Facet-inducing inequalities and a cut-and-branch algorithm for the bandwidth coloring polytope based on orientation model

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Definition 1: Bandwidth Coloring Problem (BCP).

Let G = (V, E) be an undirected graph and $d : E \to \mathbb{Z}_+$. A feasible coloring of G and d for the BCP is an assignment of colors $c : V \to \mathbb{Z}_+$ such that for each $(i, j) \in E$, the condition $|c(i) - c(j)| \ge d(i, j)$ is true. The span, defined as $\max_{i \in V} c(i)$, must be the minimum possible.



Introduction

- Important application: channel assignment in mobile wireless networks.
 - Network consists of a number of transmitters, each responsible for calls in its area.
 - Channels must respect interference constraints.
 - Spectrum usage must be minimized.



- BCP is a **particular case** of **T-coloring**, which asks for a coloring $c: V \to \mathbb{Z}_+$ such that $|c(i) c(j)| \notin T_{i,j}$ for every $(i, j) \in E$.
 - T_{*i*,*j*}: forbidden sets [Hale, 1980].

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- If d_{i,j} = 1 for every (i, j) ∈ E, then the BCP is equivalent to the classic k-coloring problem.
 - In this case, the span max c(i) is equivalent to the number of used colors.

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- GRASP [Marti et al., 2010].

Some of our results:

simulated annealing [Dias, Freitas and Maculan, 2013],

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- integer programming [Dias, Freitas, Maculan and Michelon, 2016];
- current work: polyhedral combinatorics [Dias, Freitas, Marenco and Maculan, 2017].

Our research



Happy 75 years old, Jayme!!

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At Jayme's 65 years old Aconcagua (Andes) 2007/2008



At Jayme's 70 years old

Elbrus (Russian Caucashs) 2012



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I owe a high mountain for your 75 years, Jayme!!

Integer programming models

- Variables:
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 - *z_{max}* = maximum used color ()channel).
- C = set of possible colors.

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$$\sum_{k \in C} x_{ik} = w_i \quad (\forall i \in V)$$
2
$$x_{ik} + x_{jm} \leq 1 \quad (\forall (i, j) \in E; \forall k, m \in C : |k - m| < d_{i,j})$$
3
$$x_{ik} \leq y_k \qquad (\forall i \in V; \forall k \in C)$$
4
$$z_{\max} \geq ky_k \quad (\forall k \in C)$$
5
$$x_{ik} \in \{0, 1\} \quad (\forall i \in V; \forall k \in C)$$
6
$$y_k \in \{0, 1\} \quad (\forall k \in C)$$
7
$$z_{\max} \in \mathbb{Z}_+$$

Minimize z_{max} Subject to:

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$$\sum_{k \in C} x_{ik} = w_i \quad (\forall i \in V) < \text{Color demands}$$
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Standard IP model

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$$x_{ik} \in \{0, 1\} \quad (\forall i \in V; \forall k \in C) < \text{Integrality constraints}$$
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Improved IP model with less constraints and variables [Dias et al., 2016]:

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Orientation model for the BCP

Based on the model by [Borndörfer et al., 1998] for the classical vertex coloring problem.

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• C = set of possible colors.

Minimize z_{max} Subject to:

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$$x_i + d_{i,j} \le x_j + U(1 - y_{ij}) \ (\forall (i,j) \in E \mid i < j)$$

$$2 \quad x_j + d_{i,j} \le x_i + Uy_{ij} \qquad (\forall (i,j) \in E \mid i < j)$$

$$z_{\max} \ge x_i \qquad (\forall i \in V)$$

4 $x_i \in \mathbb{Z}_+$ $(\forall i \in V)$

5 $y_{ij} \in \{0, 1\}$ $(\forall i, j \in V \mid i < j)$

2 $x_j + d_{i,j} \le x_i + Uy_{ij}$ $(\forall (i,j) \in E \mid i < j)$

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This is a new formulation for BCP!

The formulation induces an orientation on the input graph, according to colors.



Values of variables in the optimal solution:

	z _{max} = 5	
		y ₁₂ = 1
x ₁ = 1		y ₁₃ = 1
x ₂ = 3		y ₁₄ = 1
x ₃ = 5		y ₂₄ = 1
x ₄ = 4		y ₃₄ = 0

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We define PO(G, d, U) to be the convex hull of feasible solutions to the previous formulation.

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We define PO(G, d, U) to be the convex hull of feasible solutions to the previous formulation.

Theorem 1. If $U \ge \chi(G, d) + 2d_{max}$, then the polytope PO(G, d, U) is full-dimensional.

Orientation model - Valid inequalities and facets

There are some valid inequalities (facets) proved to the Orientation model - k-coloring:

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 - Clique inequalities
 - Double clique inequalities

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Variables
$$y_{ji} = \begin{cases} 1 & \text{if } x_i < x_j, \\ 0 & \text{otherwise.} \end{cases}$$

Orientation model - Valid inequalities and facets

For the BCP: additional constraints and variables are needed to use the inequalities:

Variables
$$y_{ji} = \begin{cases} 1 & \text{if } x_i < x_j, \\ 0 & \text{otherwise.} \end{cases}$$

• Constraints
$$y_{ij} + y_{ji} = 1 \ (\forall i, j \in V).$$

Clique cuts

Definition 3. Let $i \in V$ and consider a clique $K \subseteq N(i)$. We define the *clique inequality* associated with *i* and *K* to be

$$\sum_{j\in K} y_{ji} \leq x_i.$$

The clique inequalities strengthen the bounds $x_i \ge 0$.

Generalized clique cuts

Definition 4. Let $i \in V$ and consider a clique $K \subseteq N(i)$. For $k \in K$, we define $\delta_K^i(j) := \min_{t \in K \cup \{i\} \setminus \{j\}} d_{jt}$. We define the *generalized clique inequality* associated with the vertex *i* and the clique *K* to be

$$\sum_{j\in \mathcal{K}} \delta^{j}_{\mathcal{K}}(j) y_{ji} \leq x_{i}.$$

The generalized clique cuts introduce the distance constraints to the clique cuts.









$$\delta^1_{\mathsf{K}}(\mathbf{3}) \mathbf{y_{31}} + \delta^1_{\mathsf{K}}(\mathbf{4}) \mathbf{y_{41}} + \delta^1_{\mathsf{K}}(\mathbf{5}) \mathbf{y_{51}} \leq \mathbf{x_1}$$



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$$\mathbf{2y_{31}} + \delta_{\mathbf{K}}^{\mathbf{1}}(\mathbf{4})\mathbf{y_{41}} + \delta_{\mathbf{K}}^{\mathbf{1}}(\mathbf{5})\mathbf{y_{51}} \leq \mathbf{x_1}$$



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$$\mathbf{2y_{31}} + \mathbf{1y_{41}} + \mathbf{1y_{51}} \leq \mathbf{x_1}$$

Generalized clique cuts

Theorem 2. The generalized clique inequality is valid for PO(G, d, U). If

(a)
$$U \ge \chi(G, d) + 3d_{\max}$$
,

(b)
$$d_{ij} = \delta_K^i(j)$$
 for every $j \in K$, and

(c) for every $t \in N(i) \setminus K$ there exists $j \in K$ with $jt \notin E$ and $d_{it} \leq d_{ij}$,

then the generalized clique inequality induces a facet of PO(G, d, U).

Double clique cuts

Definition 5. Let $(i, j) \in E$ and consider a clique $K \subseteq N(i) \cap N(j)$. We define

$$x_i + 1 + \sum_{v \in K} (y_{ik} - y_{jk}) \leq x_j + U(1 - y_{ij}).$$

to be the *double clique inequality* associated with the edge (i, j) and the clique K.

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to be the *double clique inequality* associated with the edge (i, j) and the clique K.

The double-clique inequalities strengthen the model constraints $x_i + d_{i,j} \le x_j + U(1 - y_{ij})$.

Generalized double clique cuts

Definition 6. Let $(i, j) \in E$ and consider a clique $K \subseteq N(i) \cap N(j)$. For $v \in K$, define $\delta_K^{ij}(v) := \min_{\ell \in K \cup \{i, j\} \setminus \{v\}} d_{v, \ell}$. Also, fix a vertex $p \in K$. We define

$$oldsymbol{x}_i + oldsymbol{d}_{i,j} + \sum_{oldsymbol{v} \in \mathcal{K}} \gamma_{oldsymbol{v}}(oldsymbol{y}_{ioldsymbol{v}} - oldsymbol{y}_{joldsymbol{v}}) \ \leq \ oldsymbol{x}_j + (oldsymbol{U} + oldsymbol{d}_{i,j} - \gamma(oldsymbol{K}))oldsymbol{y}_{joldsymbol{v}})$$

to be the *generalized double clique inequality* associated with the edge (i, j), the clique K, and the vertex p, where $\gamma_p = \max\{0, 2\delta_K^{ij}(p) - d_{i,j}\}, \gamma_v = \max\{0, \delta_K^{ij}(v) - d_{i,j}\}$ for $v \in K \setminus \{p\}$, and $\gamma(K) = \sum_{v \in K} \gamma_v$.

The generalized clique cuts introduce the distance constraints to the double clique cuts.













$$x_1 + 2 + \gamma_3(y_{13} - y_{63}) + \gamma_4(y_{14} - y_{64}) + \gamma_5(y_{15} - y_{65}) \le x_6 + (U + 2 - \gamma_K)y_{61}$$



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Generalized double clique cuts

Theorem 3. The generalized double clique inequality is valid for PO(G, d, U). If

(a) $U \ge \chi(G, d) + 4d_{\max}$, and

(b)
$$d_{i,v} = d_{j,v} = \delta_{\mathcal{K}}^{ij}(v)$$
 for every $v \in \mathcal{K}$,

(c)
$$d_{p,v} = d_{p,j}$$
 for every $v \in K \setminus \{p\}$,

(d)
$$d_{i,j} \leq \delta_K^{ij}(v)$$
 for every $v \in K \setminus \{p\}$, and

(e) $(t, p) \notin E$ and $d_{i,t} + d_{t,j} \leq d_{i,j}$ for every $t \in [N(i) \cap N(j)] \setminus K$

then the generalized double clique inequality induces a facet of PO(G, d, U).

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- Instances used: GEOM set (without multicoloring demands) [Trick et al., 2002].

Cut-and-branch for BCP - pseudocode

Require: graph G = (V, E), distances $d : E \to \mathbb{Z}_{>0}$. function CUTANDBRANCH-BCP-ORIENTATION (G = (V, E), d)*IpOrient* \leftarrow ASSEMBLELPMODEL-RELAXATION(*G*) $(x, y, z_{max}) \leftarrow LPSOLVER(IpOrient)$ if (x, y, z_{max}) is not integer then $H \leftarrow \text{GENERATEMAXIMALCLIQUES}(G)$ for each clique $K \in V$ do ADD-GENERALCLIQUECUT(*lpOrient*, $(x, y, z_{max}), K$) ADD-GENERALDBLCLIQUECUT(*IpOrient*, $(x, y, z_{max}), K$) $(x, y, z_{max}) \leftarrow LPSOLVER(lpOrient)$ if (x, y, z_{max}) is integer then break if (x, y, z_{max}) is not integer then *mipOrient* \leftarrow CHANGEVARSTOINT(*lpOrient*) $(x, y, z_{max}) \leftarrow B\&C-MIPSOLVER(mipOrient)$ return (x, y, z_{max})

Computational experiments - Orientation model

Inetanco	Stand	ard model	Orientation model		
instance	Best	Time	Best	Time	
GEOM20	21	0.33	21		
GEOM30	28	0.88	28		
GEOM40	28	1.97	28		
GEOM50	28	21.44	28		
GEOM60	33	45.73	33		
GEOM70	38	533.53	38		
GEOM80	41	3019.18	41		

Computational experiments - Orientation model

Instance	Stand	ard model	Orientation model		
instance	Best	Time	Best	Time	
GEOM20	21	0.33	21	0.03	
GEOM30	28	0.88	28	0.22	
GEOM40	28	1.97	28	0.19	
GEOM50	28	21.44	28	4.26	
GEOM60	33	45.73	33	149.60	
GEOM70	38	533.53	38	121.61	
GEOM80	41	3019.18	41	2167.43	

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GEOM70	38	533.53	38	121.61	
GEOM80	41	3019.18	41	2167.43	

The orientation model has advantages on most problems in comparison with the standard IP model.

Computational experiments - Orientation model: cuts

Instance	CPLEX		C&B: CPLEX + cuts		
Instance	Best	Time (s)	Best	Time (s)	
GEOM20	21	0.03	21	0.02	
GEOM30	28	0.22	28	0.25	
GEOM40	28	0.19	28	0.87	
GEOM50	28	4.26	28	43.63	
GEOM60	33	149.60	33	18.07	
GEOM70	38	121.61	38	11.66	
GEOM80	41	2167.43	41	22.76	

The clique and double-clique inequalities are quite useful within the cut-and-branch procedure.

Computational experiments - Orientation model: cuts

Instance	CPLEX					
	Cliques	Imp.Bnd.	MI Round.	0-Half	Gomory	
GEOM20	0	7	14	1	1	
GEOM30	0	12	52	8	2	
GEOM40	0	13	49	14	4	
GEOM50	0	53	123	40	4	
GEOM60	0	45	233	54	1	
GEOM70	0	135	213	51	1	
GEOM80	0	182	318	69	1	

Instance	C&B: CPLEX + cuts					
	Cliques	Imp.Bnd.	MI Round.	0-Half	Gomory	
GEOM20	0	6	1	4	2	
GEOM30	1	24	13	3	7	
GEOM40	3	33	37	5	6	
GEOM50	17	47	72	16	22	
GEOM60	21	85	102	23	26	
GEOM70	22	94	161	44	23	
GEOM80	16	98	170	43	30	

More CPLEX clique and Gomory cuts are added when the valid inequalities are included.
Computational experiments

Orientation model and cut-and-branch: discussions

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- The clique and double-clique inequalities proved to be useful within a cut-and-branch procedure.
- More CPLEX clique and Gomory cuts are added when the valid inequalities are included.
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Orientation model and cut-and-branch: discussions

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- More CPLEX clique and Gomory cuts are added when the valid inequalities are included.
- The orientation model seems to be a better platform than the standard model for tackling BCP with integer programming.
- Further cuts are possible, which indicates that the orientation model is a very competitive approach to BCP.

We proposed a new orientation-based IP formulation for the Bandwidth Coloring Problem, which seems to be a better platform than the standard model for tackling BCP with integer programming.

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Current work:

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Current work:

- Search for more facet-inducing inequalities, and implement a branch-and-cut procedure for BCP.
- Try to apply the distance model for the BCP.

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Merci!

Thank you!

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