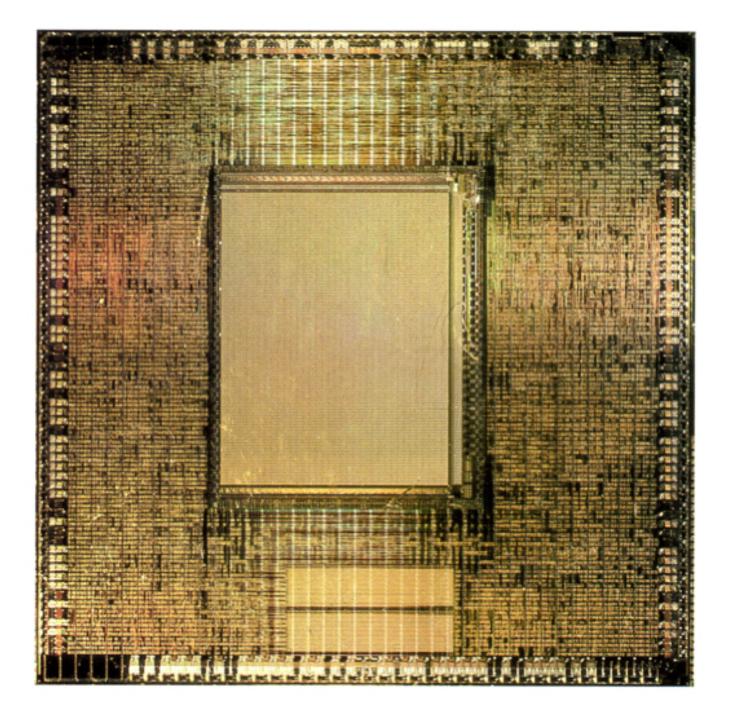
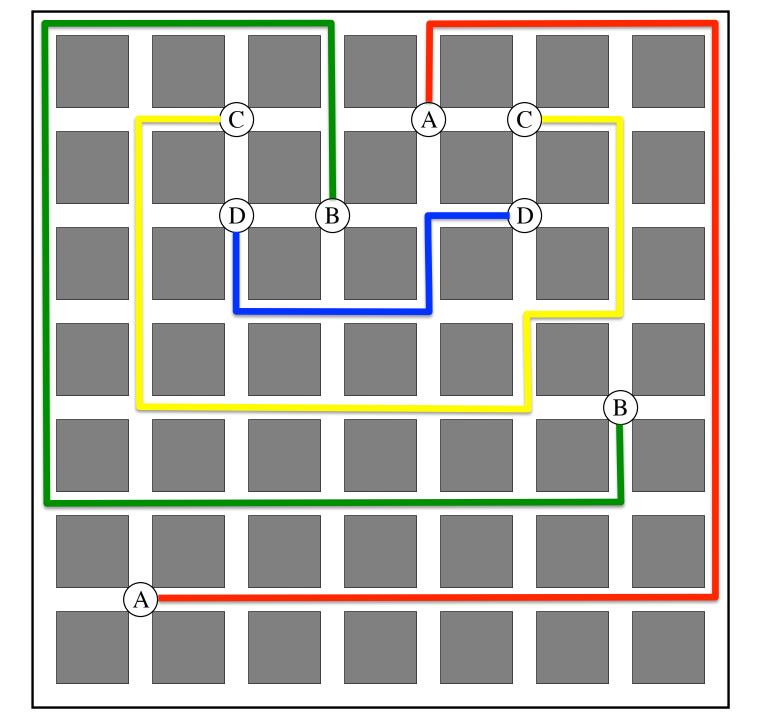


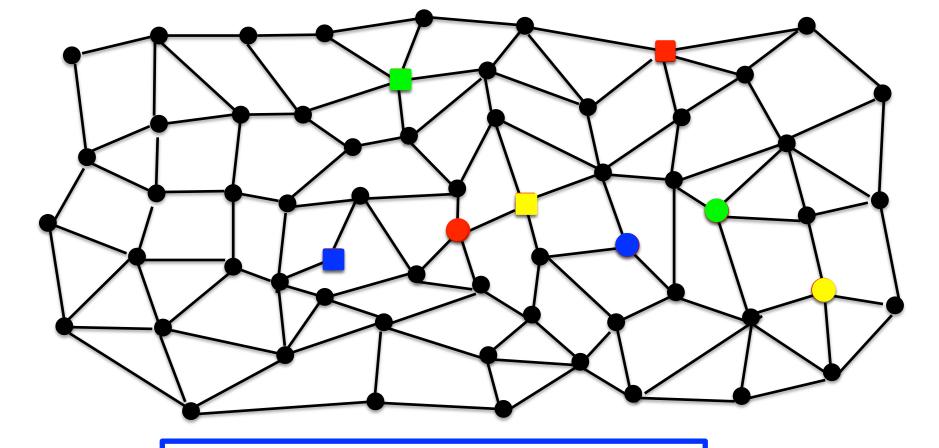
Connect sources with terminals arbitrarily: Easy

Connect given pairs of source and terminal: Hard

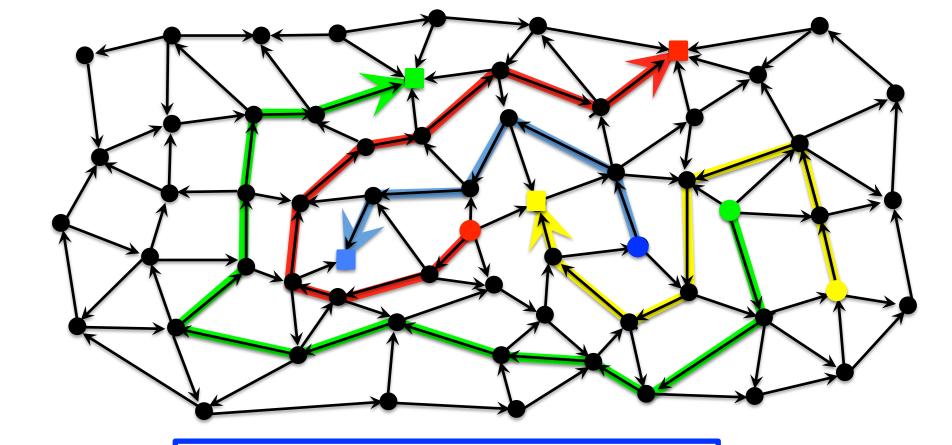
But for <u>fixed</u> number of pairs: Easy (Robertson-Seymour 1995)







What about <u>directed</u> graphs?



What about directed graphs?

For two source/terminal pairs: Hard

But for <u>planar graphs</u> and <u>fixed</u> number of source/terminal pairs: Easy

(SIAM J. Computing 1994)

**Method**: based on the *free group*  $\Gamma$  generated by  $g_1, \dots, g_k$ .

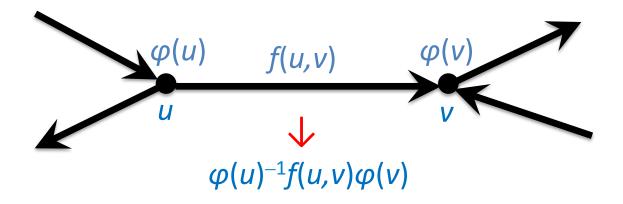
So:  $\Gamma = \{ \text{ words over the alphabet } g_1, g_1^{-1}, \dots, g_k, g_k^{-1} \text{ without } g_i g_i^{-1} \text{ or } g_i^{-1} g_i \}$ 

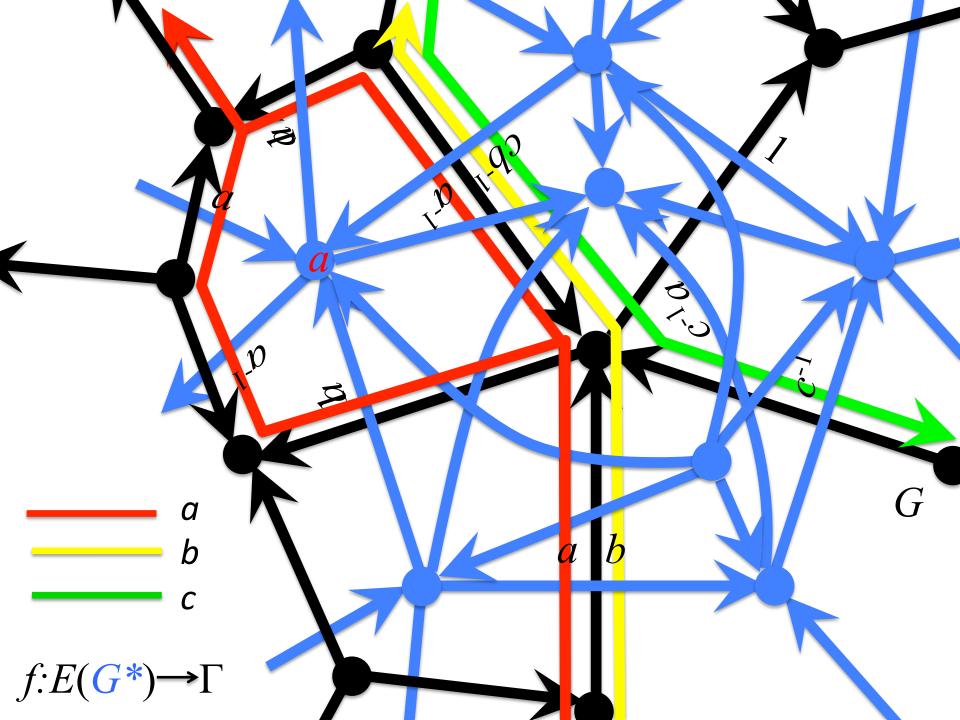
**Theorem:** The following problem is solvable in polynomial time:

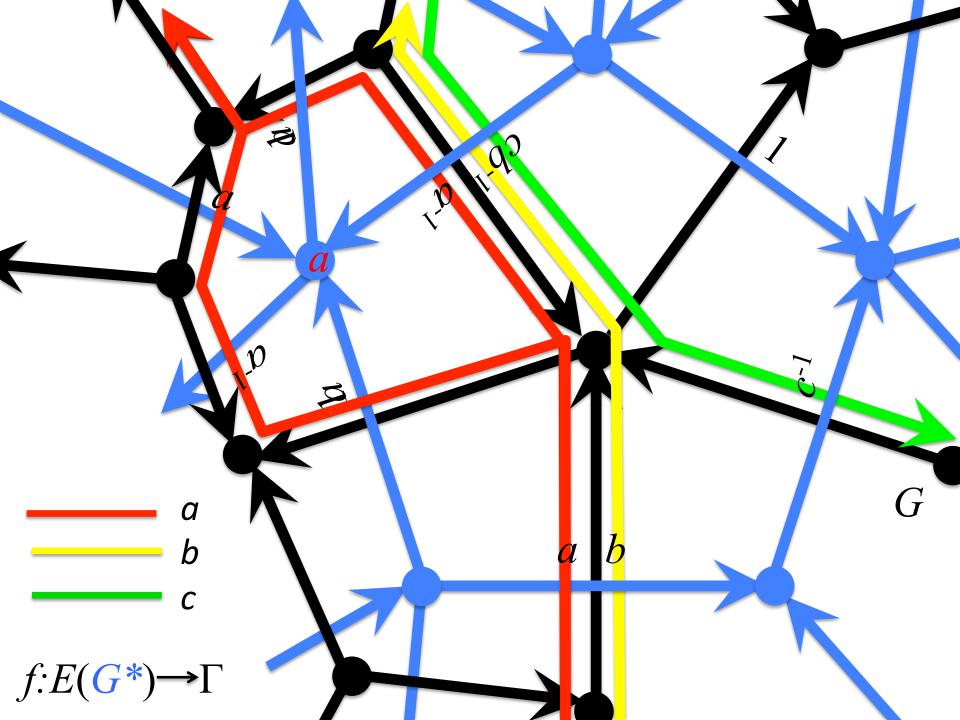
**given**: a directed graph G and a function  $f: E(G) \rightarrow \Gamma$ ,

**find**: a function  $\varphi: V(G) \to \Gamma$  such that for each edge (u,v):

$$\varphi(u)^{-1}f(u,v)\varphi(v)$$
 belongs to  $\{g_1,\ldots,g_k,1\}$ .







Method: based on the *free group*  $\Gamma$  generated by  $g_1, \dots, g_k$ .

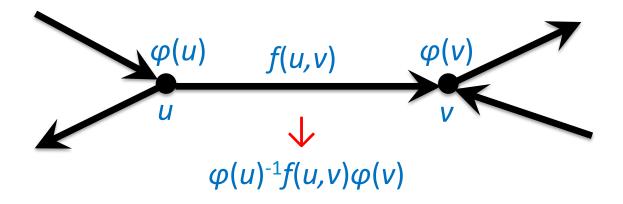
So:  $\Gamma = \{ \text{ words over the alphabet } g_1, g_1^{-1}, \dots, g_k, g_k^{-1} \text{ without } g_i g_i^{-1} \text{ or } g_i^{-1} g_i \}$ 

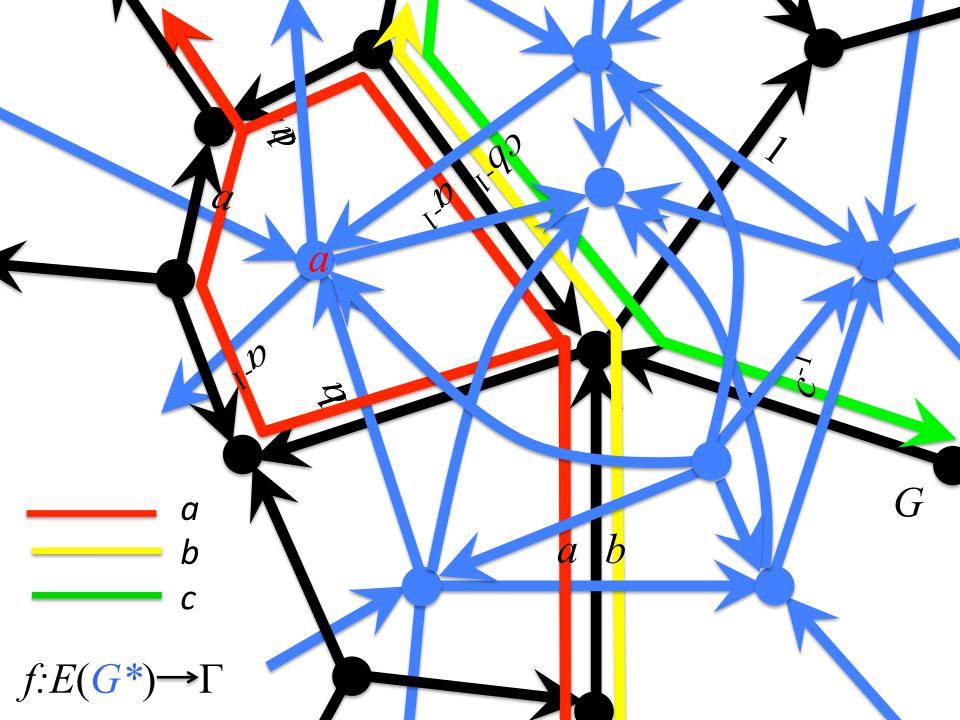
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$$\varphi(u)^{-1}f(u,v)\varphi(v)$$
 belongs to  $\{g_1,\ldots,g_k,1\}$ .





#### The *k* disjoint paths problem:

**given**: a directed graph G and vertices  $r_1, s_1, ..., r_k, s_k$  of G,

**find**: pairwise disjoint paths  $P_1, ..., P_k$  where  $P_i$  runs from  $r_i$  to  $s_i$ .

Call  $P_1, ..., P_k$  a pre-solution if

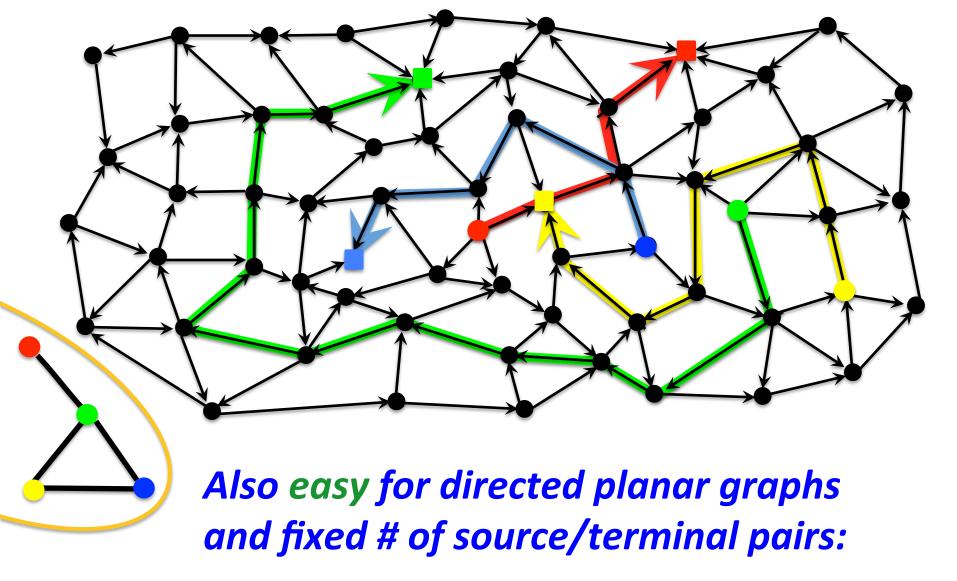
• they are undirected paths

(i.e., they may go against the direction of the edges)

they do not cross one another.

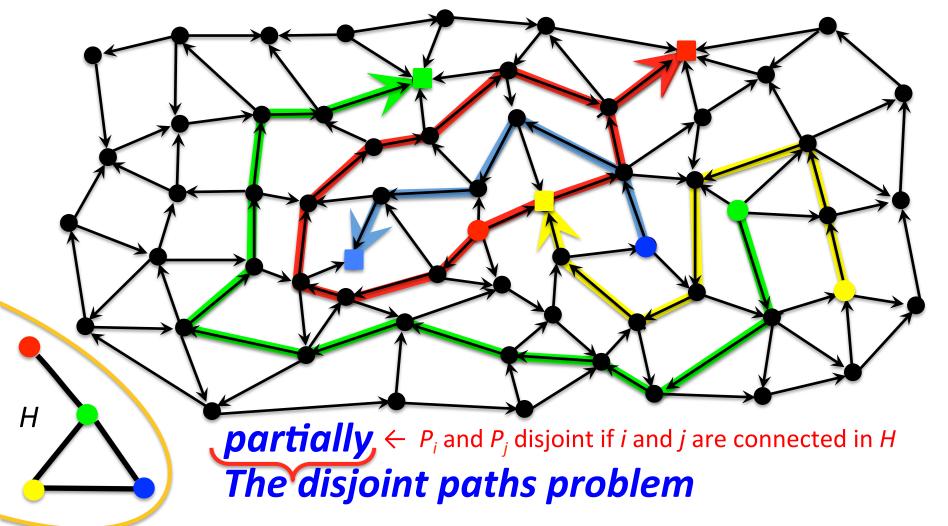
#### Algorithm:

- 1. Enumerate `sufficiently many' pre-solutions.
- 2. For each such pre-solution, check if it is homotopic to a solution.



if only certain pairs of paths need to be disjoint

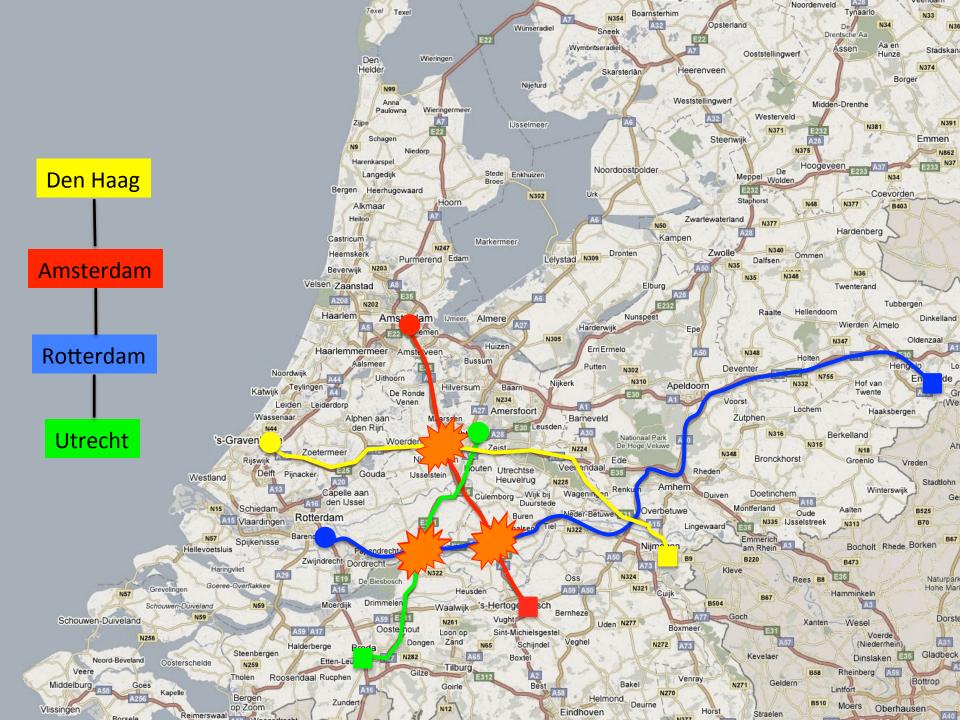
(Method: flow over the free partially commutative group)



is solvable in polynomial time for directed planar graphs for any fixed number of terminals.











given: • a graph G,

```
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• vertices r_1, s_1, \ldots, r_k, s_k of G,
```

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find: for each i a path P<sub>i</sub> in G from r<sub>i</sub> to s<sub>i</sub> such that
```

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Versions:

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Versions:

G undirected / directed

```
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Versions:

G undirected / directed vertex-disjoint / edge-disjoint paths  $P_i$ 

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given: • a graph G,
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Versions:

G undirected / directed vertex-disjoint / edge-disjoint paths  $P_i$  G planar / general

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given: \bullet a graph G,
       • vertices r_1, s_1, \ldots, r_k, s_k of G,
       • an undirected graph H with vertex set \{1,\ldots,k\},
find: for each i a path P_i in G from r_i to s_i such that
       P_i and P_i are disjoint for all i, j adjacent in H.
                              Versions:
                      G undirected / directed
             vertex-disjoint / edge-disjoint paths P_i
```

G planar / general

k fixed / unfixed

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                             Versions:
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             vertex-disjoint / edge-disjoint paths P_i
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                              Versions:
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                        G planar / general
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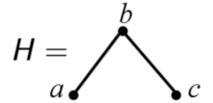
Theorem: The k partially disjoint paths problem for directed planar graphs is polynomial-time solvable, for each fixed k.

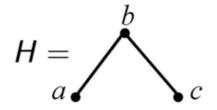
k fixed / unfixed NP-

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                              Versions:
                      G undirected / directed
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                        G planar / general
```

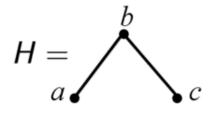
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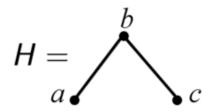




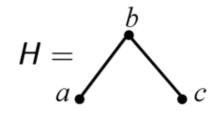
H undirected graph,



 $H = \int_{C}^{D} H \text{ undirected graph,}$   $\Gamma(H) := \text{group generated by symbol set } V(H)$ 



H = b C H undirected graph,  $\Gamma(H) := \text{group generated by symbol set } V(H)$ with relations uv = vu for all nonadjacent u, v.



H undirected graph,  $\Gamma(H) := \text{group generated by symbol set } V(H)$ C with relations uv = vu for all nonadjacent u, v.

 $aba^{-1}c$ 

$$H = \int_{a}^{b} c$$

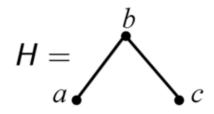
 $H = \bigcap_{a \in \mathcal{C}} H$  undirected graph,  $\Gamma(H) := \text{group generated by symbol set } V(H)$  with relations uv = vu for all nonadjacent u, v.

$$aba^{-1}c$$
  $cba^{-1}bc^{-1}aca^{-1}c$ 

$$H = \int_{a}^{b} c$$

 $H = \bigcap_{a \in \mathcal{L}} H$  undirected graph,  $\Gamma(H) := \text{group generated by symbol set } V(H)$  with relations uv = vu for all nonadjacent u, v.

$$aba^{-1}c$$
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Call 
$$x \in \Gamma(H)$$
 stable if  $x = \prod_{v \in S} v$  for some stable  $S \subseteq V(H)$ .

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Examples: ac,

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Examples: ac, b, a, c, 1.

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Examples: ac, b, a, c, 1.

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Examples: ac, b, a, c, 1.

given: undirected graph H,

$$H = \int_{a}^{b} c$$

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Examples: ac, b, a, c, 1.

given: undirected graph H, directed graph G,

$$H = \int_{a}^{b} c$$

 $H = \bigcap_{a \in \mathcal{L}} H$  undirected graph,  $\Gamma(H) := \text{group generated by symbol set } V(H)$  with relations uv = vu for all nonadjacent u, v.

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$$H = \int_{a}^{b} c$$

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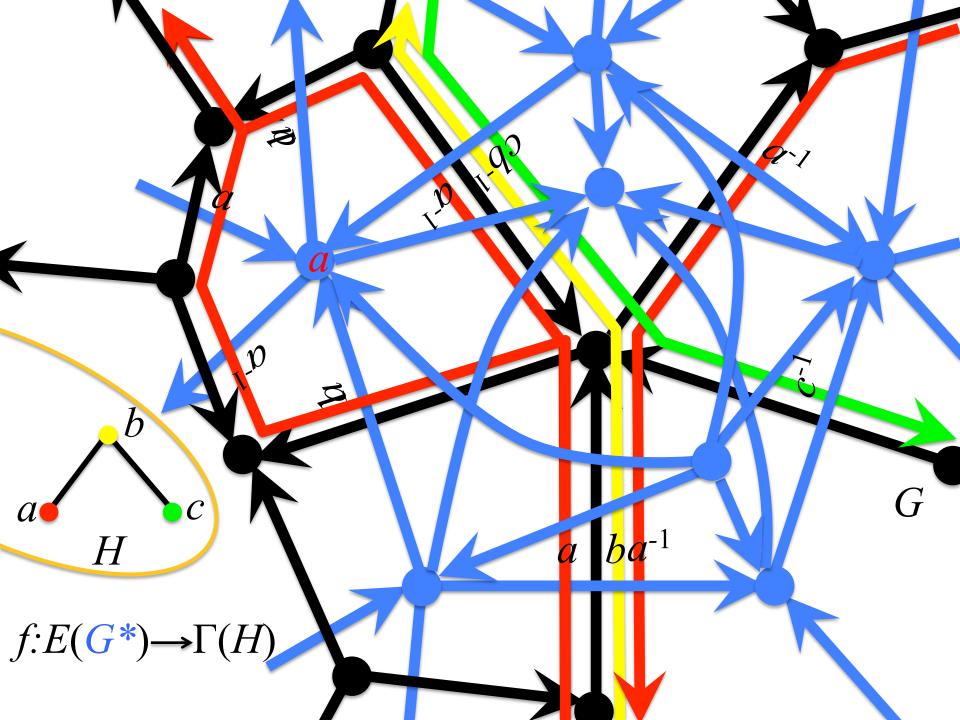
Examples: ac, b, a, c, 1.

given: undirected graph H, directed graph G, function  $f : E(G) \to \Gamma(H)$ ,

find: function  $\varphi:V(G)\to\Gamma(H)$  such that

 $\varphi(u)^{-1}f(u,v)\varphi(v)$  is stable for each edge (u,v) of G

is polynomial-time solvable.



# Algorithm

# **Algorithm**

The *k* partially disjoint paths problem:

```
given: a graph G, vertices r_1, s_1, \ldots, r_k, s_k of G, an undirected graph H with vertex set \{1, \ldots, k\},
```

```
The k partially disjoint paths problem: directed planar given: a graph G, vertices r_1, s_1, \ldots, r_k, s_k of G, an undirected graph H with vertex set \{1, \ldots, k\},
```

```
The k partially disjoint paths problem: directed planar given: a graph G, vertices r_1, s_1, \ldots, r_k, s_k of G, an undirected graph H with vertex set \{1, \ldots, k\}, find: for each i a path P_i in G from r_i to s_i such that P_i and P_i are disjoint for all i, j adjacent in H.
```

```
The k partially disjoint paths problem: directed planar given: a graph G, vertices r_1, s_1, \ldots, r_k, s_k of G, an undirected graph H with vertex set \{1, \ldots, k\}, find: for each i a path P_i in G from r_i to s_i such that P_i and P_j are disjoint for all i, j adjacent in H.
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#### Algorithm:

- 1. Enumerate 'sufficiently many' pre-solutions
- 2. For each such pre-solution, check if it is homotopic to a solution.



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