering, Boltzmann-Gibbs measures, branching processes, Twisted importance sampling,...

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

### Non commutative models

► 
$$G_n(x_n) \in \mathbb{R}^{d \times d}$$
 s.t.  $\forall u \in \mathbb{S}^{d-1} := \{|u|| = 1\}$  we have  $||G_n(x) u|| > 0$ 

•  $f_n(x_0,\ldots,x_n) \in \mathbb{R}^d$  and  $\prod_{0 \le p \le n} A_p = A_0 A_1 \ldots A_n$ 

$$\Gamma_n(f_n).u_0 := \mathbb{E}\left(f_n(X_0,\ldots,X_n)\prod_{0\leq p< n}G_p(X_p).u_0\right) \\ = \mathbb{E}\left(f_n(X_0,\ldots,X_n)\prod_{0\leq p< n}G_p(X_p)\right)$$

with

$$oldsymbol{X}_{oldsymbol{n}} = (X_n, U_n) \in ig( E_n imes \mathbb{S}^{d-1} ig) \quad ext{and} \quad oldsymbol{G}_{oldsymbol{n}}(oldsymbol{X}_{oldsymbol{n}}) = \|oldsymbol{G}_n(oldsymbol{X}_n) \cdot U_n\|$$

and the walk on the sphere model

$$U_{n+1} = \frac{G_n(X_n) \cdot U_n}{\|G_n(X_n) \cdot U_n\|}$$

< 口 > 《 昂 > 《 토 > 《 토 > 토 · · 의 < 은

$$\bigtriangledown$$
 of  $P_n(arphi)(x) = \mathbb{E}_x(arphi(Y_n))$  with  $Y_{n+1} = F_n(Y_n, W_n)$ 

#### **First variational equation**

$$\begin{aligned} \mathsf{Jac}(Y_{n+1}) &= & G_n(Y_n, W_n) \; \mathsf{Jac}(Y_n) \quad \text{with} \quad G_n^{i,j} = \partial_{x^j} F_n^i \\ &= & \prod_{0 \le p \le n} G_p(X_p) \qquad \text{with} \quad X_n = (Y_n, W_n) \end{aligned}$$

$$\Rightarrow \nabla P_n(\varphi)(x) \cdot u_0 = \mathbb{E} \left( \underbrace{f_n(X_n)}_{= \nabla(\varphi)(Y_n) \cdot U_n} \times \prod_{0 \le p < n} \underbrace{G_p(X_p)}_{= ||G_p(X_p) \cdot U_p||} \right)$$

 $\Leftrightarrow$  FK model w.r.t.  $Y_n$  weighted with the directional Lyap. exp.

$$\prod_{\mathbf{0} \leq \mathbf{p} \leq \mathbf{n}} \mathbf{G}_{\mathbf{p}}(\mathbf{X}_{\mathbf{p}}) = \| \operatorname{Jac}(Y_n) \cdot u_0 \| = \prod_{\mathbf{0} \leq \mathbf{p} \leq \mathbf{n}} \frac{\| \operatorname{Jac}(Y_p) \cdot u_0 \|}{\| \operatorname{Jac}(Y_{p-1}) \cdot u_0 \|}$$

### Related Feynman-Kac model

$$oldsymbol{X}_{oldsymbol{n}} = (X_n, X_{n+1}) \quad ext{and} \quad oldsymbol{G}_{oldsymbol{n}}(oldsymbol{X}_{oldsymbol{n}}) = \| \operatorname{Jac} (X_{n+1}) \|^{lpha} / \| \operatorname{Jac} (X_n) \|^{lpha}$$

Feynman-Kac model = The Lyapunov weighted dynamics model

$$dQ_n = \frac{1}{\mathcal{Z}_n} \|\operatorname{Jac}(X_n)\|^{\alpha} dP_n$$

•  $\alpha > 0 \Leftrightarrow dQ_n$  favors high Lyapunov trajectories

Hyper-references :

- T Laffargue, K.D. Nguyen Thu Lam, J. Kurchan, J. Tailleur LDP of Lyapunov exp. (2013)
- S. Tanese Nicola, J. Kurchan. Metastable states, transitions, basins and borders at finite temperature J. Stat. Phys. (2004).
- J. Tailleur, S. Tanese Nicola, J. Kurchan. Kramers equations an supersymmetry J. Stat. Phys. (2006).
- J. Tailleur, J. Kurchan. Probing rare physical trajectories with Lyapunov weighted dynamics, Nature Physics (2007)
- C Genealogical particle analysis of aare events (joint work with J. Garnier)AAP (2005).

### Particle Feynman-Kac measures

Unbiased particle unnormalized measures (dp MPRF (96))

$$\gamma_n^{\mathsf{N}}(f_n) := \eta_n^{\mathsf{N}}(f_n) \times \prod_{0 \le p < n} \eta_p^{\mathsf{N}}(G_p)$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

### Particle Feynman-Kac measures

Unbiased particle unnormalized measures (dp MPRF (96))  $\gamma_n^N(f_n) := \eta_n^N(f_n) \times \prod_{0 \le p < n} \eta_p^N(G_p)$ Particle backward model (dp+Doucet+Singh HAL (09), M2AN (10))  $\mathbb{Q}_n^N(d(x_0, \dots, x_n)) := \eta_n^N(dx_n) \prod_{0 \le q < n} \underbrace{\mathbb{M}_{q+1, \eta_q^N}(x_{q+1}, dx_q)}_{\propto \eta_q^N(dx_q) \ H_{q+1}(x_q, x_{q+1})}$ 

### A first theorem

Theorem [dp+Kohn+Patras, Arxiv (14), CRAS (15)+IHP (16)] Law ( $X_n \mid (\xi_{k,k})_{0 \le k \le n}$ )

= Law of backward ancestral line  $\mathbb{X}_{p}^{\flat}$  given all pop.

### A first theorem

Theorem [dp+Kohn+Patras, Arxiv (14), CRAS (15)+IHP (16)] Law (  $\mathbb{X}_n \mid (\xi_{k,k})_{0 \le k \le n}$ ) = Law of backward ancestral line  $\mathbb{X}_{p}^{\flat}$  given all pop.  $:=\eta_n^{\mathsf{N}}(dx_n) \mathbb{M}_{n,\eta_n^{\mathsf{N}}}(x_n,dx_{n-1})\cdots \mathbb{M}_{1,\eta_n^{\mathsf{N}}}(x_1,dx_0)$ with the occupation measures  $\eta_k^{\mathsf{N}} = m(\xi_{k,k}) := \frac{1}{\mathsf{N}} \sum_{1 \le i \le \mathsf{N}} \delta_{\xi_{k,k}^i}$ 

Nonlinear Markov chains

Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models ( $\supset$  filtering, rare events,...)

Particle Gibbs-Glauber dynamics Many body Feynman-Kac (particle) models Duality formulae + Taylor expansions Branching proc. and Interacting MCMC

Continuous time models

and

$$\mathcal{F}_n(\xi_n) := m(\xi_n)(f_n) \text{ and } \mathcal{G}_n(\xi_n) := m(\xi_n)(\mathcal{G}_n)$$

$$\mathcal{Z}_n(\xi) := \prod_{0 \le k < n} \mathcal{G}_k(\xi_k) \simeq \mathcal{Z}_n = \prod_{0 \le k < n} \eta_k(G_k)$$

and

$$\mathcal{F}_n(\xi_n) := m(\xi_n)(f_n) \quad \text{and} \quad \mathcal{G}_n(\xi_n) := m(\xi_n)(G_n)$$

$$\mathcal{Z}_n(\xi) := \prod_{0 \le k < n} \mathcal{G}_k(\xi_k) \simeq \mathcal{Z}_n = \prod_{0 \le k < n} \eta_k(G_k)$$

#### Unbiasedness property in terms of many-body FK measures

$$\pi_n(\mathcal{F}_n) :\propto \mathbb{E}\left(\mathcal{F}_n(\xi_n) \ \mathcal{Z}_n(\xi)\right)$$

$$\mathcal{F}_n(\xi_n) := m(\xi_n)(f_n) \quad ext{and} \quad \mathcal{G}_n(\xi_n) := m(\xi_n)(G_n)$$

and

$$\mathcal{Z}_n(\xi) := \prod_{0 \le k < n} \mathcal{G}_k(\xi_k) \simeq \mathcal{Z}_n = \prod_{0 \le k < n} \eta_k(\mathcal{G}_k)$$

Unbiasedness property in terms of many-body FK measures  $\pi_n(\mathcal{F}_n) :\propto \mathbb{E} \left( \mathcal{F}_n(\xi_n) \ \mathcal{Z}_n(\xi) \right) = \mathbb{E} \left( f_n(X_n) \ Z_n(X) \right) \propto \eta_n(f_n)$ 

(Note: the definition of  $\pi_n$  if for any symmetric functions  $\mathcal{F}_n(\xi_n)$ )

$$\mathcal{F}_n(\xi_n) := m(\xi_n)(f_n) \quad ext{and} \quad \mathcal{G}_n(\xi_n) := m(\xi_n)(G_n)$$

and

$$\mathcal{Z}_n(\xi) := \prod_{0 \le k < n} \mathcal{G}_k(\xi_k) \simeq \mathcal{Z}_n = \prod_{0 \le k < n} \eta_k(G_k)$$

Unbiasedness property in terms of many-body FK measures  $\pi_n(\mathcal{F}_n) :\propto \mathbb{E} \left( \mathcal{F}_n(\xi_n) \ \mathcal{Z}_n(\xi) \right) = \mathbb{E} \left( f_n(X_n) \ Z_n(X) \right) \propto \eta_n(f_n)$ 

(Note: the definition of  $\pi_n$  if for any symmetric functions  $\mathcal{F}_n(\xi_n)$ )

Unbiasedness property in terms of ancestral lines

$$\mathbb{E}\left(f_n(\mathbb{X}_n) \ \mathcal{Z}_n(\xi)\right) = \mathbb{E}\left(f_n(\mathbb{X}_n^{\flat}) \ \mathcal{Z}_n(\xi)\right) = \mathbb{E}\left(f_n(X_n) \ Z_n(X)\right)$$

#### Definition: (Extended) Many-body FK measures

 $\pi_n(\mathcal{F}_n) :\propto \mathbb{E}\left(\mathcal{F}_n(\mathbb{X}_n, \boldsymbol{\xi}_n) \ \mathcal{Z}_n(\boldsymbol{\xi})\right)$ 

with historical process  $\boldsymbol{\xi}_{\boldsymbol{n}} = (\xi_0, \dots, \xi_n)$  (ancestral lines evolution).



Definition: (Extended) Many-body FK measures

 $\pi_n(\mathcal{F}_n) :\propto \mathbb{E}\left(\mathcal{F}_n(\mathbb{X}_n, \boldsymbol{\xi}_n) \ \mathcal{Z}_n(\boldsymbol{\xi})\right)$ 

with historical process  $\boldsymbol{\xi}_{\boldsymbol{n}} = (\xi_0, \dots, \xi_n)$  (ancestral lines evolution).

 $\Downarrow$ 

Particle Gibbs-Glauber dynamics (PGD) Target  $Law_{\pi}(X_n, \xi_n)$ 

Definition: (Extended) Many-body FK measures

 $\pi_n(\mathcal{F}_n) :\propto \mathbb{E}\left(\mathcal{F}_n(\mathbb{X}_n, \boldsymbol{\xi_n}) \ \mathcal{Z}_n(\boldsymbol{\xi})\right)$ 

with historical process  $\boldsymbol{\xi}_{\boldsymbol{n}} = (\xi_0, \dots, \xi_n)$  (ancestral lines evolution).

 $\Downarrow$ 

Particle Gibbs-Glauber dynamics (PGD) Target  $\operatorname{Law}_{\pi}(\mathbb{X}_{n}, \xi_{n})$   $\mathbb{X}_{n} = z$  $\xi_{n} = x$   $\} \rightarrow \begin{cases} \overline{\mathbb{X}}_{n} = \overline{z} \sim (\mathbb{X}_{n} \mid \xi_{n} = x) \\ \xi_{n} = x \end{cases}$   $\} \rightarrow \begin{cases} \overline{\mathbb{X}}_{n} = \overline{z} \\ \overline{\xi}_{n} = \overline{x} \sim (\xi_{n} \mid \mathbb{X}_{n} = \overline{z}) \end{cases}$ 

▲ロト ▲□ト ▲ヨト ▲ヨト ヨー のへの

Definition: (Extended) Many-body FK measures

 $\pi_n(\mathcal{F}_n) :\propto \mathbb{E}\left(\mathcal{F}_n(\mathbb{X}_n, \boldsymbol{\xi}_n) \ \mathcal{Z}_n(\boldsymbol{\xi})\right)$ 

with historical process  $\boldsymbol{\xi}_{\boldsymbol{n}} = (\xi_0, \dots, \xi_n)$  (ancestral lines evolution).

 $\Downarrow$ 

Particle Gibbs-Glauber dynamics (PGD) Target  $\operatorname{Law}_{\pi}(\mathbb{X}_{n}, \xi_{n})$   $\mathbb{X}_{n} = z$  $\xi_{n} = x$   $\} \rightarrow \begin{cases} \overline{\mathbb{X}}_{n} = \overline{z} \sim (\mathbb{X}_{n} \mid \xi_{n} = x) \\ \xi_{n} = x \end{cases}$   $\} \rightarrow \begin{cases} \overline{\mathbb{X}}_{n} = \overline{z} \\ \overline{\xi}_{n} = \overline{x} \sim (\xi_{n} \mid \mathbb{X}_{n} = \overline{z}) \end{cases}$ 

Important observation:

 $\mathbb{X}_n \rightsquigarrow \overline{\mathbb{X}}_n$  is a Markov process on path space
# Duality formula

To sample the second PGD transition  $\downarrow$ .

# Duality formula

To sample the second PGD transition  $\downarrow$ .

**Theo.-** Duality [dp+Kohn+Patras, Arxiv (14), CRAS (15)+IHP (16)]  $\forall \mathcal{F}_n \qquad \mathbb{E}\left(\mathcal{F}_n(\mathbb{X}_n, \boldsymbol{\xi_n}) \ \mathcal{Z}_n(\boldsymbol{\xi})\right) = \mathbb{E}\left(\mathcal{F}_n(X_n, \boldsymbol{\xi_n^*}) \ Z_n(X)\right)$ with the dual process:  $\boldsymbol{\xi_n^*}$  defined as  $\boldsymbol{\xi_n}$  but with a given frozen ancestral line  $X_n$ 

## Duality formula

To sample the second PGD transition  $\downarrow$ .

**Theo.-** Duality [dp+Kohn+Patras, Arxiv (14), CRAS (15)+IHP (16)]  $\forall \mathcal{F}_n \qquad \mathbb{E} \left( \mathcal{F}_n(\mathbb{X}_n, \boldsymbol{\xi_n}) \ \mathcal{Z}_n(\boldsymbol{\xi}) \right) = \mathbb{E} \left( \mathcal{F}_n(X_n, \boldsymbol{\xi_n^*}) \ Z_n(X) \right)$ with the dual process:  $\boldsymbol{\xi_n^*}$  defined as  $\boldsymbol{\xi_n}$  but with a given frozen ancestral line  $X_n$ 

Corollary - Backward duality  $\rightsquigarrow$  Same duality  $\oplus$  PGD when

 $(\mathbb{X}_n, \boldsymbol{\xi_n})$  is replaced by  $(\mathbb{X}_n^{\flat}, \boldsymbol{\xi_{n,n}})$ 

with the population historical process

$$\boldsymbol{\xi}_{\boldsymbol{n},\boldsymbol{n}} = (\xi_{k,k})_{0 \leq k \leq n}$$

# Taylor expansions

 $\mathbb{X}_n \rightsquigarrow \overline{\mathbb{X}}_n$  Markov process on path space with  $\eta_n$ -reversible transition  $\mathbb{K}_n$ 

n = FIXED length/Duration of the ancestral trajectories N = number of particles used in the genealogical trees

# Taylor expansions

 $\mathbb{X}_n \rightsquigarrow \overline{\mathbb{X}}_n$  Markov process on path space with  $\eta_n$ -reversible transition  $\mathbb{K}_n$ 

n = FIXED length/Duration of the ancestral trajectories N = number of particles used in the genealogical trees

Theo. [dp+Kohn+Patras, Arxiv (14), CRAS (15)+IHP (16)]  $\mathbb{K}_n(x,.) = \eta_n + \sum_{1 \le k \le l} \frac{1}{N^k} d^{(k)} \mathbb{K}_n(x,.) + \frac{1}{N^{l+1}} \partial^{l+1} \mathbb{K}_n(x,.)$   $(\forall l \ge 1) \oplus \text{Derivatives} \sim \text{coalescent/colored trees.}$ 

∜

## Taylor expansions

 $\mathbb{X}_n \rightsquigarrow \overline{\mathbb{X}}_n$  Markov process on path space with  $\eta_n$ -reversible transition  $\mathbb{K}_n$ 

n = FIXED length/Duration of the ancestral trajectories N = number of particles used in the genealogical trees

Theo. [dp+Kohn+Patras, Arxiv (14), CRAS (15)+IHP (16)]  $\mathbb{K}_n(x,.) = \eta_n + \sum_{1 \le k \le l} \frac{1}{N^k} d^{(k)} \mathbb{K}_n(x,.) + \frac{1}{N^{l+1}} \partial^{l+1} \mathbb{K}_n(x,.)$ ( $\forall l \ge 1$ )  $\oplus$  Derivatives ~ coalescent/colored trees.

∜

$$\left\|d^{(k)}\mathbb{K}_n\right\| \le (cnk^2)^k \text{ and } \left\|\partial^{(l+1)}\mathbb{K}_n\right\| \le (cn(l+1)^2)^{l+1}$$
  
as soon as  $N > cn(l+1)^2$ , for some  $c < \infty$ .

A couple of <u>direct</u> corollaries

# A couple of <u>direct</u> corollaries

**Cor.** 1:  $\forall m \geq 1$  and  $osc(f) \leq 1$ 

$$|\mathbb{K}_n^m(f)(x) - \eta_n(f)| \leq \beta \left(\mathbb{K}_n^m\right) \leq (cn/N)^m \quad \left( \longrightarrow_{\min(N,m) \to \infty} 0 \right)$$

#### A couple of <u>direct</u> corollaries

**Cor.** 1:  $\forall m \geq 1$  and  $osc(f) \leq 1$ 

$$|\mathbb{K}_n^m(f)(x) - \eta_n(f)| \leq \beta (\mathbb{K}_n^m) \leq (cn/N)^m \quad \left( \longrightarrow_{\min(N,m) \to \infty} 0 \right)$$

**Cor. 2:**  $\forall m \geq 1$ ,  $\infty \geq p \geq 1$  and  $\|f\| \leq 1$ 

$$\left\|\mathbb{K}_{n}^{m}(f)-\eta_{n}(f)\right\|_{\mathbb{L}_{p}(\eta_{n})}-N^{-m}\left\|\left[d^{(1)}\mathbb{K}_{n}\right]^{m}(f)\right\|_{\mathbb{L}_{p}(\eta_{n})}\right|\leq(cn/N)^{m+1}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

29/42

**Spatial branching processes**  $\rightsquigarrow$  varying pop. size  $N_n$ 

First moments  $\subset$  FK-models  $\Rightarrow$  FK-particle = fixed pop.size

**Spatial branching processes**  $\rightsquigarrow$  varying pop. size  $N_n$ 

First moments  $\subset$  FK-models  $\Rightarrow$  FK-particle = fixed pop.size

▶ Particle/Absorption models = FK models with potential  $G \in [0, 1]$  $\eta_n = \text{Law}(X_n^c \mid T^{killing} > n) \longrightarrow \eta_\infty = \text{quasi-invariant meas.}$ 

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

**Spatial branching processes**  $\rightsquigarrow$  varying pop. size  $N_n$ 

First moments  $\subset$  FK-models  $\Rightarrow$  FK-particle = fixed pop.size

▶ Particle/Absorption models = FK models with potential  $G \in [0, 1]$  $\eta_n = \text{Law}(X_n^c \mid T^{killing} > n) \longrightarrow \eta_\infty = \text{quasi-invariant meas.}$ 

Mutations = MCMC with target η<sub>n</sub> ∝ e<sup>-β<sub>n</sub>V(x)</sup> λ(dx) and branching rates/selection weights

 $e^{-(\beta_{n+1}-\beta_n)V(x)}$   $\beta_n \uparrow \implies$  interacting MCMC/SMC/...

**Spatial branching processes**  $\rightsquigarrow$  varying pop. size  $N_n$ 

First moments  $\subset$  FK-models  $\Rightarrow$  FK-particle = fixed pop.size

- ▶ Particle/Absorption models = FK models with potential  $G \in [0, 1]$  $\eta_n = \text{Law}(X_n^c \mid T^{killing} > n) \longrightarrow \eta_\infty = \text{quasi-invariant meas.}$
- Mutations = MCMC with target η<sub>n</sub> ∝ e<sup>-β<sub>n</sub>V(x)</sup> λ(dx) and branching rates/selection weights

 $e^{-(\beta_{n+1}-\beta_n)V(x)}$   $\beta_n \uparrow \implies$  interacting MCMC/SMC/...

• Mutations = MCMC with target  $\eta_n \propto 1_{A_n}(x) \lambda(dx)$  and branching rates/selection weights

 $1_{A_{n+1}}$   $A_n \downarrow \implies$  interacting MCMC/SMC/Multilevel splitting...

Nonlinear Markov chains

Mean field particle methods

Some stochastic perturbation tools

Feynman-Kac models ( $\supset$  filtering, rare events,...)

Particle Gibbs-Glauber dynamics

Continuous time models Feynman-Kac models - Diffusion Monte Carlo Gradient type diffusions Ensemble Kalman-Bucy filter Stability + Unif. prop. chaos

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ

(weak sense) : infinitesimal generators  $L_{t,\eta}$ 

$$\partial_t \eta_t(f) = \eta_t L_{t,\eta_t}(f) := \int_S \eta_t(dx) L_{t,\eta_t}(f)(x)$$

 $L_{t,\eta}$  regular familly  $\Rightarrow \exists \overline{X}_t \iff \exists McKean measure) \rightsquigarrow Ex. jump-diff.$ 

$$\begin{array}{lll} \mathcal{L}_{t,\eta}(f)(x) &=& a_t(x,\eta) \ f'(x) + \frac{1}{2} \ \sigma_t^2(x,\eta) \ f''(x) \\ && + \lambda_t(x,\eta) \ \int \ (f(y) - f(x)) \ \mathcal{K}_{t,\eta}(x,dy) \end{array}$$

(weak sense) : infinitesimal generators  $L_{t,\eta}$ 

$$\partial_t \eta_t(f) = \eta_t L_{t,\eta_t}(f) := \int_S \eta_t(dx) L_{t,\eta_t}(f)(x)$$

 $L_{t,\eta}$  regular familly  $\Rightarrow \exists \overline{X}_t \iff \exists McKean measure) \rightsquigarrow Ex. jump-diff.$ 

$$\begin{array}{lll} \mathcal{L}_{t,\eta}(f)(x) &=& a_t(x,\eta) \ f'(x) + \frac{1}{2} \ \sigma_t^2(x,\eta) \ f''(x) \\ && + \lambda_t(x,\eta) \ \int \ (f(y) - f(x)) \ \mathcal{K}_{t,\eta}(x,dy) \end{array}$$

Mean field particle model

$$\xi_t^i \text{ with generator } L_{t,\eta_t^N} \text{ with } \eta_t^N = N^{-1} \sum_{1 \le i \le N} \delta_{\xi_t^i}$$

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のへで

(weak sense) : infinitesimal generators  $L_{t,\eta}$ 

$$\partial_t \eta_t(f) = \eta_t L_{t,\eta_t}(f) := \int_S \eta_t(dx) L_{t,\eta_t}(f)(x)$$

 $L_{t,\eta} \text{ regular family} \Rightarrow \exists \ \overline{X}_t \ (\Leftrightarrow \exists \ \mathsf{McKean measure}) \rightsquigarrow \mathsf{Ex. jump-diff.}$ 

$$\begin{array}{lll} \mathcal{L}_{t,\eta}(f)(x) &=& a_t(x,\eta) \; f'(x) + \frac{1}{2} \; \sigma_t^2(x,\eta) \; f''(x) \\ && + \lambda_t(x,\eta) \; \int \; (f(y) - f(x)) \; \mathcal{K}_{t,\eta}(x,dy) \end{array}$$

Mean field particle model

$$\xi_t^i \text{ with generator } L_{t,\eta_t^N} \text{ with } \eta_t^N = N^{-1} \sum_{1 \le i \le N} \delta_{\xi_t^i}$$

Local perturbation eq.

$$d\eta_t^N(f) = \eta_t^N L_{t,\eta_t^N}(f) \ dt + rac{1}{\sqrt{N}} \ dM_t^N(f)$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

**FKS**-semigroups  $\gamma_t = \gamma_s Q_{s,t}$ 

$$Q_{s,t}(f)(x) = \mathbb{E}\left(f(X_t)\exp\left\{-\int_s^t V_u(X_u)du\right\} \mid X_s = x\right)$$

Normalization

$$\eta_t(f)$$
 :=  $\gamma_t(f)/\gamma_t(1)$ 

Jump-diffusion particles with

$$L_{t,\eta}(f)(x) = L^{X}(f)(x) + V(x) \int (f(y) - f(x)) \eta_{t}(dy)$$

Denormalization

$$\gamma_t(f) = \eta_t(f) \exp\left(-\int_0^t \eta_s(V_s) ds\right)$$

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ ■ のへで

# **FKS**-Stochastic analysis

Particle estimations

$$\mathbb{E}\left(f(X_t)\exp\left[\int_0^t W(X_s)ds\right]\right) = \eta_t(f) \exp\left[\int_0^t \eta_s(W)ds\right]$$
  
$$\stackrel{\text{unbias}}{\simeq_N} \eta_t^N(f) \exp\left[\int_0^t \eta_s^N(W)ds\right]$$

## **FKS**-Stochastic analysis

Particle estimations

$$\mathbb{E}\left(f(X_t)\exp\left[\int_0^t W(X_s)ds\right]\right) = \eta_t(f) \exp\left[\int_0^t \eta_s(W)ds\right]$$
  
$$\stackrel{\text{unbias}}{\simeq_N} \eta_t^N(f) \exp\left[\int_0^t \eta_s^N(W)ds\right]$$

Ground states of Schrodinger op. : (⊃ DMC, QMC) (v.p. λ ⊕ ground state h (L μ-reversible))

$$\lim_{N,t\to\infty}\eta_t^N\propto h\ d\mu\qquad\text{et}\quad\exp\left[\int_0^t\eta_s^N(W)ds\right]\simeq e^{\lambda t}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

# **FKS**-Stochastic analysis

Particle estimations

$$\mathbb{E}\left(f(X_t)\exp\left[\int_0^t W(X_s)ds\right]\right) = \eta_t(f) \exp\left[\int_0^t \eta_s(W)ds\right]$$
  
$$\stackrel{\text{unbias}}{\simeq_N} \eta_t^N(f) \exp\left[\int_0^t \eta_s^N(W)ds\right]$$

Ground states of Schrodinger op. : (⊃ DMC, QMC) (v.p. λ ⊕ ground state h (L μ-reversible))

$$\lim_{N,t\to\infty}\eta_t^N\propto h\ d\mu\qquad\text{et}\quad\exp\left[\int_0^t\eta_s^N(W)ds\right]\simeq e^{\lambda t}$$

► Asymptotic theory "~" discrete time models.

Some refs: dp+Miclo [00,02,03,07] ⊕ Mathias Rousset, Tony Lelièvre, and Gabriel Stoltz

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ ののの

 $\in$  MATHERIALS/MICMAC INRIA team.

Gradient diff. - Ex:  $V(x) := \frac{x^4}{4} - \frac{x^2}{2}$  and  $F(x) := \alpha \frac{x^2}{2}$ 

$$d\overline{X}_{t} = -\left[\nabla V + \nabla F * \eta_{t}\right]\left(\overline{X}_{t}\right) dt + \sigma dB_{t}$$

Applications : micro-macro-dilute physical models

$$N = 10^{25} \rightsquigarrow N^2 = 10^{50}$$
 particles "algorithm" ?

Gradient diff. - Ex:  $V(x) := \frac{x^4}{4} - \frac{x^2}{2}$  and  $F(x) := \alpha \frac{x^2}{2}$   $d\overline{X}_t = -[\nabla V + \nabla F * \eta_t](\overline{X}_t) dt + \sigma dB_t$ Applications : micro-macro-dilute physical models  $N = 10^{25} \rightsquigarrow N^2 = 10^{50}$  particles "algorithm" ?

▶ *V* convex ~→ pioneering work of Malrieux [01]+Bakry-Emery tools.

Gradient diff. - Ex:  $V(x) := \frac{x^4}{4} - \frac{x^2}{2}$  and  $F(x) := \alpha \frac{x^2}{2}$   $d\overline{X}_t = -[\nabla V + \nabla F * \eta_t](\overline{X}_t) dt + \sigma dB_t$ Applications : micro-macro-dilute physical models  $N = 10^{25} \rightsquigarrow N^2 = 10^{50}$  particles "algorithm" ?

- ▶ V convex ~→ pioneering work of Malrieux [01]+Bakry-Emery tools.
- V and F symmetric + constant first moment (a.k.a. Law(X
  0) symmetric or stationnary or ?) and α := inf F" > sup − V" > 0

$$\implies$$
  $F(x) := F(x) - \alpha \frac{x^2}{2}$  and  $V(x) := V(x) + \alpha \frac{x^2}{2}$ 

 $\subset$  convex case  $\rightsquigarrow$  Carillo-McCann-Villani [03]

Gradient diff. - Ex:  $V(x) := \frac{x^4}{4} - \frac{x^2}{2}$  and  $F(x) := \alpha \frac{x^2}{2}$   $d\overline{X}_t = -[\nabla V + \nabla F * \eta_t](\overline{X}_t) dt + \sigma dB_t$ Applications : micro-macro-dilute physical models  $N = 10^{25} \rightsquigarrow N^2 = 10^{50}$  particles "algorithm" ?

- ▶ *V* convex ~→ pioneering work of Malrieux [01]+Bakry-Emery tools.
- V and F symmetric + constant first moment (a.k.a. Law(X₀) symmetric or stationnary or ?) and α := inf F" > sup − V" > 0

$$\implies$$
  $F(x) := F(x) - \alpha \frac{x^2}{2}$  and  $V(x) := V(x) + \alpha \frac{x^2}{2}$ 

 $\subset$  convex case  $\rightsquigarrow$  Carillo-McCann-Villani [03]

V non convex and σ too small ⇒ non uniqueness invariant measures → pionnering work by Tugaut [10], σ large enough and α > 1 → Uniform propagation of chaos dp+Tugaut [13].

# Kalman-Bucy filter

#### Linear+Gaussian filtering problem

$$\begin{cases} dX_t = A X_t dt + R^{1/2} dW_t \\ dY_t = C X_t dt + \Sigma^{1/2} dV_t & \rightsquigarrow \mathcal{F}_t := \sigma(Y_s, s \leq t). \end{cases}$$

**Optimal**  $\mathbb{L}_2$ -filter = Kalman-Bucy filter

 $\widehat{X}_t := \mathbb{E}(X_t \mid \mathcal{F}_t) \quad \text{and} \quad P_t := \mathbb{E}\left( \left( X_t - \mathbb{E}(X_t \mid \mathcal{F}_t) \right) \left( X_t - \mathbb{E}(X_t \mid \mathcal{F}_t) \right)' \right)$ 

(日) (日) (日) (日) (日) (日) (日) (日) (日)

### Kalman-Bucy filter

#### Linear+Gaussian filtering problem

$$\begin{cases} dX_t = A X_t dt + R^{1/2} dW_t \\ dY_t = C X_t dt + \Sigma^{1/2} dV_t & \rightsquigarrow \mathcal{F}_t := \sigma(Y_s, s \leq t). \end{cases}$$

**Optimal**  $\mathbb{L}_2$ -filter = Kalman-Bucy filter

$$\widehat{X}_t := \mathbb{E}(X_t \mid \mathcal{F}_t) \quad ext{and} \quad \mathcal{P}_t := \mathbb{E}\left( (X_t - \mathbb{E}(X_t \mid \mathcal{F}_t)) \left( X_t - \mathbb{E}(X_t \mid \mathcal{F}_t) \right)' 
ight)$$

$$\psi$$
  
$$d\widehat{X}_t = A \ \widehat{X}_t \ dt + P_t \ C' \Sigma^{-1} \ \left( dY_t - C \widehat{X}_t \ dt \right)$$

with the Riccati equation

$$\partial_t P_t = \operatorname{Ricc}(P_t) := AP_t + P_t A' - P_t SP_t + R \quad \text{with} \quad S := C' \Sigma C$$

# Nonlinear Kalman-Bucy diffusion

$$d\overline{X}_{t} = A \,\overline{X}_{t} dt + R^{1/2} \, d\overline{W}_{t} + \mathcal{P}_{\eta_{t}} C' \Sigma^{-1} \left[ dY_{t} - \left( C\overline{X}_{t} dt + \Sigma^{1/2} \, d\overline{V}_{t} \right) \right]$$

with the covariance matrices

$$\begin{aligned} \mathcal{P}_{\eta_t} &= \eta_t \left[ (e - \eta_t(e))(e - \eta_t(e))' \right] \quad \text{with} \quad e(x) := x. \\ & \downarrow \\ & \mathbb{E} \left( \overline{X}_t \mid \mathcal{F}_t \right) = \widehat{X}_t \quad \text{and} \quad \mathcal{P}_{\eta_t} = P_t. \end{aligned}$$

**Ensemble Kalman-Bucy filter** 

= Interacting particles with empirical covariance

$$p_t := \mathcal{P}_{\eta_t^N} \simeq P_t \quad \text{and} \quad m_t = \eta_t^N(e) \simeq \mathbb{E}(X_t \mid \mathcal{F}_t)$$

### Nonlinear models

#### **Extended Kalman-Bucy-filters**

$$d\widehat{X}_t = A(\widehat{X}_t) \ dt + P_t C' \ \Sigma^{-1} \ \left[ dY_t - C\widehat{X}_t \ dt \right]$$

with the "stochastic" Riccati equation:

$$\partial_t P_t = \partial A(\widehat{X}_t) P_t + P_t \ \partial A(\widehat{X}_t)' + R - P_t SP_t$$

### Nonlinear models

#### **Extended Kalman-Bucy-filters**

$$d\widehat{X}_t = A(\widehat{X}_t) \ dt + P_t C' \ \Sigma^{-1} \ \left[ dY_t - C\widehat{X}_t \ dt \right]$$

with the "stochastic" Riccati equation:

$$\partial_t P_t = \partial A(\widehat{X}_t) P_t + P_t \ \partial A(\widehat{X}_t)' + R - P_t SP_t$$

#### **McKean-Vlasov interpretation**

$$d\overline{X}_{t} = \mathcal{A}\left(\overline{X}_{t}, \mathbb{E}[\overline{X}_{t} \mid \mathcal{G}_{t}]\right) dt + R^{1/2} d\overline{W}_{t} \\ + \mathcal{P}_{\eta_{t}}C'R_{2}^{-1} \left[dY_{t} - \left(C\overline{X}_{t} dt + \Sigma^{1/2} d\overline{V}_{t}\right)\right]$$

with the drift function

$$\mathcal{A}(x,m) := A[m] + \partial A[m] (x-m).$$

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ ▲□ ● ● ●

#### Some illustrations

Langevin type signal processes

$$R = \sigma^2 \ Id$$
 and  $(A, \partial A) = (-\partial \mathcal{V}, -\partial^2 \mathcal{V})$ 

Non quadratic potential  $(q \in \mathbb{R}^r, Q_1, Q_2 \ge 0)$ 

$$\mathcal{V}(x) = rac{1}{2} \langle \mathcal{Q}_1 x, x 
angle + \langle q, x 
angle + rac{1}{3} \langle \mathcal{Q}_2 x, x 
angle^{3/2}$$

Interacting diffusion gradient flows

$$\mathcal{V}(x) = \sum_{1 \leq i \leq r} \mathcal{U}_1(x_i) + \sum_{1 \leq i \neq j \leq r} \mathcal{U}_2(x_i, x_j)$$

for some convex confining potential  $\mathcal{U}_i : \mathbb{R}^i \mapsto [0, \infty[$ 

# Regularity conditions

**Full observation**  $S = s \ ld$  and

 $-\lambda_{\partial A}$  :=  $\sup_{x \in \mathbb{R}'^1} \lambda_{max}(\partial A(x) + \partial A(x)') < 0$ 

(日) (日) (日) (日) (日) (日) (日) (日) (日)

$$\|\partial A(x) - \partial A(y)\| \leq \kappa_{\partial A} \|x - y\|$$

**Examples: Langevin signal-diffusion** 

$$(\lambda_{\partial A}, \kappa_{\partial A}) = \beta \left( 2^{-1} \lambda_{\min}(\mathcal{Q}_1), 2\lambda_{\max}^{3/2}(\mathcal{Q}_2) \right).$$

more generally  $\partial^2 \mathcal{V} \ge v$  Id  $\oplus$  Lipschitz condition

## Stability theorem

$$(\overline{X}_t, \overline{Z}_t) =$$
McKean-Vlasov starting at  $(\overline{X}_0, \overline{Z}_0)$ 

∜

**Theo** [dp-Kurtzmann-Tugaut]

When  $\lambda_{\partial A}$  is sufficiently large we have

 $\mathbb{W}_2(\operatorname{Law}(\overline{X}_t),\operatorname{Law}(\overline{Z}_t)) \leq c \ \exp\left[-t \ \lambda\right] \ \ \text{for some} \ \ \lambda > 0.$ 

(日) (日) (日) (日) (日) (日) (日) (日) (日)

 $\exists$  more explicit description in terms of  $(R, S, \kappa_{\partial A})$ .

# Propagation of chaos

$$\mathbb{P}_t^N := \operatorname{Law}(m_t, p_t) \qquad \mathbb{P}_t := \operatorname{Law}(\widehat{X}_t, P_t)$$

and

$$\mathbb{Q}_t^N := \operatorname{Law}(\xi_t^1) \qquad \mathbb{Q}_t := \operatorname{Law}(\overline{X}_t)$$

11

Theo SIAM Control & Opt [16] [dp-Kurtzmann-Tugaut]

When 
$$\lambda_{\partial A}$$
 is sufficiently large,  $\exists \beta \in ]0, 1/2]$  s.t.  
$$\sup_{t \ge 0} \mathbb{W}_2\left(\mathbb{P}_t^N, \mathbb{P}_t\right) \lor \sup_{t \ge 0} \mathbb{W}_2\left(\mathbb{Q}_t^N, \mathbb{Q}_t\right) \le c \ N^{-\beta}$$

Linear models  $\rightsquigarrow$  unif. propagation of chaos with  $\beta=1/2$  for any stable drift matrix.

- Arxiv 1 (Stability KBF)+ A.N. Bishop
- Arxiv 2 (Perturbation KBF)+ A.N. Bishop
- Arxiv 3 (Unif. EnKBF)+ J. Tugaut.
- Arxiv 4 (Stability EKBF)+ A. Kurtzmann, J. Tugaut.

► =