

Boundary conditions in generalized belief propagation, singularities of regionalizations

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1 Context : finite statistical structures and learning

A family of finite sets $E_i; i \in I$, and a subset A of $\mathcal{P}(I)$, seen as a poset with inclusion $\beta \subseteq \alpha$ denoted by $\alpha \rightarrow \beta$. Our main interests are a simplicial complex, specially a PL manifold with boundary, or a network of disjoint cells $\alpha \in A$, connected by synapses $i \in I$. We denote by E_α the product of the E_i where i belong to α , and x_α is the generic point of E_α .

Data are *energy functions* $H_\alpha : E_\alpha \rightarrow \mathbb{R}; \alpha \in A$, giving weights $f_\alpha = e^{-\beta H_\alpha}$. For this talk, we assume that $\forall \alpha, \forall x_\alpha, f_\alpha(x_\alpha) > 0$. We denote f the product of all the $f_\alpha; \alpha \in A$.

Statistical Mechanics is interested with probability laws p on the whole product $E = \prod_i E_i$.

The statistical equilibrium is the unique minimum of the *standard free energy* (Helmholtz, Boltzmann, Gibbs)

$$F_G(p) = E_p(-\beta^{-1} \ln f) - k_B^{-1} S(p). \quad (1)$$

Where $S(p) = -k_B \sum_x p(x) \ln p(x)$ is the entropy of p .

let us take $\beta = k_B = 1$ for simplicity. For this minimum p^* , $F_G(p^*) = -\ln Z$, the Helmholtz energy.

For a Bayesian learning models, we consider probabilities on a product $E \times \Theta$, where Θ is a finite set parameterizing probability laws $p_\theta; \theta \in \Theta$ on E , such that (tautologically) the conditional probability $p((x, \theta') | \theta' = \theta)$ is $p_\theta(x)$, and (by definition) the marginal over x is the *a priori* law $p_a(\theta)$. Suppose that a subset A' of A is given, with a probability p' on the product of the sets $E_{\alpha'}; \alpha' \in A'$; the aim of learning is to identify the probability p_b on Θ which gives the better explanation of p' . It is given by the marginal p_b of the law P' on $E' \times \Theta$ which minimizes $F_V(P') = D_{KL}(P'; p' \otimes p_a)$, where $D_{KL}(P; Q) = \sum_y P(y) \ln \frac{P(y)}{Q(y)}$ is the Kullback-Leibler distance. A simple calculation shows that

$$F_V(P') = \mathbb{E}_{p_b}(-\ln p_a(\theta) + D_{KL}(X'_*(p_\theta); p') - S(p_b); \quad (2)$$

where X'_* denotes the marginal on E' . Then we find the stat structure, with the log of *a priori* as an energy, and as we will see, p' as a flux of information. However the new problem is how to compute $S(p_b)$ in a finite time?

2 Generalized Bethe free energies, Kikuchi et al.

A *regionalization* \mathcal{R} of the system is a subset of $\mathcal{P}(A)$, also seen as a poset, with $r \rightarrow s$ meaning $s \subseteq r$. We write $E_r = \prod_{i \in \alpha; \alpha \in r} E_i$, $f_r(x_r) = \prod_{\alpha \in r} f_\alpha(\pi_\alpha(x_r))$ and more generally, if $r \rightarrow s$, $f_{r,s}$ denotes the product of the $f_\alpha(\pi_\alpha(x_r))$, for $\alpha \subseteq r$, but $\alpha \not\subseteq s$.

$\mathcal{C}(\mathcal{R})$ denotes the family of probabilities on the sets E_r for $r \in \mathcal{R}$, and $\mathcal{P}(\mathcal{R})$ the subset satisfying the gluing rules (of marginals) on all possible intersections of sets r, s in \mathcal{R} on the elements of A , a presheaf.

There exists a unique family of relative integers $(c_r), r \in \mathcal{R}$, such that

$$\forall r \in \mathcal{R}, \quad \sum_{t \in \mathcal{R} | t \rightarrow r} c_t = 1. \quad (3)$$

In fact,

$$c_r = \sum_{t | t \rightarrow r} \mu_{t,r}; \quad (4)$$

wher the Moebius function $\mu : \mathcal{R} \times \mathcal{R} \rightarrow \mathbb{Z}$ of the poset \mathcal{R} satisfies

$$\forall r, s, \quad \delta_{r=s} = \sum_{t | r \rightarrow t \rightarrow s} \mu_{r,t} = \sum_{r \rightarrow t \rightarrow s} \mu_{t,s}. \quad (5)$$

Definitions : $F_{B,\mathcal{R}}(q) = \sum_{r \in \mathcal{R}} c_r F_r(q_r).$

\mathcal{R}^* is the subset of \mathcal{R} defined by $c_r \neq 0$.

Oral remarks and pictures : boundaries and butterflies

The regions r such that $c_r = 0$ appear as *singularities* in \mathcal{R} .

Definitions of $\mathcal{C}^*(\mathcal{R})$ and $\mathcal{P}^*(\mathcal{R})$ follow.

If we add the following constraints on \mathcal{R} : $\sum_{r \in \mathcal{R} | i \in r} c_r = 1, \quad \sum_{r \in \mathcal{R} | \alpha \subset r} c_r = 1$;
we recover the usual internal energy, but only local entropies :

$$F_{B,\mathcal{R}}(q) = \mathbb{E}_q(-\ln f(x)) - \sum_{r \in \mathcal{R}} c_r S(q_r). \quad (6)$$

In the case of a d -dimensional PL manifold K with smooth boundary ∂K ,
and the simplicial subdivision, this gives

$$F_B(q) = \mathbb{E}_q(-\ln f) - \sum_{\alpha \in K^*} (-1)^{d-|\alpha|} S(q_\alpha), \quad (7)$$

$$F_B(q) = \mathbb{E}_q(-\ln f) - \sum_{\alpha \in K} (-1)^{|\alpha|+1} I_{|\alpha|}(X_\alpha; q_\alpha), \quad (8)$$

where $I_{|\alpha|}(X_\alpha; q_\alpha)$ denotes the mutual information of order $|\alpha|$ of all variables associated with the vertices of α .

With these signs the combination is "almost convex", cf. Baudot and Bennequin (announcement).

Questions : existence of a minimum ? unicity ? gluing in a total probability ?

3 Generalized belief propagation

A family of messages is a set of strictly positive functions $m_{r \rightarrow s}(x_s)$. Two families are considered to be equivalent if they differ by strictly positive multiplicative constants $\lambda_{r \rightarrow s}$. The propagation algorithm is

$$m'_{r \rightarrow s}(x_s) \approx \sum_{x_r \setminus x_s} f_{r,s}(x_r) \prod_{r' \rightarrow s' | r \rightarrow s', r \nrightarrow r', s \nrightarrow s'} m_{r' \rightarrow s'}(x_{s'}) \prod_{(r' \rightarrow s' | s \nrightarrow r', r \rightarrow r', s \rightarrow s')} m_{r' \rightarrow s'}^{-1}(x_{s'}). \quad (9)$$

History: Gallager 63, Pearl 88, Yedidia, Freeman, Weiss 2001

Explanation : evolution of beliefs $b_r(x_r)$, that are probability laws :

$$n_{s \hookrightarrow r}(x_s) = \prod_{t \rightarrow s | r \nrightarrow t} m_{t \rightarrow s}(x_s); \quad b_r(x_r) \approx \prod_{r \rightarrow s} n_{s \hookrightarrow r}(x_s); \quad (10)$$

$$\frac{m'_{r \rightarrow s}(x_s)}{m_{r \rightarrow s}(x_s)} \approx \frac{\sum_{x_r \setminus x_s} b_r(x_r)}{b_s(x_s)}. \quad (11)$$

We will see later a co-homological interpretation.

The Brouwer's fixed point theorem (plus a positivity argument) implies that there always exists fixed points of the algorithm.

Divide $\mathcal{R} \setminus \mathcal{R}^*$ in two parts \mathcal{R}' and \mathcal{R}'' , such that there never exists $s' \rightarrow s''$. And choose compatible probabilities $q_{\mathcal{R}'_r}^0(x_{\mathcal{R}'_r})$ over the subsets \mathcal{R}' covered by the regions $r \in \mathcal{R}$; they are the *Dirichlet data*. And for each pair $r \rightarrow s''$, with $s'' \in \mathcal{R}''$ and $r \in \mathcal{R}^*$, a return message $n''_{s'' \hookrightarrow r}(x_{s''})$, they are the *Neumann data*.

The modified algorithm is given by the preceding rules, except

$$\forall r \in \mathcal{R}, \quad b_r(x_r) = \frac{f_r(x_r) \prod_{s|r \rightarrow s} n_{s \rightarrow r}(x_s) q_{\mathcal{R}'_r}^0(x_{\mathcal{R}'_r})}{\sum_{x_r \setminus x_{\mathcal{R}'_r}} f_r(x_r) \prod_{s|r \rightarrow s} n_{s \rightarrow r}(x_s)}. \quad (12)$$

In this case also, there always exists fixed points of the algorithm.

$\mathcal{Q} = P^*(\mathcal{R}; \mathcal{R}'' | \mathcal{R}')$ is the set of probabilities on the $E_r; r \in \mathcal{R}$, that have coherent marginals at every s in $\mathcal{R} \setminus \mathcal{R}''$, and induce the Dirichlet data in \mathcal{R}'' .

Then consider the modified generalized Bethe (Kikuchi) function on \mathcal{Q}

$$F_{B,\mathcal{R},M}(q) = \sum_{r \in \mathcal{R}} c_r (\mathbb{E}_{q_r} (-\ln f_r(x_r) - \sum_{s'' \hookrightarrow r} \ln n''_{s'' \hookrightarrow r}(x_{s''})) - S(q_r)). \quad (13)$$

Theorem : Every interior critical point of $F_{B,\mathcal{R},M}$ is the belief of a fixed point of the modified generalized belief propagation algorithm *BPNGM*. Conversely, every (non-degenerate) fixed point of *BPNGM* gives a critical belief.

This is a corrected version of the main result of Yedidia, Freeman and Weiss. See the key lemma below.

The usual implicit assumption is uniform homogeneous Neumann condition, i.e. all n'' are equal to 1, then the fixed point satisfies $m_r = 1$ for each r singular, in $\mathcal{R} \setminus \mathcal{R}^*$. However, in this case, \mathcal{Q} is a set of probabilities in R^* only, without gluing assumptions in $\mathcal{R} \setminus \mathcal{R}^*$.

4 Analogy and homology

Consider a domain Ω in \mathbb{R}^N , with a smooth boundary $\partial\Omega$, and the Poisson equation $\Delta u = f$. Two kinds of boundary conditions are usually considered : the Dirichlet condition, where the values of the solution are prescribed on the boundary $u(y) = q(y)$, and the Neumann condition, where the normal derivative along the boundary is given $\partial_\nu u(y) = n(y)$. They can be combined on different pieces $\partial'\Omega$ and $\partial''\Omega$ respectively of $\partial\Omega$.

The corresponding variational problem is

$$Min_u \int_{\Omega} \left(\frac{1}{2} |\nabla u(x)|^2 - f(x)u(x) \right) dx - \int_{\partial''\Omega} u(y)n(y) d\sigma(y); \quad (14)$$

where u is constrained to be equal to given q on $\partial'\Omega$.

It is tempting to consider f as the analog of H , the kinetic energy as the analog of minus the entropy, the Dirichlet conditions as fixed beliefs, and the Neumann conditions as fixed incoming messages n ".

Here too, homogeneous Neumann data correspond to unchanged functional and unchanged functional space.

Here too, singular points in the domain or on the boundary introduce difficulties.

In the case of a tree Γ , with roots and ending branches (picture), Pearl had shown in what sense fixed probability laws on ending branches are dual of incoming message in roots, giving a firm understanding of the belief propagation algorithm, from the principle of bayesian analysis.

With loops and higher dimensions, we enter in the field of Information Topology.

A (small) part of the thesis of Olivier Peltre.

Here we suppose that A contains the empty set \emptyset , and that for every α, β in A the inresection $\alpha \cap \beta$ belongs to A . The height (resp. depth) of α is the maximal length of a non-degenerate chain starting (resp. ending) in α . The notation \mathfrak{g}^α designate the vector space of the applications from E_α to \mathbb{R} ; the space \mathfrak{g}^\emptyset is reduced to 0. The canonical projections $\pi^{\alpha\beta} : E_\alpha \rightarrow E_\beta$ (where $\alpha \rightarrow \beta$) give injections $j_{\alpha\beta} : \mathfrak{g}^\beta \rightarrow \mathfrak{g}^\alpha$, that make from \mathfrak{g} a contravariant functor on A .

$A^{(n)}$ denote the set of non-degenerate chains of length n , and $\mathfrak{g}^{(n)}$ the direct sum of the spaces $g^{\underline{a}} \times 0_a$, where $\underline{a} = \partial_n a$ is the end of the chain a , when a describe $A^{(n)}$. The *boundary operator* ∂ from $\mathfrak{g}^{(n)}$ to $\mathfrak{g}^{(n-1)}$ is defined by

$$\forall b \in A^{(n-1)}, \quad \partial_b(\varphi_a) = \sum_{k=0}^n (-1)^{n-k} \sum_{a' | \partial_k a' = b} \varphi_{a'}; \quad (15)$$

in such a way that $\partial \circ \partial = 0$.

In particular, from $\mathfrak{g}^{(2)}$ to $\mathfrak{g}^{(1)}$,

$$\forall \gamma \in A, \quad \partial_b(\varphi_{\alpha \rightarrow \beta}) = \sum_{\beta | \gamma \rightarrow \beta} \varphi_{\gamma \rightarrow \beta} - \sum_{\alpha | \alpha \rightarrow \gamma} \varphi_{\alpha \rightarrow \gamma}. \quad (16)$$

Olivier Peltre has computed the homology of ∂ and found that only H_0 is non-trivial and isomorphic with the convex-hull of the space $\mathcal{P}(X)$. The dimension is given explicitly by the Moebius function :

$$h_0(\partial) = \sum_{\alpha} \sum_{\beta} \mu_{\alpha\beta} |\beta|. \quad (17)$$

By using the marginal $j_{\alpha\beta}^*$, the exponential and logarithm, he defined a non-linear complex of dual operators.

Definition : the *non-linear co-boundary operator* from $g^{(1)}$ to $g^{(2)}$ is defined by

$$(D^*H)_{\alpha \rightarrow \beta}(x_{\beta}) = H_{\beta}(x_{\beta}) - \ln \sum_{x_{\alpha} \setminus x_{\beta}} e^{-H_{\alpha}(x_{\alpha})}. \quad (18)$$

Proposition : the generalized belief propagation algorithm, at the level of $\ln b_{\alpha}$ consists to transform the collection $H_{\alpha}; \alpha \in A$ into the collection $H_{\alpha} + (\Delta H)_{\alpha}$, where

$$(\Delta H)_{\alpha} = \sum_{\beta | \alpha \rightarrow \beta} \partial_{\beta}(D^*H). \quad (19)$$

Then, the belief propagation algorithm can be written as a discrete non-linear heat equation :

$$\partial_{\tau} H = \Delta H. \quad (20)$$

The key lemma for establishing the theorem, by identification of Lagrange multipliers of the generalized and modified Bethe free energy with the log of the messages.

Lemma (adapted from Yedidia, Freeman, Weiss) : (i) the projection from $\mathcal{C}(\mathcal{R})$ to $\mathcal{C}^*(\mathcal{R})$ induces a bijection from $\mathcal{P}(\mathcal{R}; \mathcal{R}_1)$ to $\mathcal{P}^*(\mathcal{R}; \mathcal{R}_1)$.
(ii) The image of this projection is defined by the following "dual" set of equations :

$$\forall r \in \mathcal{R}, \forall s \in \mathcal{R} \setminus \mathcal{R}_1, r \rightarrow s, \forall x_s \in E_s : \sum_{t \in \mathcal{R} | t \rightarrow s, t \nrightarrow r} c_t \sum_{x_t \setminus x_s} q_t(x_t) = 0. \quad (21)$$

This is true for any set of singular points \mathcal{R}_1 , the case which is needed is $\mathcal{R}_1 = \mathcal{R}$.